

# Assignment4 Concept Questions

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## 1 Concepts Questions

### 1.1 Question 1

**Question:** Calculate  $b$  from the Laplace distribution  $Lap(x|b)$  that satisfies  $\epsilon$ -differential privacy with an  $\ell_1$ -sensitivity of 1.

Laplace mechanism is defined as :

$$M(x, f(\cdot), \epsilon) = f(x) + Y$$

,where  $Y$  is a random variable drawn from  $Lap(\Delta f / \epsilon)$ .

Cause the Laplace distribution  $Lap(x|b)$  that satisfies  $\epsilon$ -differential privacy with an  $\ell_1$ -sensitivity of 1,

$$\max_{\|x-y\|_1 \leq 1} \|f(x) - f(y)\|_1 = 1$$

Let  $p_x$  denote the PDF of  $M(x)$  and  $p_y$  denote the PDF of  $M(y)$ . At some arbitrary point  $z$ :

$$\begin{aligned} \frac{p_x(z)}{p_y(z)} &= \frac{\exp(-\frac{|f(x)-z|}{b})}{\exp(-\frac{|f(y)-z|}{b})} \\ &= \exp((|f(x)-z| - |f(y)-z|)/b) \leq \exp(\|f(x) - f(y)\|_1/b) \\ &\leq \exp(\frac{1}{b}) = \exp(\epsilon) \end{aligned}$$

So that we have  $\epsilon = \frac{1}{b}$ , i.e.  $b = \frac{1}{\epsilon}$ .

### 1.2 Question 2

**Question:** Describe the algorithm for Differentially Private Stochastic Gradient Descent.

Part one: Input

The algorithm takes examples  $x_1, \dots, x_N$  as input. The loss function is defined as  $L(\theta) = \frac{1}{N} \sum_i L(\theta, x_i)$ . The parameters are defined as below: learning rate  $\eta_i$ , noise scale  $\sigma$ , gradient norm bound  $C$ .

### Part two: Iteration

- First, we randomly initialize the model parameters.
- Second, for each  $t \in [T]$ , we take a random sample  $L_t$  with sampling probability  $L/N$ .

Next, we compute the gradient of the loss function with respect to the model parameters, i.e  $g_t(x_i) \leftarrow \nabla_{\theta_t} L(\theta_t, x_i)$  and clip the gradient in order to make all gradients satisfy  $\|g\|_2 \leq C$ .

Then, we add random noise  $N(0, \sigma^2 C^2 I)$  clipped gradients to ensure privacy.

Finally, we use this clipped gradient with gradient added to do gradient descent and update parameters.

### Part three: Output

The algorithm outputs network parameters after  $T$  updating iterations and the overall privacy cost  $(\epsilon, \delta)$  using a privacy accounting method.

## 1.3 Question 3

**Question:** Design an algorithm to enhance differentially private SGD based on the following requirements. Let  $g(x_i) \in R^p$  be the gradient of the example  $x_i$ , and  $G \in R^{n \times p} = [g(x_1)g(x_2)...g(x_n)]$  be the gradient matrix. Create an algorithm to compress the gradient matrix such that  $\hat{G} = GB$ , where  $\hat{G} \in R^{n \times k}, k < p$ , and  $B \in R^{p \times k}$  is a direction matrix, related to the direction of  $G$ , and it needs to be guaranteed to be orthogonal. Utilize  $\hat{G}$  to perform per-example clipping and add Gaussian noise in DPSGD. Finally, project the noise gradient back to  $R^p$  using  $B^T$  and update the model's parameters. Provide the algorithm for the entire process.

### Part one: Input

The algorithm takes examples  $x_1, \dots, x_N$  as input. The loss function is defined as  $L(\theta) = \frac{1}{N} \sum_i L(\theta, x_i)$ . The parameters are defined as below: learning rate  $\eta_i$ , noise scale  $\sigma$ , gradient norm bound  $C$ .

### Part two: Iteration

- First, we randomly initialize the model parameters.

- Second, for each  $t \in [T]$ , we take a random sample  $L_t$  with sampling probability  $L/N$ .

Next, we compute the gradient of the loss function with respect to the model parameters, i.e  $g_t(x_i) \leftarrow \nabla_{\theta_t} L(\theta_t, x_i)$  and clip the gradient in order to make all gradients satisfy  $\|g\|_2 \leq C$ .

Let  $G_t = [g_t(x_1)g_t(x_2)...g_t(x_n)]$ . We use Singular Value Decomposition (SVD) method to decompose the gradient matrix:  $G_t = U\Sigma V^T$ , where  $\Sigma$  is a  $p \times p$  rectangular diagonal matrix,  $U, V$  are  $n \times p$  real orthogonal matrices.

Select the top-k columns of  $V$  and transpose it to obtain a direction matrix:  $B \in R^{p \times k}$ , then the compressed gradient matrix  $\hat{G} = GB$ .

Add Gaussian noise to the clipped gradient: Let  $n_i \in R^k$  be a vector drawn from a Gaussian distribution with zero mean and a variance matrix of  $\sigma^2 C^2 I$ . Add  $n_i$  to the i-th row of  $\hat{G}$  to obtain the noisy compressed gradient:  $\hat{G}_i = \hat{G}_i + n_i$ . Uncompress the gradient matrix:  $\hat{G} = \hat{G}B^T$ . Then we can use it to do gradient descent and update parameters.

### Part three: Output

The algorithm outputs network parameters after  $T$  updating iterations and the overall privacy cost  $(\epsilon, \sigma)$  using a privacy accounting method.