

18CSE365J ARTIFICIAL INTELLIGENCE

SEMESTER VI



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(Under SECTION 3 of the UGC Act, 1956)

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KANCHEEPURAM DISTRICT



FACULTY OF ENGINEERING AND TECHNOLOGY

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Certified to be the bonafide record of work done by AYSHWARYA S of

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Date: _____

Examiner - 1

Examiner - 2

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AIM:-

To implement toy problem using python.

Algorithm:-

Step 1: Now our board looks like 000 000 000 (tenary number) convert it into decimal no. The decimal no is 0

Step 2: Use the computed number ie 0 as an index into the move table and access the vector stored in

Step 3: New Board Position.

Step 4: The new board position is 000 010 000

Step 5: The vector selected in step 2(000 010 000) represents the way the board will look after the move that should be made. So set board equal to that vector.

Code:-

```
import random
def select_letter():
    let=""
    auto_let=""
    while(let != "x" and let != "o"):
        let=input("Select X or O: ").replace(" ", "").strip().lower()
        if let == "x":
            auto_let="o"
        else:
            auto_let="x"
    return let, auto_let
def clean_board():
    brd=[" " for x in range(10)]
    return brd

def is_board_full(board):
    return board.count(" ")==0

def insert_letter(board,letter,pos):
    board[pos]=letter

def computer_move(board,letter):
    computer_letter=letter
    possible_moves=[]
    available_corners=[]
    available_edges=[]
    available_center=[]
    position=-1

    for i in range(1,len(board)):
```

```

        if board[i] == " ":
            possible_moves.append(i)
    for let in ["x", "o"]:
        for i in possible_moves:
            board_copy = board[:]
            board_copy[i] = let
            if is_winner(board_copy, let):
                position = i

    if position == -1:
        for i in range(len(board)):
            if board[i] == " ":
                if i in [1, 3, 7, 9]:
                    available_corners.append(i)
                if i is 5:
                    available_center.append(i)
                if i in [2, 4, 6, 8]:
                    available_edges.append(i)
        if len(available_corners) > 0:
            print("it comes here")
            position = random.choice(available_corners)
        elif len(available_center) > 0:
            position = available_center[0]
        elif len(available_edges) > 0:
            position = random.choice(available_edges)
    board[position] = computer_letter

def draw_board(board):
    board[0] = -1
    print(" | | ")
    print(" "+board[1]+" | "+board[2]+" | "+board[3]+" ")
    print(" | | ")
    print("-"*11)
    print(" | | ")
    print(" "+board[4]+" | "+board[5]+" | "+board[6]+" ")
    print(" | | ")
    print("-"*11)
    print(" | | ")
    print(" "+board[7]+" | "+board[8]+" | "+board[9]+" ")
    print(" | | ")
    print("-"*11)
    return board

def is_winner(board, letter):
    return (board[1] == letter and board[2] == letter and board[3] == letter) or \
        (board[4] == letter and board[5] == letter and board[6] == letter) or \
        (board[7] == letter and board[8] == letter and board[9] == letter) or \
        (board[1] == letter and board[4] == letter and board[7] == letter) or \
        (board[2] == letter and board[5] == letter and board[8] == letter) or \
        (board[3] == letter and board[6] == letter and board[9] == letter) or \

```

```
(board[1] == letter and board[5] == letter and board[9] == letter) or \
(board[3] == letter and board[5] == letter and board[7] == letter)
```

```
def repeat_game():
```

```
    repeat=input("Play again? Press y for yes and n for no: ")
    while repeat != "n" and repeat != "y":
        repeat=input("PLEASE, press y for yes and n for no: ")
    return repeat
```

```
def play_game():
```

```
    letter, auto_letter= select_letter()
    board=clean_board()
    board=draw_board(board)
    while is_board_full(board) == False:
        try:
            position=int(input("Select a position (1-9) to place an "+letter+" : " ))

        except:
            position=int(input("PLEASE enter position using only NUMBERS from 1-9: "))

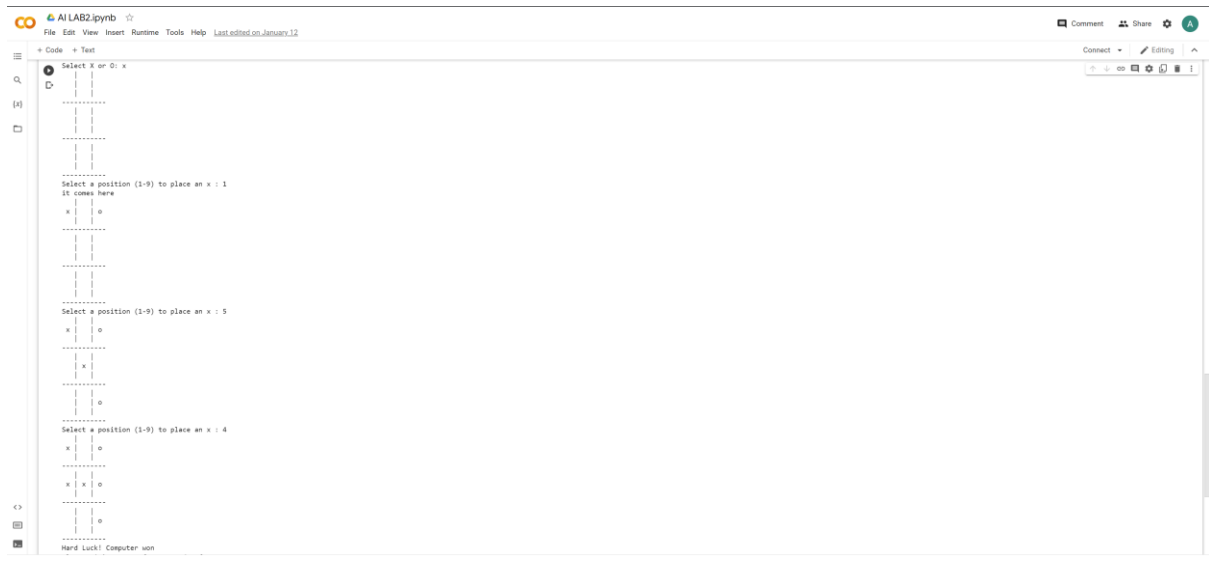
        if position not in range(1,10):
            position=int(input("Please, choose another position to place an "+letter+" from 1 to 9 :"))

        if board[position] != " ":
            position=int(input("Please, choose an empty position to place an "+letter+" from 1 to 9: "))

        insert_letter(board,letter,position)
        computer_move(board,auto_letter)
        board=draw_board(board)

        if is_winner(board,letter):
            print("Congratulations! You Won.")
            return repeat_game()
        elif is_winner(board,auto_letter):
            print("Hard Luck! Computer won")
            return repeat_game()
        if is_board_full(board):
            print("Tie Game :)")
            return repeat_game()
    print("Welcome to Tic Tac Toe.")
    repeat="y"
    while(repeat=="y"):
        repeat=play_game()
```

Output:-



```
AI LAB2.ipynb
File Edit View Insert Runtime Tools Help Last edited on January 12
Code Text
Select x or o: x
| | |
| | |
| | |
-----
| | |
| | |
| | |
-----
Select a position (1-9) to place an x : 1
it comes here
x | | o
| | |
| | |
-----
| | |
| | |
| | |
-----
Select a position (1-9) to place an x : 5
x | | o
| | |
| x |
| | |
| | |
| | o
| | |
-----
Select a position (1-9) to place an x : 4
x | | o
| | |
| x | o
| | |
| | o
| | |
-----
Hard Luck! Computer won
```

Results:-

We have successfully implemented the toy problem.

AIM:-

To implement 8-puzzle problem using python.

Algorithm:-

Step 1: Randomly move or alter the state

Step 2: Assess the energy of the new state using an objective function

Step 3: Compare the energy to the previous state and decide whether to accept the new solution or reject it based on the current temperature.

