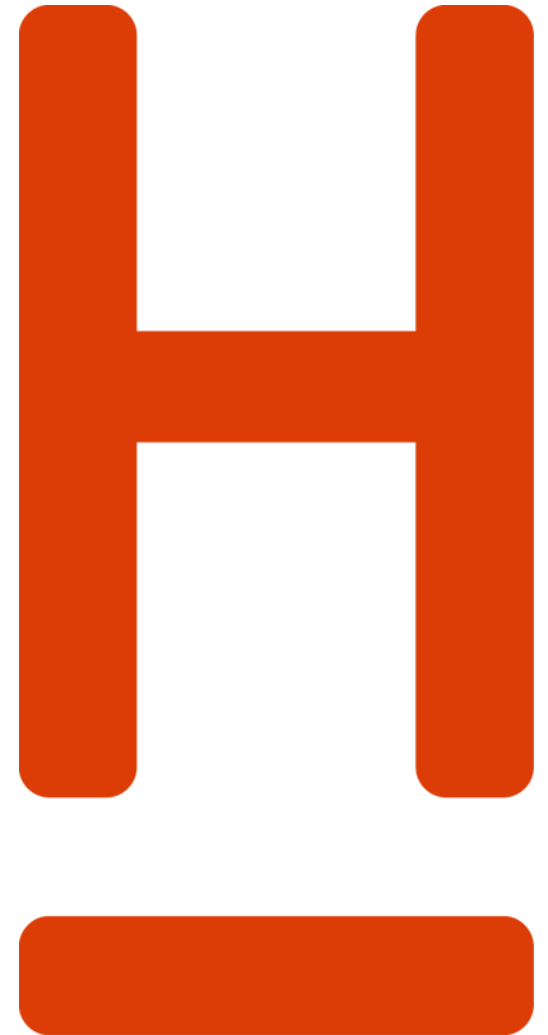


**HOCHSCHULE  
HANNOVER**  
UNIVERSITY OF  
APPLIED SCIENCES  
AND ARTS

–  
*Fakultät IV  
Wirtschaft und  
Informatik*

# **Fahrzeugvernetzung – V2X**

*Lecture 4: Medium Access Control Protocols*



# Lecture 4

## *Previous Lecture*

- ▶ **Geographic Networking (GeoNetworking)**
  - ▶ *GeoNetworking Beaconing*
- ▶ **Addressing Methods**
  - ▶ *GeoUnicast, GeoAnyCast, GeoBroadcast,*
  - ▶ *Single-Hop Broadcast, Topological Scoped Broadcast (TSB)*
- ▶ **Forwarding Algorithms**
  - ▶ *Greedy Forwarding (GF) algorithm*
  - ▶ *Contention-based Forwarding (CBF) algorithm*
- ▶ **Location Service**
  - ▶ *Reactive Location Service (RLS)*
  - ▶ *Simple Location Service (SLS)*
- ▶ **Duplicate Packet Detection Technique**



# Lecture 4

## *Outline*

- ▶ Multiple Access Approaches
- ▶ Random Access Protocols
- ▶ Reservation-based Access Protocols
- ▶ Carrier Sense Multiple Access
- ▶ Hidden/Exposed Terminal Problem
- ▶ TDMA-based MAC Protocols for V2X



# Lecture 4

## *Coordination of Access to Communication Medium*

- ▶ How to **coordinate the access** of **multiple sending** and **receiving** stations to a **shared** broadcast channel?
- ▶ Consider a **classroom** where a **teacher** and **students** share the same, single, broadcast medium. A central problem is that of determining **who** gets to talk (that is, transmit into the channel), and **when**
  - ▶ We have to elaborate a set of protocols for sharing the broadcast channel:
    - ▶ *“Raise your hand if you have a question”*
    - ▶ *“Don’t monopolize the conversation”*
    - ▶ *“Don’t interrupt when someone is speaking”*
- ▶ Computer networks similarly have protocols - so-called **multiple access protocols** - by which stations **regulate their transmissions** into the shared broadcast channel



# Lecture 4

## *Multiple Access Approaches (1/2)*

### ► Characteristics:

- **Shared medium:** All stations share the same communication channel
- **Broadcast medium:** All stations within a transmission range of sender receive the signal

### ► Challenges:

- Often **no centralized control** and **uncoordinated** channel access
- A sender **cannot block access** to the channel by others
- If more than **two stations** transmit at the same time **collisions may occur** at all of the receivers



# Lecture 4

## *Multiple Access Approaches (2/2)*

- ▶ **Static allocation** of sub-channel:
  - ▶ Channel capacity is **divided** among the stations
  - ▶ **Frequency, time, or code** is reserved for each station
  - ▶ **No further control** of channel access is needed
  - ▶ Provide well-defined **quality of service** (latency, throughput, etc.)
  
- ▶ **Dynamic assignment** of the channel
  - ▶ **No a priori allocation** – Before sending stations have to **obtain permission** to send
  - ▶ Access procedure can have **centralized** control or it can be **decentralized**
  
- ▶ **Random access**
  - ▶ **No a priori allocation** – No coordination of/among stations
  - ▶ **Collisions** are inevitable – But have to be detected and fixed



# Lecture 4

## *Medium Access Control (MAC) Protocols*

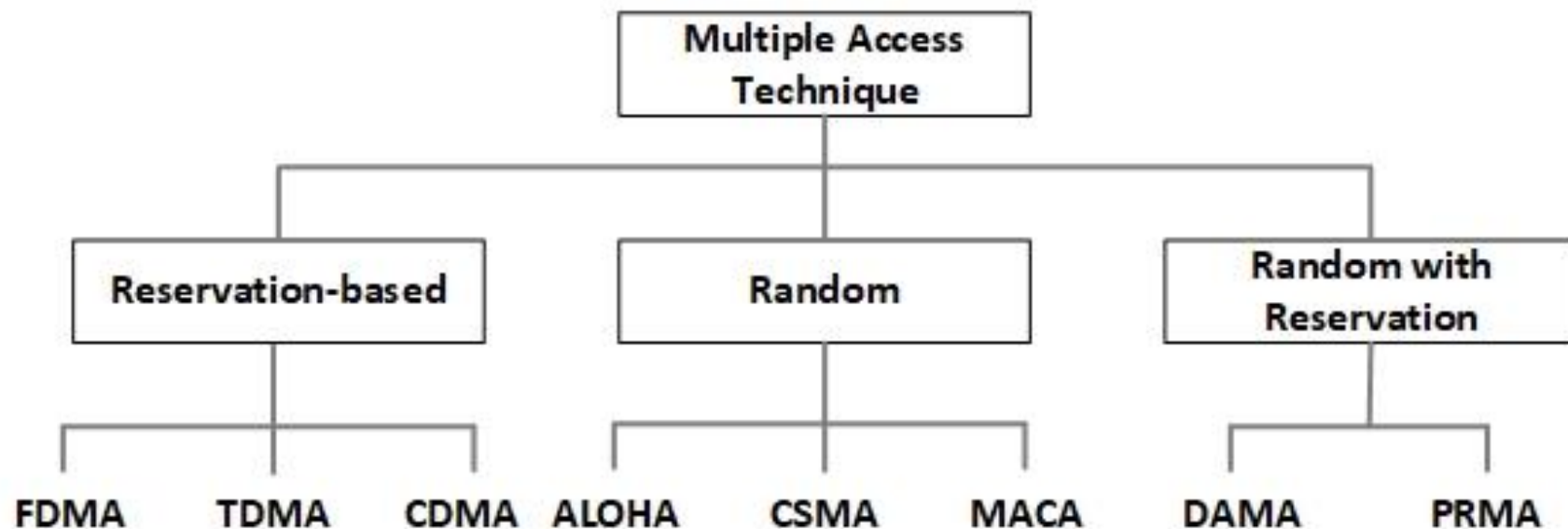
- ▶ Medium access control protocols are needed – Which approach to choose?
  - ▶ Centralized vs. distributed
  - ▶ Deterministic vs. stochastic
  - ▶ **Challenge: Coordination among stations (Who? When?)**
  
