

Smoothness and Strong Convexity

Instructor: Jin Zhang

Department of Mathematics
Southern University of Science and Technology

Fall 2023

Contents

- 1 L -Smooth Functions
- 2 Strong Convexity
- 3 Smoothness and Strong Convexity Correspondence

1. L -Smoothness

Recall

- **(vector l_p norm and its dual).** For a given $1 \leq p < \infty$, the l_p -norm on \mathbb{R}^n is given by

$$\|x\|_p = \sqrt[p]{\sum_{i=1}^n |x_i|^p} \text{ for all } x = (x_1, \dots, x_n)^T \in \mathbb{R}^n.$$

The l_∞ -norm on \mathbb{R}^n is defined by

$$\|x\|_\infty = \max_{i=1, \dots, n} |x_i|.$$

l_q -norm is the dual of l_p -norm ($1 \leq p \leq \infty$), where q satisfies $\frac{1}{p} + \frac{1}{q} = 1$.

Recall

- **(induced matrix norm).** Given l_a -norm and l_b -norm on \mathbb{R}^n and \mathbb{R}^m , respectively, the induced matrix norm on $\mathbb{R}^{m \times n}$ is given by

$$\|A\|_{a,b} = \max_{x \in \mathbb{R}^n} \{ \|Ax\|_b \mid \|x\|_a \leq 1 \} \text{ for all } A \in \mathbb{R}^{m \times n}.$$

It can be easily shown that for any $A \in \mathbb{R}^{m \times n}$ and $x \in \mathbb{R}^n$,

$$\|Ax\|_b \leq \|Ax\|_{a,b} \|x\|_a.$$

Definition: (L -smoothness)

Let $L \geq 0$. Then $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ is said to be L -smooth over a set $D \in \mathbb{R}^n$ if it is differentiable over D and satisfies

$$\|\nabla f(x) - \nabla f(y)\|_* \leq L \|x - y\| \text{ for all } x, y \in D.$$

The constant L is called the smoothness parameter.

Remark:

1. $C_L^{1,1}(D) = \{f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}} \mid f \text{ is } L\text{-smooth over } D \subset \mathbb{R}^n\}$.
2. Let $0 \leq L_1 \leq L_2$, then $C_{L_1}^{1,1}(D) \subset C_{L_2}^{1,1}(D)$.
3. We say $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is L -smooth if f is L -smooth over \mathbb{R}^n .

Example (0-smoothness of affine functions).

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be given by $f(x) = \langle b, x \rangle + c$, where $b \in \mathbb{R}^n$ and $c \in \mathbb{R}$. Then f is 0-smooth.

Recall: Let $C \subset \mathbb{R}^n$ be nonempty, then P_C is the orthogonal projection mapping associated with C defined by

$$P_C(x) = \arg \min_{y \in C} \|y - x\|.$$

In addition, if C is closed and convex, P_C is well-defined and the function $\varphi_C(x) : \mathbb{R}^n \rightarrow \mathbb{R}$ given by

$$\varphi_C(x) \equiv \frac{1}{2} d_C^2(x) = \frac{1}{2} \|x - P_C(x)\|^2$$

is convex. Under the l_2 -norm setting, φ_C is differentiable with

$$\nabla \varphi_C(x) \equiv x - P_C(x).$$

Theorem:

Let $C \subset \mathbb{R}^n$ be nonempty closed and convex. Then

(a). **(firm nonexpansiveness)** For any $v, w \in \mathbb{R}^n$,

$$\langle P_C(v) - P_C(w), v - w \rangle \geq \|P_C(v) - P_C(w)\|^2.$$

(b). **(nonexpansiveness)** For any $v, w \in \mathbb{R}^n$,

$$\|P_C(v) - P_C(w)\| \leq \|v - w\|.$$

Example (1-smoothness of $\frac{1}{2}d_C^2$).

Let $C \subset \mathbb{R}^n$ be nonempty closed and convex. Consider the function $\varphi_C(x) = \frac{1}{2}d_C^2$, then φ_C is 1-smooth with respect to (w.r.t.) the l_2 -norm (over \mathbb{R}^n).

