Fusion Data Framework Documentation Release 0.0.0

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ABOUT FDF

Fusion Data Framework (FDF) is a data access, management, and visualization framework for magnetic fusion experiments.

Repository: https://github.com/Fusion-Data-Framework/fdf

HTML Documentation or PDF Documentation

Submit bugs or feature requests: https://github.com/Fusion-Data-Framework/fdf/issues

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To contribute to the FDF project, please contact John, David, Kevin, or Howard.

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USER GUIDE

This guide is for people who want to use FDF on the PPPL Linux cluster. If you wish to contribute to the FDF code repository (https://github.com/Fusion-Data-Framework/fdf), see :ref:'developer-guide'.

HTML documentation is available here: http://fusion-data-framework.github.io/fdf/

To use FDF on the PPPL Linux cluster (portal.pppl.gov), load the module nstx/fdf (you may need to unload other nstx modules):

```
[sunfire06:~] % module load nstx/fdf
[sunfire06:~] % module list
Currently Loaded Modulefiles:
1) torque/2.5.2 5) idl/8.2 9) java/v1.6
2) moab/5.4.0 6) nstx/treedefs 10) nstx/mdsplus5
3) ppplcluster/1.1 7) nstx/epics 11) nstx/fdf
4) freetds/0.91 8) nstx/idldirs
```

Verify that python points to /p/fdf/anaconda/bin/python:

```
[sunfire06:~] % which python /p/fdf/anaconda/bin/python
```

If python does not point to /p/fdf/anaconda/bin/python, then PATH contains to a different python distribution ahead of /p/fdf/anaconda/bin. In this case, you need to modify PATH so /p/fdf/anaconda/bin is the first python distribution in PATH.

Finally, you can launch python and import the FDF package:

```
[sunfire06:~] % python
Python 2.7.10 |Anaconda 2.3.0 (64-bit)| (default, Sep 15 2015, 14:50:01)
[GCC 4.4.7 20120313 (Red Hat 4.4.7-1)] on linux2
Type "help", "copyright", "credits" or "license" for more information.
Anaconda is brought to you by Continuum Analytics.
Please check out: http://continuum.io/thanks and https://anaconda.org
>>> import fdf
>>>
```

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USAGE EXAMPLES

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PACKAGE REFERENCE

5.1 Module factory.py

Root module for the FDF package.

Classes

- Machine root class for the FDF package
- Shot shot container class
- Logbook logbook connection class
- Container diagnostic container class
- Node mdsplus signal node class
- FdfError error class for FDF package

Usage:

```
>>> import fdf
>>> nstx = fdf.Machine('nstx')
>>> nstx.s140000.logbook()
>>> nstx.addshots(xp=1048)
>>> nstx.s140000.mpts.plot()
```

5.2 Class Machine

```
class factory.Machine (name='nstx', shotlist=[], xp=[], date=[])
Factory root class that contains shot objects and MDS access methods.

Basic class initialization is performed as follows: >>>nstx = Machine(name='nstx')
the Machine class contains a model shot object: nstx.s0
shot data can be accessed directly through the Machine class: >>> nstx.s141398 >>> nstx.s141399
alternatively, a list of shot #'s may be provided during initialization: >>>nstx = Machine(name='nstx', shotlist=[141398, 141399])
or added later using the addshot method: >>>nstx.addshot([141398, 141399])
```

5.3 Class Shot

class factory.Shot (shot, root=None, parent=None)

5.4 Class Logbook

class factory.Logbook (name='nstx', root=None)

5.5 Module fdf_signal.py

fdf-signals.py - module containing Signal class

Classes

• Signal - signal class for data objects

Created on Tue Jun 23 2015

@author: hyuh

5.6 Class Signal

```
class fdf_signal.Signal(**kwargs)
    sig=fdf.Signal(signal_ndarray, units='m/s', axes=['radius','time'], axes_values=[ax1_1Darray,
    ax2_1Darray], axes_units=['s','cm']
    e.g.: mds.Signal(np.arange((20*10)).reshape((10,20)), units='keV', axes=['radius','time'],
    axes_values=[100+np.arange(10)*5, np.arange(20)*0.1], axes_units=['s','cm'])
    or an empty signal: s=mds.Signal() default axes order=[time, space] sig=fdf.Signal(units='m/s',
    axes=['radius','time'], axes_values=[radiusSignal, timeSignal])
```

5.7 Module fdf_globals.py

fdf_globals.py contains package-level constants

Created on Thu Jun 18 11:18:16 2015

@author: ktritz

5.3. Class Shot 6

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