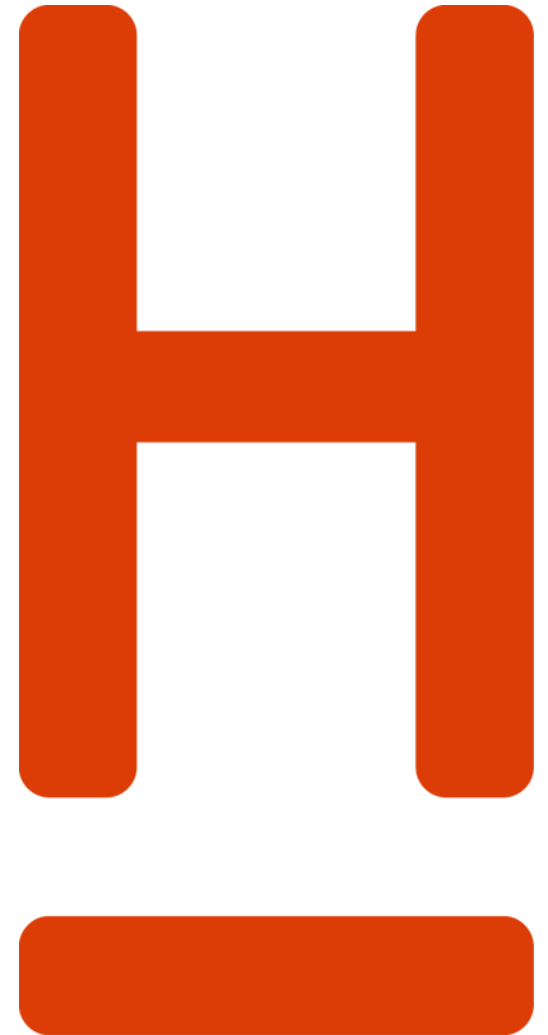


Fahrzeugvernetzung – V2X

Lecture 5: Physical Layer and Channel Propagation Modeling



Lecture 5

Previous Lecture

- ▶ **Multiple Access**
- ▶ **Random Access Protocols**
 - ▶ Pure ALOHA, Slotted ALOHA
- ▶ **Reservation-based Access Protocols**
 - ▶ TDMA, FDMA, CDMA
- ▶ **Carrier Sense Multiple Access**
 - ▶ CSMA
- ▶ **Hidden/Exposed Terminal Problem**
- ▶ **TDMA-based MAC Protocols for V2X**



Lecture 5

Outline

- ▶ Overview Physical Layer
 - ▶ IEEE 802.11p
- ▶ Propagation Characteristics
- ▶ Multipath Propagation
- ▶ Orthogonal Frequency-Division Multiplexing
- ▶ Channel Propagation Models



Lecture 5

IEEE 802.11p (1/2)

- ▶ An approved amendment to the well-known **IEEE 802.11** standard introducing several modifications
 - ▶ Adapt the **physical (PHY) layer** and **Medium Access Control (MAC)** sublayer to the requirements of **highly dynamic** vehicular environment
 - ▶ Derived from **802.11a**
- ▶ Operation in the **5.9 GHz band**
- ▶ **10MHz physical layer (PHY)** mode with all timings doubled for greater robustness against delay-spread
- ▶ **No synchronization, authentication and association** with an access point as in 802.11a
 - ▶ These procedures are **very time-intensive**



Lecture 5

IEEE 802.11p (2/2)

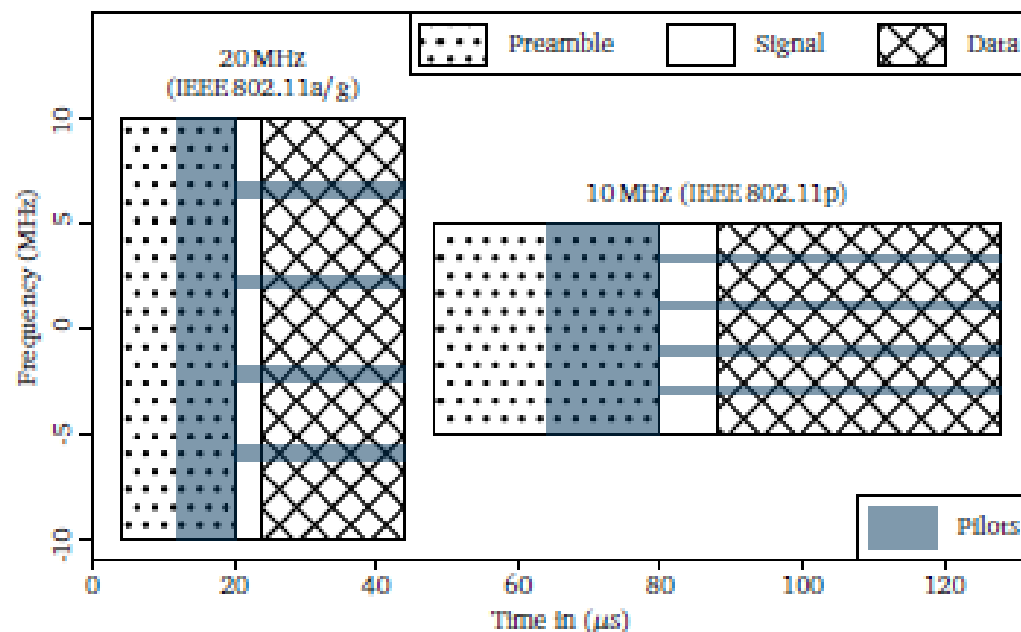
- ▶ A new operation mode in the **MAC layer** (*managed, monitor, ad-hoc*)
 - ▶ **Outside-the-context-of-a-BSS** mode
 - ▶ Allows **immediate** communication without connection setup
 - ▶ Stations can operate **without being part of a BSS** (Basic Service Set)
 - ▶ No authentication/association procedures as a station may never join a BSS
 - ▶ Stations transmit/receive using **pre-agreed PHY parameters** or using a signaling channel to agree on such **parameters**
- ▶ Enhanced Distributed Channel Access (EDCA) for Quality of Service (QoS) that allows to prioritize safety messages
 - ▶ **Frames** classified into four distinct **access categories** w.r.t to different channel access parameters



Lecture 5

Physical Layer

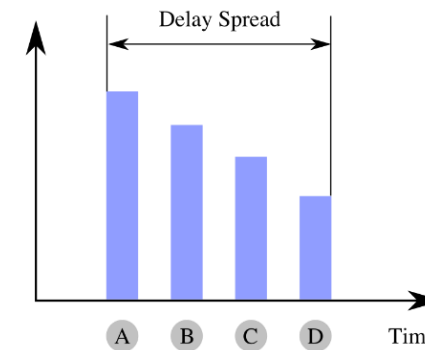
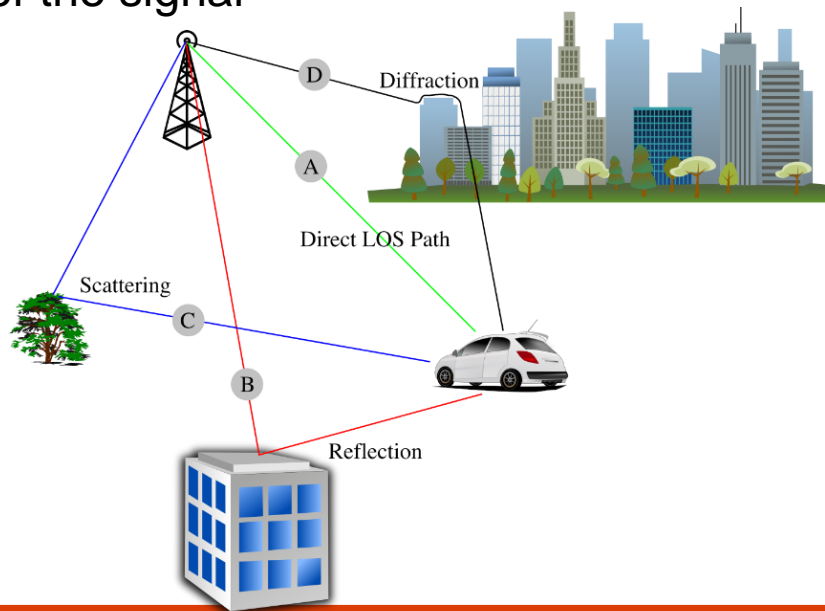
- ▶ The PHY of IEEE 802.11p is based on **IEEE 802.11a**
 - ▶ but with all timings doubled, transforming the 20MHz channels of IEEE 802.11a into the 10MHz channels of IEEE 802.11p
 - ▶ Doubling the **timings** stretches the frame in **time domain** and shrinks it in **frequency domain**. The area in time-frequency domain remains **constant**
 - ▶ Spectral efficiency in **bits per Hertz per second** remains also constant



