## Subgradients

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### 1. Definitions and First Examples

#### **Definitions**

• (subgradient) Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and let  $x \in \text{dom}(f)$ . Then  $g \in \mathbb{R}^n$  is called a subgradient of f at x if

$$f(y) \ge f(x) + \langle g, y - x \rangle$$
 for all  $y \in \mathbb{R}^n$ .

• (subdifferential) The set of all subgradients of f at  $x \in dom(f)$  is called the subdifferential of f at x and is denoted by  $\partial f(x)$ :

$$\partial f(x) \equiv \left\{g \in \mathbb{R}^n \, : \, f(y) \geq f(x) + \langle g, y - x \rangle \text{ for all } y \in \mathbb{R}^n \right\}.$$

When  $x \notin dom(f)$ , we define  $\partial f(x) = \emptyset$ .



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• Example 1 (subdifferential of norms at 0). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be given by f(x) = ||x||, where  $||\cdot||$  is the endowed norm on  $\mathbb{R}^n$ . Then the subdifferential of f at x = 0 is the dual norm unit ball:

$$\partial f(0) = \mathbb{B}_{\|\cdot\|_*}[0,1] = \{g \in \mathbb{R}^n \, : \, \|g\|_* \le 1\} \, .$$

• Example 2 (subdifferential of the  $l_1$ -norm at 0). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be given by  $f(x) = \|x\|_1$ . Then

$$\partial f(0) = \mathbb{B}_{\|\cdot\|_{\infty}} [0,1] = [-1,1]^n.$$

• Definition (normal cone). Given a set  $S \subseteq \mathbb{R}^n$  and a point  $x \in S$ , the normal cone of S at x is defined as

$$N_S(x) = \{ y \in \mathbb{R}^n : \langle y, z - x \rangle \le 0 \text{ for any } z \in S \}.$$

When  $x \notin S$ , we define  $N_S(x) = \emptyset$ .

• Example 3 (subdifferential of indicator functions). Suppose that  $S \subset \mathbb{R}^n$  is nonempty and consider the indicator function  $\delta_S$ . Then for any  $x \in S$ , we have that

$$\partial \delta_S(x) = N_S(x).$$

Example 4 (subdifferential of the indicator functions of the unit ball).
 Let

$$S = \mathbb{B}[0,1] = \{x \in \mathbb{R}^n : ||x|| \le 1\}.$$

Then

$$\partial \delta_{\mathbb{B}[0,1]} = N_{\mathbb{B}[0,1]}(x) = \begin{cases} \{ y \in \mathbb{R}^n : ||y||_* \le \langle y, x \rangle \}, & ||x|| \le 1, \\ \emptyset, & ||x|| > 1. \end{cases}$$

 Example 5 (subgradient of the dual function). Consider the minimization problem

$$\min \{ f(x) : g(x) \le 0, x \in X \},\$$

where  $\varnothing \neq X \subseteq \mathbb{R}^n$ ,  $f: \mathbb{R}^n \to \mathbb{R}$  and  $g: \mathbb{R}^n \to \mathbb{R}^m$  is vector-valued. The Lagrangian dual objective function is given by

$$q(\lambda) = \min_{x \in X} \left\{ L(x; \lambda) \equiv f(x) + \lambda^T g(x) \right\}.$$

The effective domain of -q is given by

$$\operatorname{dom}(-q) = \left\{ \lambda \in \mathbb{R}^m_+ \, : \, q(\lambda) > -\infty \right\}.$$

No matter whether the primal problem is convex or not, the the dual problem

$$\max_{\lambda \in \mathbb{R}^m} \left\{ q(\lambda) \, : \, \lambda \in \mathsf{dom}(-q) \right\}$$

is always convex.

Let  $\lambda_0 \in \text{dom}(-q)$  and assume that the minimum in the minimization problem defining  $q(\lambda_0)$ ,

$$q(\lambda_0) = \min_{x \in X} \left\{ f(x) + \lambda_0^T g(x) \right\},\,$$

is attained at  $x_0 \in X$ .

We seek to find a subgradient of the convex function -q at  $\lambda_0$ :

$$-g(x_0) \in \partial(-q)(\lambda_0).$$

• Example 6 (subgradient of the maximum eigenvalue function). Consider the function  $f:\mathbb{S}^n\to\mathbb{R}$  given by  $f(X)=\lambda_{\max}(X)$  (where  $\mathbb{S}^n$  is the set of all  $n\times n$  symmetric matrices). Let  $X\in\mathbb{S}^n$  and let v be a normalized eigenvector of X ( $\|v\|_2=1$ ) associated with the maximum eigenvalue of X. Then

$$vv^T \in \partial f(X)$$
.