Step 4: Repeat until you have converged on an acceptable answer

Code:-

```
import copy
from heapq import heappush, heappop
n = 3
row = [ 1, 0, -1, 0 ]
col = [ 0, -1, 0, 1 ]
class priorityQueue:
    def __init__(self):
        self.heap = []
    def push(self, k):
        heappush(self.heap, k)
    def pop(self):
        return heappop(self.heap)
    def empty(self):
        if not self.heap:
            return True
        else:
            return False
class node:

    def __init__(self, parent, mat, empty_tile_pos,
        cost, level):
        self.parent = parent
        self.mat = mat
        self.empty_tile_pos = empty_tile_pos
        self.cost = cost
        self.level = level
    def __lt__(self, nxt):
        return self.cost < nxt.cost
def calculateCost(mat, final) -> int:

    count = 0
    for i in range(n):
```



```

        for j in range(n):
            if ((mat[i][j]) and
                (mat[i][j] != final[i][j])):
                count += 1

    return count

def newNode(mat, empty_tile_pos, new_empty_tile_pos,
            level, parent, final) -> node:
    new_mat = copy.deepcopy(mat)
    x1 = empty_tile_pos[0]
    y1 = empty_tile_pos[1]
    x2 = new_empty_tile_pos[0]
    y2 = new_empty_tile_pos[1]
    new_mat[x1][y1], new_mat[x2][y2] = new_mat[x2][y2], new_mat[x1][y1]
    cost = calculateCost(new_mat, final)

    new_node = node(parent, new_mat, new_empty_tile_pos,
                    cost, level)
    return new_node
def printMatrix(mat):

    for i in range(n):
        for j in range(n):
            print("%d " % (mat[i][j]), end = " ")

        print()
def isSafe(x, y):

    return x >= 0 and x < n and y >= 0 and y < n
def printPath(root):

    if root == None:
        return

    printPath(root.parent)
    printMatrix(root.mat)
    print()
def solve(initial, empty_tile_pos, final):
    pq = priorityQueue()
    cost = calculateCost(initial, final)
    root = node(None, initial, empty_tile_pos, cost, 0)
    pq.push(root)
    while not pq.empty():
        minimum = pq.pop()
        if minimum.cost == 0:
            printPath(minimum)
        return

```

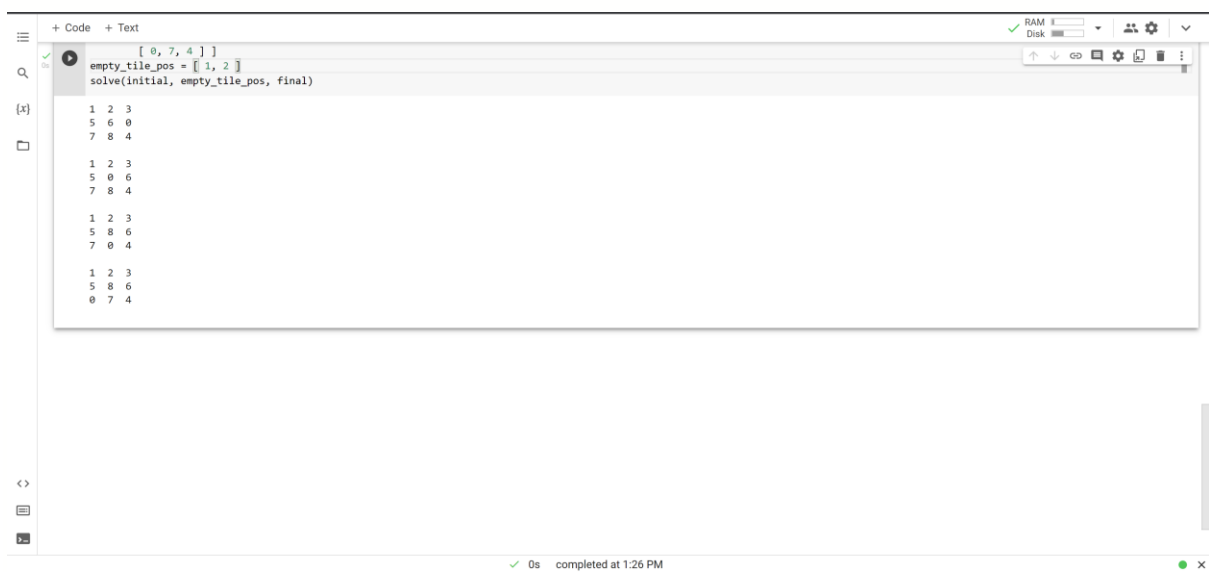
```

for i in range(n):
    new_tile_pos = [
        minimum.empty_tile_pos[0] + row[i],
        minimum.empty_tile_pos[1] + col[i], ]

    if isSafe(new_tile_pos[0], new_tile_pos[1]):
        child = newNode(minimum.mat,
                        minimum.empty_tile_pos,
                        new_tile_pos,
                        minimum.level + 1,
                        minimum, final,)
        pq.push(child)
initial = [ [ 1, 2, 3 ],
            [ 5, 6, 0 ],
            [ 7, 8, 4 ] ]
final = [ [ 1, 2, 3 ],
          [ 5, 8, 6 ],
          [ 0, 7, 4 ] ]
empty_tile_pos = [ 1, 2 ]
solve(initial, empty_tile_pos, final)

```

OUTPUT:-



```

+ Code + Text
[ 0, 7, 4 ]
empty_tile_pos = [ 1, 2 ]
solve(initial, empty_tile_pos, final)

{
  1 2 3
  5 6 0
  7 8 4

  1 2 3
  5 0 6
  7 8 4

  1 2 3
  5 8 6
  7 0 4

  1 2 3
  5 8 6
  0 7 4
}

0s completed at 1:26 PM

```

RESULT:-

We have successfully implemented the 8-puzzle problem.

AIM:-

To implement developing agent programs for real world problems using python.

Algorithm:-

Step 1: Enter LOCATION A/B in capital letters where A and B are the two adjacent rooms respectively.

Step 2: Enter Status 0/1 accordingly where 0 means CLEAN and 1 means DIRTY.

Step 3: Vacuum Cleaner senses the status of the other room before performing any action, also known as Environment sensing.

Code:-

```
def vacuum_world():
    goal_state = {'A': '0', 'B': '0'}
    cost = 0

    location_input = input("Enter Location of Vacuum:")
    status_input = input("Enter status of " + location_input+":")
    status_input_complement = input("Enter status of other room:")
    print("Initial Location Condition:" + str(goal_state))

    if location_input == 'A':

        print("Vacuum is placed in Location A")
        if status_input == '1':
            print("Location A is Dirty.")

            goal_state['A'] = '0'
            cost += 1
            print("Cost for CLEANING A " + str(cost))
            print("Location A has been Cleaned.")

        if status_input_complement == '1':

            print("Location B is Dirty.")
            print("Moving right to the Location B. ")
            cost += 1
            print("COST for moving RIGHT" + str(cost))

            goal_state['B'] = '0'
            cost += 1
            print("COST for SUCK " + str(cost))
            print("Location B has been Cleaned. ")
        else:
            print("No action" + str(cost))
```

```

    print("Location B is already clean.")

if status_input == '0':
    print("Location A is already clean ")
    if status_input_complement == '1':
        print("Location B is Dirty.")
        print("Moving RIGHT to the Location B. ")
        cost += 1
        print("COST for moving RIGHT " + str(cost))

        goal_state['B'] = '0'
        cost += 1
        print("Cost for SUCK " + str(cost))
        print("Location B has been Cleaned. ")
    else:
        print("No action " + str(cost))
        print(cost)

    print("Location B is already clean.")

else:
    print("Vacuum is placed in location B")
    if status_input == '1':
        print("Location B is Dirty.")
        goal_state['B'] = '0'
        cost += 1
        print("COST for CLEANING " + str(cost))
        print("Location B has been Cleaned.")

    if status_input_complement == '1':

        print("Location A is Dirty.")
        print("Moving LEFT to the Location A. ")
        cost += 1
        print("COST for moving LEFT" + str(cost))

        goal_state['A'] = '0'
        cost += 1
        print("COST for SUCK " + str(cost))
        print("Location A has been Cleaned.")

    else:
        print(cost)
        print("Location B is already clean.")

    if status_input_complement == '1':
        print("Location A is Dirty.")

```

```

    print("Moving LEFT to the Location A. ")
    cost += 1
    print("COST for moving LEFT " + str(cost))
    goal_state['A'] = '0'
    cost += 1
    print("Cost for SUCK " + str(cost))
    print("Location A has been Cleaned. ")
else:
    print("No action " + str(cost))
    print("Location A is already clean.")
print("GOAL STATE: ")
print(goal_state)
print("Performance Measurement: " + str(cost))

```

vacuum_world()

Output:-

```

vacuum_cleaner.ipynb
File Edit View Insert Runtime Tools Help Last edited on January 31
+ Code + Text
print(goal_state)
print("Performance Measurement: " + str(cost))
vacuum_world()
Enter Location of Vacuum:A
Enter status of A:0
Enter status of other room:1
Initial Location Condition: {'A': '0', 'B': '0'}
Vacuum is placed in Location A
Location A is already clean
Location B is Dirty.
Moving RIGHT to the Location B.
COST for moving RIGHT 1
Cost for SUCK2
Location B has been Cleaned.
GOAL STATE:
{'A': '0', 'B': '0'}
Performance Measurement: 2

```

Results:-

We have successfully implemented vacuum cleaner problem.

AIM:-

To implement analysis of bfs for an application using python.

Algorithm:-

Step 1: SET STATUS = 1 (ready state) for each node in G

Step 2: Enqueue the starting node A and set its STATUS = 2 (waiting state)

Step 3: Repeat Steps 4 and 5 until QUEUE is empty

Step 4: Dequeue a node N. Process it and set its STATUS = 3 (processed state).

