

Question.2-03

함수 f 가 $\vec{\theta}$ 에 대해 다음과 같이 주어졌을 때, Jacobian matrix $\frac{\partial f(\vec{\theta})}{\partial \vec{\theta}}$ 를 구하시오.

$$1) \quad \vec{\theta} = \begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} \quad f(\vec{\theta}) = (\theta_1)^3 - 2(\theta_2)^2 + \theta_1\theta_3$$

$$2) \quad \vec{\theta} = \begin{pmatrix} \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} \quad f(\vec{\theta}) = \ln^2(\theta_1) - 3e^{\theta_2\theta_3} + \tan(\theta_3)$$

1) 주어진 $f(\vec{\theta})$ 가 $\theta_1, \theta_2, \theta_3$ 에 대한 함수이므로 Jacobian을 구하기 위해서는 $\frac{\partial f(\vec{\theta})}{\partial \theta_1}$, $\frac{\partial f(\vec{\theta})}{\partial \theta_2}$, $\frac{\partial f(\vec{\theta})}{\partial \theta_3}$ 를 각각 구해야 한다. 이를 계산해보면 다음과 같다.

$$\begin{aligned} \frac{\partial f(\vec{\theta})}{\partial \theta_1} &= \frac{\partial}{\partial \theta_1} [(\theta_1)^3 - 2(\theta_2)^2 + \theta_1\theta_3] \\ &= \frac{\partial}{\partial \theta_1} [(\theta_1)^3] - 2\frac{\partial}{\partial \theta_1} [(\theta_2)^2] + \frac{\partial}{\partial \theta_1} [\theta_1\theta_3] \\ &= 3\theta_1^2 + \theta_3 \end{aligned}$$

$$\begin{aligned} \frac{\partial f(\vec{\theta})}{\partial \theta_2} &= \frac{\partial}{\partial \theta_2} [(\theta_1)^3 - 2(\theta_2)^2 + \theta_1\theta_3] \\ &= \frac{\partial}{\partial \theta_2} [(\theta_1)^3] - 2\frac{\partial}{\partial \theta_2} [(\theta_2)^2] + \frac{\partial}{\partial \theta_2} [\theta_1\theta_3] \\ &= -4\theta_2 \end{aligned}$$

$$\begin{aligned} \frac{\partial f(\vec{\theta})}{\partial \theta_3} &= \frac{\partial}{\partial \theta_3} [(\theta_1)^3 - 2(\theta_2)^2 + \theta_1\theta_3] \\ &= \frac{\partial}{\partial \theta_3} [(\theta_1)^3] - 2\frac{\partial}{\partial \theta_3} [(\theta_2)^2] + \frac{\partial}{\partial \theta_3} [\theta_1\theta_3] \\ &= \theta_1 \end{aligned}$$

따라서 Jacobian은 다음과 같다.

$$\begin{aligned} \frac{\partial f(\vec{\theta})}{\partial \vec{\theta}} &= \left(\frac{\partial f(\vec{\theta})}{\partial \theta_1}, \frac{\partial f(\vec{\theta})}{\partial \theta_2}, \frac{\partial f(\vec{\theta})}{\partial \theta_3} \right) \\ &= (3\theta_1^2 + \theta_3, -4\theta_2, \theta_1) \end{aligned}$$

2) 1)과 같은 방법으로 partial derivative를 구하면

$$\begin{aligned} \frac{\partial f(\vec{\theta})}{\partial \theta_1} &= \frac{\partial}{\partial \theta_1} [\ln^2(\theta_1) - 3e^{\theta_2\theta_3} + \tan(\theta_3)] \\ &= \frac{\partial}{\partial \theta_1} [\ln^2(\theta_1)] - 3\frac{\partial}{\partial \theta_1} [e^{\theta_2\theta_3}] + \frac{\partial}{\partial \theta_1} [\tan(\theta_3)] \\ &= 2\ln(\theta_1) \cdot \frac{\partial}{\partial \theta_1} [\ln(\theta_1)] \\ &= \frac{2}{\theta_1} \ln(\theta_1) \end{aligned}$$

$$\begin{aligned}
 \frac{\partial f(\vec{\theta})}{\partial \theta_2} &= \frac{\partial}{\partial \theta_2} [\ln^2(\theta_1) - 3e^{\theta_2 \theta_3} + \tan(\theta_3)] \\
 &= \frac{\partial}{\partial \theta_2} [\ln^2(\theta_1)] - 3 \frac{\partial}{\partial \theta_2} [e^{\theta_2 \theta_3}] + \frac{\partial}{\partial \theta_2} [\tan(\theta_3)] \\
 &= -3e^{\theta_2 \theta_3} \cdot \frac{\partial}{\partial \theta_2} [\theta_2 \theta_3] \\
 &= -3\theta_3 e^{\theta_2 \theta_3}
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial f(\vec{\theta})}{\partial \theta_3} &= \frac{\partial}{\partial \theta_3} [\ln^2(\theta_1) - 3e^{\theta_2 \theta_3} + \tan(\theta_3)] \\
 &= \frac{\partial}{\partial \theta_3} [\ln^2(\theta_1)] - 3 \frac{\partial}{\partial \theta_3} [e^{\theta_2 \theta_3}] + \frac{\partial}{\partial \theta_3} [\tan(\theta_3)] \\
 &= -3e^{\theta_2 \theta_3} \cdot \frac{\partial}{\partial \theta_3} [\theta_2 \theta_3] + \sec^2(\theta_3) \\
 &= -3\theta_2 e^{\theta_2 \theta_3} + \sec^2(\theta_3)
 \end{aligned}$$

따라서 Jacobian은 다음과 같다.

$$\begin{aligned}
 \frac{\partial f(\vec{\theta})}{\partial \vec{\theta}} &= \left(\frac{\partial f(\vec{\theta})}{\partial \theta_1}, \frac{\partial f(\vec{\theta})}{\partial \theta_2}, \frac{\partial f(\vec{\theta})}{\partial \theta_3} \right) \\
 &= \left(\frac{2}{\theta_1} \ln(\theta_1), -3\theta_3 e^{\theta_2 \theta_3}, -3\theta_2 e^{\theta_2 \theta_3} + \sec^2(\theta_3) \right)
 \end{aligned}$$