### 2. Properties of the Subdifferential Set

Recall that the subdifferential of f at x is denoted by

$$\partial f(x) \equiv \left\{g \in \mathbb{R}^n \, : \, f(y) \geq f(x) + \langle g, y - x \rangle \text{ for all } y \in \mathbb{R}^n \right\}.$$

• Theorem (closedness and convexity of the subdifferential set). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper. Then the set  $\partial f(x)$  is closed and convex for any  $x \in \mathbf{R}^n$ .

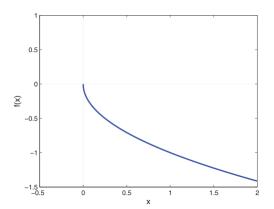
• **Definition (subdifferentiability).** A proper function  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  is called subdifferentiable at  $x \in \text{dom}\,(f)$  if  $\partial f(x) \neq \varnothing$ . The collection of points of subdifferentiability is denoted by  $\text{dom}\,(\partial f)$ :

$$\operatorname{dom}(\partial f) = \left\{ x \in \mathbb{R}^n : \partial f(x) \neq \varnothing \right\}.$$

• Lemma (nonemptiness of subdifferential sets  $\Rightarrow$  convexity). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and assume that  $\mathrm{dom}(f)$  is convex. Suppose that for any  $x \in \mathrm{dom}(f)$ , the set  $\partial f(x)$  is nonempty. Then f is convex.

• Example (A convex function, which is not subdifferentiable at one of the points in its domain). Consider the convex function  $f:\mathbb{R}\to\overline{\mathbb{R}}$  defined by

$$f(x) = \begin{cases} -\sqrt{x}, & x \ge 0, \\ \infty, & \text{else.} \end{cases}$$



It is not subdifferentiable at x = 0

• Theorem (supporting hyperplane theorem). Let  $\varnothing \neq C \subseteq \mathbb{R}^n$  be convex, and let  $y \notin \operatorname{int}(C)$ . Then there exists  $0 \neq p \in \mathbb{R}^n$  such that

$$\langle p, x \rangle \leq \langle p, y \rangle$$
 for any  $x \in C$ .

- Theorem (nonemptiness and boundedness of the subdifferential set at interior points of the domain). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and assume that  $\tilde{x} \in \operatorname{int}(\operatorname{dom}(f))$ . Then  $\partial f(\tilde{x})$  is nonempty and bounded.
- Corollary (subdifferentiability of real-valued convex functions). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be convex. Then f is subdifferentiable over  $\mathbb{R}^n$ .

• Theorem (boundedness of subgradients over compact sets). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and assume that  $X \subseteq \operatorname{int} (\operatorname{dom}(f))$  is nonempty and compact. Then  $Y = \bigcup_{x \in X} \partial f(x)$  is nonempty and bounded.

Recall that the relative interior of a convex set  $S\subseteq\mathbb{R}^n$  is denoted by  $\mathrm{ri}(S)=\{x\in\mathrm{aff}(S):\exists V\text{ be some neighborhood of }x\text{ s.t. }V\cap\mathrm{aff}(S)\subseteq S\}\,.$ 

• Theorem (nonemptiness of the relative interior). Let  $\emptyset \neq C \subseteq \mathbb{R}^n$  be convex. Then ri(C) is nonempty.

- Theorem (nonemptiness of the subdifferential set at relative interior points). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and let  $\tilde{x} \in \operatorname{ri}(\operatorname{dom}(f))$ . Then  $\partial f(\tilde{x})$  is nonempty.
- Corollary. Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex. Then there exists  $x \in \text{dom}(f)$  for which  $\partial f(x)$  is nonempty.

• Theorem (unboundedness of the subdifferential set when  $\dim(\operatorname{dom}(f)) < n$ ). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex. Suppose that  $\dim(\operatorname{dom}(f)) < n$  and let  $x \in \operatorname{dom}(f)$ . If  $\partial f(x) \neq \emptyset$ , then  $\partial f(x)$  is unbounded.