Step 5: Enqueue all the neighbours of N that are in the ready state (whose STATUS = 1) and set their STATUS = 2 (waiting state) [END OF LOOP]

Step 6: EXIT

Code:-

```
import time as t
```

```
puzzle=[]  
solved=[1, 2, 3, 4, 5, 6, 7, 8, 0]  
def zeroindex(puzzle):  
    for i in range(9):  
        if puzzle[i] == 0:  
            return i  
        break
```

```
def check(puzzle):  
    count=0  
    for i in range(9):  
        for j in range(i+1, 9):  
            if j==9:  
                break  
            if puzzle[i]>puzzle[j] and puzzle[i]!=0 and puzzle[j]!=0:  
                count+=1  
    if (not count%2):  
        return True  
    else:  
        return False
```

```
def heuristic(puzzle):    #finds the heursitic value  
    man_dist=sum(abs((val-1)%3 - i%3) + abs((val-1)//3 - i//3) for i, val in enumerate(puzzle) if val)  
    return man_dist
```

```
def min_heuristics(lists):    #finds the minimum heuristic among a list of heurisitc values and returns i  
    t's position  
    min=999999  
    for i in range(len(lists)):
```

```

    if lists[i]<min:
        min=lists[i]
        index=i
    return(index)

```

```

def machineplay(puzzle):
    openlist=[]
    openLIST=[]
    closedlist=[]
    heuristicval=[]
    openlist.append(puzzle)
    x=[]
    x=openlist.pop(0)
    a=x[9]                                #stores the index of 0
    while x[:9]!=solved:
        if a%3!=0:                        #left
            statespace1=x.copy()
            temp=statespace1[a]
            statespace1[a]=statespace1[a-1]
            statespace1[a-1]=temp
            statespace1[9]=a-1
            statespace1.append("LEFT")

            if statespace1[:9] == solved:
                print("SOLVED!")
                print("The steps to solve are:- \n")
                print(", ".join(statespace1[10:]))
                break
            else:
                if statespace1[:9] not in closedlist and statespace1[:9] not in openLIST:
                    openlist.append(statespace1) #for printing the steps
                    openLIST.append(statespace1[:9]) #to prevent loops
                    heuristicval.append(heuristic(statespace1[:9]))

        if a%3!=2:                        #right
            statespace2=x.copy()
            temp=statespace2[a]
            statespace2[a]=statespace2[a+1]
            statespace2[a+1]=temp
            statespace2[9]=a+1
            statespace2.append("RIGHT")

            if statespace2[:9] == solved:
                print("SOLVED!")
                print("The steps to solve are:- \n")
                print(", ".join(statespace2[10:]))
                break
            else:
                if statespace2[:9] not in closedlist and statespace2[:9] not in openLIST:
                    openlist.append(statespace2)

```

```

        openLIST.append(statespace2[:9])
        heuristicval.append(heuristic(statespace2[:9]))

    if a!=0 and a!=1 and a!=2:                                #up
        statespace3=x.copy()
        temp=statespace3[a]
        statespace3[a]=statespace3[a-3]
        statespace3[a-3]=temp
        statespace3[9]=a-3
        statespace3.append("UP")

    if statespace3[:9] == solved:
        print("SOLVED!")
        print("The steps to solve are:- \n")
        print(" ", ".join(statespace3[10:]))
        break
    else:
        if statespace3[:9] not in closedlist and statespace3[:9] not in openLIST:
            openlist.append(statespace3)
            openLIST.append(statespace3[:9])
            heuristicval.append(heuristic(statespace3[:9]))

    if a!=6 and a!=7 and a!=8:                                #down
        statespace4=x.copy()
        temp=statespace4[a]
        statespace4[a]=statespace4[a+3]
        statespace4[a+3]=temp
        statespace4[9]=a+3
        statespace4.append("DOWN")
        if statespace4[:9] == solved:
            print("\nSOLVED!")
            print("\nThe steps to solve are:- ")
            print(" ", ".join(statespace4[10:]))
            break
        else:
            if statespace4[:9] not in closedlist and statespace4[:9] not in openLIST:
                openlist.append(statespace4)
                openLIST.append(statespace4[:9])
                heuristicval.append(heuristic(statespace4[:9]))
        closedlist.append(x[:9])
        y=min_heuristics(heuristicval)
        tem=heuristicval.pop(y)
        x=openlist.pop(y)
        a=x[9]

    # print("SOLVED!")
    # print("CLOSED LIST:", len(closedlist), "nodes")

def show_board(puzzle):
    print("""\n+---+---+---+
| {} | {} | {} |

```



```

+---+---+---+
| {} | {} | {} |
+---+---+---+
| {} | {} | {} |
+---+---+---+
+"".format(puzzle[0], puzzle[1], puzzle[2], puzzle[3], puzzle[4], puzzle[5], puzzle[6], puzzle[7], puzzle[8]))

```

```

def enterBoard(puzzle):
    hmm = "n"
    while(hmm=="n"):
        print("\nEnter the board values with spaces: ")
        puzzle = list(map(int, input().split()))
        print("\nIs the following board correct?")
        show_board(puzzle)
        print("\n")
        hmm = input("[Y/N]: ").lower()
    return puzzle

```

```

puzzle = enterBoard(puzzle)
k=zeroindex(puzzle)
if check(puzzle):
    puzzle.append(k)
    # start_time=t.time()
    machineplay(puzzle)

```

Output:-

```

puzzle = enterBoard(puzzle)
k=zeroindex(puzzle)
if check(puzzle):
    puzzle.append(k)
    machineplay(puzzle)

```

Enter the board values with spaces:
1 0 3 4 2 5 7 8 6

Is the following board correct?

```

+---+---+---+
| 1 | 0 | 3 |
+---+---+---+
| 4 | 2 | 5 |
+---+---+---+
| 7 | 8 | 6 |
+---+---+---+

```

[Y/N]: Y

SOLVED!

The steps to solve are:-
DOWN, RIGHT, DOWN

Results:-

We have successfully implemented BFS.

Date:
Expt.No: 05

IMPLEMENTATION AND ANALYSIS OF DFS FOR AN APPLICATION

AIM:-

To implement analysis of dfs for an application using python.

Algorithm:-

Step 1: SET STATUS = 1 (ready state) for each node in G

Step 2: Push the starting node A on the stack and set its STATUS = 2 (waiting state)

Step 3: Repeat Steps 4 and 5 until STACK is empty

Step 4: Pop the top node N. Process it and set its STATUS = 3 (processed state)

Step 5: Push on the stack all the neighbours of N that are in the ready state (whose STATUS= 1) and set their STATUS=2(waitingstate) [END OF LOOP]

Step 6: EXIT

Code:-

```
from collections import defaultdict

class Graph:

    def __init__(self):

        self.graph = defaultdict(list)

    def addEdge(self, u, v):

        self.graph[u].append(v)

    def DFSUtil(self, v, visited):

        visited.add(v)

        print(v, end=' ')

        for neighbour in self.graph[v]:

            if neighbour not in visited:

                self.DFSUtil(neighbour, visited)

    def DFS(self, v):

        visited = set()

        self.DFSUtil(v, visited)

g = Graph()

g.addEdge(0, 1)

g.addEdge(0, 2)

g.addEdge(1, 2)

g.addEdge(2, 0)

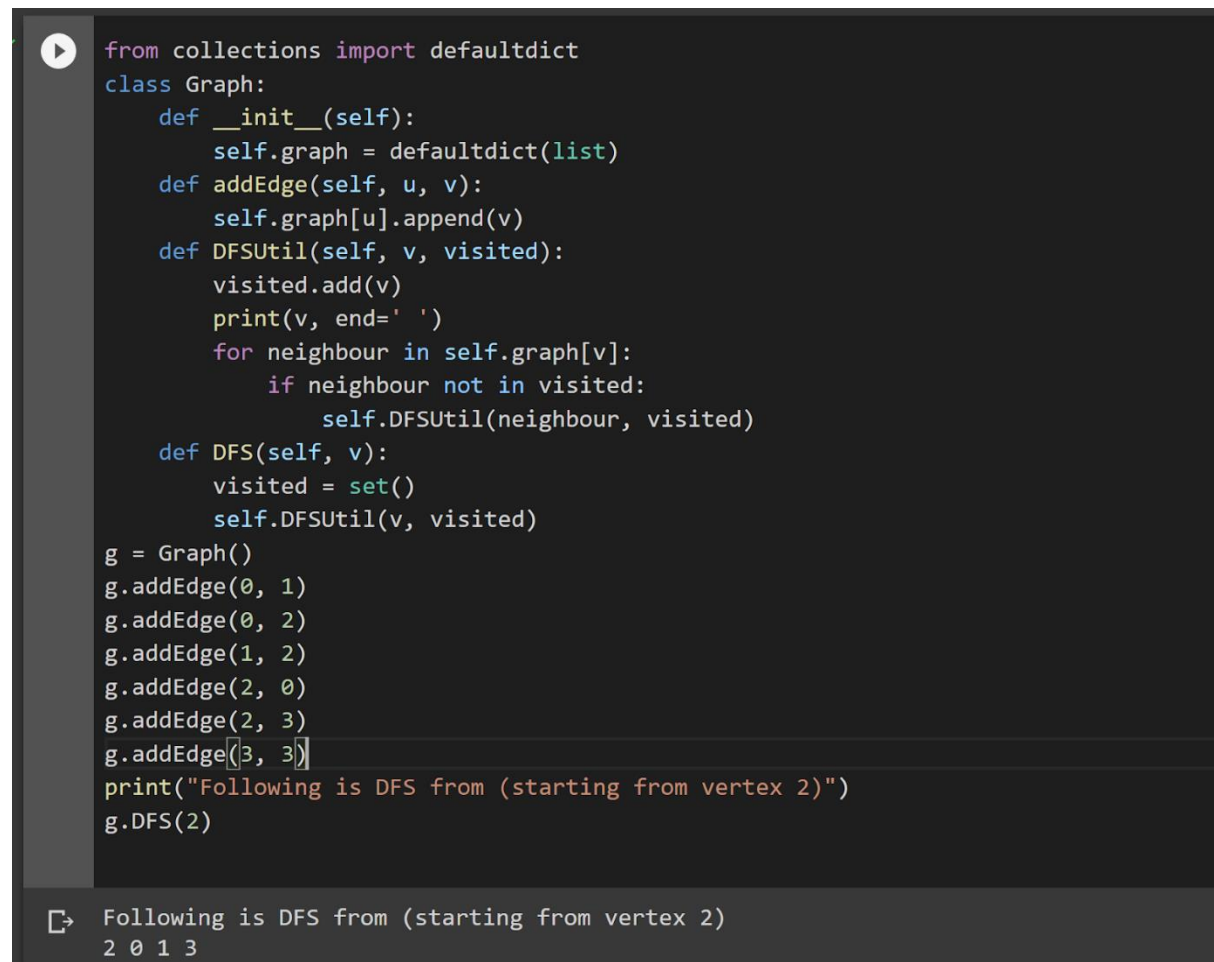
g.addEdge(2, 3)
```

```
g.addEdge(3, 3)

print("Following is DFS from (starting from vertex 2)")

g.DFS(2)
```