- ▶ MAC protocol is responsible for **regulating access** to the **shared communication medium** by scheduling transmissions in
  - ▶ Time - TDMA
  - ▶ Frequency - FDMA
  - ▶ Space - SDMA
  - ▶ Unique codes - CDMAto distinguish different users



# Lecture 4

## *Classification of Wireless MAC Protocols*

- ▶ Three main categories of MAC protocols for **wireless networks**:
  - ▶ **Reservation-based**: Static allocation or dynamic assignment of resources to stations
  - ▶ **Random access**: Stations compete for the channel using randomized procedures - No collision free allocation
  - ▶ **Random with reservation**: Stations compete using **random access** to obtain a dynamic assignment of resources

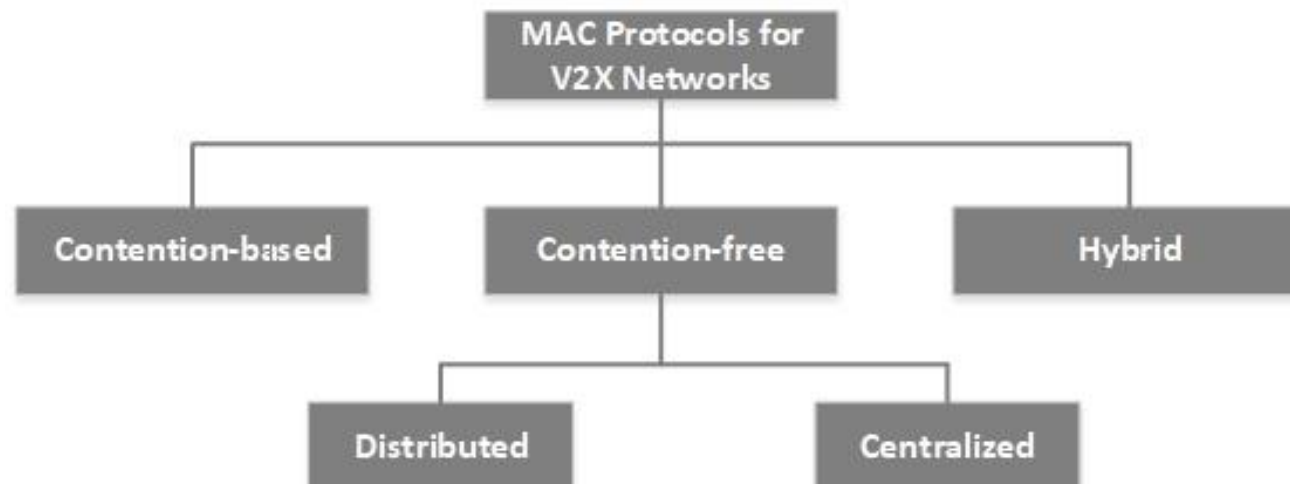




# Lecture 4

## MAC Protocols for V2X

- ▶ Three main categories of MAC protocols for **V2X networks**:
  - ▶ **Contention-based**: No predetermined schedule and vehicles are allow to access the channel randomly when they need to transmit – Collisions may occur
  - ▶ **Contention-free**: Requires a predetermined channel access schedule. Each vehicle is allow to access the channel by a predetermined time slot, frequency band or code sequence
    - ▶ No message collisions between vehicles in the **same** two-hop neighborhood
  - ▶ **Hybrid**: Combine contention-based and contention-free to provide a high QoS and reduce the collision probability



# Lecture 4

## *Requirements on MAC Layer for V2X-Networks*

- ▶ **Self-organizing:** Scheduling of transmissions have to be performed in a distributed manner
- ▶ **Reactiveness:** Management of allocated resources should be flexible and fast enough to let the protocol react timely to topology changes due to mobility
- ▶ **Scalability:** Number of stations participating in the network is **unknown a priori**. This number is expected to grow to several hundreds of stations that are within radio range of each other
  - ▶ MAC protocol should be non-blocking such that new vehicles can always transmit
- ▶ **Mitigation of hidden terminal situations:** Hidden terminal problem is present in V2X networks regardless of MAC method
  - ▶ For each MAC protocol it is necessary to evaluate the **impact of hidden terminals** in terms of performance degradations