Lecture 5

Doubling Time Parameters

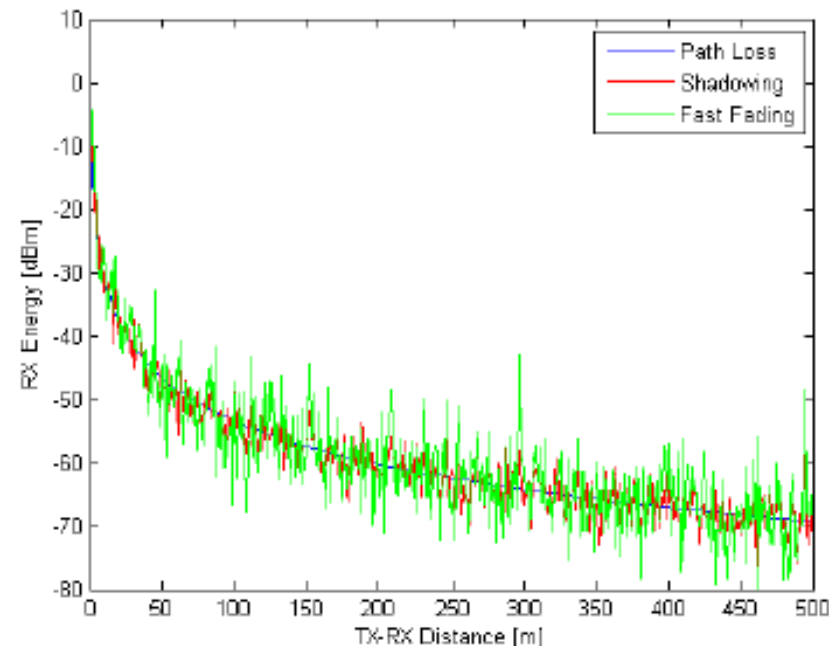
- ▶ Doubling the time parameters may improve the **robustness** against the effects of mobility
- ▶ Doubled **guard interval** reduces the **inter-symbol interference (ISI)** caused by multipath propagation
- ▶ Robust to maximum **delay spreads**
 - ▶ Total elapsed time between the first (**direct line-of-sight path**) and last echo of the signal



Lecture 5

Multipath and Shadowing Effects

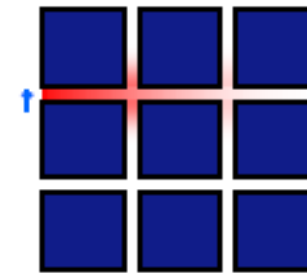
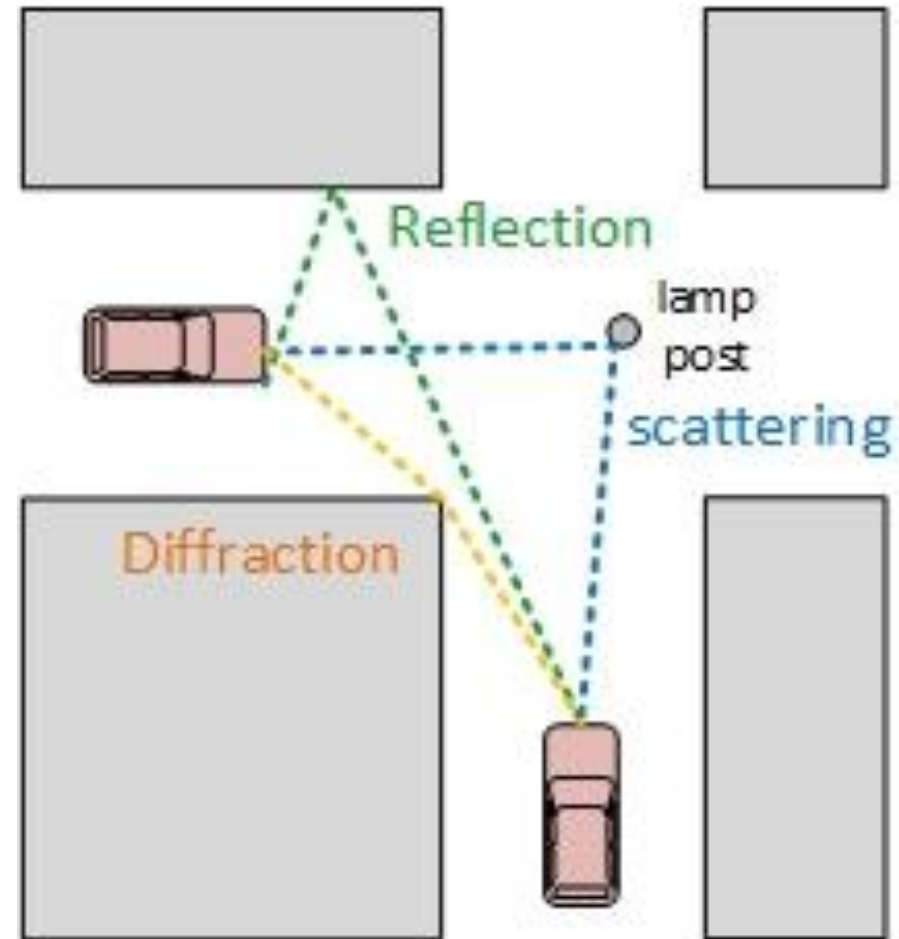
- ▶ BUT the increased **frame duration** makes the signal more sensitive against **fast-fading** effects
- ▶ **Fast fading** originates due to effects of constructive and destructive interference patterns which is caused due to multipath
- ▶ Effects particularly pronounced given the **small wavelength** (~5 cm at 5.9 GHz) and the high **relative velocities**



Lecture 5

Propagation Characteristics

- ▶ **Reflection:** Occurs when a wave hits a smooth object that is larger than the wave itself
 - ▶ Wave may bounce in another direction (phase shift)
- ▶ **Diffraction:** Bending and spreading around of a signal when it encounters an obstruction
- ▶ **Scattering:** Occurs when a signal's wavelength is larger than pieces of a medium → Wave is reflected into multiple directions
- ▶ **Wave guiding:** Signal propagation along street canyons
- ▶ If no LOS exists → diffraction and scattering are primary means of reception