### 3. Directional Derivatives

## 3.1 Definition and Basic Properties

• **Definition.** Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper. The directional derivative of f at  $x \in \operatorname{int}(\operatorname{dom}(f))$  in a given direction  $d \in \mathbb{R}^n$ , if it exists, is defined by

$$f'(x;d) \equiv \lim_{\alpha \to 0^+} \frac{f(x+\alpha d) - f(x)}{\alpha}.$$

• Theorem. Let  $f:\mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex and let  $x \in \operatorname{int}(\operatorname{dom}(f))$ . Then for any  $d \in \mathbb{R}^n$ , the directional derivative f'(x;d) exists.

- Lemma (convexity and homogeneity of  $d \mapsto f'(x;d)$ ). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex and let  $x \in \operatorname{int}(\operatorname{dom}(f))$ . Then
  - (a). the function  $d \mapsto f'(x; d)$  is convex;
  - (b). for any  $\lambda \geq 0$  and  $d \in \mathbb{R}^n$ , it holds that  $f'(x; \lambda d) = \lambda f'(x; d)$ .
- Lemma. Let  $f:\mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and let  $x \in \operatorname{int} (\operatorname{dom}(f))$ . Then

$$f(y) \ge f(x) + f'(x; y - x)$$
 for all  $y \in dom(f)$ .

Theorem (directional derivative of maximum of functions).
 Suppose that

$$f(x) = \max \{f_1(x), f_2(x), \dots, f_m(x)\},\$$

where  $f_1, f_2, \cdots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  are proper. Let  $x \in \bigcap_{i=1}^m \operatorname{int} (\operatorname{dom}(f))$  and  $d \in \mathbb{R}^n$ . Assume that  $f_i{'}(x;d)$  exist for any  $i \in \{1, 2, \cdots, m\}$ . Then

$$f'(x;d) = \max_{i \in I(x)} f_i'(x;d),$$

where  $I(x) = \{i : f_i(x) = f(x)\}.$ 

 Corollary (directional derivative of maximum of functions -convex case).

Suppose that

$$f(x) = \max \{f_1(x), f_2(x), \dots, f_m(x)\},\$$

where  $f_1, f_2, \cdots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  are proper convex. Let  $x \in \bigcap_{i=1}^m \operatorname{int} (\operatorname{dom}(f))$  and  $d \in \mathbb{R}^n$ . Then

$$f'(x;d) = \max_{i \in I(x)} f_i'(x;d),$$

where  $I(x) = \{i : f_i(x) = f(x)\}.$ 

# 3. Directional Derivatives3.2 The Max Formula

• Theorem (max formula). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex. Then for any  $x \in \operatorname{int}(\operatorname{dom}(f))$  and  $d \in \mathbb{R}^n$ ,

$$f'(x;d) = \max \{\langle g, d \rangle : g \in \partial f(x) \}.$$

 Remark. The max formula can also be rewritten using the support function notation as follows:

$$f'(x;d) = \sigma_{\partial f(x)}(d).$$

## 3. Directional Derivatives

### 3.3 Differentiability

• **Definition (differentiability).** The function  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  is said to be differentiable at  $x \in \operatorname{int}(\operatorname{dom}(f))$  if there exists  $g \in \mathbb{R}^n$  such that

$$\lim_{h \to 0} \frac{f(x+h) - f(x) - \langle g, h \rangle}{\|h\|} = 0.$$

In this case it's obvious that g is uniquely defined. The unique vector g is called the gradient of f at x and is denoted by  $\nabla f(x)$ .

• Theorem (directional derivatives at points of differentiability). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper, and suppose that f is differentiable at  $x \in \operatorname{int}(\operatorname{dom}(f))$ . Then for any  $d \in \mathbb{R}^n$ 

$$f'(x;d) = \langle \nabla f(x), d \rangle.$$

 Example 1 (directional derivative of maximum of differentiable function). Consider the function

$$f(x) = \max \{f_1(x), f_2(x), \dots, f_m(x)\},\$$

where  $f_1, f_2, \dots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  are proper and differentiable at a given point  $x \in \bigcap_{i=1}^m \operatorname{int}(\operatorname{dom}(f))$ . Then for any  $d \in \mathbb{R}^n$ , f'(x;d) exists and

$$f'(x;d) = \max_{i \in I(x)} \langle \nabla f_i(x), d \rangle,$$

where  $I(x) = \{i : f_i(x) = f(x)\}.$ 

• Example 2 (gradient of  $\frac{1}{2}d_C^2(\cdot)$ ). Let  $\Omega \subseteq \mathbb{R}^n$ , then  $P_{\Omega}$  is the so-called orthogonal projection mapping defined by

$$P_{\Omega}(x) \equiv \underset{y \in \Omega}{\operatorname{arg \, min}} \|y - x\|.$$

It is well known that  $P_{\Omega}$  is well-defined when  $\Omega$  is nonempty closed and convex.