# Lecture 4

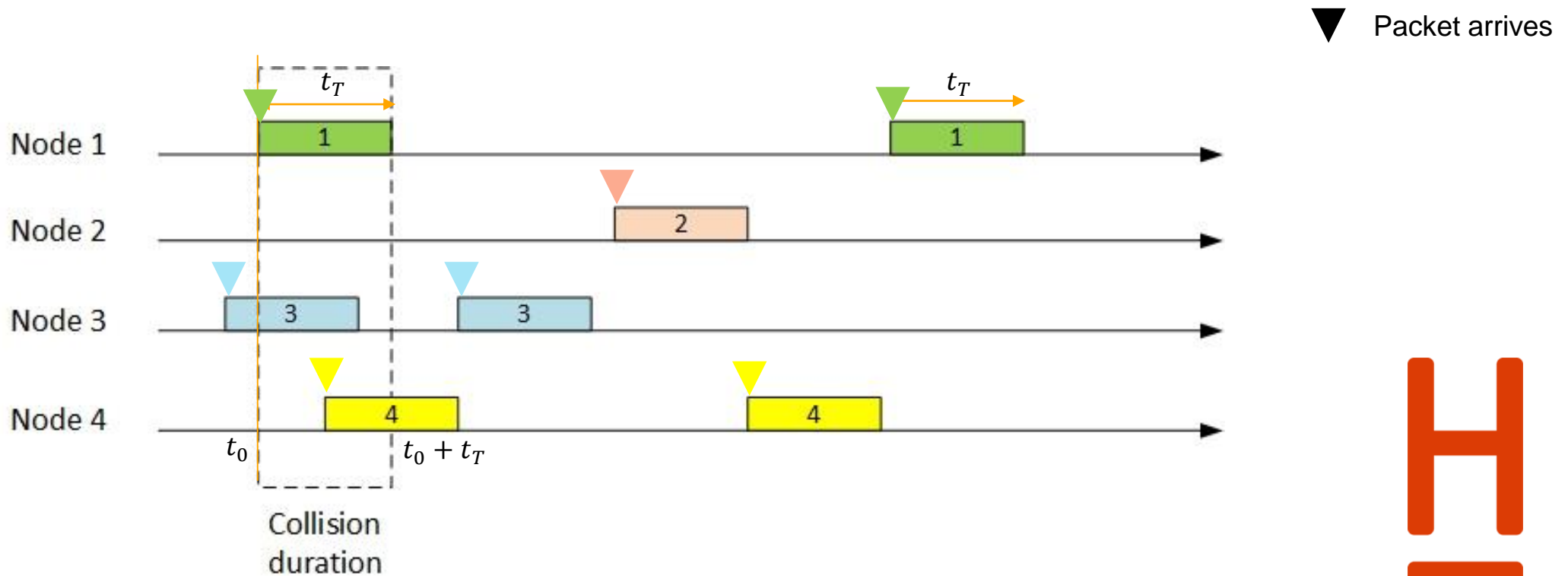
## *Requirements on MAC Layer for Road Traffic Safety Applications*

- ▶ **Delay:** Road traffic safety applications require a **predictable channel access** such that the maximum channel access delay is upper-bounded
  - ▶ Real-time deadlines can be supported
  
- ▶ **Reliability:** MAC protocol should schedule transmissions to minimize interference between stations
  - ▶ Minimize **interference** between transmitters to maximize the **packet reception probability** for the **closest neighboring** stations is desirable
  
- ▶ **Fairness:** All the stations should be able to access the channel with **equal probability** within a limited time period, e.g. the CAM update frequency
  - ▶ This can be enforced by a predictable MAC method

# Lecture 4

## Pure ALOHA Protocol

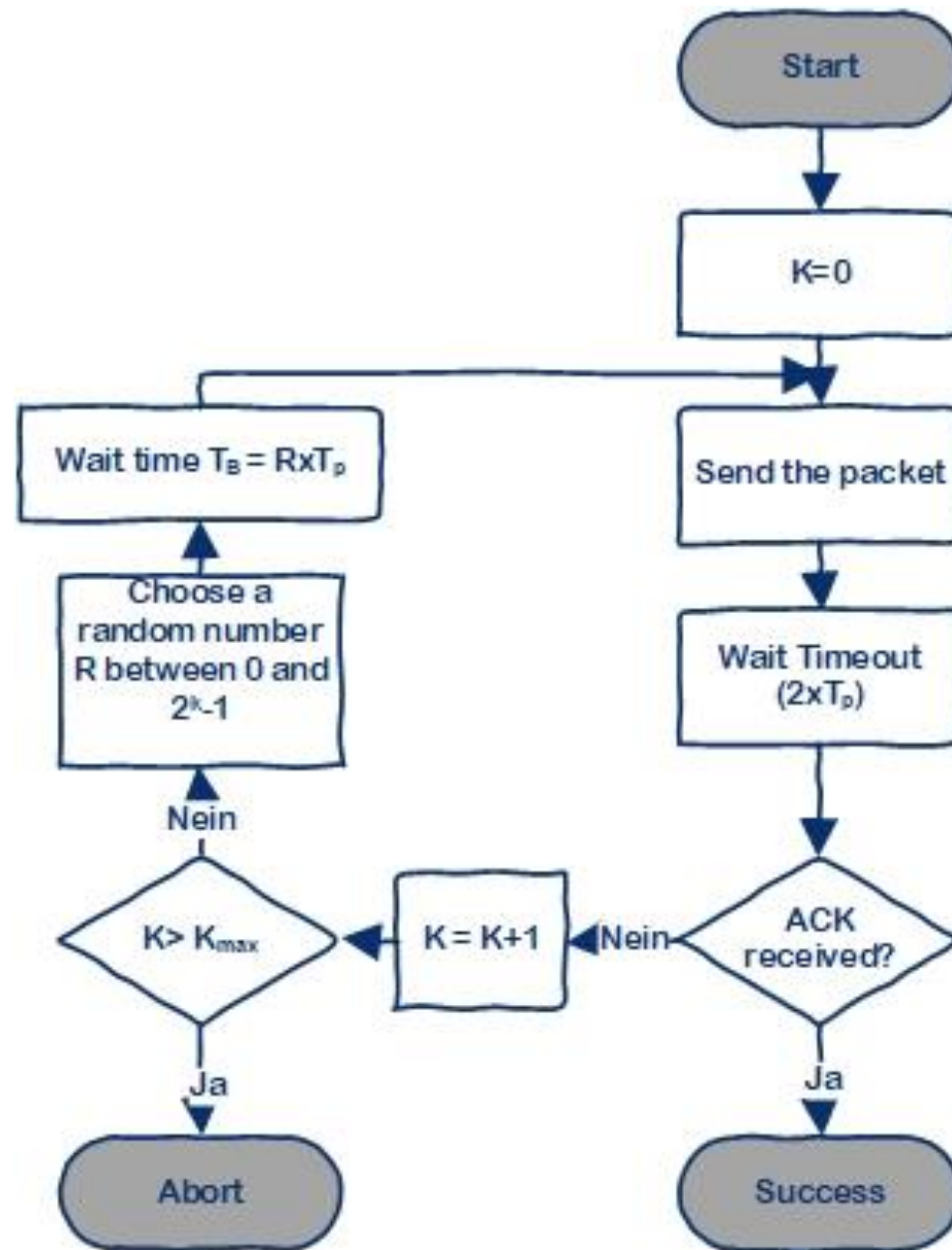
- ▶ An unslotted **fully decentralized** protocol
- ▶ Whenever a station has a packet to send, it **simply transmits** the packet
  - ▶ If collision occurs, it waits for a **random period** of time and re-sends it again



# Lecture 4

## Procedure for pure ALOHA

- $K$  is the number of attempts,  $K_{\max}$  is 15
- $T_p$  is the maximum propagation time



# Lecture 4

## *Derivation of Efficiency of pure ALOHA*

- ▶ Suppose there are  $N$  stations
- ▶ Assume all stations use packets with transmission duration  $t_T$
- ▶ Assume that each station always has a packet to send and that the station transmits with **probability  $p$**  for a fresh packet as well as for a packet retransmission
- ▶ Probability that all other stations do not begin a transmission in the interval  $[t_0 - t_T, t_0]$  is  $(1 - p)^{N-1}$
- ▶ Probability that all other stations do not begin a transmission in the interval  $[t_0, t_0 + t_T]$  is also  $(1 - p)^{N-1}$