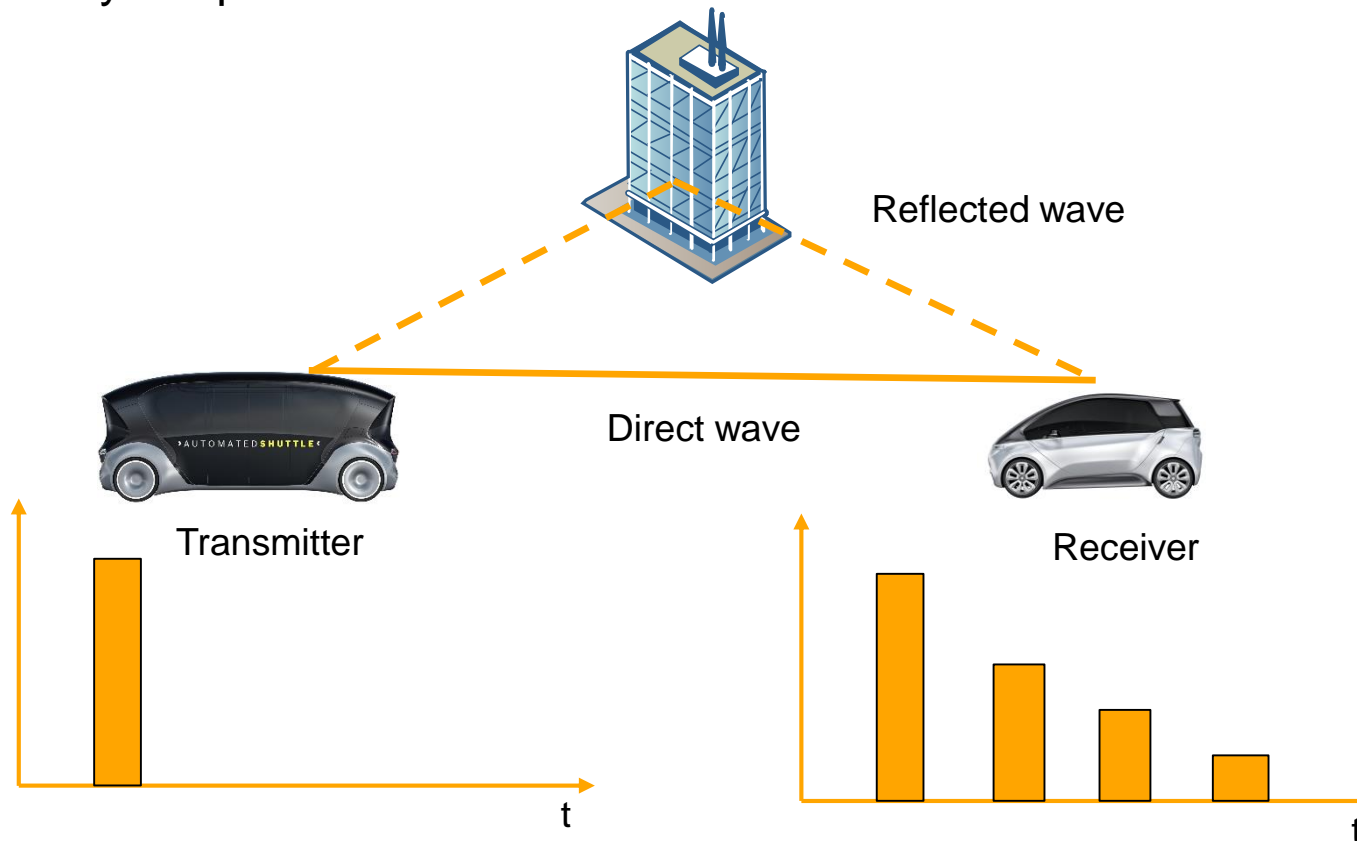
Waveguiding



Lecture 5

Multipath Propagation

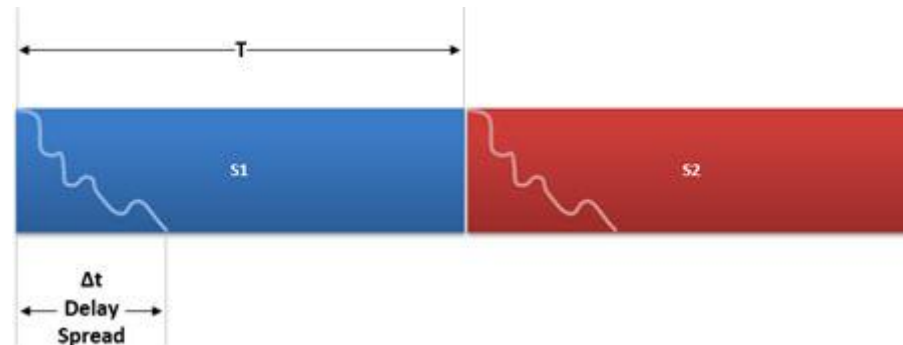
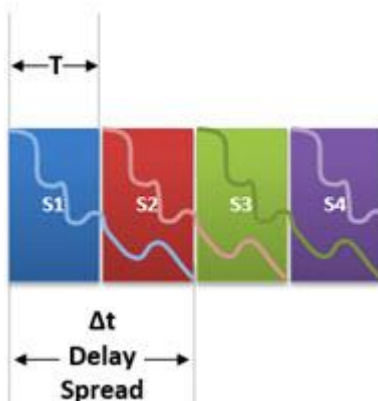
- Multipath signals are **all time shifted** with respect to one another, as they travel different paths
- Same signal arriving to the receiver through **different paths** and hence with different delays or phase shifts



Lecture 5

Delay Spread

- ▶ Delay spread is the time between **first and last versions** of a signal
- ▶ Doubling guard interval reduces the inter-symbol interference (ISI) caused by multipath propagation
 - ▶ (a) If the **symbol period T is very short** compared to the delay spread Δt the impact is **significant** ($T \ll t$)
 - ▶ (b) if the **symbols length is extended**, most of symbols will **not suffer** the impact of ISI ($T \gg t$)
- ▶ Increasing symbol length makes the physical layer **robust to maximum delay spreads**



Lecture 5

Typical Delay Spread Values

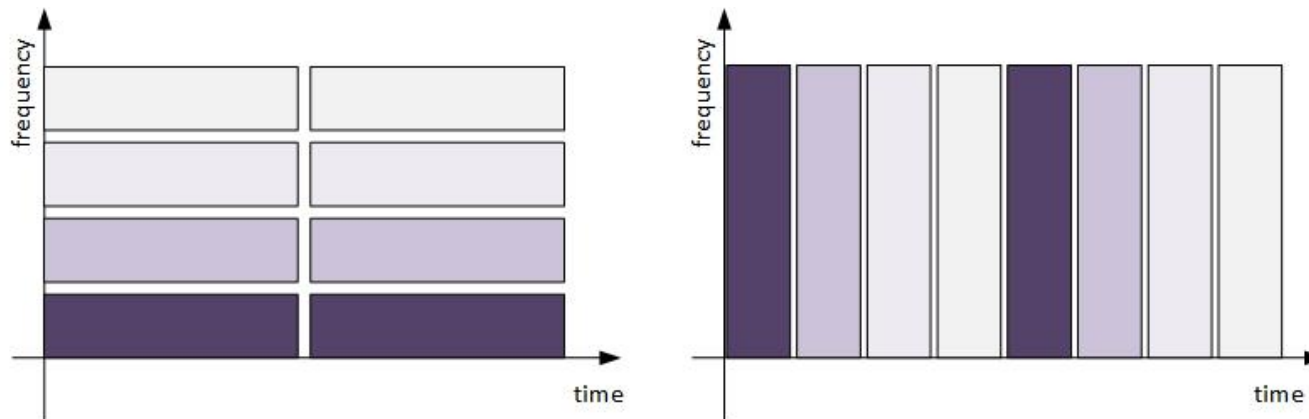
- ▶ Delay spread varies with the environment → 90% of delays introduced by multipath effect are lower than
 - ▶ Suburban: **0.6us**
 - ▶ Highway: **1.4us**
 - ▶ Rural: **1.5us**
- ▶ OFDM guard interval need to be longer than 1.5us
 - ▶ A channel width of 10MHz with **1.6us** is used for 802.11p
 - ▶ **8.5MHz** as a theoretical optimal channel width might **offers highest protection** again delay spread
 - ▶ Ease of implementation with 802.11a is a reasonable choice



Lecture 5

OFDM - Orthogonal Frequency-Division Multiplexing (1/3)