Example (1-smoothness of $\frac{1}{2}\|\cdot\|_2^2 - \frac{1}{2}d_C^2$).

Let $C \subset \mathbb{R}^n$ be nonempty closed and convex. Consider the function $\psi_C(x) = \frac{1}{2}\|x\|_2^2 - \frac{1}{2}d_C^2(x)$. Then ψ_C is 1-smooth with respect to (w.r.t.) the l_2 -norm.

1. L -Smooth Functions

1.1 The Descent Lemma

Lemma: (descent lemma).

Let $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be L -smooth over a given convex set Ω . Then for any $x, y \in \Omega$,

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2} \|x - y\|^2.$$

1. L -Smooth Functions

1.2 Characterizations of L -Smooth Functions

Theorem: (characterizations of L -smoothness).

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be real-valued convex and differentiable over \mathbb{R}^n , and let $L > 0$. Then the following claims are equivalent:

- (i). f is L -smooth.
- (ii). $f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2} \|x - y\|^2$ for all $x, y \in \mathbb{R}^n$.
- (iii). $f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{1}{2L} \|\nabla f(x) - \nabla f(y)\|_*^2$ for all $x, y \in \mathbb{R}^n$.
- (iv). $\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq \frac{1}{L} \|\nabla f(x) - \nabla f(y)\|_*^2$ for all $x, y \in \mathbb{R}^n$.
- (v). $f(\lambda x + (1 - \lambda)y) \geq \lambda f(x) + (1 - \lambda)f(y) - \frac{L}{2} \lambda(1 - \lambda) \|x - y\|^2$ for any $x, y \in \mathbb{R}^n$ and $0 \leq \lambda \leq 1$.

Recall: Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be convex and differentiable over \mathbb{R}^n . Then for any $x, y \in \mathbb{R}^n$,

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$$

Remark: necessity of convexity for L -smoothness characterization.

Consider the function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ given by $f(x) = -\frac{1}{2} \|x\|_2^2$. Then f is 1-smooth w.r.t. the l_2 -norm but is not L -smooth w.r.t. the l_2 -norm for $L < 1$. However, $-f$ is convex, so for any $x, y \in \mathbb{R}^n$,

$$(-f)(y) \geq (-f)(x) + \langle \nabla(-f)(x), y - x \rangle,$$

or equivalently,

$$f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle,$$

which implies that (ii) of Theorem (characterization of L -smoothness) is satisfied with $L = 0$.

1. L -Smooth Functions

1.3 Second-Order Characterization

Theorem: (L -smoothness and boundedness of the Hessian).

Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be twice continuously differentiable. Then for a given $L \geq 0$, the following two claims are equivalent:

- (i). f is L -smooth w.r.t. the l_p -norm ($1 \leq p \leq \infty$).
- (ii). $\|\nabla^2 f(x)\|_{p,q} \leq L$ for any $x \in \mathbb{R}^n$, where q satisfies $\frac{1}{p} + \frac{1}{q} = 1$.

Recall:

- Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be twice continuously differentiable convex over \mathbb{R}^n . Then $\nabla^2 f(x) \succeq 0$ for any $x \in \mathbb{R}^n$.
- If $A \in \mathbb{R}^{n \times n}$ is nonnegative definite, $\|A\|_{2,2} = \|A\|_2 = \lambda_{\max}(A)$.

Example: (1-smoothness of $\sqrt{1 + \|\cdot\|_2^2}$).

The function $f : \mathbb{R}^n \rightarrow \mathbb{R}$, given by

$$f(x) = \sqrt{1 + \|x\|_2^2},$$

is 1-smooth w.r.t. the l_2 -norm.

2. Strong Convexity

Definition: (strong convexity).

$f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ is called σ -strongly convex for a given $\sigma > 0$ if $\text{dom}(f)$ is convex and the following inequality holds for any $x, y \in \text{dom}(f)$ and $0 \leq \lambda \leq 1$:

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y) - \frac{\sigma}{2}\lambda(1 - \lambda) \|x - y\|^2$$

Theorem

$f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ is σ -strongly convex w.r.t the l_2 -norm if and only if $f(\cdot) - \frac{\sigma}{2} \|\cdot\|_2^2$ is convex.