- ▶ Probability that **a given station has a successful** transmission

$$p(1 - p)^{N-1}(1 - p)^{N-1} = p(1 - p)^{2(N-1)}$$

- ▶ Efficiency: Probability that any one of the  **$N$  stations** has a success (Transmission without collision)

$$E(p) = Np(1 - p)^{2(N-1)}$$



# Lecture 4

## Maximum Efficiency of pure ALOHA

- **Efficiency:** Probability that any one of the  $N$  stations has a success  $E(p) = Np(1 - p)^{2(N-1)}$
- Maximum efficiency  $E_{\max}$  → Find the  $p^*$  that maximizes the efficiency for a large number of stations  $N \rightarrow \infty$

$$\frac{dE(p)}{dp} = 0 \xrightarrow{\text{yields}} N(1 - p^*)^{2(N-1)} - Np^*2(N-1)(1 - p^*)^{2(N-1)-1} = 0$$

$$N(1 - p^*)^{2(N-1)-1}((1 - p^*) - p^*2(N-1)) = 0$$

$$p^* = \frac{1}{2N-1} \rightarrow E_{\max} = \frac{N}{2N-1} \left(1 - \frac{1}{2N-1}\right)^{2(N-1)}$$

$$\lim_{N \rightarrow \infty} \left(1 - \frac{1}{N}\right)^N = 1/e$$

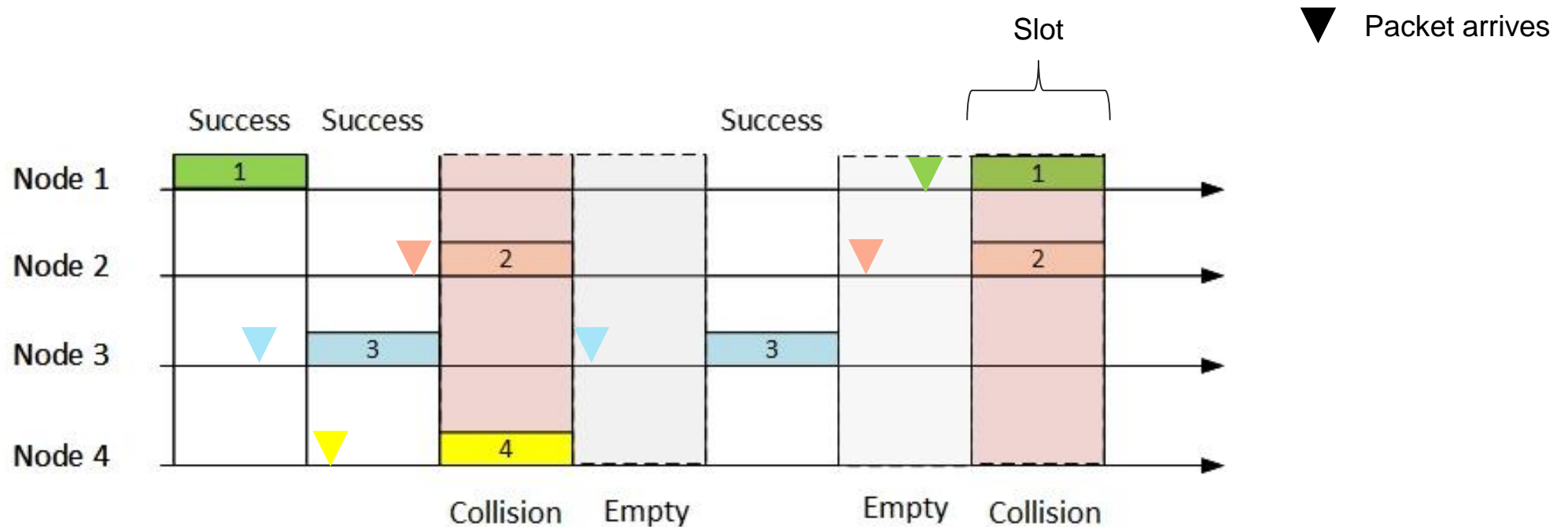
$$\lim_{N \rightarrow \infty} E_{\max} = \lim_{N \rightarrow \infty} \frac{N}{2N-1} \left(1 - \frac{1}{2N-1}\right)^{2(N-1)}$$

$$\lim_{N \rightarrow \infty} \frac{N}{2N-1} \frac{\left(1 - \frac{1}{2N-1}\right)^{2N-1}}{\left(1 - \frac{1}{2N-1}\right)} = \frac{1}{2} \cdot \frac{1}{e} = \mathbf{0.184}$$

# Lecture 4

## Slotted ALOHA Protocol

- ▶ An slotted, fully decentralized protocol
- ▶ Time is divided into **slots of fixed size**
- ▶ When the station has a fresh packet to send, it **waits until the beginning of the next slot** and transmits the entire packet in the slot





# Lecture 4

## *Derivation of efficiency of slotted ALOHA*

- ▶ Suppose there are **N stations**
- ▶ Assume that each station always has a packet to send and that the station transmits with **probability p** for a fresh packet as well as for a packet retransmission
- ▶ Probability that a given station transmits is **p**
- ▶ Probability that the **remaining stations do not transmit** is  $(1 - p)^{N-1}$
- ▶ Probability that a **given station** has a **successful transmission**

$$p(1 - p)^{N-1}$$

- ▶ Efficiency: Probability that **any one of the N stations** has a success (Transmission without collision)

$$E(p) = Np(1 - p)^{N-1}$$

# Lecture 4

## Maximum Efficiency of slotted ALOHA

- **Efficiency:** Probability that any station of the N stations has a success

$$E(p) = Np(1 - p)^{N-1}$$

- **Maximum efficiency**  $E_{\max}$  → Find the  $p^*$  that maximizes this efficiency for a large number of nodes

$$\frac{dE(p)}{dp} = 0 \rightarrow N(1 - p^*)^{N-1} - Np^*(N - 1)(1 - p^*)^{N-2} = 0$$

$$N(1 - p^*)^{N-2}((1 - p^*) - p^*(N - 1)) = 0$$

$$p^* = \frac{1}{N} \Rightarrow E_{\max} = \left(1 - \frac{1}{N}\right)^{N-1}$$

$$\lim_{N \rightarrow \infty} E_{\max} = \lim_{N \rightarrow \infty} \left(1 - \frac{1}{N}\right)^{N-1}$$