Let  $C\subseteq\mathbb{R}^n$  be nonempty closed and convex. Consider the function  $\varphi_C:\mathbb{R}^n\to\mathbb{R}$  given by

$$\varphi_C(x) \equiv \frac{1}{2} d_C^2(x) = \frac{1}{2} \|x - P_C(x)\|^2.$$

Then for any  $x \in \mathbb{R}^n$ ,

$$\nabla \varphi_C(x) = x - P_C(x).$$

• Theorem (the subdifferential at points of differentiability). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and let  $x \in \operatorname{int}(\operatorname{dom}(f))$ . If f is differentiable at x, then  $\partial f(x) = \{\nabla f(x)\}$ . Conversely, if f has a unique subgradient at x, then it is differentiable at x and  $\partial f(x) = \{\nabla f(x)\}$ .

• Example 3 (subdifferential of the  $l_2$ -norm). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be given by  $f(x) = ||x||_2$ . Then

$$\partial f(x) = \begin{cases} \left\{ \frac{x}{\|x\|_2} \right\}, & x \neq 0, \\ \mathbb{B}_{\|\cdot\|_2}[0, 1], & x = 0. \end{cases}$$

# 4. Computing Subgradients4.1 Multiplication by a Positive Scalar

**Theorem.** Let  $f:\mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and let  $\alpha>0$ . Then for any  $x\in \mathrm{dom}(f)$ 

$$\partial(\alpha f)(x) = \alpha \partial f(x).$$

## 4. Computing Subgradients

### 4.2 Summation

**Theorem.** Let  $f_1, f_2 : \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and let  $x \in \text{dom}(f_1) \cap \text{dom}(f_2)$ .

(a). The following inclusion holds:

$$\partial f_1(x) + \partial f_2(x) \subseteq \partial (f_1 + f_2)(x).$$

(b). If  $x \in \operatorname{int} (\operatorname{dom}(f_1)) \cap \operatorname{int} (\operatorname{dom}(f_1))$ , then

$$\partial (f_1 + f_2)(x) = \partial f_1(x) + \partial f_2(x).$$

**Corollary.** Let  $f_1, f_2, \dots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and let  $x \in \bigcap_{i=1}^m \mathrm{dom}(f_i)$ .

(a). (weak sum rule of subdifferential calculus) The following inclusion holds:

$$\sum_{i=1}^{m} \partial f_i(x) \subseteq \partial \left(\sum_{i=1}^{m} f_i\right)(x).$$

(b). If  $x \in \bigcap_{i=1}^m \operatorname{int}(\operatorname{dom}(f_i))$ , then

$$\partial \left(\sum_{i=1}^{m} f_i\right)(x) = \sum_{i=1}^{m} \partial f_i(x).$$

**Corollary.** Let  $f_1, f_2, \cdots, f_m : \mathbb{R}^n \to \mathbb{R}$  be real-valued convex. Then for any  $x \in \mathbf{R}^n$ 

$$\partial \left(\sum_{i=1}^{m} f_i\right)(x) = \sum_{i=1}^{m} \partial f_i(x).$$

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Theorem (sum rule of subdifferential calculus). Let  $f_1, f_2, \cdots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and assume that  $\bigcap_{i=1}^m \operatorname{ri} (\operatorname{dom}(f_i)) \neq \emptyset$ . Then for any  $x \in \mathbb{R}^n$ 

$$\partial \left(\sum_{i=1}^{m} f_i\right)(x) = \sum_{i=1}^{m} \partial f_i(x).$$

**Example 1 (subdifferential set of the**  $l_1$ -norm function). Consider the function  $f: \mathbb{R}^n \to \mathbb{R}$  given by  $f(x) = \|x\|_1$ .

(a). (strong result). Let

$$I_{\neq}(x) = \{i : x_i \neq 0\}, I_0(x) = \{i : x_i = 0\}.$$

Then

$$\partial f(x) = \left\{ z \in \mathbb{R}^n \, : \, z_i = \mathrm{sgn}(x_i), i \in I_{\neq}(x), |z_j| \le 1, j \in I_0(x) \right\}.$$

(b). (weak result). We have

$$\operatorname{sgn}(x) \in \partial f(x)$$
.