Output:-



```
from collections import defaultdict
class Graph:
    def __init__(self):
        self.graph = defaultdict(list)
    def addEdge(self, u, v):
        self.graph[u].append(v)
    def DFSUtil(self, v, visited):
        visited.add(v)
        print(v, end=' ')
        for neighbour in self.graph[v]:
            if neighbour not in visited:
                self.DFSUtil(neighbour, visited)
    def DFS(self, v):
        visited = set()
        self.DFSUtil(v, visited)

g = Graph()
g.addEdge(0, 1)
g.addEdge(0, 2)
g.addEdge(1, 2)
g.addEdge(2, 0)
g.addEdge(2, 3)
g.addEdge(3, 3)
print("Following is DFS from (starting from vertex 2)")
g.DFS(2)
```

Following is DFS from (starting from vertex 2)
2 0 1 3

Results:-

We have successfully implemented DFS.

AIM:-

To implement analysis of A* Algorithm for an application using python.

Algorithm:-

Step 1. Initialize the open list

Step 2. Initialize the closed list put the starting node on the open list (you can leave its f at zero)

Step 3. while the open list is not empty

- a) find the node with the least f on the open list, call it "q"
- b) pop q off the open list
- c) generate q's 8 successors and set their parents to q
- d) push q on the closed list end (while loop)
- e) stop

Code:-

A*ALGORITHM

```
import math
from simpleai.search import SearchProblem, astar
class MazeSolver(SearchProblem):
    def __init__(self, board):
        self.board = board
        self.goal = (0, 0)

        for y in range(len(self.board)):
            for x in range(len(self.board[y])):
                if self.board[y][x].lower() == "o":
                    self.initial = (x, y)
                elif self.board[y][x].lower() == "x":
                    self.goal = (x, y)

        super(MazeSolver, self).__init__(initial_state=self.initial)
    def actions(self, state):
        actions = []
        for action in COSTS.keys():
            newx, newy = self.result(state, action)
            if self.board[newy][newx] != "#":
                actions.append(action)

        return actions

    def result(self, state, action):
        x, y = state

        if action.count("up"):
            y -= 1
```

```

        if action.count("down"):
            y += 1
        if action.count("left"):
            x -= 1
        if action.count("right"):
            x += 1

    new_state = (x, y)

    return new_state

def is_goal(self, state):
    return state == self.goal

def cost(self, state, action, state2):
    return COSTS[action]

def heuristic(self, state):
    x, y = state
    gx, gy = self.goal

    return math.sqrt((x - gx) ** 2 + (y - gy) ** 2)

if __name__ == "__main__":

    MAP = """
#####
#      #      # #
# #### #####  # #
# o # #      # #
# ### ##### ##### #
#  # ### #      #
#  # # # # # ####
# ##### # # # x #
#      #  #  #
#####
"""

    print(MAP)
    MAP = [list(x) for x in MAP.split("\n") if x]

    cost_regular = 1.0
    cost_diagonal = 1.7

    COSTS = {
        "up": cost_regular,
        "down": cost_regular,
        "left": cost_regular,
        "right": cost_regular,
        "up left": cost_diagonal,
        "up right": cost_diagonal,
    }

```

```

        "down left": cost_diagonal,
        "down right": cost_diagonal,
    }
    problem = MazeSolver(MAP)
    result = astar(problem, graph_search=True)
    path = [x[1] for x in result.path()]
    print()
    for y in range(len(MAP)):
        for x in range(len(MAP[y])):
            if (x, y) == problem.initial:
                print('o', end=" ")
            elif (x, y) == problem.goal:
                print('x', end=" ")
            elif (x, y) in path:
                print('.', end=" ")
            else:
                print(MAP[y][x], end=" ")
        print()

```

OUTPUT:-

The screenshot shows a Jupyter Notebook with a code cell and an output cell. The code cell contains a loop that prints the maze state for each row. The output cell shows two maze visualizations. The first visualization shows the initial state with 'o' at (1,1) and 'x' at (4,4). The second visualization shows the path from 'o' to 'x' marked with dots, with the final path being o -> x.

Result:-

We have successfully implemented the experiments.

AIM:-

To implement of constraint satiation problems using python.

Algorithm:-

Step 1. Graph / map colouring problems are those where the nodes are assigned colors such that the adjacent connected nodes / regions don't have the same color assigned.

Step 2. At the same time, it is required to use the minimum number of colors possible – called the chromatic number.

Step 3. Start by coloring the first node with a color.

Step 4. Color the subsequent connected nodes with a different color.

Step 5. Check at every step that it satisfies the condition.

Code:-

```
from ortools.sat.python import cp_model
class VarArraySolutionPrinter(cp_model.CpSolverSolutionCallback):
    def __init__(self, variables):
        cp_model.CpSolverSolutionCallback.__init__(self)
        self.__variables = variables
        self.__solution_count = 0
    def on_solution_callback(self):
        self.__solution_count += 1
        for v in self.__variables:
            print('%s=%i' % (v, self.Value(v)), end=' ')
        print()
    def solution_count(self):
        return self.__solution_count
def main():
    model = cp_model.CpModel()
    base = 10
    c = model.NewIntVar(1, base - 1, 'C')
    p = model.NewIntVar(0, base - 1, 'P')
    i = model.NewIntVar(1, base - 1, 'I')
    s = model.NewIntVar(0, base - 1, 'S')
    f = model.NewIntVar(1, base - 1, 'F')
    u = model.NewIntVar(0, base - 1, 'U')
    n = model.NewIntVar(0, base - 1, 'N')
    t = model.NewIntVar(1, base - 1, 'T')
    r = model.NewIntVar(0, base - 1, 'R')
    e = model.NewIntVar(0, base - 1, 'E')

    # We need to group variables in a list to use the constraint AllDifferent.
    letters = [c, p, i, s, f, u, n, t, r, e]
    assert base >= len(letters)
    model.AddAllDifferent(letters)
    model.Add(c * base + p + i * base + s + f * base * base + u * base +
              n == t * base * base * base + r * base * base + u * base + e)
```

```

solver = cp_model.CpSolver()
solution_printer = VarArraySolutionPrinter(letters)
# Enumerate all solutions.
solver.parameters.enumerate_all_solutions = True
# Solve.
status = solver.Solve(model, solution_printer)
# Statistics.
print('\nStatistics')
print(f' status : {solver.StatusName(status)}')
print(f' conflicts: {solver.NumConflicts()}')
print(f' branches : {solver.NumBranches()}')
print(f' wall time: {solver.WallTime()} s')
print(f' sol found: {solution_printer.solution_count()}')
if __name__ == '__main__':
    main()