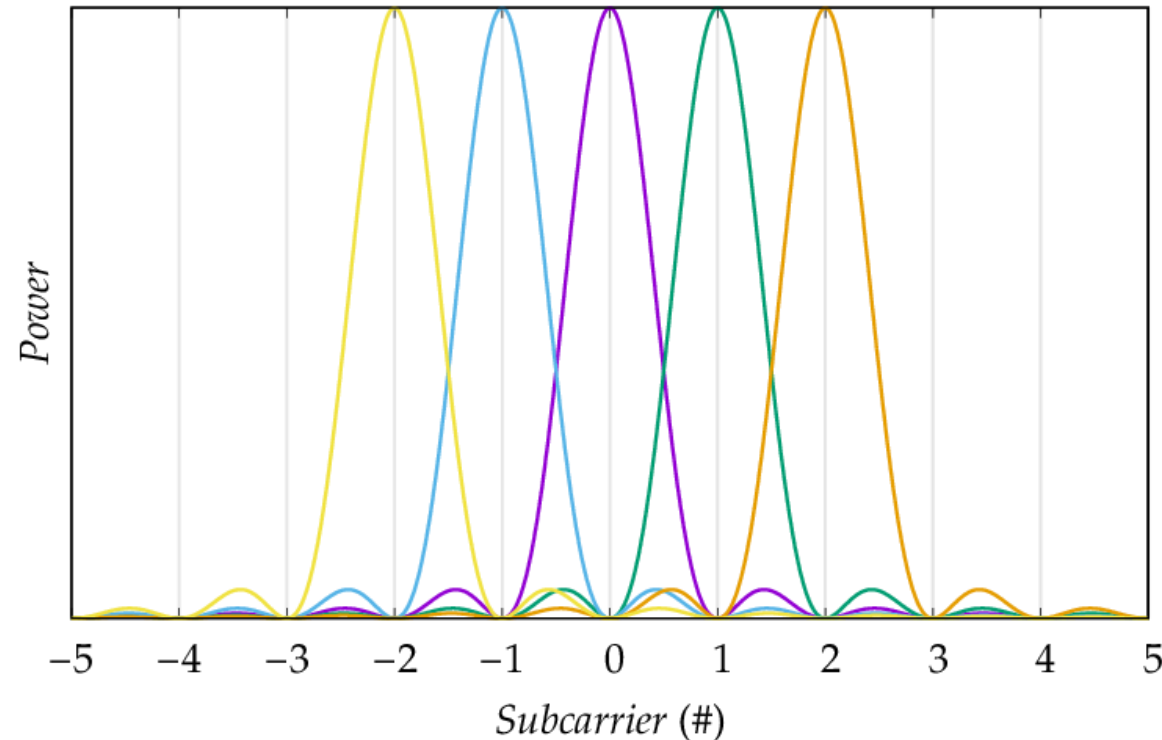
- ▶ IEEE 802.11p PHY adopts **OFDM** to combat inter-symbol interference and the preamble for signal detection, time synchronization, carrier frequency offset and channel estimation
- ▶ Frequency division multiplexing (FDM) scheme used as a digital multi-carrier modulation method
- ▶ Use **multiple narrow-band subcarriers** instead of a **single wide-band carrier**



Lecture 5

OFDM - Orthogonal Frequency-Division Multiplexing (2/3)

- ▶ It copes with severe channel conditions
 - ▶ **Multipath fading**
- ▶ Subcarrier signals are **orthogonal** to one another
- ▶ Inter-carrier **guard bands** are not **required**
- ▶ Spectra of the individual subcarriers **overlap**
 - ▶ They do not interfere at the **center frequencies** of other subcarriers
 - ▶ Contributions of each subcarrier are **zero** at multiples of the subcarrier spacing, i.e., the center frequencies of adjacent subcarriers



Lecture 5

OFDM - Orthogonal Frequency-Division Multiplexing (3/3)

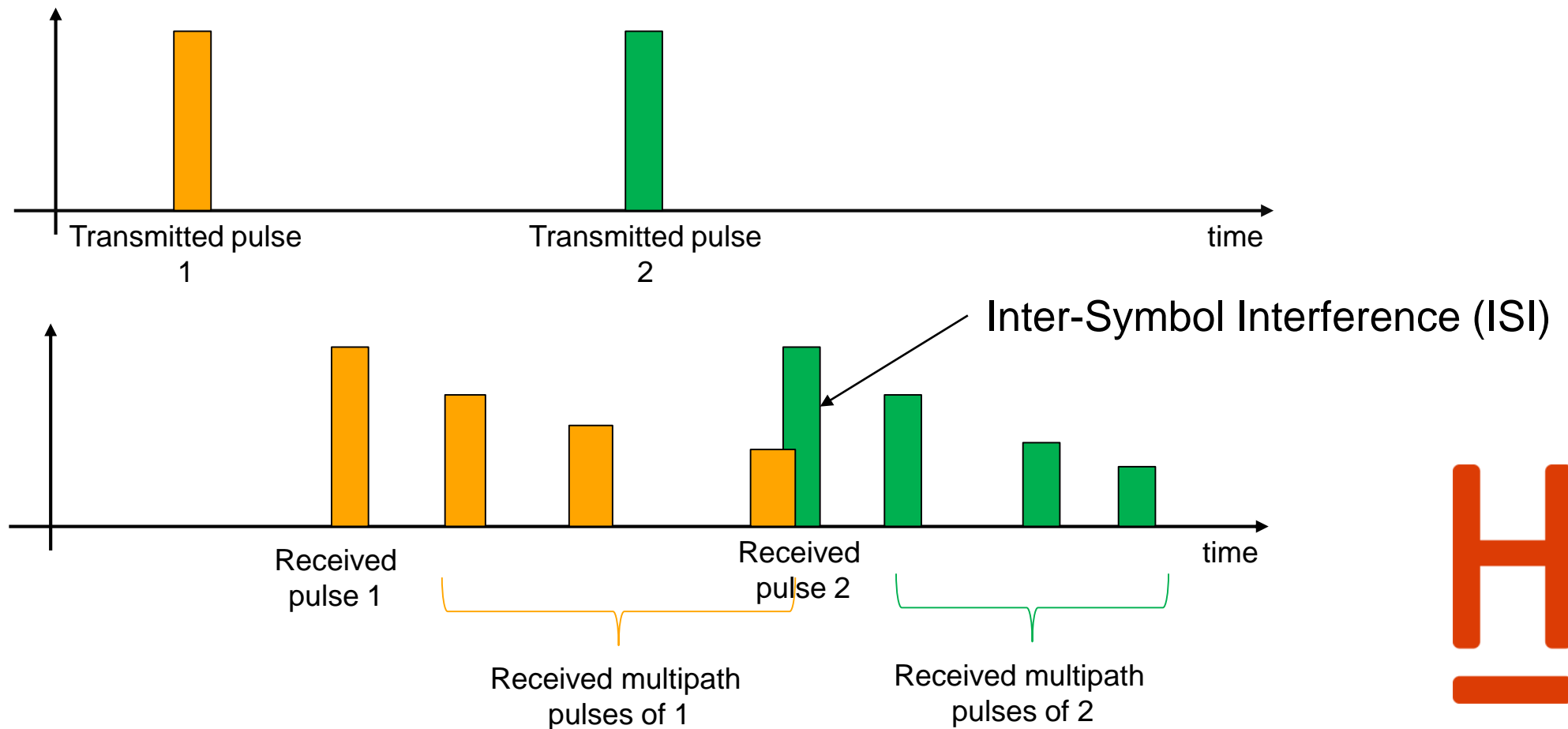
- ▶ Some drawbacks
 - ▶ Need for a **guard period** between successive OFDM symbols
 - ▶ Duration of the guard period is chosen with regard to the **delay-spread** of the channel
 - ▶ It ensures that an OFDM symbol does not leak into the useful symbol time of the successive symbol, which would introduce **inter-symbol interference** and degrade performance
 - ▶ High Peak-to-Average Power Ratio (PAPR)
 - ▶ Contributions of the subcarriers occasionally add up, leading to peaks that can easily drive the **power amplifier into saturation**



Lecture 5

Inter-Symbol Interference

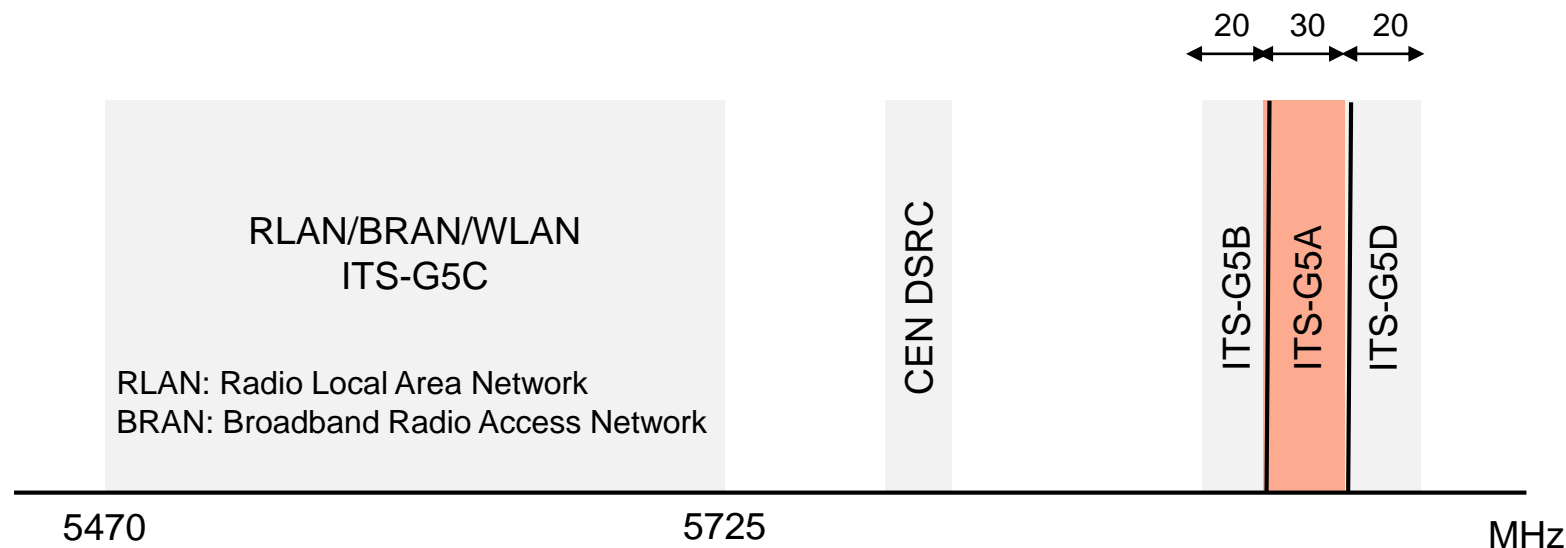
- ▶ Multipath may add **constructively** or **destructively**
- ▶ Delay spread is the time between **first and last versions** of a signal