## 4. Computing Subgradients

### 4.3 Affine Transformation

**Theorem.** Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex and  $\mathcal{A}: \mathbb{R}^p \to \mathbb{R}^n$  be a linear transformation. Let  $h(x) = f(\mathcal{A}(x) + b)$  with  $b \in \mathbb{R}^n$ . Assume that h is proper.

(a). (weak affine transformation rule of subdifferential calculus). For any  $x \in \text{dom}(h)$ ,

$$\mathcal{A}^T \left( \partial f \left( \mathcal{A}(x) + b \right) \right) \subseteq \partial h(x).$$

(b). (affine transformation of subdifferential calculus). If  $x \in \operatorname{int}(\operatorname{dom}(h))$  and  $\mathcal{A}(x) + b \in \operatorname{int}(\operatorname{dom}(f))$ , then

$$\partial h(x) = \mathcal{A}^T \left( \partial f \left( \mathcal{A}(x) + b \right) \right).$$

**Example 2 (subdifferential of**  $||Ax + b||_1$ **).** Let  $f : \mathbb{R}^n \to \mathbb{R}$  be the function given by  $f(x) = ||Ax + b||_1$ , where  $A = (a_1, \cdots, a_m)^T \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ . We conclude that

$$\partial f(x) = \sum_{i \in I_{\neq}(x)} \operatorname{sgn}\left(a_i^T x + b_i\right) a_i + \sum_{i \in I_0(x)} \left[-a_1, a_i\right],$$

where

$$I_{\neq}(x) = \left\{ i : a_i^T x + b_i \neq 0 \right\}$$
  
$$I_0(x) = \left\{ i : a_i^T x + b_i = 0 \right\}.$$

**Example 3 (subdifferential of**  $||Ax+b||_2$ **).** Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be the function given by  $f(x) = ||Ax+b||_2$ , where  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ . We conclude that

$$\partial f(x) = \begin{cases} \frac{A^T(Ax+b)}{\|Ax+b\|_2}, & Ax+b \neq 0, \\ A^T \mathbb{B}_{\|\cdot\|_2}[0,1], & Ax+b = 0. \end{cases}$$

# 4. Computing Subgradients4.4 Composition

**Theorem.** Suppose that f is continuous on [a,b] (a < b) and that  $f'_+(a)$  exists. Let g be a function defined on an open interval I which contains the range of f, and assume that g is differentiable at f(a). Then the function

$$h(t) = g(f(t)) \quad (a \le t \le b)$$

is right differentiable at t = a and

$$h'_{+}(a) = g'(f(a)) f'_{+}(a).$$

Theorem (chain rule of subdifferential calculus). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be convex and  $g: \mathbb{R} \to \mathbb{R}$  be nondecreasing convex. Let  $x \in \mathbb{R}^n$ , and suppose that g is differentiable at the point f(x). Let  $h = g \circ f$ . Then

$$\partial h(x) = g'(f(x)) \partial f(x).$$

**Example 4 (subdifferential of**  $\|\cdot\|_1^2$ **).** Consider the function  $h: \mathbb{R}^n \to \mathbb{R}$  given by  $h(x) = \|x\|_1^2$ . Then

$$\partial h(x) = 2 \|x\|_1 \left\{ z \in \mathbb{R}^n \ : \ z_i = \mathrm{sgn}(x_i), i \in I_{\neq}(x), |z+_j| \le 1, j \in I_0(x) \right\},$$
 where  $I_{\neq}(x) = \left\{ i \ : \ x_i \ne 0 \right\}, \ I_0(x) = \left\{ i \ : \ x_i = 0 \right\}.$ 

**Example 5 (subdifferential of**  $d_C(\cdot)$ **).** Let  $C \subseteq \mathbb{R}^n$  be nonempty closed and convex. Then we have

$$\partial d_C(x) = \begin{cases} N_C(x) \cap \mathbb{B}[0,1] & \text{if } x \in C. \\ \left\{ \frac{x - P_C(x)}{d_C(x)} \right\} & \text{otherwise }. \end{cases}$$