```

OUTPUT:-

The screenshot shows a Jupyter Notebook interface with a browser window at the top displaying the URL: `colab.research.google.com/drive/1MzWhZqwhsOu3oXK9nWqpPHzMEcMB6uf#scrollTo=IIGuaMoQW_60`. The notebook is titled "Constraints and Satisfaction - Crypt arithmetic problems.ipynb". The code cell shows a list of solutions, each represented as a string of 14 characters (P, S, U, N, T, R, E, C, H, A, S, E, D, I, N, G). The solutions are listed in a single column, with the first few being:

```

C=7 P=6 I=2 S=3 F=9 U=8 N=5 T=1 R=0 E=4
C=7 P=5 I=2 S=3 F=9 U=8 N=6 T=1 R=0 E=4
C=7 P=6 I=2 S=3 F=9 U=4 N=5 T=1 R=0 E=6
C=7 P=6 I=2 S=5 F=9 U=4 N=3 T=1 R=0 E=6
C=7 P=3 I=2 S=5 F=9 U=4 N=8 T=1 R=0 E=6
C=7 P=5 I=2 S=3 F=9 U=4 N=8 T=1 R=0 E=6
C=7 P=3 I=2 S=8 F=9 U=4 N=5 T=1 R=0 E=6
C=7 P=5 I=2 S=8 F=9 U=4 N=3 T=1 R=0 E=6
C=2 P=5 I=7 S=8 F=9 U=4 N=3 T=1 R=0 E=6
C=4 P=6 I=5 S=8 F=9 U=2 N=3 T=1 R=0 E=7
C=5 P=6 I=4 S=8 F=9 U=2 N=3 T=1 R=0 E=7
C=6 P=5 I=3 S=4 F=9 U=2 N=8 T=1 R=0 E=7
C=6 P=4 I=3 S=8 F=9 U=2 N=5 T=1 R=0 E=7
C=5 P=6 I=4 S=3 F=9 U=2 N=8 T=1 R=0 E=7
C=4 P=6 I=5 S=3 F=9 U=2 N=8 T=1 R=0 E=7
C=4 P=3 I=5 S=6 F=9 U=2 N=6 T=1 R=0 E=7
C=5 P=3 I=4 S=6 F=9 U=2 N=6 T=1 R=0 E=7
C=5 P=3 I=4 S=6 F=9 U=2 N=8 T=1 R=0 E=7
C=3 P=5 I=6 S=4 F=9 U=2 N=8 T=1 R=0 E=7
C=3 P=5 I=6 S=8 F=9 U=2 N=4 T=1 R=0 E=7
C=3 P=8 I=6 S=5 F=9 U=2 N=4 T=1 R=0 E=7
C=3 P=8 I=6 S=4 F=9 U=2 N=5 T=1 R=0 E=7
C=4 P=8 I=5 S=3 F=9 U=2 N=6 T=1 R=0 E=7
C=5 P=8 I=4 S=3 F=9 U=2 N=6 T=1 R=0 E=7
C=6 P=8 I=3 S=4 F=9 U=2 N=5 T=1 R=0 E=7
C=6 P=8 I=3 S=5 F=9 U=2 N=4 T=1 R=0 E=7
C=5 P=8 I=4 S=6 F=9 U=2 N=3 T=1 R=0 E=7
C=4 P=8 I=5 S=6 F=9 U=2 N=3 T=1 R=0 E=7
C=3 P=7 I=6 S=2 F=9 U=8 N=5 T=1 R=0 E=4
C=3 P=5 I=6 S=2 F=9 U=8 N=7 T=1 R=0 E=4
C=3 P=7 I=6 S=5 F=9 U=8 N=2 T=1 R=0 E=4

```

The notebook also shows a "Statistics" section at the bottom of the code cell, which displays the following information:

```

Statistics
status : OPTIMAL
conflicts: 179
branches : 828
wall time: 0.096367958 s
sol found: 72

```

The notebook interface shows a status bar at the bottom indicating "0s completed at 2:30 PM".

Result:-

We have successfully implemented the experiments.

AIM:-

To implement minmax algorithm for an application using python.

Algorithm:-

Step 1. Minimax algorithm, also known as Maximin, is a technique in AI to minimize the maximum loss or maximize the minimum gain while decision making.

Step 2. A recursive algorithm, used in two player games (predominantly) where a tree structure is used to denote the position of the player.

Step 3. The goal is to obtain the maximum possible score without knowing the decision of the other players in the game.

Step 4. The levels of the tree are alternatively names as max and min, where the root level takes max

Code:-

```
tree = [[[5, 1, 2], [8, -8, -9]], [[9, 4, 5], [-3, 4, 3]]]
root = 0
pruned = 0
```

```
def children(branch, depth, alpha, beta):
    global tree
    global root
    global pruned
    i = 0
    for child in branch:
        if type(child) is list:
            (nalpha, nbeta) = children(child, depth + 1, alpha, beta)
            if depth % 2 == 1:
                beta = nalpha if nalpha < beta else beta
            else:
                alpha = nbeta if nbeta > alpha else alpha
            branch[i] = alpha if depth % 2 == 0 else beta
            i += 1
    else:
        if depth % 2 == 0 and alpha < child:
            alpha = child
        if depth % 2 == 1 and beta > child:
            beta = child
        if alpha >= beta:
            pruned += 1
            break
    if depth == root:
        tree = alpha if root == 0 else beta
    return (alpha, beta)
```

```
def alphabeta(in_tree=tree, start=root, upper=-15, lower=15):
    global tree
    global pruned
    global root
```

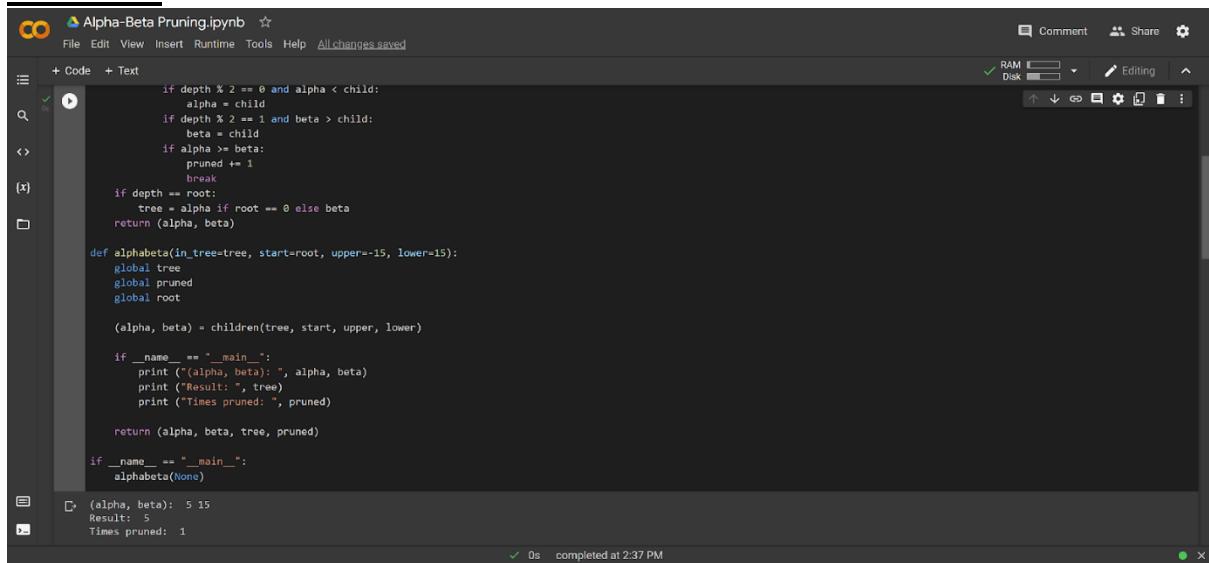
```
(alpha, beta) = children(tree, start, upper, lower)
```

```
if __name__ == "__main__":  
    print("(alpha, beta): ", alpha, beta)  
    print("Result: ", tree)  
    print("Times pruned: ", pruned)
```

```
return (alpha, beta, tree, pruned)
```

```
if __name__ == "__main__":  
    alphabeta(None)
```

OUTPUT:-



```
Alpha-Beta Pruning.ipynb  
File Edit View Insert Runtime Tools Help All changes saved  
+ Code + Text  
if depth % 2 == 0 and alpha < child:  
    alpha = child  
    if depth % 2 == 1 and beta > child:  
        beta = child  
    if alpha >= beta:  
        pruned += 1  
        break  
if depth == root:  
    tree = alpha if root == 0 else beta  
return (alpha, beta)  
  
def alphabeta(in_tree=tree, start=root, upper=-15, lower=15):  
    global tree  
    global pruned  
    global root  
  
    (alpha, beta) = children(tree, start, upper, lower)  
  
    if __name__ == "__main__":  
        print("(alpha, beta): ", alpha, beta)  
        print("Result: ", tree)  
        print("Times pruned: ", pruned)  
  
    return (alpha, beta, tree, pruned)  
  
if __name__ == "__main__":  
    alphabeta(None)  
  
(alpha, beta): 5 15  
Result: 5  
Times pruned: 1  
0s completed at 2:37 PM
```

Result:-

We have successfully implemented the experiments.

AIM:-

To implement unification and resolution for real world using python.

Algorithm:-

Unification

Step. 1: If $\Psi 1$ or $\Psi 2$ is a variable or constant, then:

1. If $\Psi 1$ or $\Psi 2$ are identical, then return NIL.
2. Else if $\Psi 1$ is a variable, a. then if $\Psi 1$ occurs in $\Psi 2$, then return FAILURE b. Else return $\{(\Psi 2 / \Psi 1)\}$.
3. Else if $\Psi 2$ is a variable, a. If $\Psi 2$ occurs in $\Psi 1$ then return FAILURE, b. Else return $\{(\Psi 1 / \Psi 2)\}$.
4. Else return FAILURE.

Step.2: If the initial Predicate symbol in $\Psi 1$ and $\Psi 2$ are not same, then return FAILURE.

Step. 3: IF $\Psi 1$ and $\Psi 2$ have a different number of arguments, then return FAILURE.

Step. 4: Set Substitution set(SUBST) to NIL.

