

MASSIMILIANO PATACCHIOLA

Name	Massimiliano
Surname	Patacchiola
Address	Plymouth, Devon, United Kingdom
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Nationality	Italian
Sex	Male

Profile

Researcher specialised in computational modelling through machine learning and deep learning techniques. Interdisciplinary skills in robotics, artificial intelligence, neuroscience and experimental psychology. Interests: trust and transparency in AI, deep learning, reinforcement learning, robotics.

Education

2015-present	PhD candidate in “Cognitive Robotics and Computational Modelling”. Plymouth University, School of Computing, Electronics and Mathematics. United Kingdom. Supervisors: Angelo Cangelosi, Torbjorn Dahl, Giorgio Metta www.thrive-project.org
2009-2011	MSc in “Cognitive Neuroscience”. La Sapienza University. Rome, Italy. Supervisors: Stefano Puglisi Allegra, Gianluca Baldassarre, Domenico Parisi
2006-2009	BSc in “Experimental Cognitive Psychology”. La Sapienza University. Rome, Italy. Supervisor: Marta Olivetti Belardinelli
1999-2004	Secondary School. Scientific Course: National Plan of Computer Science. Rieti, Italy. It gives entry to university. Main subjects: computer science, mathematics (linear algebra, pre-calculus, calculus), physics, biology, English, French.

Work/Research Experience

2015-present	Teaching assistant and demonstrator. Plymouth University. United Kingdom. I prepared and presented the material for individual lessons and workshops on Deep Learning, Bayesian Networks and Robotics.
2012-2015	Robotics Engineer. Eurolink Systems group. Rome. Italy. My duties involved creating algorithms and models for the control of UGV (Unmanned Ground Vehicle) and UAV (Unmanned Aerial Vehicle) (www.eurolinksystems.com)
2011-2012	Internship, LARAL (Laboratory of Artificial Life and Robotics). Institute of Cognitive Sciences and Technologies. Rome, Italy. My duties involved creating

cognitive models for simulations in Evolutionary Robotics (<http://laral.istc.cnr.it>)

2008-2009 Placement, ECONA (Research Centre for Cognitive Elaboration on Natural and Artificial Systems). La Sapienza University. Rome, Italy. Research project on visual perception and memory (<https://web.uniroma1.it/econa>)

Technical Skills

Machine Learning	-Programming experience with TensorFlow for Deep Learning applications. -Experience with Artificial Neural Networks and the most recent Deep Learning techniques (e.g MLP, CNN, ResNet, GAN, Inception, etc). -Experience with supervised, unsupervised learning algorithms, reinforcement learning (DQN, Double DQN, MC, SARSA, etc), and Bayesian networks.
Robotics	-I developed libraries for the control of humanoid robots, drones and autonomous ground rover. -Experience with the most important software tools for Robotics and Computer Vision (e.g. ROS, YARP, NAOqi, OpenAI Gym, OpenCV).
Computer Science	-Advanced knowledge of Unix OS (Shell, Bash scripting, SSH). -Proficiency in Python (Numpy) and familiarity with several programming languages (C/C++, C#, Java, Visual Basic, HTML, PHP, JavaScript).

Languages

Italian (native speaker), English (advanced), French (intermediate)

Awards, Fellowships and Scholarships

2018-present	Associate Fellowship, Higher Education Academy (HEA). Programme that supports early career researchers who have responsibility for teaching and learning.
03-2016	Academic Hardware Grant, NVIDIA corporation. I received a Tesla K40 GPU in support of a project on head pose estimation through convolutional neural networks.
2012-present	Member, Mensa International. Society for people with high intelligence quotient.

Talks, Conferences, Workshops, Media

27-07-2017	(Extra) BBC documentary. Hyper Evolution: Rise of the Robots. Episode 1 and 2, the iCub humanoid robot at CRNS lab.
2015-present	(Reviewer) I have been the reviewer for different conferences and journals: ICRA (International Conference on Robotics and Automation), IROS (International Conference on Intelligent Robots and Systems), ACM Transactions on Interactive

Selected Publications [\[scholar\]](#)

Polvara* R., **Patacchiola* M.**, Sharma, S., Wan J., Manning, A., Sutton R., Cangelosi, A. (under review). “Autonomous Quadrotor Landing using Deep Reinforcement Learning”. *Co-first authors, [\[arxiv\]](#)

Patacchiola, M., Cangelosi, A. (2017). “Head Pose Estimation in the Wild using Convolutional Neural Networks and Adaptive Gradient Methods”. *Pattern Recognition*, vol. 71, pp. 132-143. [\[pdf\]](#)

Zanatto, D., **Patacchiola, M.**, Goslin, J., Cangelosi, A. (2016). “Priming antropomorphism: Can the credibility of humanlike robots be transferred to non-humanlike robots?”. *In Proceeding of the Eleventh Annual ACM/IEEE International Conference on Human Robot Interaction*, Christchurch, New Zeland, pp. 534-544. [\[pdf\]](#)

Paglieri, F., Parisi D., **Patacchiola, M.**, Petrosino, G. (2015). “Investigating intertemporal choice trough experimental evolutionary robotics”. *Behavioural Processes*, vol. 115, pp. 1-18. [\[pdf\]](#)