# 4. Computing Subgradients4.5 Maximization

Theorem (max rule of subdifferential calculus). Let  $f_1, f_2, \dots, f_m : \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex, and define

$$f(x) = \max \{f_1(x), f_2(x), \dots, f_m(x)\}.$$

Let  $x \in \bigcap_{i=1}^m \operatorname{int} (\operatorname{dom}(f_i))$ . Then

$$\partial f(x) = \operatorname{co}\left(\bigcup_{i \in I(x)} \partial f_i(x)\right),$$

where  $I(x) = \{i = 1, 2, \dots, m : f_i(x) = f(x)\}.$ 

**Example 6 (subdifferential of the max function).** Let  $f: \mathbb{R}^n \to \mathbb{R}$  be given by  $f(x) = \max\{x_1, x_2, \dots, x_n\}$ . Denote

$$I(x) = \{i : f(x) = x_i\}.$$

Then

$$\partial f(x) = \left\{ \sum_{i \in I(x)} \lambda_i e_i : \sum_{i \in I(x)} \lambda_i = 1, \lambda_j \ge 0, j \in I(x). \right\}$$

**Example 7 (subdifferential of the**  $l_{\infty}$ -norm). Let  $f: \mathbb{R}^n \to \mathbb{R}$  be given by  $f(x) = ||x||_{\infty}$ . Denote

$$I(x) = \{i : |x_i| = ||x||_{\infty}\}.$$

Then

$$\partial f(x) = \begin{cases} \mathbb{B}_{\|\cdot\|_1}[0,1], & x = \\ \left\{ \sum_{i \in I(x)} \lambda_i \mathrm{sgn}(x_i) e_i : \sum_{i \in I(x)} \lambda_i = 1, \lambda_j \ge 0, j \in I(x) \right\}, & x \ne 0 \end{cases}$$

Example 8 (subdifferential of piecewise linear functions). Consider the piecewise linear function  $f: \mathbb{R}^n \to \mathbb{R}$  given by

$$f(x) = \max_{i=1,2,\cdots,m} \left\{ a_i^T x + b_i \right\},\,$$

where  $a_i \in \mathbb{R}^n, b_i \in \mathbb{R}, i = 1, 2, \cdots, m$ . Then

$$\partial f(x) = \left\{ \sum_{i \in I(x)} \lambda_i a_i : \sum_{i \in I(x)} \lambda_i = 1, \lambda_j \ge 0, j \in I(x) \right\},\,$$

where  $I(x) = \{i : f(x) = a_i^T x + b_i\}.$ 

Theorem (weak maximum rule of subdifferential calculus). Let I be an arbitrary set, and suppose that any  $i \in I$  is associated with a proper convex function  $f_i : \mathbb{R}^n \to \overline{\mathbb{R}}$ . Let

$$f(x) = \max_{i \in I} f_i(x).$$

Then for any  $x \in dom(f)$ 

$$\operatorname{\mathsf{co}}\left(igcup_{i\in I(x)}\partial f_i(x)
ight)\subseteq\partial f(x),$$

where  $I(x) = \{i \in I : f(x) = f_i(x)\}.$ 

#### 5. The Value Function

Consider the minimization problem

$$\min_{x \in X} \left\{ f(x) : g(x) \le 0, Ax + b = 0 \right\},\tag{1}$$

where  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$ ,  $g = (g_1, g_2, \cdots, g_m)^T : \mathbb{R}^n \to \overline{\mathbb{R}}^m$ ,  $\varnothing \neq X \subseteq \mathbb{R}^n$ ,  $A \in \mathbb{R}^{p \times n}$ , and  $b \in \mathbb{R}^p$ .

The value function associated with Problem (1) is the function  $v: \mathbb{R}^m \times \mathbb{R}^p \to [-\infty, \infty]$  given by

$$v(u,t) = \min_{x \in X} \{ f(x) : g(x) \le u, Ax + b = t \}.$$
 (2)

The feasible set of the minimization problem in (2) will be denoted by

$$C(u,t) = \{x \in X : g(x) \le u, Ax + b = t\}.$$

The value function can be rewritten as  $v(u,t)=\min\{f(x):x\in C(u,t))\}$ . By convention  $v(u,t)=\infty$  if  $C(u,t)=\varnothing$ .

**Lemma.** Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$ ,  $g: \mathbb{R}^n \to \overline{\mathbb{R}}^m$ ,  $\varnothing \neq X \subseteq \mathbb{R}^n$ ,  $A \in \mathbb{R}^{p \times n}$ , and  $b \in \mathbb{R}^p$ . Let v be the value function of Problem (1).