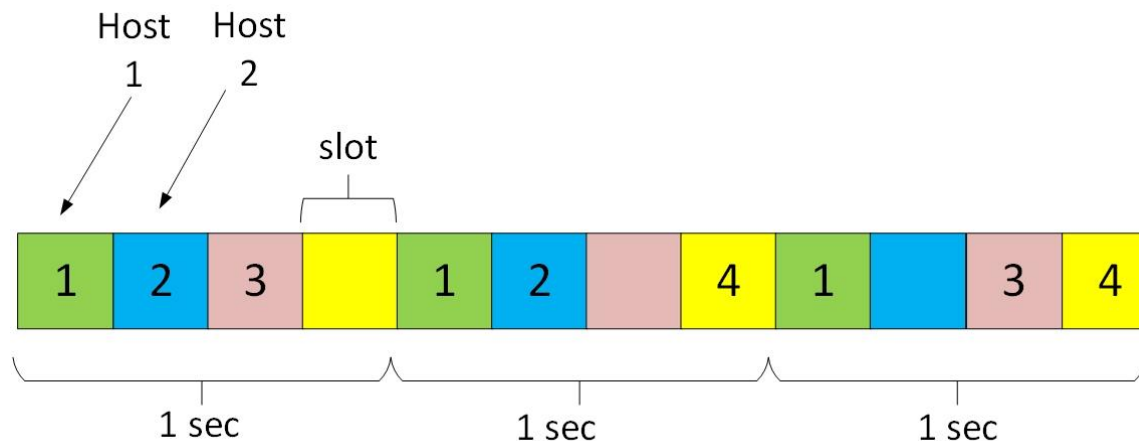
$$\lim_{N \rightarrow \infty} \left(1 - \frac{1}{N}\right)^N = 1/e$$

$$\lim_{N \rightarrow \infty} \frac{\left(1 - \frac{1}{N}\right)^N}{\left(1 - \frac{1}{N}\right)} = \frac{1}{e} \approx \mathbf{0.37}$$

# Lecture 4

## *Time Division Multiple Access (TDMA)*

- ▶ Divide channel into rounds of **n time slots** each
  - ▶ Assign **different stations** to **different time slots** within a round
  - ▶ Unused time slots are idle
  - ▶ Used in GSM cell phones & digital cordless phones
  - ▶ Robust against **frequency shifts**
- ▶ Scenario with 1-second rounds, 4 timeslots (250ms each) per round



# Lecture 4

## *Time Division Multiple Access (TDMA)*

- ▶ TDMA systems can easily **assign the channel dynamically**
  - ▶ Centralized control required
  - ▶ Stations need to obtain permission to send
  - ▶ Base station give permission to send to a station
  - ▶ Base station is a single point of failure



# Lecture 4

## *TDMA Limitations*

- ▶ A station is limited to **an average rate** even when it is **the only** station with packets to send
  - ▶ A station must **always wait for its turn** in the transmission sequence even when it is the **only station** with a frame to send
- ▶ Receiver has to **synchronize precisely**
- ▶ Overhead for keeping **tight time synchronization** among all stations
- ▶ Synchronization issue specific to V2X-Networks
  - ▶ Transmission times must be **perfectly synchronized** to ensure that packets are received in the **correct time slot** and do not cause interference
  - ▶ Each time slot must have a **guard time**, which reduces the interference probability, but **decreases the spectral efficiency**



# Lecture 4

## *Frequency Division Multiple Access (FDMA)*

- ▶ Divide the channel into **different frequencies**
  - ▶ Assign **each frequency to one** of the stations
- ▶ It avoids **collisions** and divides the bandwidth fairly among the nodes
- ▶ Fixed frequency allocation
  - ▶ Permanent, e.g. radio broadcast
  - ▶ Frequency hopping, e.g. GSM, Bluetooth
- ▶ FDMA shares both the advantages and drawbacks of TDMA
  - ▶ **Simple** to implement, **no time synchronization** needed



# Lecture 4

## *FDMA Limitations*

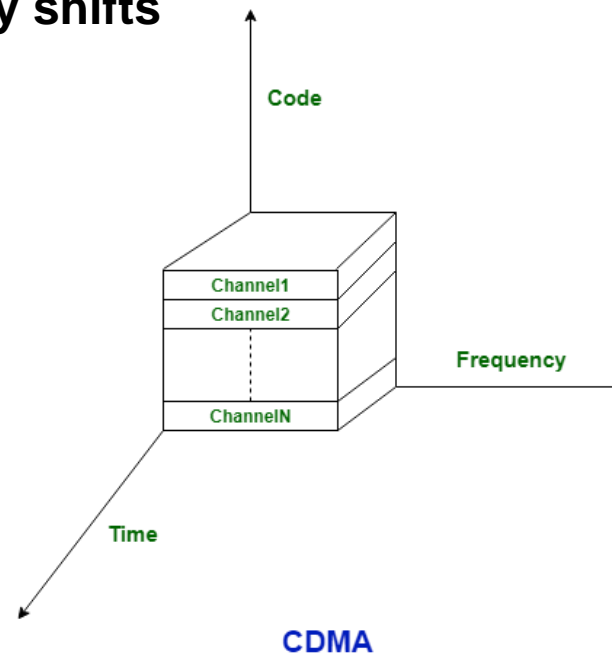
- ▶ A station has a limited bandwidth even when it is the only station with packets to send
- ▶ **Receiver** has to have a precise **bandpassfilter**
- ▶ **Guard bands** between individual frequency bands needed
- ▶ **Frequency shifts** are specific to V2X-Networks
  - ▶ Due to the unpredictable **Doppler shift** of the signal spectrum because of user mobility, a guard band between adjacent channels must be added
    - ▶ **Guard bands** will reduce the probability that adjacent channels will interfere, but **decrease the utilization of the spectrum**



# Lecture 4

## *Code Division Multiple Access (CDMA)*

- ▶ Assign a **different code** to **each station**
  - ▶ Each station uses its unique code to encode the data bits it sends
- ▶ Different stations can transmit **simultaneously** assuming the receiver **knows** the sender's **code**
- ▶ Robustness against **time and frequency shifts**