Step. 5: For $i=1$ to the number of elements in $\Psi 1$. a) Call Unify function with the i th element of $\Psi 1$ and i th element of $\Psi 2$, and put the result into S. b) If $S = \text{failure}$ then returns Failure c) If $S \neq \text{NIL}$ then do, a. Apply S to the remainder of both L1 and L2. b. $\text{SUBST} = \text{APPEND}(S, \text{SUBST})$.

Step.6: Return SUBST

Code:-

Unification

```
def unify(E1, E2):
    constants = [chr(i) for i in range(ord('a'), ord('w') + 1)]
    variables = [chr(i) for i in range(ord('A'), ord('Z') + 1)]
    variables.extend(['x', 'y', 'z'])
    if (E1 in constants and E2 in constants) or (E1 is None and E2 is None): # base case
        if E1 == E2:
            return None
        else:
            return "FAIL"

    elif E1 in variables:
        if E1 in E2:
            return "FAIL - E1 occurs in E2"
        else:
            return (E2 + "/" + E1)

    elif E2 in variables:
        if E2 in E1:
            return "FAIL - E2 occurs in E1"
        else:
            return (E1 + "/" + E2)
```

```

else:
    if '(' in E1 and '(' not in E2:
        return "FAIL - E1 is a function and E2 is a variable/constant"
    elif '(' not in E1 and '(' in E2:
        return "FAIL - E1 is a variable/constant and E2 is a function"

print("Enter the Expressions (without spaces):")
s1 = input()
s2 = input()
E1 = s1[2:len(s1)-1].split(',')
E2 = s2[2:len(s2)-1].split(',')
if s1[0] != s2[0]:
    print("FAIL - Initial Predicate Symbols in E1 and E2 are not identical")
elif len(E1) != len(E2):
    print("FAIL - E1 and E2 have different number of arguments")
else:
    n = len(E1)
    s = [] # General Unifiers
    print("-----")
    for i in range(n):
        print("E1:", E1[i])
        print("E2:", E2[i])
        print("Result:", unify(E1[i],E2[i]))
        print("-----")
        if "FAIL" not in unify(E1[i],E2[i]):
            s.append(unify(E1[i],E2[i]))

    if len(s) == n:
        print("General Unifiers: { ", end = "")
        for i in range(len(s)):
            if i != len(s)-1:
                print(s[i] + " , ", end = "")
            else:
                print(s[i] + " }", end = "")

```

Resolution:-

Algorithm:-

Step-1: Conversion of Facts into FOL

Step-2: Conversion of FOL into CNF

- Eliminate all implication (\rightarrow) and rewrite
- Move negation (\neg) inwards and rewrite
- Rename variables or standardize variables
- Eliminate existential instantiation quantifier by elimination.
- Drop Universal quantifiers

Step-3: Negate the statement to be proved

Step-4: Draw Resolution graph:

Code:-

```
import copy
import time
```

```
class Parameter:
```

```
    variable_count = 1
```

```
    def __init__(self, name=None):
```

```
        if name:
```

```
            self.type = "Constant"
```

```
            self.name = name
```

```
        else:
```

```
            self.type = "Variable"
```

```
            self.name = "v" + str(Parameter.variable_count)
```

```
            Parameter.variable_count += 1
```

```
    def isConstant(self):
```

```
        return self.type == "Constant"
```

```
    def unify(self, type_, name):
```

```
        self.type = type_
```

```
        self.name = name
```

```
    def __eq__(self, other):
```

```
        return self.name == other.name
```

```
    def __str__(self):
```

```
        return self.name
```

```
class Predicate:
```

```
    def __init__(self, name, params):
```

```
        self.name = name
```

```
        self.params = params
```

```
    def __eq__(self, other):
```

```
        return self.name == other.name and all(a == b for a, b in zip(self.params, other.params))
```

```
    def __str__(self):
```

```
        return self.name + "(" + ",".join(str(x) for x in self.params) + ")"
```

```
    def getNegatedPredicate(self):
```

```
        return Predicate(negatePredicate(self.name), self.params)
```

```
class Sentence:
```

```
    sentence_count = 0
```

```
    def __init__(self, string):
```

```
        self.sentence_index = Sentence.sentence_count
```

```
        Sentence.sentence_count += 1
```

```
        self.predicates = []
```

```
        self.variable_map = { }
```

```

local = {}

for predicate in string.split("|"):
    name = predicate[:predicate.find("(")]
    params = []

    for param in predicate[predicate.find("(") + 1: predicate.find(")"]].split(","):
        if param[0].islower():
            if param not in local: # Variable
                local[param] = Parameter()
                self.variable_map[local[param].name] = local[param]
            new_param = local[param]
        else:
            new_param = Parameter(param)
            self.variable_map[param] = new_param

        params.append(new_param)

    self.predicates.append(Predicate(name, params))

def getPredicates(self):
    return [predicate.name for predicate in self.predicates]

def findPredicates(self, name):
    return [predicate for predicate in self.predicates if predicate.name == name]

def removePredicate(self, predicate):
    self.predicates.remove(predicate)
    for key, val in self.variable_map.items():
        if not val:
            self.variable_map.pop(key)

def containsVariable(self):
    return any(not param.isConstant() for param in self.variable_map.values())

def __eq__(self, other):
    if len(self.predicates) == 1 and self.predicates[0] == other:
        return True
    return False

def __str__(self):
    return "".join([str(predicate) for predicate in self.predicates])

class KB:
    def __init__(self, inputSentences):
        self.inputSentences = [x.replace(" ", "") for x in inputSentences]
        self.sentences = []
        self.sentence_map = {}

    def prepareKB(self):
        self.convertSentencesToCNF()

```

```

for sentence_string in self.inputSentences:
    sentence = Sentence(sentence_string)
    for predicate in sentence.getPredicates():
        self.sentence_map[predicate] = self.sentence_map.get(predicate, []) + [sentence]

def convertSentencesToCNF(self):
    for sentenceIdx in range(len(self.inputSentences)):
        if "=>" in self.inputSentences[sentenceIdx]: # Do negation of the Premise and add them as literal
            self.inputSentences[sentenceIdx] = negateAntecedent(self.inputSentences[sentenceIdx])

def askQueries(self, queryList):
    results = []

    for query in queryList:
        negatedQuery = Sentence(negatePredicate(query.replace(" ", "")))
        negatedPredicate = negatedQuery.predicates[0]
        prev_sentence_map = copy.deepcopy(self.sentence_map)
        self.sentence_map[negatedPredicate.name] = self.sentence_map.get(negatedPredicate.name, []) + [negatedQuery]
        self.timeLimit = time.time() + 40

        try:
            result = self.resolve([negatedPredicate], [False]*(len(self.inputSentences) + 1))
        except:
            result = False

        self.sentence_map = prev_sentence_map

        if result:
            results.append("TRUE")
        else:
            results.append("FALSE")

    return results

def resolve(self, queryStack, visited, depth=0):
    if time.time() > self.timeLimit:
        raise Exception
    if queryStack:
        query = queryStack.pop(-1)
        negatedQuery = query.getNegatedPredicate()
        queryPredicateName = negatedQuery.name
        if queryPredicateName not in self.sentence_map:
            return False
        else:
            queryPredicate = negatedQuery
            for kb_sentence in self.sentence_map[queryPredicateName]:
                if not visited[kb_sentence.sentence_index]:
                    for kbPredicate in kb_sentence.findPredicates(queryPredicateName):

```

```

        canUnify, substitution = performUnification(copy.deepcopy(queryPredicate), copy.deepcopy(kbPredicate))

```

```

    if canUnify:

```

```

        newSentence = copy.deepcopy(kb_sentence)
        newSentence.removePredicate(kbPredicate)
        newQueryStack = copy.deepcopy(queryStack)

```

```

    if substitution:

```

```

        for old, new in substitution.items():
            if old in newSentence.variable_map:
                parameter = newSentence.variable_map[old]
                newSentence.variable_map.pop(old)
                parameter.unify("Variable" if new[0].islower() else "Constant", new)
                newSentence.variable_map[new] = parameter

```

```

        for predicate in newQueryStack:

```

```

            for index, param in enumerate(predicate.params):

```

```

                if param.name in substitution:

```

```

                    new = substitution[param.name]

```

```

                    predicate.params[index].unify("Variable" if new[0].islower() else "Cons

```

```

tant", new)

```

```

        for predicate in newSentence.predicates:

```

```

            newQueryStack.append(predicate)

```

```

        new_visited = copy.deepcopy(visited)

```

```

        if kb_sentence.containsVariable() and len(kb_sentence.predicates) > 1:

```

```

            new_visited[kb_sentence.sentence_index] = True

```

```

        if self.resolve(newQueryStack, new_visited, depth + 1):

```

```

            return True

```

```

        return False

```

```

    return True

```

```

def performUnification(queryPredicate, kbPredicate):

```

```

    substitution = {}

```

```

    if queryPredicate == kbPredicate:

```

```

        return True, {}

```

```

    else:

```

```

        for query, kb in zip(queryPredicate.params, kbPredicate.params):

```

```

            if query == kb:

```

```

                continue

```

```

            if kb.isConstant():

```

```

                if not query.isConstant():

```

```

                    if query.name not in substitution:

```

```

                        substitution[query.name] = kb.name

```

```

                    elif substitution[query.name] != kb.name:

```

```

                        return False, {}

```

```

                    query.unify("Constant", kb.name)

```

```

            else:

```



```

        return False, {}
    else:
        if not query.isConstant():
            if kb.name not in substitution:
                substitution[kb.name] = query.name
            elif substitution[kb.name] != query.name:
                return False, {}
            kb.unify("Variable", query.name)
        else:
            if kb.name not in substitution:
                substitution[kb.name] = query.name
            elif substitution[kb.name] != query.name:
                return False, {}
    return True, substitution

def negatePredicate(predicate):
    return predicate[1:] if predicate[0] == "~" else "~" + predicate

def negateAntecedent(sentence):
    antecedent = sentence[:sentence.find("=>")]
    premise = []

    for predicate in antecedent.split("&"):
        premise.append(negatePredicate(predicate))

    premise.append(sentence[sentence.find("=>") + 2:])
    return "|".join(premise)

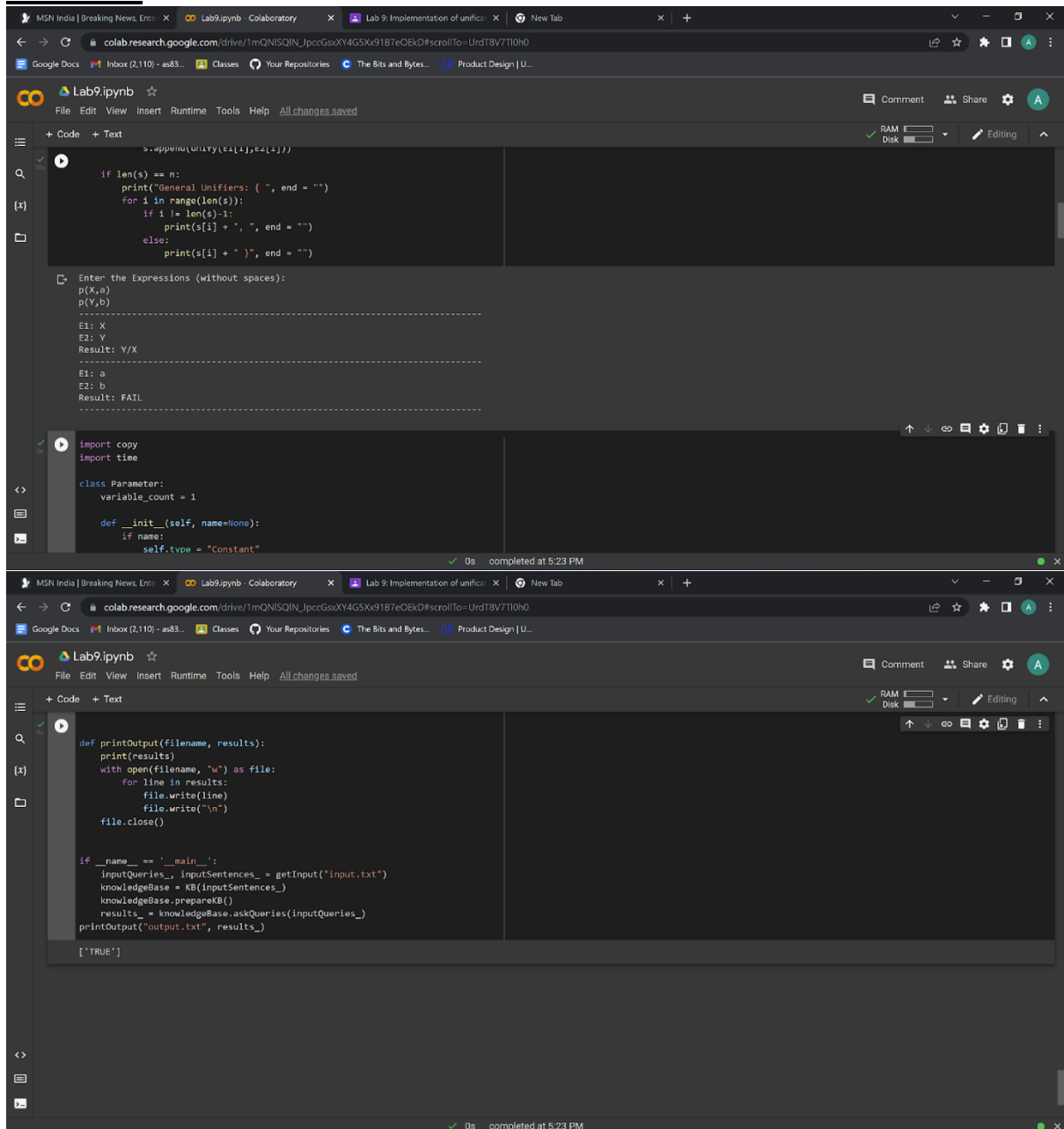
def getInput(filename):
    with open(filename, "r") as file:
        noOfQueries = int(file.readline().strip())
        inputQueries = [file.readline().strip() for _ in range(noOfQueries)]
        noOfSentences = int(file.readline().strip())
        inputSentences = [file.readline().strip() for _ in range(noOfSentences)]
    return inputQueries, inputSentences

def printOutput(filename, results):
    print(results)
    with open(filename, "w") as file:
        for line in results:
            file.write(line)
            file.write("\n")
    file.close()

if __name__ == '__main__':
    inputQueries_, inputSentences_ = getInput("input.txt")
    knowledgeBase = KB(inputSentences_)
    knowledgeBase.prepareKB()
    results_ = knowledgeBase.askQueries(inputQueries_)
    printOutput("output.txt", results_)

```

OUTPUT:-



The image displays two screenshots of a Google Colab notebook interface, showing the execution of a unification algorithm. The notebook is titled "Lab9.ipynb" and is part of a "Lab 9: Implementation of unification" project.

Top Screenshot: The code defines a function `s.append(u[1], c[1])` and a loop that prints "General Unifiers: (", end = "" followed by a loop over `len(s)`. The output shows the execution of the code, with the first part of the output being "General Unifiers: (". Below the code, there is a section for "Enter the Expressions (without spaces):" with input fields for `E1: X` and `E2: Y`, resulting in `Result: Y/X`. Below that, there is a section for `E1: a` and `E2: b`, resulting in `Result: FAIL`.

Bottom Screenshot: The code defines a function `printOutput(filename, results):` that prints the results and writes them to a file. The code also defines a `__main__` block that reads input from "input.txt", processes it using the `KB` (Knowledge Base) and `askQueries` function, and prints the output to "output.txt". The output shows the execution of the code, with the first part of the output being `['TRUE']`.

Result:-

We have successfully implemented the experiments.

Date:
Expt.No: 10

IMPLEMENTATION OF BLOCK WORLD PROBLEM

AIM:-

To implement block world problem using python.

Algorithm:-

Step 1: start

Step 2: Move Tatable(a,b,c)

Step 3: Construct Preconditions: On(a,b), Clear(a), Clear(c)

Step 4: Effects: On(a,c), Clear(b), NOT(On(a,b)), NOT(Clear(c))

Step 5: Stop

Code:-

Main.py

```
from BlockWorldAgent import BlockWorldAgent
def test():
    # This will test your BlockWorldAgent
    # with eight initial test cases.
    test_agent = BlockWorldAgent()

    initial_arrangement_1 = [["A", "B", "C"], ["D", "E"]]
    goal_arrangement_1 = [["A", "C"], ["D", "E", "B"]]
    goal_arrangement_2 = [["A", "B", "C", "D", "E"]]
    goal_arrangement_3 = [["D", "E", "A", "B", "C"]]
    goal_arrangement_4 = [["C", "D"], ["E", "A", "B"]]

    print(test_agent.solve(initial_arrangement_1, goal_arrangement_1))
    print(test_agent.solve(initial_arrangement_1, goal_arrangement_2))
    print(test_agent.solve(initial_arrangement_1, goal_arrangement_3))
    print(test_agent.solve(initial_arrangement_1, goal_arrangement_4))

    initial_arrangement_2 = [["A", "B", "C"], ["D", "E", "F"], ["G", "H", "I"]]
    goal_arrangement_5 = [["A", "B", "C", "D", "E", "F", "G", "H", "I"]]
    goal_arrangement_6 = [["I", "H", "G", "F", "E", "D", "C", "B", "A"]]
    goal_arrangement_7 = [["H", "E", "F", "A", "C"], ["B", "D"], ["G", "I"]]
    goal_arrangement_8 = [["F", "D", "C", "I", "G", "A"], ["B", "E", "H"]]

    print(test_agent.solve(initial_arrangement_2, goal_arrangement_5))
    print(test_agent.solve(initial_arrangement_2, goal_arrangement_6))
    print(test_agent.solve(initial_arrangement_2, goal_arrangement_7))
    print(test_agent.solve(initial_arrangement_2, goal_arrangement_8))

if __name__ == "__main__":
    test()
```