(a). (monotonicity of the value function). Then

 $v(u,t) \geq v(w,t)$  for any  $u,w \in \mathbb{R}^m, t \in \mathbb{R}^p$  satisfying  $u \leq w.$ 

(b). (convexity of the value function). Moreover, let  $f, g_1, g_2, \cdots, g_m$  be convex functions and X be convex set. Suppose that the value function v is proper. Then v is convex over  $\mathbb{R}^m \times \mathbb{R}^p$ .

#### 6. Lipschitz Continuity and Boundedness of Subgradients

Theorem (Lipschitz continuity and boundedness of the subdifferential sets). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and convex. Suppose that  $X \subseteq \operatorname{int}(\operatorname{dom}(f))$ . Consider the following two claims:

- (i).  $|f(x) f(y)| \le L ||x y||$  for any  $x, y \in X$ .
- (ii).  $\|g\|_* \le L$  for any  $g \in \partial f(x)$ ,  $x \in X$ .

Then

- (a). the implication  $(i) \Rightarrow (ii)$  holds;
- (b). if X is open, then (i) holds if and only if (ii) holds.

## Corollary (Lipschitz continuity of convex functions over compact domains).

Let  $f:\mathbb{R}^n\to\overline{\mathbb{R}}$  be proper and convex. Suppose that  $X\subseteq \mathrm{int}\,(\mathrm{dom}(f))$  is compact. Then there exists L>0 for which

$$|f(x) - f(y)| \le L ||x - y||$$
 for any  $x, y \in X$ .

# 7. Optimality Conditions7.1 Fermat's Optimality Condition

Theorem (Fermat's optimality condition). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex. Then

$$x^* \in \arg\min \{ f(x) : x \in \mathbb{R}^n \}$$

if and only if  $0 \in \partial f(x^*)$ .

**Example 1 (minimizing piecewise linear functions).** Consider the problem

$$\min_{x \in \mathbb{R}^n} \left[ f(x) \equiv \max_{i=1,2,\cdots,m} \left\{ a_i^T x + b_i \right\} \right],$$

where  $a_i \in \mathbb{R}^n$ ,  $b_i \in \mathbb{R}$ ,  $i = 1, 2, \dots, m$ . Denote

$$I(x) = \{i : f(x) = a_i^T x + b_i\}.$$

Then  $x^*$  is an optimal solution if and only if

$$\exists \lambda \in \Delta_m \text{ s.t. } A^T \lambda = 0 \text{ and } \lambda_j \left( a_j^T x^* + b_j - f(x^*) \right), j = 1, 2, \cdots, m.$$

# 7. Optimality Conditions 7.2 Convex Constrained Optimization

## Theorem (necessary and sufficient optimality conditions for convex constrained optimization).

Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and convex, and let  $C \subseteq \mathbb{R}^n$  be convex for which  $\operatorname{ri} (\operatorname{dom}(f)) \cap \operatorname{ri} (C) \neq \emptyset$ . Then  $x^* \in C$  is an optimal solution of

$$\min \left\{ f(x) \, : \, x \in C \right\}$$

if and only if

there exists  $g \in \partial f(x^*)$  for which  $-g \in N_C(x^*)$ .

### Corollary (necessary and sufficient optimality conditions for convex constrained optimization-second version).

Let  $f:\mathbb{R}^n \to \overline{\mathbb{R}}$  be proper and convex, and let  $C\subseteq \mathbb{R}^n$  be convex for which  $\operatorname{ri}\left(\operatorname{dom}(f)\right)\cap\operatorname{ri}\left(C\right) \neq \varnothing$ . Then  $x^*\in C$  is an optimal solution of

$$\min \left\{ f(x) \, : \, x \in C \right\}$$

if and only if

there exists  $g \in \partial f(x^*)$  for which  $\langle g, x - x^* \rangle \geq 0$  for any  $x \in C$ .