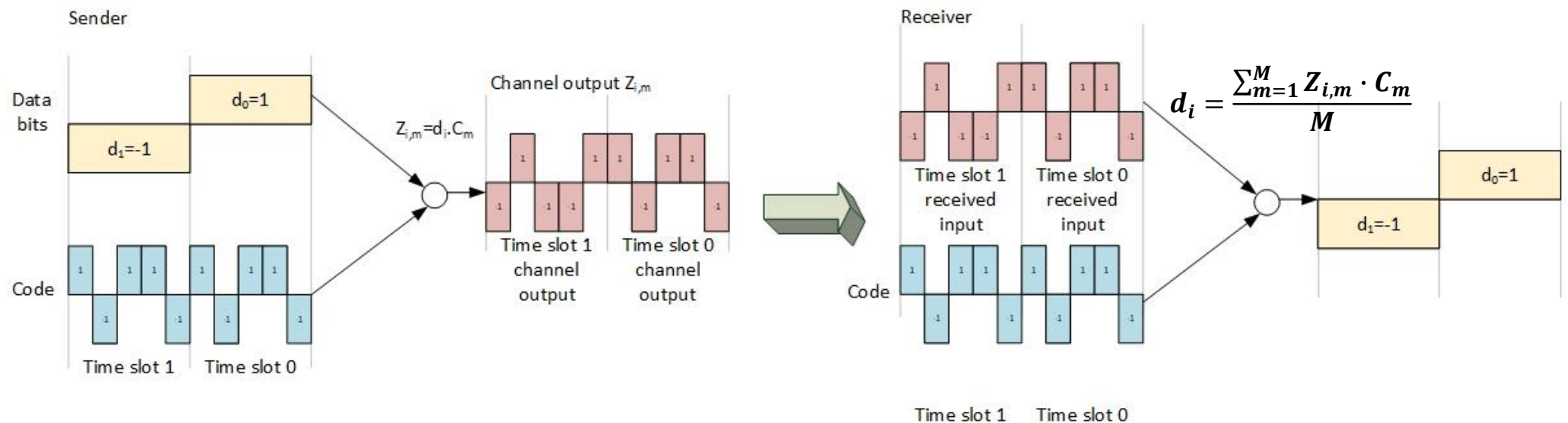




# Lecture 4

## CDMA Encoding

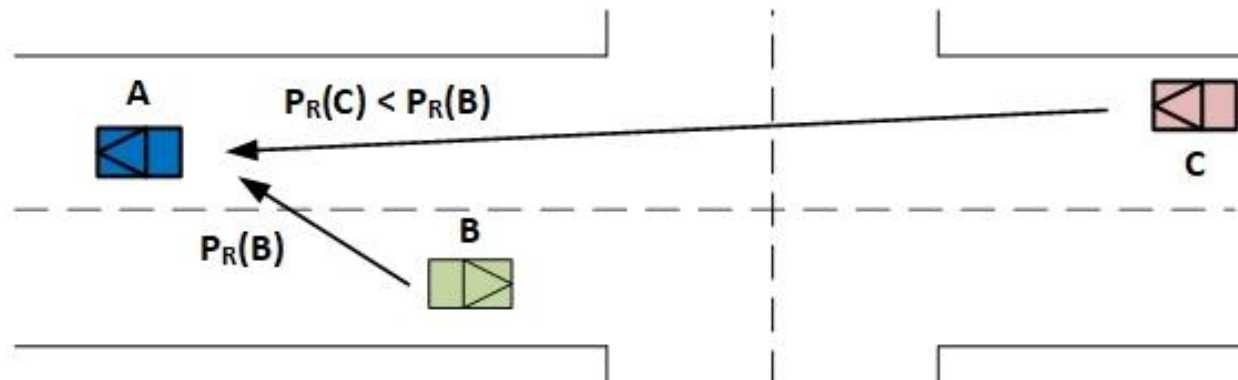
- Each bit being sent is encoded by multiplying it by a signal (the code) that changes at a much faster rate than the original sequence of data bits



# Lecture 4

## CDMA Limitations

- ▶ All signals **have** to arrive at a **receiver with roughly the same power level**
  - ▶ **Closed-loop power control**: A dedicated channel is needed to continuously give feedback to **participating users** on how much their **transmit power should be**
- ▶ **Near-Far Effect**: Vehicles A, B and C share the same frequency band and their signals are separable at the vehicle A by their unique code
- ▶ Received power of B at a particular time instant might be much greater than that from C
- ▶ If power control is not applied, **the signal of B will overpower the signal of C** at the vehicle A



# Lecture 4

## *Comparison of Reservation-based MAC Protocols*

|                          | <b>TDMA</b>  | <b>FDMA</b>  | <b>CDMA</b>   |
|--------------------------|--|--|---|
| <b>Idea</b>              | Time is slotted, static or dynamic time slot allocation                      | Frequency is segmented into sub-bands                          | Spread spectrum with orthogonal codes                             |
| <b>Stations</b>          | Stations are active for short disjoint periods of time on the same frequency | Each station has its own frequency band and is not interrupted | All stations can be active at the same time on the same frequency |
| <b>Signal separation</b> | Synchronization in time domain   | Bandpass filtering in frequency domain                         | Matched filter in code domain                                     |
| <b>Advantages</b>        | Flexible, can assign time slots on demand                                    | Simple, robust   | Flexible, other codes only add noise                              |
| <b>Disadvantages</b>     | Synchronization is difficult, guard times needed                             | Inflexible, frequency is scarce                                | Complex receivers, need sophisticated power control               |

# Lecture 4

## *Carrier Sense Multiple Access (CSMA)*

- ▶ The CSMA/CA is a **random contention-based access mechanism** following the principle of ***listen before talk*** called ***carrier sensing***
  - ▶ A station listens to the channel before transmitting, i.e., **the channel is only accessed if it is sensed to be idle**
- ▶ Goal is to **minimize the interference** in the system → Increase the packet reception probability
- ▶ When the physical layer observes no activities on it
  - ▶ A station then waits a **random back-off time** chosen from the interval  $[0, CW]$
  - ▶ CW is known as the **contention window size** and is **decremented** as the medium is idle
  - ▶ Whenever the **countdown reaches zero**, the frame is **immediately transmitted**

CW: Contention Window

# Lecture 4

## CSMA Back-off Procedure

► Back-off procedure works as follows:

