$$c_t = c1 c_{t+1} + (1 - c1) c_{t-1} - c2 (r_t - \pi_{t+1} - \varepsilon_{b_t})$$

$$\tag{1}$$

$$i_t = i1 i_{t-1} + (1-i1) i_{t+1} + i2 q_t + \varepsilon_{q_t}$$
(2)

$$q_t = q_1 r^k_{t+1} - (r_t - \pi_{t+1} - \varepsilon_{bt}) + (1 - q_1) q_{t+1}$$
(3)

$$y_t = c_t \cos y + i_t \sin y + \cos y + \varepsilon_{q_t} \tag{4}$$

$$y_t = cpsip \ (calpha \ k_t + (1 - calpha) \ n_t + \varepsilon_{at}) \tag{5}$$

$$\pi_t - cgammap \,\pi_{t-1} = pi1 \,\left(\pi_{t+1} - \pi_t \, cgammap\right) - pi2 \,\left(100 \,\varepsilon_{p_t} - mc_t\right) \tag{6}$$

$$mc_t = (1 - calpha) w_t + calpha r^k_t - \varepsilon_{at}$$
 (7)

$$\pi_t + w_t - w_{t-1} = \pi_{t-1} cgammaw + cbeta (\pi_{t+1} + w_{t+1} - w_t - \pi_t cgammaw) - w1 (comega u_t - 100 \varepsilon_{wt})$$
(8)

$$comega u_t = w_t - (z_t + \varepsilon_{st} + comega e_t)$$

$$(9)$$

$$comega u^n_t = 100 \varepsilon_{wt} \tag{10}$$

$$l_t = u_t + e_t \tag{11}$$

$$z_{t} = (1 - cv) z_{t-1} + \frac{cv}{1 - \frac{ch}{ctau}} \left(c_{t} - c_{t-1} \frac{ch}{ctau} \right)$$
(12)

$$\bar{k}_t = k1 \,\bar{k}_{t-1} + i_t \,(1 - k1) + \varepsilon_{q_t} \,k2 \tag{13}$$

$$k_t = v_t + \bar{k}_{t-1} \tag{14}$$

$$v_t = r^k_t \, \frac{1 - cpsi}{cpsi} \tag{15}$$

$$k_t = n_t + w_t - r^k_{\ t} \tag{16}$$

$$r_t = crhointr \, r_{t-1} + (1 - crhointr) \, \left(\pi_t \, crpi + cry \, y^{gap}_{\ t} + crdy \, \left(y^{gap}_{\ t} - y^{gap}_{\ t-1} \right) \right) - \varepsilon_{rt}$$

$$\tag{17}$$

$$e_t - e_{t-1} = cbeta \ (e_{t+1} - e_t) + e1 \ (n_t - e_t)$$
 (18)

$$cf_{t} = c1 cf_{t+1} + (1 - c1) cf_{t-1} - c2 (rf_{t} - \varepsilon_{bt})$$

$$(19)$$

$$invf_t = \varepsilon_{q_t} + i1 invf_{t-1} + (1 - i1) invf_{t+1} + i2 qf_t$$
 (20)

$$qf_{t} = q1 \, rk f_{t+1} - (rf_{t} - \varepsilon_{bt}) + (1 - q1) \, qf_{t+1} \tag{21}$$

$$yf_t = \varepsilon_{g_t} + ccy \, cf_t + ciy \, inv f_t + cvy \, vf_t \tag{22}$$

$$yf_t = cpsip\left(\varepsilon_{at} + calpha \, kf_t + (1 - calpha) \, nf_t\right) \tag{23}$$

$$0 = (1 - calpha) w f_t + calpha r k f_t - \varepsilon_{at}$$

$$(24)$$

$$wf_t = \varepsilon_{st} + zf_t + comega \, nf_t \tag{25}$$

$$zf_t = (1 - cv) zf_{t-1} + \frac{cv}{1 - \frac{ch}{ctau}} \left(cf_t - \frac{ch}{ctau} cf_{t-1} \right)$$

$$\tag{26}$$

$$kbarf_t = \varepsilon_{q_t} k2 + k1 \, kbarf_{t-1} + (1 - k1) \, invf_t$$
 (27)

$$kf_t = vf_t + kbarf_{t-1} \tag{28}$$

$$vf_t = \frac{1 - cpsi}{cpsi} \, rkf_t \tag{29}$$

$$kf_t = nf_t + wf_t - rkf_t \tag{30}$$

$$ef_t - ef_{t-1} = cbeta (ef_{t+1} - ef_t) + e1 (nf_t - ef_t)$$
 (31)

$$y^{gap}_{t} = y_t - yf_t \tag{32}$$

$$\varepsilon_{bt} = \operatorname{crhob} \varepsilon_{bt-1} + \eta_{bt} \tag{33}$$

$$\varepsilon_{q_t} = \operatorname{crhoq} \varepsilon_{q_{t-1}} + \eta_{q_t} \tag{34}$$

$$\varepsilon_{g_t} = \operatorname{crhog} \varepsilon_{g_{t-1}} + \eta_{g_t} + \operatorname{crhoga} \eta_{a_t} \tag{35}$$

$$\varepsilon_{at} = \eta_{at} + crhoa\,\varepsilon_{at-1} \tag{36}$$

$$\varepsilon_{p_t} = \operatorname{crhop} \varepsilon_{p_{t-1}} + \eta_{p_t} - \operatorname{cmup} AUX_EXO_LAG_54_0_{t-1} \tag{37}$$

$$\varepsilon_{rt} = \operatorname{crhor} \varepsilon_{rt-1} + \eta_{rt} \tag{38}$$

$$\varepsilon_{st} = \operatorname{crhos} \varepsilon_{st-1} + \eta_{st} \tag{39}$$

$$\varepsilon_{wt} = \operatorname{crhow} \varepsilon_{wt-1} + \eta_{wt} - \operatorname{cmuw} AUX_EXO_LAG_56_0_{t-1}$$

$$\tag{40}$$

$$dyobs_t = y_t + ctaubar + cebar - y_{t-1} (41)$$

$$dcobs_t = c_t + ctaubar + cebar - c_{t-1} (42)$$

$$diobs_t = i_t + ctaubar + cebar - i_{t-1} \tag{43}$$

$$piobs_t = \pi_t + cpibar \tag{44}$$

$$dwobs_t - piobs_t = w_t + ctaubar - w_{t-1} - (\pi_t - \pi_{t-1})$$

$$\tag{45}$$

$$deobs_t = e_t + cebar - e_{t-1} \tag{46}$$

$$uobs_t = u_t + cubar (47)$$

$$robs_t = 4 \, crbar + r_t \, 4 \tag{48}$$

$$ryear_t = r_t \, 4 \tag{49}$$

$$piyear_t = \pi_t + \pi_{t-1} + AUX_ENDO_LAG_2_1_{t-1} + AUX_ENDO_LAG_2_2_{t-1}$$
 (50)

$$AUX_ENDO_LAG_2_1_t = \pi_{t-1} \tag{51}$$

$$AUX_ENDO_LAG_2_2_t = AUX_ENDO_LAG_2_1_{t-1}$$
(52)

$$AUX_EXO_LAG_54_0_t = \eta_{p_t} \tag{53}$$

$$AUX_EXO_LAG_56_0t = \eta_{wt} \tag{54}$$