Lecture 5

V2X Channel Allocation

- ▶ Channel allocation in the 5 GHz range
 - ▶ **ITS-G5A**: ITS road safety related applications
 - ▶ **ITS-G5B**: ITS non-safety applications
 - ▶ **ITS-G5C**: RLAN, BRAN, WLAN
 - ▶ **ITS-G5D**: Future ITS applications
 - ▶ **CEN DSRC**: Electronic toll collection

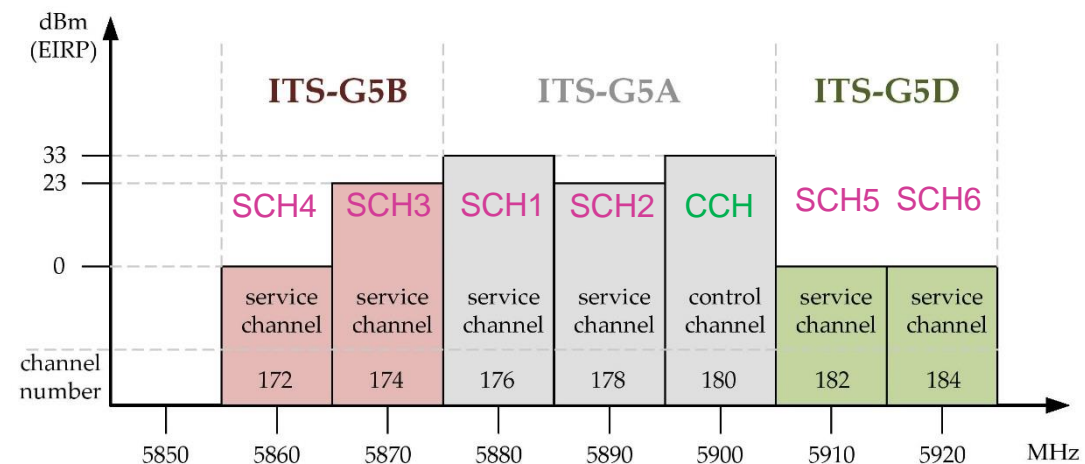


Lecture 5

Channel Allocation

- ▶ Control Channel (CCH) is placed **at lower bound** of the frequency range
 - ▶ Benefit from less interference sources from nearby channels
 - ▶ Lowest part of the range is used as guard-band
- ▶ Control Channel is followed by SCH2, rather than SCH1
 - ▶ Nodes are allowed to transmit only at 23 dBm rather than 33 dBm
 - ▶ **Limit adjacent-channel interference**

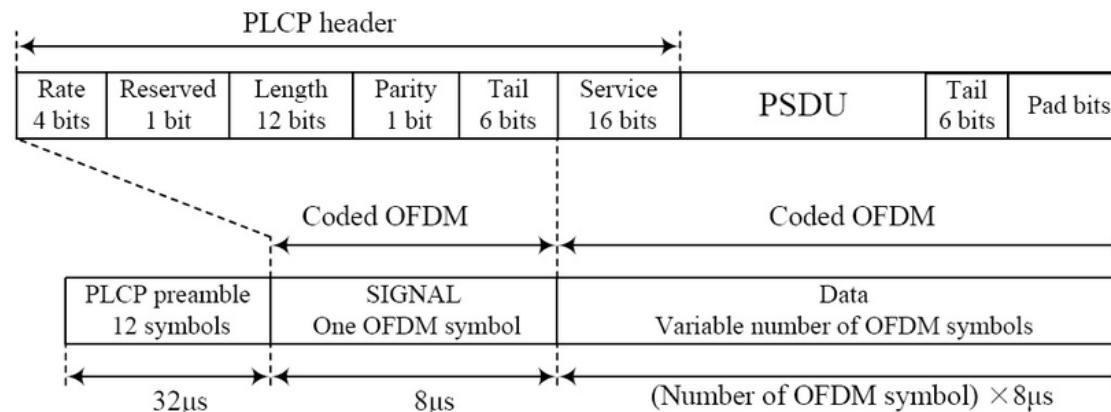
	Channel type	Centre frequency	Channel number	Default data rate	Tx Power limit (EIRP)
ITS-G5A	CCH	5900 MHz	180	6 Mbit/s	33 dBm
	SCH2	5890 MHz	178	12 Mbit/s	23 dBm
	SCH1	5880 MHz	176	6 Mbit/s	33 dBm
ITS-G5B	SCH3	5870 MHz	174	6 Mbit/s	23 dBm
	SCH4	5860 MHz	172	6 Mbit/s	0 dBm
ITS-G5D	SCH5	5910 MHz	182	6 Mbit/s	0 dBm
ITS-G5D	SCH6	5920 MHz	184	6 Mbit/s	0 dBm



Lecture 5

Frame Reception

- ▶ A sender may select **any modulation** and coding rate to transmit a frame
- ▶ To successfully receive a frame, a receiver needs to know whether the signal detected corresponds to a frame or just noise
 - ▶ Frame duration length, modulation rate and coding rate should be known
- ▶ Every frame starts with known **bit sequence** called **preamble**
 - ▶ Use to notify receivers of the eminent arrival of a frame
- ▶ The preamble is followed by the **physical layer convergence procedure (PLCP)**
 - ▶ Contains details on frame payload: frame length, modulation and coding rate