### 7. Optimality Conditions

### 7.3 The Nonconvex Composite Model

Theorem (optimality conditions for the composite problem). Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper, and let  $g: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex such that  $dom(g) \subseteq int(dom(f))$ . Consider the problem

$$(P) \quad \min_{x \in \mathbb{R}^n} f(x) + g(x).$$

(a). (necessary condition). If  $x^* \in \text{dom}(g)$  is a local optimal solution of (P) and f is differentiable at  $x^*$ , then

$$-\nabla f(x^*) \in \partial g(x^*).$$

(b). (necessary and sufficient condition for convex problem). Suppose that f is convex. If f is differentiable at  $x^* \in \text{dom}(g)$ , then  $x^*$  is a global optimal solution of (P) if and only if

$$-\nabla f(x^*) \in \partial g(x^*).$$

**Definition (stationary).** Let Let  $f: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper, and let  $g: \mathbb{R}^n \to \overline{\mathbb{R}}$  be proper convex such that  $\operatorname{dom}(g) \subseteq \operatorname{int}(\operatorname{dom}(f))$ . Consider the problem

$$(P) \quad \min_{x \in \mathbb{R}^n} f(x) + g(x).$$

A point  $x^*$  in which f is differentiable is called a stationary point of (P) if

$$-\nabla f(x^*) \in \partial g(x^*).$$

Example 2 (convex constrained nonconvex programming). When  $g = \delta_C$  for a nonempty convex set  $C \subseteq \mathbb{R}^n$ , Problem (P) becomes

$$\min \left\{ f(x) : x \in C \right\}.$$

A point  $x^{\ast} \in C$  in which f is differentiable is a stationary point if and only if

$$\langle \nabla f(x^*), x - x^* \rangle \ge 0$$
 for any  $x \in C$ .

#### **Example 3.** Consider the problem

$$\min_{x \in \mathbb{R}^n} f(x) + \lambda \|x\|_1,$$

where  $\lambda \geq 0$ . A point  $x^* \in \operatorname{int} (\operatorname{dom}(f))$  in which f is differentiable is a stationary point if and only if

$$\frac{\partial f(x^*)}{\partial x_i} \begin{cases} = -\lambda, & x_i^* > 0, \\ = \lambda, & x_i^* < 0, \\ \in [-\lambda, \lambda], & x_i^* = 0. \end{cases}$$

## 7. Optimality Conditions 7.4 The KKT Conditions

**Lemma.** Let  $f,g_1,g_2,\cdots,g_m:\mathbb{R}^n\to\mathbb{R}$  be real-valued. Consider the problem

$$\begin{aligned} & \min \quad f(x) \\ & \text{s.t.} \quad g_i(x) \leq 0, \quad i = 1, 2, \cdots, m. \end{aligned}$$

Assume that the minimum value of the above problem is finite and equal to  $\bar{f}$ . Define the function

$$F(x) \equiv \max \left\{ f(x) - \bar{f}, g_1(x), g_2(x), \cdots, g_m(x) \right\}.$$

Then the optimal set of the above inequalities constrained problem is the same as the set of minimizers of F.

**Theorem (Fritz-John necessary optimality conditions).** Consider the minimization problem

min 
$$f(x)$$
  
s.t.  $g_i(x) \le 0$ ,  $i = 1, 2, \dots, m$ .

where  $f, g_1, g_2, \dots, g_m : \mathbb{R}^n \to \mathbb{R}$  be real-valued convex. Let  $x^*$  be an optimal solution. Then there exist  $\lambda_0, \lambda_1, \dots, \lambda_m \geq 0$ , not all zeros, for which

$$0 \in \lambda_0 \partial f(x^*) + \sum_{i=1}^m \lambda_i \partial g_i(x^*)$$
$$\lambda_i g_i(x^*) = 0, \quad i = 1, 2, \dots, m.$$

Theorem (KKT conditions). Consider the minimization problem

$$\begin{aligned} & \min \quad f(x) \\ & \text{s.t.} \quad g_i(x) \leq 0, \quad i = 1, 2, \cdots, m. \end{aligned}$$

where  $f, g_1, g_2, \cdots, g_m : \mathbb{R}^n \to \mathbb{R}$  be real-valued convex.

(a). Let  $x^*$  be an optimal solution, and assume that Slater's condition

there exists  $\bar{x} \in \mathbb{R}^n$  for which  $g_i(\bar{x}) < 0, \quad i = 1, 2, \cdots, m$ .

is satisfied. Then there exist  $\lambda_1, \dots, \lambda_m \geq 0$  for which

$$0 \in \partial f(x^*) + \sum_{i=1}^{m} \lambda_i \partial g_i(x^*)$$
$$\lambda_i q_i(x^*) = 0, \quad i = 1, 2, \dots, m.$$

(b). If  $x^*$  satisfies both above conditions for some  $\lambda_1, \dots, \lambda_m \geq 0$ , then it is an optimal solution.

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