Block.py

```
import copy
import time
class BlockWorldAgent:

    def __init__(self):
        pass

    def solve(self, initial_arrangement, goal_arrangement):
        start = time.time()

        class State:
            def __init__(self, first_stack, second_stack, total_num, moves=None):
                if moves is None:
                    moves = []
                self.first_stack = first_stack
                self.second_stack = second_stack
                self.total_num = total_num
                self.moves = moves

            def __eq__(self, other):
                return (self.first_stack == other.first_stack and self.second_stack == other.second_stack
                        and self.total_num == other.total_num and self.moves == other.moves)

            def goal_state_move(self):
                while self.difference() != 0:
                    self = self.select_move()
                return self.moves

            def select_move(self): # will select and return the best move
                # first try moving the top block to a stack, if the diff is not reduced, then move it to the
temp_table
                for index, stack in enumerate(self.first_stack):
                    for index2, stack2 in enumerate(self.first_stack):
                        if index != index2: # don't move to itself stack
                            curr_table, move = self.valid_state_move(self.first_stack, index, index2)
                            new_state = State(curr_table, self.second_stack, self.total_num,
copy.copy(self.moves))
                            new_state.moves.append(move)
                            if new_state.difference() < self.difference():
                                return new_state

                # move the top block to the temp_table, skip if it is already on the table (itself alone on a
table)
                for index, stack in enumerate(self.first_stack):
                    if len(stack) > 1: # not it self alone
                        curr_table, move = self.valid_state_move(self.first_stack, index, -1) # -1 means table
                        new_state = State(curr_table, self.second_stack, self.total_num,
copy.copy(self.moves))
                        new_state.moves.append(move)
                        if new_state.difference() <= self.difference():
```

```

        return new_state

def valid_state_move(self, table, start_index, end_index):
    temp_table = copy.deepcopy(table)
    left = temp_table[start_index]
    top_block = left.pop()
    right = []

    if end_index < 0: # move to table (-1)
        temp_table.append(right)
        move = (top_block, 'Table')
    else: # move to stack
        right = temp_table[end_index]
        move = (top_block, right[-1])
    right.append(top_block)

    if len(left) == 0:
        temp_table.remove(left)
    return temp_table, move

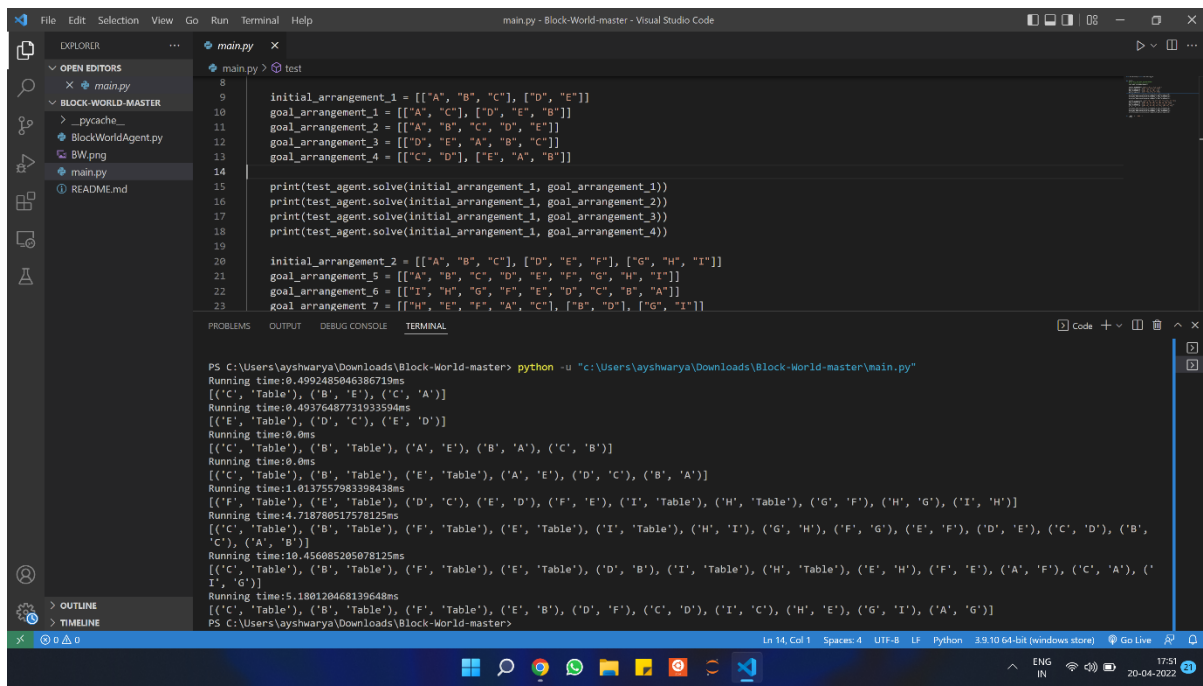
def difference(self):
    same_num = 0
    # compare each stack on two stacks
    for left in self.first_stack:
        for right in self.second_stack:
            index = 0
            while index < len(left) and index < len(right):
                if left[index] == right[index]:
                    same_num += 1
                    index += 1
            else:
                break
    diff = self.total_num - same_num
    return diff

total_num = 0
for ls in initial_arrangement:
    for e in ls:
        total_num += 1
state = State(initial_arrangement, goal_arrangement, total_num)
solution = state.goal_state_move()

end = time.time()
run_time = str((end - start) * 1000)
print("Running time:" + run_time + "ms")
return solution

```

OUTPUT:-



The screenshot displays the Visual Studio Code interface with a Python file named `main.py` open. The file contains a test script for a Block-World problem solver. The script defines several initial and goal arrangements and tests the solver's ability to find a solution for each goal arrangement starting from a specific initial arrangement.

```
8 initial_arrangement_1 = [['A', 'B', 'C'], ['D', 'E']]
9
10 goal_arrangement_1 = [['A', 'C'], ['D', 'E', 'B']]
11 goal_arrangement_2 = [['A', 'B', 'C', 'D', 'E']]
12 goal_arrangement_3 = [['D', 'E', 'A', 'B', 'C']]
13 goal_arrangement_4 = [['C', 'D'], ['E', 'A', 'B']]
14
15 print(test_agent.solve(initial_arrangement_1, goal_arrangement_1))
16 print(test_agent.solve(initial_arrangement_1, goal_arrangement_2))
17 print(test_agent.solve(initial_arrangement_1, goal_arrangement_3))
18 print(test_agent.solve(initial_arrangement_1, goal_arrangement_4))
19
20 initial_arrangement_2 = [['A', 'B', 'C'], ['D', 'E', 'F'], ['G', 'H', 'I']]
21 goal_arrangement_5 = [['A', 'B', 'C', 'D', 'E', 'F', 'G', 'H', 'I']]
22 goal_arrangement_6 = [['I', 'H', 'G', 'F', 'E', 'D', 'C', 'B', 'A']]
23 goal_arrangement_7 = [['H', 'E', 'F', 'A', 'C'], ['B', 'D'], ['G', 'I']]
```

The terminal window shows the execution of the script using the command `python -u "c:\Users\ayshwarya\Downloads\Block-World-master\main.py"`. The output displays the solutions for each goal arrangement, showing the sequence of blocks in the table and the blocks being moved. For example, the first goal arrangement is solved by moving block 'B' to the table and then block 'C' to the table.

```
PS C:\Users\ayshwarya\Downloads\Block-World-master> python -u "c:\Users\ayshwarya\Downloads\Block-World-master\main.py"
Running time:0.4992485946386719ms
[('C', 'Table'), ('B', 'E'), ('C', 'A')]
Running time:0.49376487731933594ms
[('E', 'Table'), ('D', 'C'), ('E', 'D')]
Running time:0.0ms
[('C', 'Table'), ('B', 'Table'), ('A', 'E'), ('B', 'A'), ('C', 'B')]
Running time:0.0ms
[('C', 'Table'), ('B', 'Table'), ('E', 'Table'), ('A', 'E'), ('D', 'C'), ('B', 'A')]
Running time:1.0137557983398438ms
[('F', 'Table'), ('E', 'Table'), ('D', 'C'), ('E', 'D'), ('F', 'E'), ('I', 'Table'), ('H', 'Table'), ('G', 'F'), ('H', 'G'), ('I', 'H')]
Running time:4.718780517578125ms
[('C', 'Table'), ('B', 'Table'), ('F', 'Table'), ('E', 'Table'), ('I', 'Table'), ('H', 'I'), ('G', 'H'), ('F', 'G'), ('E', 'F'), ('D', 'E'), ('C', 'D'), ('B', 'C'), ('A', 'B')]
Running time:10.456085205078125ms
[('C', 'Table'), ('B', 'Table'), ('F', 'Table'), ('E', 'Table'), ('D', 'B'), ('I', 'Table'), ('H', 'Table'), ('E', 'H'), ('F', 'E'), ('A', 'F'), ('C', 'A'), ('I', 'G')]
Running time:5.180120468139648ms
[('C', 'Table'), ('B', 'Table'), ('F', 'Table'), ('E', 'B'), ('D', 'F'), ('C', 'D'), ('I', 'C'), ('H', 'E'), ('G', 'I'), ('A', 'G')]
PS C:\Users\ayshwarya\Downloads\Block-World-master>
```

Result:-

We have successfully implemented the experiments.