Lecture 5

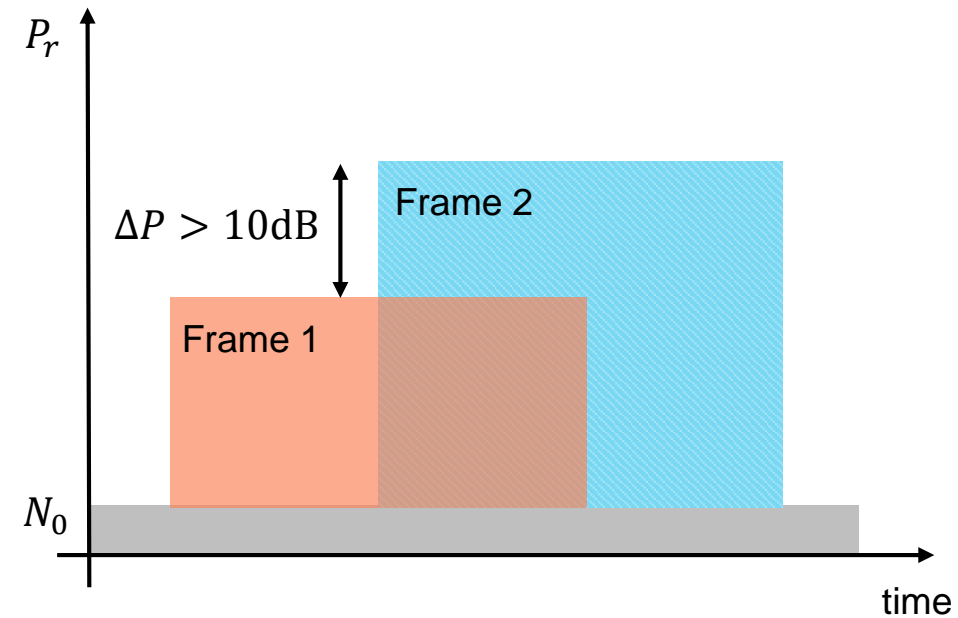
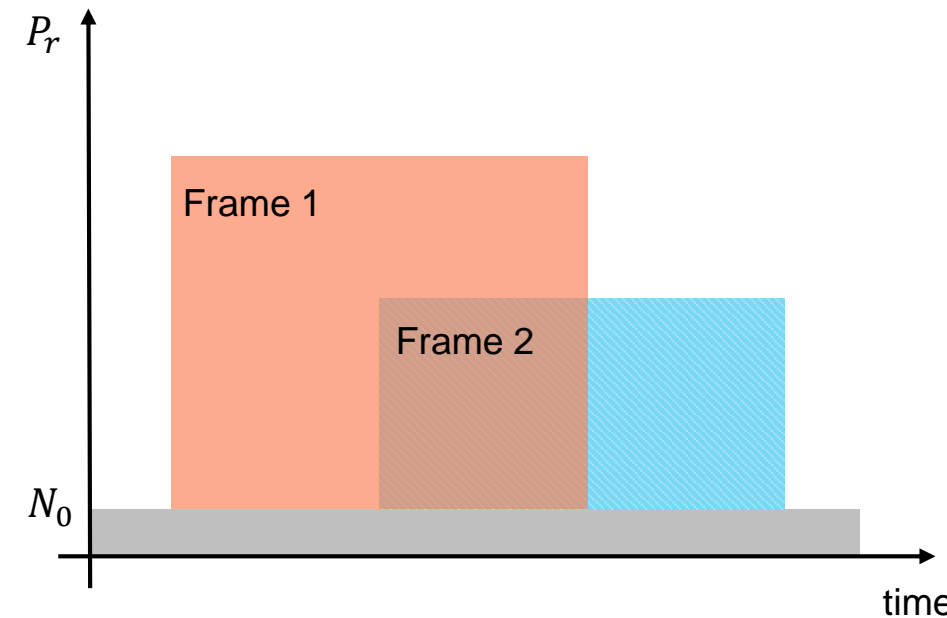
Frame Reception Sequence

- ▶ When a radio is listening for incoming frames, it continuously looks for the **known pattern of the preamble** by demodulating the received signal
- ▶ Upon detection of the preamble, the receiver attempts to **decode the PLCP header**
- ▶ Upon success, the receiver demodulates incoming waveforms according to the **frame modulation, coding and duration** indicated in the PLCP header
- ▶ Raw bits are then passed to the **MAC layer** where a cyclic redundancy check (CRC) determined whether the frame is successfully received
- ▶ A receiver might be able to successfully **receive and decode preamble and PLCP header** but fails to receive the **frame body** (depends on signal quality)
- ▶ When a radio is **already receiving a frame**, it is not able to receive another **incoming frame**
 - ▶ It would treat the preamble of the new incoming frame as **part of the frame** being demodulated

Lecture 5

Frame Body Capture Effect

- ▶ Robust process for **decoding the preamble and PLCP header**
 - ▶ If a new frame arrives when a radio is still receiving the frame preamble and PLCP header of an earlier frame
 - ▶ The radio may choose **to lock onto the new frame** if it has sufficiently higher power than the earlier
 - ▶ It is also possible to capture a new incoming frame during the frame body reception
 - ▶ When a **sudden sharp (e.g. greater than 10dB)** is detected, the receiver assumes the arrival of a new frame with a **stronger signal**
 - ▶ Previous frame is then **abandoned** and preamble and PLPC of the new incoming frame is attempted to be decoded



Lecture 5

Frame Body Capture Effect

- ▶ Incoming frames associated with **stronger signal** are **preferred** over other others
 - ▶ They are likely originated by **nearby stations**
- ▶ Suitable for V2X enabling a cooperative awareness
 - ▶ Vehicles may preferred messages from **closer vehicles** over message from vehicles that are **further away**
 - ▶ Nearby vehicles will more likely impose **immediate risks** than faraway vehicles
- ▶ **Frame body capture** can also reduced the negative **impact of hidden terminal effects**



Lecture 5

Wireless Channel

- ▶ Wireless channel is a **medium** used to transmit data wirelessly from the transmitter antenna to the receiver antenna



Lecture 5

Channel Modeling

- ▶ Channel propagation model is a **mathematical representation** of the **effects** of a communication channel through which wireless signals are propagated
- ▶ Channel propagation models are used for **simulation** and **system testing**
- ▶ Channel propagation model is modeled **analytically** or **empirically** by real world measurements

- ▶ Two main approaches to model the channel
 - ▶ **Deterministic**
 - ▶ **Stochastic**



Lecture 5

Path Loss Model

- ▶ Knowledge of the propagation channel is essential for V2X communication systems
 - ▶ Required for the evaluation of interference and scalability analysis
- ▶ **Received** power depends on **transmit** power, antenna gains and number of potential **loss terms**

$$P_r = P_t + G_t + G_r - \sum_x L_x \text{ in dB}$$

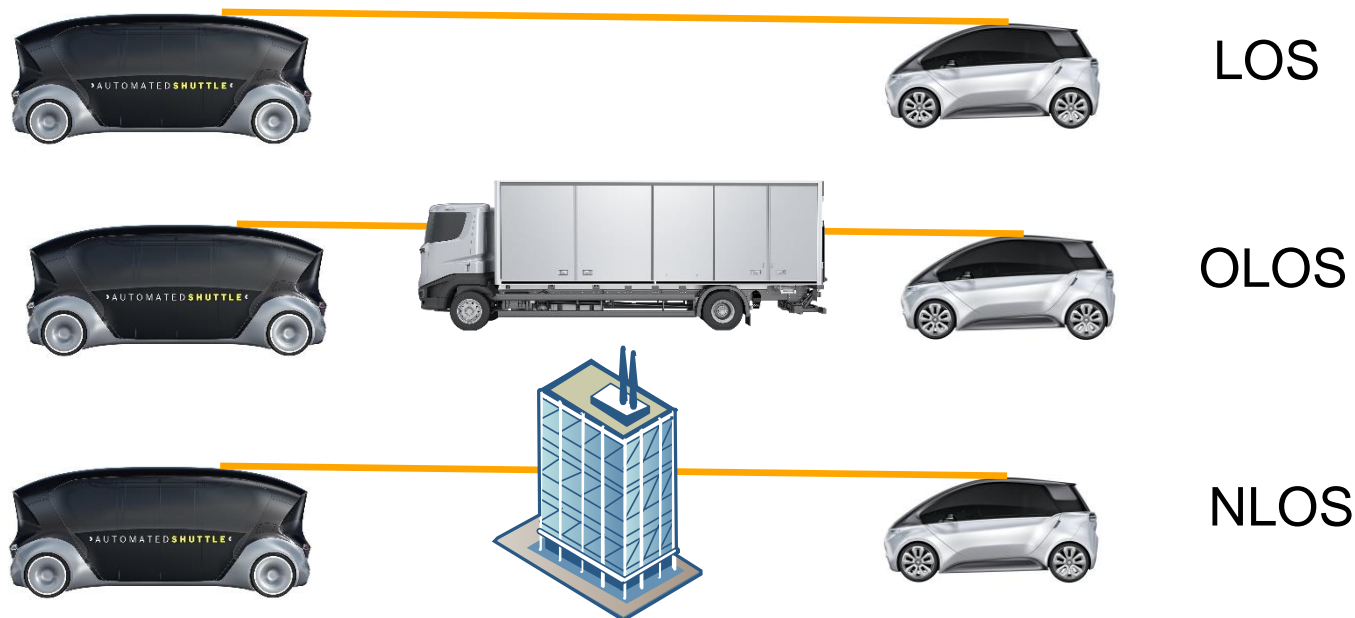
- ▶ How to derive the **path loss terms** $\sum_x L_x$?



