

Question.2-05

함수 \vec{f} 가 $\vec{\theta}$ 에 대해 다음과 같이 주어졌을 때, Jacobian matrix $\frac{\partial \vec{f}(\vec{\theta})}{\partial \vec{\theta}}$ 를 구하시오.

$$\vec{\theta} = \begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \quad \vec{f}(\vec{\theta}) = \begin{pmatrix} f_1(\vec{\theta}) \\ f_2(\vec{\theta}) \\ f_3(\vec{\theta}) \end{pmatrix} = \begin{pmatrix} (\theta_1)^3 - 2(\theta_2)^2 + 10 \\ \ln(\theta_1) - \sin(\theta_1)\cos(\theta_2) \\ e^{\theta_1+10} - e^{2\theta_2} \end{pmatrix}$$

즉각 $\vec{\theta}, \vec{f}$ 에 대한 Jacobian은

$$\frac{\partial \vec{f}(\vec{\theta})}{\partial \vec{\theta}} = \begin{pmatrix} \frac{\partial f_1(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_1(\vec{\theta})}{\partial \theta_2} \\ \frac{\partial f_2(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_2(\vec{\theta})}{\partial \theta_2} \\ \frac{\partial f_3(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_3(\vec{\theta})}{\partial \theta_2} \end{pmatrix} = \begin{pmatrix} \nabla_{\vec{\theta}} f_1(\vec{\theta}) \\ \nabla_{\vec{\theta}} f_2(\vec{\theta}) \\ \nabla_{\vec{\theta}} f_3(\vec{\theta}) \end{pmatrix}$$

이제, 이제 각각 $\nabla_{\vec{\theta}} f_1(\vec{\theta}), \nabla_{\vec{\theta}} f_2(\vec{\theta}), \nabla_{\vec{\theta}} f_3(\vec{\theta})$ 를 구하면 다음과 같다.

$$\begin{aligned} \frac{\partial f_1(\vec{\theta})}{\partial \theta_1} &= \frac{\partial}{\partial \theta_1} [(\theta_1)^3 - 2(\theta_2)^2 + 10] = 3(\theta_1)^2 \\ \frac{\partial f_1(\vec{\theta})}{\partial \theta_2} &= \frac{\partial}{\partial \theta_2} [(\theta_1)^3 - 2(\theta_2)^2 + 10] = -4\theta_2 \end{aligned} \quad \longrightarrow \quad \nabla_{\vec{\theta}} f_1(\vec{\theta}) = \begin{pmatrix} \frac{\partial f_1(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_1(\vec{\theta})}{\partial \theta_2} \end{pmatrix} = (3(\theta_1)^2, -4\theta_2)$$

$$\begin{aligned} \frac{\partial f_2(\vec{\theta})}{\partial \theta_1} &= \frac{\partial}{\partial \theta_1} [\ln(\theta_1) - \sin(\theta_1)\cos(\theta_2)] = \frac{1}{\theta_1} - \cos(\theta_1)\cos(\theta_2) \\ \frac{\partial f_2(\vec{\theta})}{\partial \theta_2} &= \frac{\partial}{\partial \theta_2} [\ln(\theta_1) - \sin(\theta_1)\cos(\theta_2)] = \sin(\theta_1)\sin(\theta_2) \end{aligned} \quad \longrightarrow \quad \nabla_{\vec{\theta}} f_2(\vec{\theta}) = \begin{pmatrix} \frac{\partial f_2(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_2(\vec{\theta})}{\partial \theta_2} \end{pmatrix} = \left(\frac{1}{\theta_1} - \cos(\theta_1)\cos(\theta_2), \sin(\theta_1)\sin(\theta_2) \right)$$

$$\begin{aligned} \frac{\partial f_3(\vec{\theta})}{\partial \theta_1} &= \frac{\partial}{\partial \theta_1} [e^{(\theta_1+10)} - e^{2\theta_2}] = e^{\theta_1+10} \\ \frac{\partial f_3(\vec{\theta})}{\partial \theta_2} &= \frac{\partial}{\partial \theta_2} [e^{(\theta_1+10)} - e^{2\theta_2}] = -2e^{2\theta_2} \end{aligned} \quad \longrightarrow \quad \nabla_{\vec{\theta}} f_3(\vec{\theta}) = \begin{pmatrix} \frac{\partial f_3(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_3(\vec{\theta})}{\partial \theta_2} \end{pmatrix} = (e^{\theta_1+10}, -2e^{2\theta_2})$$

따라서 구하고자하는 Jacobian은 다음과 같다.

$$\frac{\partial \vec{f}(\vec{\theta})}{\partial \vec{\theta}} = \begin{pmatrix} \frac{\partial f_1(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_1(\vec{\theta})}{\partial \theta_2} \\ \frac{\partial f_2(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_2(\vec{\theta})}{\partial \theta_2} \\ \frac{\partial f_3(\vec{\theta})}{\partial \theta_1} & \frac{\partial f_3(\vec{\theta})}{\partial \theta_2} \end{pmatrix} = \begin{pmatrix} 3(\theta_1)^2 & -4\theta_2 \\ \frac{1}{\theta_1} - \cos(\theta_1)\cos(\theta_2) & \sin(\theta_1)\sin(\theta_2) \\ e^{\theta_1+10} & -2e^{2\theta_2} \end{pmatrix}$$