Example: (strong convexity of quadratic functions).

Consider the quadratic function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ given by

$$f(x) = \frac{1}{2}x^T A x + b^T x + c,$$

where $A \in \mathbb{R}^{n \times n}$ is symmetric, $b \in \mathbb{R}^n$ and $c \in \mathbb{R}$.

Then f is strongly convex w.r.t. the l_2 -norm if and only if $A > 0$, and in that case, $\lambda_{\min}(A)$ is its largest possible strong convexity parameter.

Lemma:

Let $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be σ -strongly convex and let $g : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be convex. Then $f + g$ is σ -strongly convex.

Example: (strong convexity of $\frac{1}{2} \|\cdot\|_2^2 + \delta_C$).

Let $C \subset \mathbb{R}^n$ be nonempty convex. Then the function $\frac{1}{2} \|\cdot\|_2^2 + \delta_C$ is 1-strongly convex.

Lemma:

Let $f : \mathbb{R} \rightarrow \overline{\mathbb{R}}$ be closed convex and let $[a, b] \subseteq \text{dom} f$ ($a \leq b$). Then

$$f(b) - f(a) = \int_a^b h(t) dt,$$

where $h : (a, b) \rightarrow \mathbb{R}$ satisfies $h(t) \in \partial f(t)$ for any $t \in (a, b)$

Lemma: (line segment principle).

Let $C \subset \mathbb{R}^n$ be nonempty convex. Suppose that $x \in \text{ri}(C)$, $y \in \text{cl}(C)$, and let $\lambda \in (0, 1]$. Then $\lambda x + (1 - \lambda)y \in \text{ri}(C)$.

Theorem: (first-order characterizations of strong convexity).

Let $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be proper closed and convex. Then for a given $\sigma > 0$, the following three claims are equivalent:

- (i). f is σ -strongly convex.
- (ii). For any $x \in \text{dom} \partial f$, $y \in \text{dom} f$ and $g \in \partial f(x)$ we have

$$f(y) \geq f(x) + \langle g, y - x \rangle + \frac{\sigma}{2} \|y - x\|^2$$

- (iii). For any $x, y \in \text{dom} \partial f$, and $g_x \in \partial f(x)$, $g_y \in \partial f(y)$ we have

$$\langle g_x - g_y, x - y \rangle \geq \sigma \|x - y\|^2.$$

Theorem: (existence and uniqueness of a minimizer of closed strongly convex functions)

Let $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be proper closed and σ -convex. Then

- (a). f has a unique minimizer;
- (b). $f(x) - f(x^*) \geq \frac{\sigma}{2} \|x - x^*\|^2$ for all $x \in \text{dom}(f)$, where x^* is the unique minimizer of f .

3. Smoothness and Strong Convexity Correspondence

3.1 The Conjugate Correspondence Theorem

Theorem: (conjugate correspondence theorem).

Let $\sigma > 0$. Then

- (a). If $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is $\frac{1}{\sigma}$ -smooth and convex, then f^* is σ -strongly convex with respect to the dual norm $\|\cdot\|_*$.
- (b). If $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ is proper closed and σ -strongly convex, then $f^* : \mathbb{R}^n \rightarrow \mathbb{R}$ is $\frac{1}{\sigma}$ -smooth w.r.t the dual norm $\|\cdot\|_*$.

3. Smoothness and Strong Convexity Correspondence

3.2 Smoothness of the Infimal Convolution

Theorem: (smoothness of the infimal convolution).

Let $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be proper closed and convex, and let real-valued function $w : \mathbb{R}^n \rightarrow \mathbb{R}$ be L -smooth and convex. Assume that $f \square w$ is real-valued. Then the following hold:

- (a). $f \square w$ is L -smooth.
- (b). Let $x \in \mathbb{R}^n$, and assume that $u(x)$ is a minimizer of

$$\min_u \{f(u) + w(x - u)\}.$$

Then $\nabla(f \square w)(x) = \nabla w(x - u(x))$.