Lecture 5

V2X Link Categories

- ▶ **Line-of-sight (LOS):** Situation where a line-of-sight between the TX and RX exists
- ▶ **Obstructed-line-of-sight (OLOS):** Situation where a line-of-sight between the TX and RX is obstructed partially by another object (dynamic blockages e.g. other vehicles)
- ▶ **Non-line-of-sight (NLOS):** Situation where the line-of-sight between the TX and RX is completely blocked by a larger object, e.g. a building

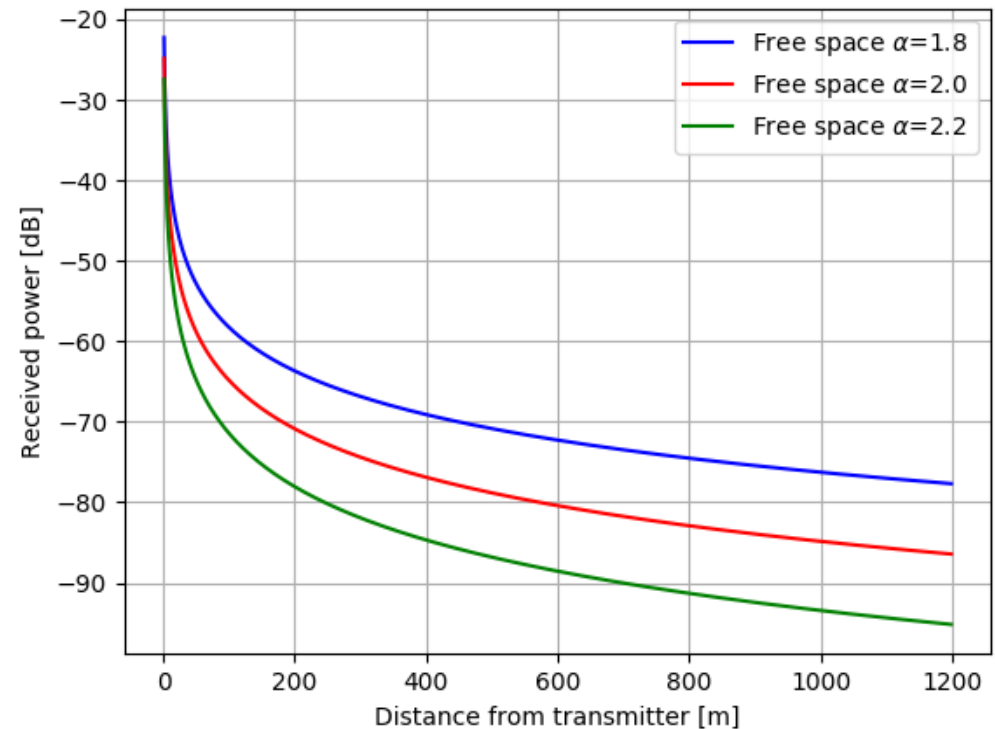


Lecture 5

Free Space Model

- ▶ Path loss model computes the **average attenuation** of a signal in relation to the propagation **distance**
- ▶ **Free-space model** is the simplest deterministic path loss model known as Friis model
 - ▶ Consider only the distance and the wavelength λ
 - ▶ Path-loss exponent α for non-ideal channel conditions → **Environment-dependent**

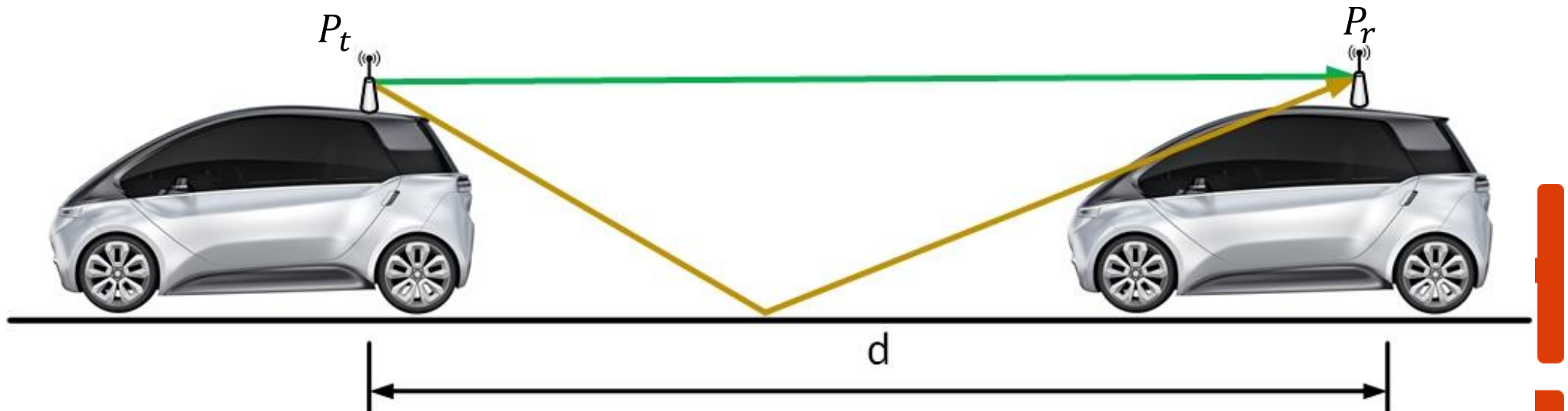
$$L_{FS} = 10\log(16\pi^2 \frac{d^\alpha}{\lambda^\alpha})$$



Lecture 5

Two-Ray Interference Model (1/4)

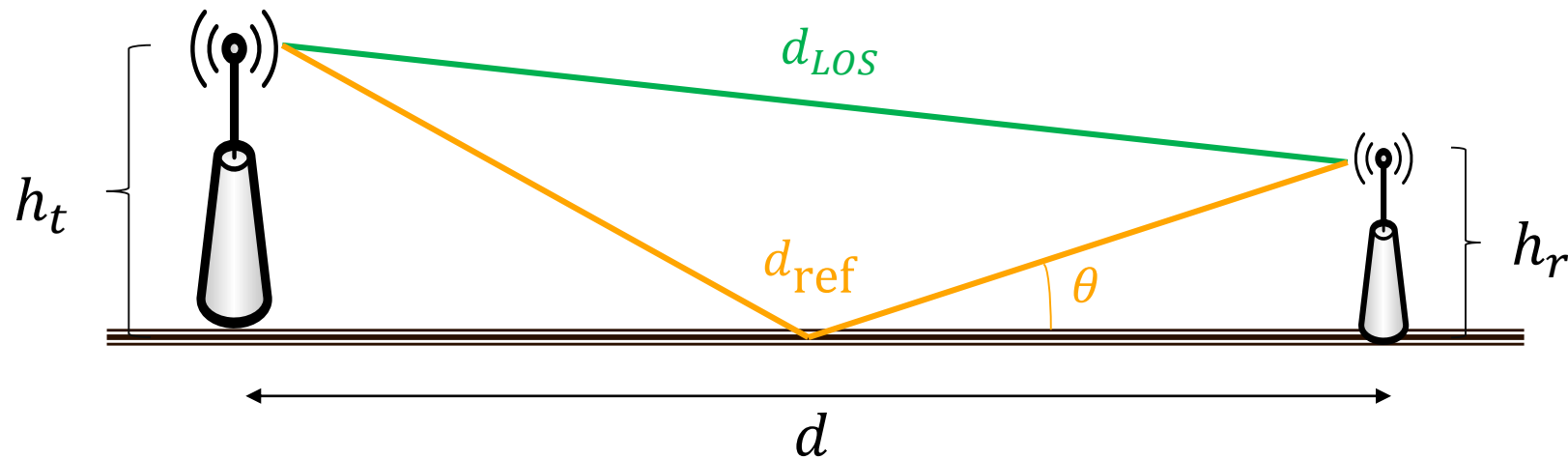
- ▶ Deterministic channel model
- ▶ A **physically more accurate approximation** of path loss
 - ▶ **Phase difference** of two interfering rays: **direct** line-of-sight and **reflected** non-line-of-sight path
 - ▶ Received power $P_r = ?$



Lecture 5

Two-Ray Interference Model (2/4)

- Radio signal reflected at the ground is also considered → more realistic



Lecture 5

Two-Ray Interference Model (3/4)

- **Phase difference** by the ray that is reflected from the ground compared to the direct path

- **Angle of incidence** θ

$$\sin \theta = \frac{h_t + h_r}{d_{ref}} \quad \cos \theta = \frac{d}{d_{ref}}$$