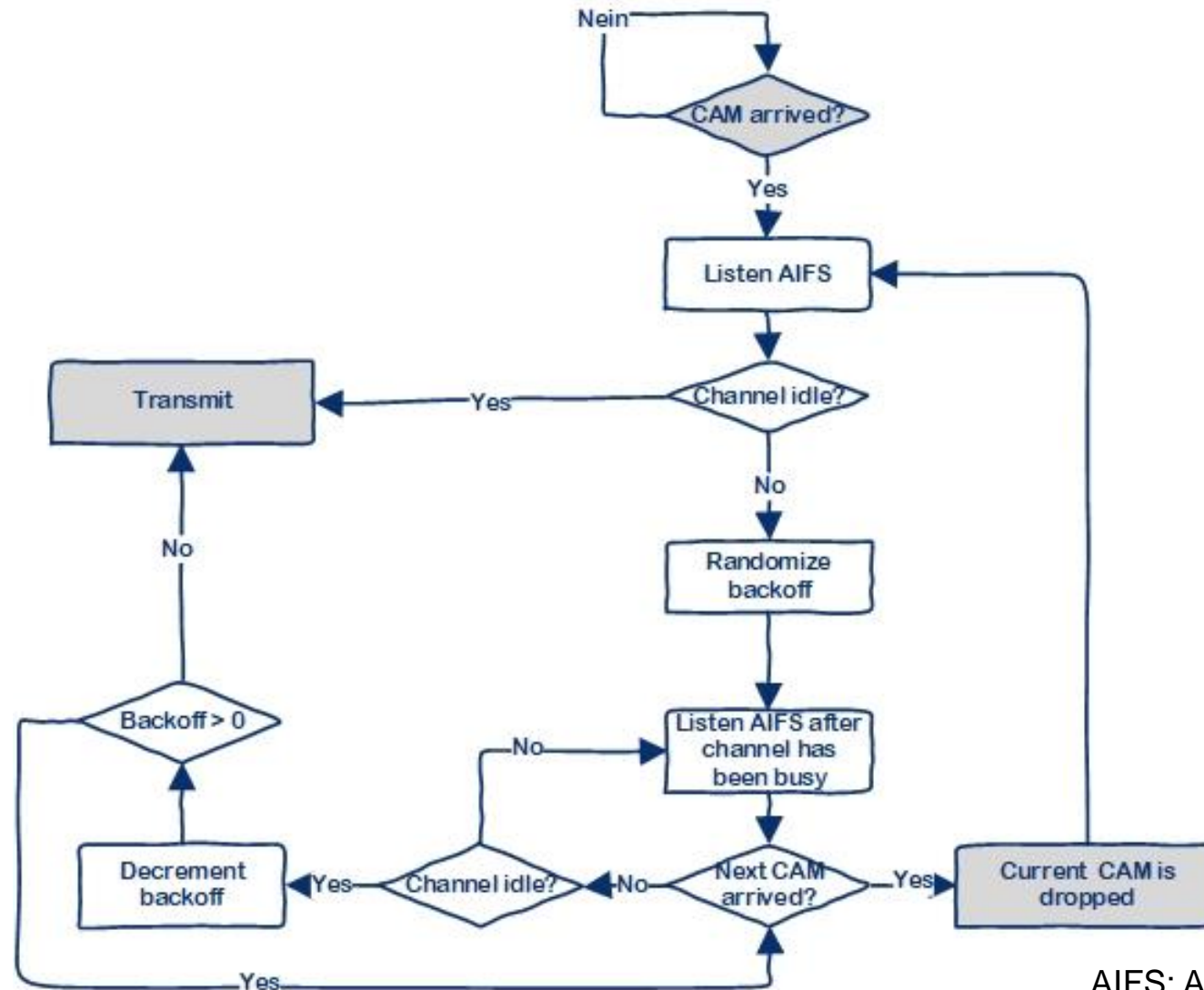
- 1) Draw an **integer** from a **uniform distribution**  $[0, CW]$
- 2) Multiply this integer with the **slot time**,  $T_{\text{slot}}$ , derived from the PHY layer in use ( $T_{\text{slot}} = 13 \mu\text{s}$ ), and set this as the **back-off value**
- 3) Decrease the back-off value by **one**  $T_{\text{slot}}$  **for every**  $T_{\text{slot}}$  the channel is sensed as free
- 4) Upon reaching a **back-off value of 0**, transmit directly



CW: Contention Window

# Lecture 4

## *Procedure of CSMA when broadcasting CAMs*



AIFS: Arbitration Interframe Spacing

# Lecture 4

## Quality of Service (QoS) for IEEE802.11p

- ▶ 802.11p MAC supports QoS
  - ▶ Dividing the data traffic into **four different queues** called access categories (AC)
  - ▶ Highest priority queue has the shortest  $T_{AIFS}$  and the smallest initial CW

| Priority | Traffic Type | AC    | $T_{AIFS}$ [ $\mu$ s] | $CW_{min}$ | $CW_{max}$ |
|----------|--------------|-------|-----------------------|------------|------------|
| Highest  | Voice        | AC_VO | 58                    | 3          | 7          |
|          | Video        | AC_VI | 71                    | 7          | 15         |
|          | Best Effort  | AC_BE | 110                   | 15         | 1023       |
| Lowest   | Background   | AC_BK | 149                   | 15         | 1023       |

AIFS: Arbitration Interframe Spacing  
CW: Contention Window

# Lecture 4

## *CSMA for Unicast Transmissions*

- ▶ In **unicast transmissions**, the receiver transmits a receipt also known as **acknowledged (ACK)** upon **successful** reception
- ▶ During high network utilization periods ACKs can be lost due to **simultaneous transmissions caused by hidden nodes** or wireless **channel impairments** such as **fading**
- ▶ For every attempt to transmit a specific packet (where the ACK from the receiver is repeatedly missing), the station **doubles the CW**, resulting in a greater spread of simultaneous transmission attempts during high utilization periods
- ▶ BUT the **reliability** comes at the **expense of a random delay** which is not upper bounded
- ▶ Due to the **lack of ACK in broadcast communication**, CW in V2X is always set to its  $CW_{\min}$  (**CW will never be doubled no matter what the network condition is**)

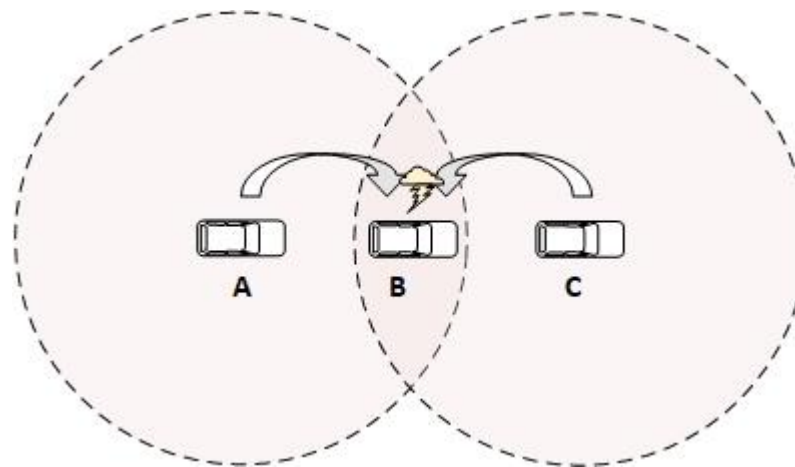




# Lecture 4

## *Hidden Terminal Problem (1/2)*

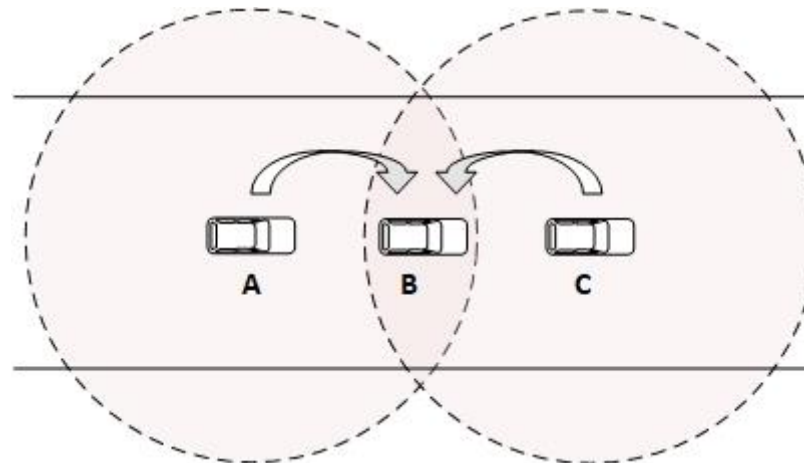
- ▶ Hidden terminal problem is one of the **performance limiting factor** in V2X Networks
  - ▶ In other centralized networks, where TDMA or CDMA are used, the AP/BS controls channel access and the hidden terminal problem does not exist
  - ▶ A is hidden from C and C is hidden from A
    - ▶ A senses free medium and starts sending to B
    - ▶ C cannot hear A
    - ▶ C senses free medium and starts sending to B
    - ▶ A cannot hear C
- Leading to a **packet collision** at B



