Fusion Data Framework Documentation Release 0.0.0

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ABOUT FDF

Fusion Data Framework (FDF) is a data access, management, and visualization framework for magnetic fusion experiments.

Repository: https://github.com/Fusion-Data-Framework/fdf

HTML Documentation or PDF Documentation

Submit bugs or feature requests: https://github.com/Fusion-Data-Framework/fdf/issues

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To contribute to the FDF project, please contact John, David, Kevin, or Howard.

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GETTING STARTED GUIDE

- 2.1 User Guide
- 2.2 Developer Guide

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USAGE EXAMPLES

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PACKAGE REFERENCE

4.1 Module factory.py

Root module for the FDF package.

Classes

- Machine root class for the FDF package
- Shot shot container class
- Logbook logbook connection class
- Container diagnostic container class
- Node mdsplus signal node class
- FdfError error class for FDF package

Usage:

```
>>> import fdf
>>> nstx = fdf.Machine('nstx')
>>> nstx.s140000.logbook()
>>> nstx.addshots(xp=1048)
>>> nstx.s140000.mpts.plot()
```

4.2 Class Machine

```
class factory.Machine (name='nstx', shotlist=[], xp=[], date=[])
Factory root class that contains shot objects and MDS access methods.

Basic class initialization is performed as follows: >>>nstx = Machine(name='nstx')
the Machine class contains a model shot object: nstx.s0
shot data can be accessed directly through the Machine class: >>> nstx.s141398 >>> nstx.s141399
alternatively, a list of shot #'s may be provided during initialization: >>>nstx = Machine(name='nstx', shotlist=[141398, 141399])
or added later using the addshot method: >>>nstx.addshot([141398, 141399])
```

4.3 Class Shot

class factory.Shot (shot, root=None, parent=None)

4.4 Class Logbook

class factory.Logbook (name='nstx', root=None)

4.5 Module fdf_signal.py

fdf-signals.py - module containing Signal class

Classes

• Signal - signal class for data objects

Created on Tue Jun 23 2015

@author: hyuh

4.6 Class Signal

```
class fdf_signal.Signal(**kwargs)
    sig=fdf.Signal(signal_ndarray, units='m/s', axes=['radius','time'], axes_values=[ax1_1Darray,
    ax2_1Darray], axes_units=['s','cm']
    e.g.: mds.Signal(np.arange((20*10)).reshape((10,20)), units='keV', axes=['radius','time'],
    axes_values=[100+np.arange(10)*5, np.arange(20)*0.1], axes_units=['s','cm'])
    or an empty signal: s=mds.Signal() default axes order=[time, space] sig=fdf.Signal(units='m/s',
    axes=['radius','time'], axes_values=[radiusSignal, timeSignal])
```

4.7 Module fdf_globals.py

fdf_globals.py contains package-level constants

Created on Thu Jun 18 11:18:16 2015

@author: ktritz

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