- **Reflection coefficient** γ

$$\gamma = \frac{\sin \theta - \sqrt{\epsilon_r - \cos^2 \theta}}{\sin \theta + \sqrt{\epsilon_r - \cos^2 \theta}}$$

- **Correction term** for the phase and magnitude of interference by the reflected ray

$$L_{TR} = 20 \log \left(4\pi \frac{d}{\lambda} \left| 1 + \gamma e^{i\varphi} \right| \right)$$

$$\varphi = 2\pi \frac{d_{los} - d_{ref}}{\lambda}$$

$$d_{los} = \sqrt{d^2 + (h_t - h_r)^2}$$

$$d_{ref} = \sqrt{d^2 + (h_t + h_r)^2}$$



Lecture 5

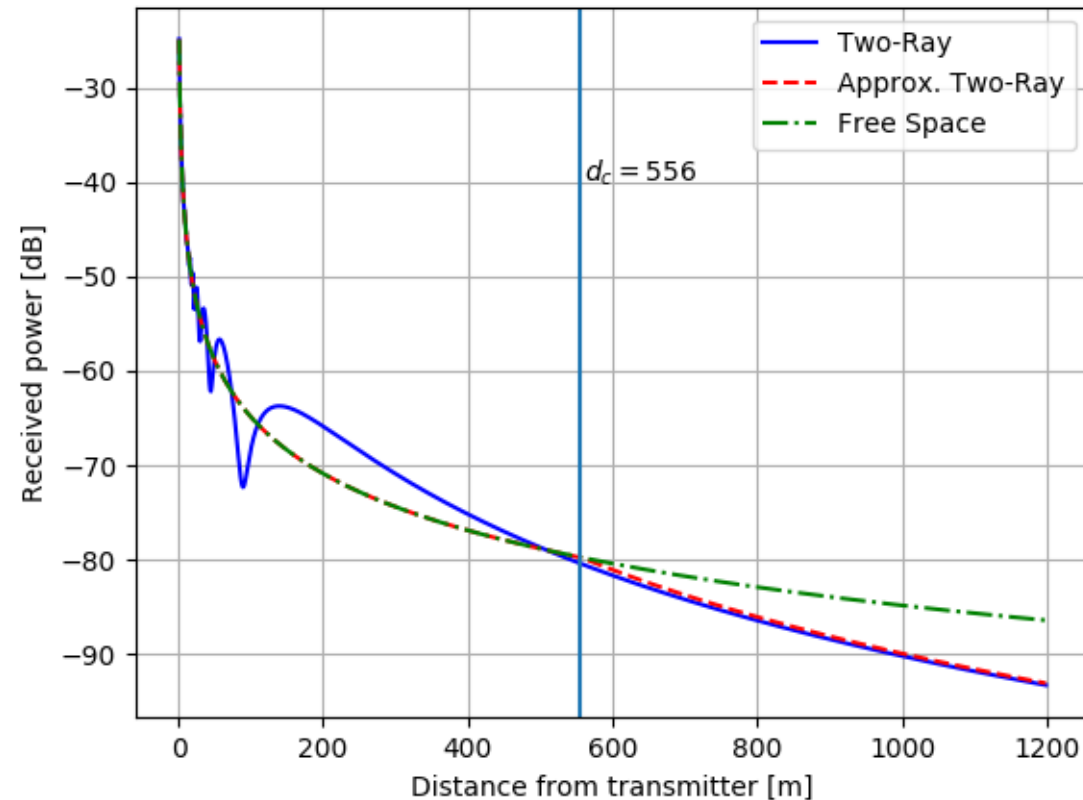
Two-Ray Interference Model (4/4)

- **Approximation** of two-ray interference model for **large distance**
- To enable **fast simulation** but with the best level of accuracy

$$L_{TR, \text{far}} = 20 \log \left(\frac{d^2}{h_t h_r} \right)$$

- Introducing a **cross-distance** $d_c = 4\pi \frac{h_t h_r}{\lambda}$
- Complete approximated two-ray interference model

$$L_{TR} = \begin{cases} L_{FS} , & d \leq d_c \\ L_{TR, \text{far}} , & d > d_c \end{cases}$$

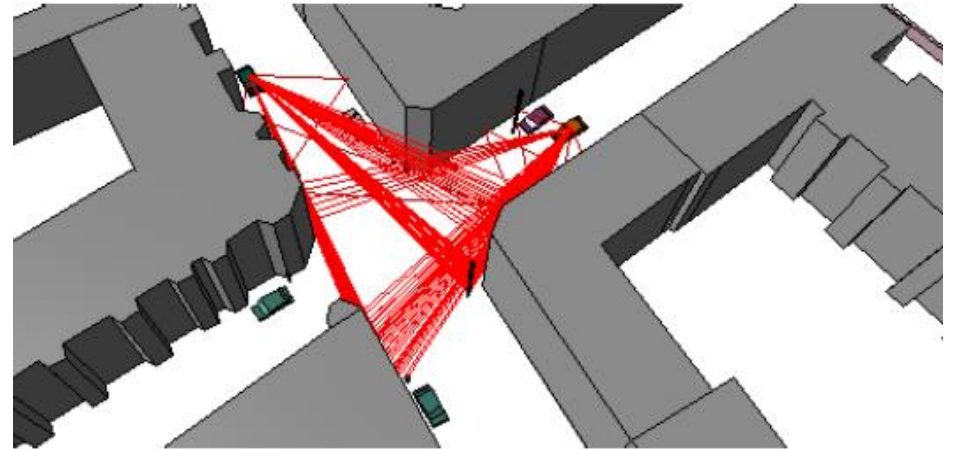


Lecture 5

3D Ray-optical Channel Model

- ▶ Deterministic channel modeling approaches using **3D ray-optical algorithms**
- ▶ Direct path, **reflections** as well as **diffuse scattering** are taken into account
- ▶ All objects in the environment need to be modeled with **characteristics** (permittivity, conductivity and thickness)
- ▶ Each ray is **individually** evaluated
- ▶ Provides **accurate models** BUT requires high computational **efforts**

$$h(t) = \sum_{n=1}^N A_n \delta(t - \tau_n) \exp(-j\theta_n)$$



- ▶ Receive signal $h(t)$ has N time-delayed impulses (rays), each of which is an attenuated and phase-shifted version of the original transmitted signal

Lecture 5

Log-Normal Shadowing Model

- ▶ **Free space** and **two-ray interference** models do not include the critical fading effects found in a vehicular environment, i.e. shadowing or fading
- ▶ Shadowing models consider **additional factors** that contribute to path loss such as **obstacles**, which shield a receiver from all or part of the radiated power
- ▶ For every individual transmission the received power is then drawn from a **distribution**
 - ▶ With a certain probability two nodes close to each other cannot communicate
 - ▶ With a certain probability two nodes beyond the deterministic transmission range can communicate
- ▶ **Log-Normal Shadowing model** uses a normal distribution with variance σ to distribute reception power

$$PL_{LN} = 10\alpha\log(d) + X_{\sigma}$$

- ▶ X_{σ} is a zero-mean Gaussian distributed random variable with standard deviation σ expressed in dB, used to emulate the shadowing effect



Lecture 5

Nakagami Model

- ▶ Stochastic channel model
- ▶ It models situations used when scattered signals reach a receiver by multipath
- ▶ Reception power follows a **gamma distribution**

$$P_r(d, m) = \text{Gamma}(m, \frac{P_{r, \text{det}}(d)}{m})$$

- ▶ Parameter m specifies the intensity of fading
- ▶ Distance dependence of the fading severity as a function of the distance between transmitter and receiver

$$m(d) = 2.7 \exp(-0.01(d-1)) + 1$$



Lecture 5

Literature

- ▶ E.M. van Eenennaam: “A Survey of Propagation Models used in Vehicular Ad hoc Network (VANET) Research”
- ▶ C. Sommer et al.: “Simulation Tools and Techniques for Vehicular Communications and Applications”, 2015
- ▶ T. Abbas et al.: “A Measurement Based Shadow Fading Model for Vehicle-to-Vehicle Network Simulations”, 2015
- ▶ B. Bloessl, "A Physical Layer Experimentation Framework for Automotive WLAN," Dissertation, Department of Computer Science, Paderborn University, June 2018

