

## Chapter 4: Continuous Variables and Their Probability Distributions

Chapter 4 extends probability theory from discrete to continuous random variables, introducing the mathematical machinery necessary to model measurements and quantities that can take any value within an interval.

### Introduction and Fundamental Concepts (Sections 4.1-4.2)

The transition from discrete to continuous random variables requires replacing probability mass functions with probability density functions (PDFs). For continuous variables, individual point probabilities are zero; instead, we work with probabilities over intervals. The probability density function  $f(y)$  satisfies  $f(y) \geq 0$  and  $\int_{-\infty}^{\infty} f(y)dy = 1$ . Probabilities are computed as areas under the density curve:  $P(a \leq Y \leq b) = \int_a^b f(y)dy$ .

The cumulative distribution function (CDF)  $F(y) = P(Y \leq y) = \int_{-\infty}^y f(t)dt$  provides an alternative representation. A key property distinguishing continuous from discrete variables: for continuous random variables,  $P(Y = c) = 0$  for any specific value  $c$ , which means  $P(a < Y < b) = P(a \leq Y \leq b)$ —endpoint inclusion doesn't affect probability.

### Expected Values (Section 4.3)

Expected values extend continuous variables, replacing summation with integration. For a continuous random variable  $Y$  with density  $f(y)$ :

- Mean:  $E(Y) = \mu = \int_{-\infty}^{\infty} yf(y)dy$
- Variance:  $V(Y) = \sigma^2 = \int_{-\infty}^{\infty} (y - \mu)^2 f(y)dy = E(Y^2) - [E(Y)]^2$
- General expectations:  $E[g(Y)] = \int_{-\infty}^{\infty} g(y)f(y)dy$

Linear transformations preserve the linearity properties:  $E(aY + b) = aE(Y) + b$  and  $V(aY + b) = a^2V(Y)$ .

### The Uniform Distribution (Section 4.4)

The uniform distribution represents complete uncertainty over an interval  $(\theta_1, \theta_2)$ , with constant density:

$$f(y) = \frac{1}{\theta_2 - \theta_1}, \quad \theta_1 \leq y \leq \theta_2$$

Key properties include  $E(Y) = \frac{\theta_1 + \theta_2}{2}$  and  $V(Y) = \frac{(\theta_2 - \theta_1)^2}{12}$ .

## The Normal Distribution (Section 4.5)

The normal (Gaussian) distribution is

$$f(y) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(y-\mu)^2/(2\sigma^2)}, \quad -\infty < y < \infty$$

The standard normal distribution has  $\mu = 0$  and  $\sigma = 1$ . Any normal variable can be standardized via  $Z = \frac{Y-\mu}{\sigma}$ , enabling probability calculations using standard normal tables. The normal distribution is symmetric about its mean, with approximately 68% of observations within one standard deviation, 95% within two standard deviations, and 99.7% within three standard deviations (the empirical rule).

## The Gamma Distribution (Section 4.6)

The gamma distribution models waiting times and durations, with density:

$$f(y) = \frac{y^{\alpha-1}e^{-y/\beta}}{\beta^\alpha \Gamma(\alpha)}, \quad y > 0$$

where  $\Gamma(\alpha) = \int_0^\infty y^{\alpha-1}e^{-y}dy$  is the gamma function. Parameters are  $\alpha$  (shape) and  $\beta$  (scale), with  $E(Y) = \alpha\beta$  and  $V(Y) = \alpha\beta^2$ .

Special cases include:

- Exponential distribution:  $\alpha = 1$ , modeling time between events
- Chi-squared distribution:  $\alpha = \nu/2$ ,  $\beta = 2$ , fundamental in statistical inference

The exponential distribution is memoryless:  $P(Y > s + t | Y > s) = P(Y > t)$ .

## The Beta Distribution (Section 4.7)

The beta distribution is defined on the interval  $(0, 1)$ , used for proportional probabilities

$$f(y) = \frac{y^{\alpha-1}(1-y)^{\beta-1}}{B(\alpha, \beta)}, \quad 0 < y < 1$$

where  $B(\alpha, \beta) = \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)}$  is the beta function. The mean is  $E(Y) = \frac{\alpha}{\alpha+\beta}$  and variance is  $V(Y) = \frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$ .

Note: symmetric when  $\alpha = \beta$ , skewed right when  $\alpha < \beta$ , skewed left when  $\alpha > \beta$ . The special case  $\alpha = \beta = 1$  reduces to the uniform distribution.

## Distribution Relationships (Section 4.8)

Several distributions are interconnected through limiting processes or parameter specializations. The normal approximates the binomial for large  $n$ . The exponential is a special case of the gamma. Linear transformations of normal variables remain normal.

## Moment-Generating Functions (Section 4.9)

Moment-generating functions  $m(t) = E(e^{tY})$  Key MGFs include:

- Exponential:  $m(t) = (1 - \beta t)^{-1}$
- Normal:  $m(t) = e^{\mu t + \frac{1}{2}\sigma^2 t^2}$
- Gamma:  $m(t) = (1 - \beta t)^{-\alpha}$

MGFs uniquely determine distributions and facilitate proving that linear combinations of independent normal variables are normal.

## Tchebysheff's Theorem (Section 4.10)

Tchebysheff's theorem provides distribution-free probability bounds:

$$P(|Y - \mu| \leq k\sigma) \geq 1 - \frac{1}{k^2}$$

This applies to any distribution with finite variance, guaranteeing that at least 75% of observations lie within two standard deviations of the mean, and at least 89% within three standard deviations. While conservative for specific distributions (like the normal), it provides useful bounds when the exact distribution is unknown.

## Chapter 4 in a Nutshell

Integrate where you would sum in discrete probability distributions.