# Lecture 4

## *Hidden Terminal Problem (2/2)*

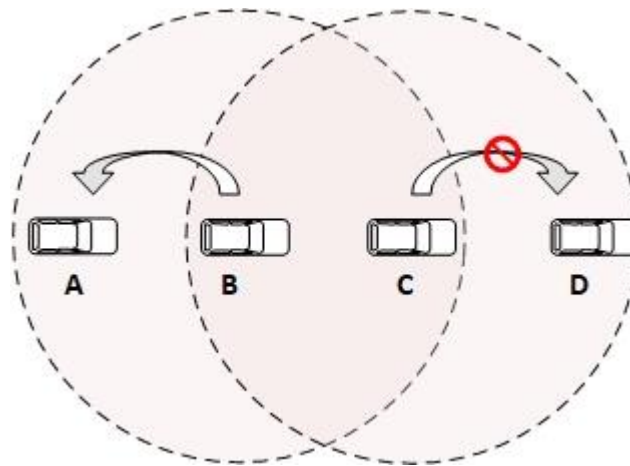
- ▶ Can be combatted by preceding every transmission with control packets
  - ▶ Request-to-send (**RTS**) and clear-to-send (**CTS**) used to notify all stations in the network about an **upcoming transmission**
- ▶ Not feasible in V2X networks due to the **broadcast nature** of the data traffic, implying more than **one intended receiver**



# Lecture 4

## *Exposed Terminal Problem (2/2)*

- ▶ C is exposed to the transmission of B
  - ▶ B senses free medium and starts sending to A
  - ▶ C want to transmit data to D
  - ▶ C could transmit to D without causing a collision
    - ▶ Neither at receiver A nor at receiver D
- C senses busy medium and **does not start sending to D**



# Lecture 4

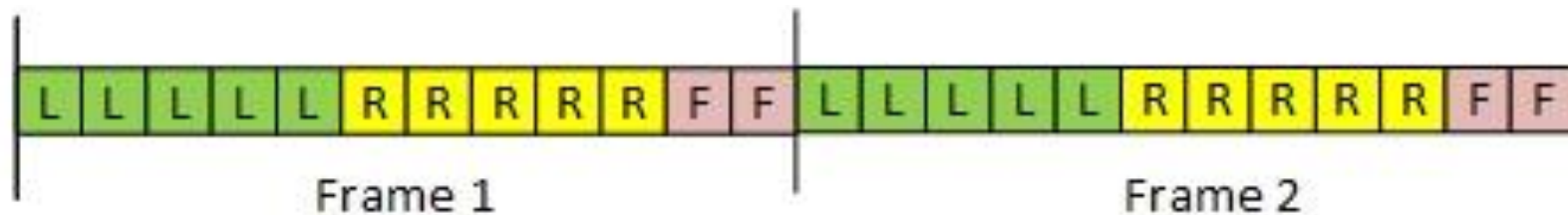
## *AdHoc MAC*

- ▶ Distributed **TDMA-based MAC** protocol
  - ▶ It is contention-free MAC protocol which implements a **dynamic TDMA mechanism** that is able to provide prompt access based on distributed access technique
- ▶ **Vehicles are grouped** into a **set of clusters** with no cluster head
- ▶ Each cluster contains a restricted number of vehicles that are one-hop away
- ▶ Vehicles broadcast the **status of time slots used** by all the other vehicles within its one-hop neighborhood
- ▶ Upon receiving the status information, **each vehicle knows the time slots used by all of the vehicles within its two-hop** neighborhood and the set of accessible time slots
- ▶ Vehicles **randomly select the free time slot** to transmit its data without causing any packet collisions

# Lecture 4

## *VeMAC*

- ▶ Distributed multi-channel **TDMA-based MAC** protocol
  - ▶ It is contention free MAC protocol
- ▶ In the **control channel**, the vehicle exchanges the **status information of time slots** with its one-hop neighbors
- ▶ Each vehicle determines **its time slot in the service channel** and achieves contention-free accessing channel
- ▶ Time slots is allocated to the vehicle **based on their direction on the road**
  - ▶ L and R group of time slots are allocated to left and right direction vehicles respectively, and time slots of F is allocated to RSU



# Lecture 4

## *Unified TDMA-based Scheduling Protocol (UTSP)*

- ▶ Contention-free centralized **TDMA-based MAC** protocol
- ▶ **Roadside units (RSU)** collect the information of the vehicles within its communication range
- ▶ RSU **decides how to allocate the time slots to the vehicles** for their data transmission requests based on a **weight-factor-based scheduler**
- ▶ Weight factor takes into consideration the **channel quality** of communication links, the **speed** based fairness among vehicles, and different **access categories**
- ▶ Interference problem can occur between vehicles in the **overlapping regions** where several RSUs are used to coordinate access to the channel

# Lecture 4

## *Adaptive Collision-Free MAC (ACFM)*

- ▶ Contention-free centralized **TDMA-based MAC** protocol based on a **dynamic time slot reservation mechanism in Roadside Units (RSUs)**
- ▶ Time is divided into frames and **each frame is divided into a fixed number of time slots**
  - ▶ 1 RSU Slot (RS) which is used by an RSU to **broadcast control messages** to the vehicles within its coverage area
  - ▶ 36 Data Slots (DS) which can be used by the vehicles to broadcast CAMs to their neighboring vehicles
  - ▶ Control message that is periodically diffused by an RSU contains the **DS assignment schedule for vehicles under its coverage**
- ▶ Due to high node mobility, the interval of time in which the vehicle stays in an RSU region is very short → **Leading to communication blackouts**

# Lecture 4

## *Literature*

- ▶ James F. Kurose, Keith W. Ross: "Computer Networking: A Top-Down Approach", Sixth Edition, Addison-Wesley, 2013.
- ▶ Markus Fidler: "Rechnernetze", Leibniz Universität Hannover, 2016
- ▶ ETSI TR 102 862 V1.1.1: "Intelligent Transport Systems (ITS); Performance Evaluation of Self-Organizing TDMA as Medium Access Control Method Applied to ITS; Access Layer Part".
- ▶ Hadded M. et al. "TDMA-based MAC Protocols for Vehicular Ad Hoc Networks: A Survey, Qualitative Analysis and Open Research Issues". Communications Surveys and Tutorials, IEEE Communications Society, Institute of Electrical and Electronics Engineers, 2015.