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/* Skeleton 2-1/2D Electromagnetic MPI PIC code */
/* written by Viktor K. Decyk, UCLA */
#include <stdlib.h>
#include <stdio.h>
#include <complex.h>
#include <sys/time.h>
#include "pbpush2.h"
#include "pplib2.h"
void dtimer(double *time, struct timeval *itime, int icntrl);
int main(int argc, char *argv[]) {
   int indx = 9, indy = 9;
   int npx = 3072, npy =
                            3072;
   int ndim = 3;
   float tend = 10.0, dt = 0.04, qme = -1.0;
/* float tend = 10.0, dt = 0.025, qme = -1.0;
   float vtx = 1.0, vty = 1.0, vx0 = 0.0, vy0 = 0.0;
   float vtz = 1.0, vz0 = 0.0;
   float ax = .912871, ay = .912871, ci = 0.1;
/* idimp = dimension of phase space = 5 */
/* sortime = number of time steps between standard electron sorting */
/* relativity = (no,yes) = (0,1) = relativity is used */
   int idimp = 5, ipbc = 1, sortime = 50, relativity = 1;
/* idps = number of partition boundaries */
   int idps = 2;
   float wke = 0.0, we = 0.0, wf = 0.0, wm = 0.0, wt = 0.0;
/* declare scalars for standard code */
   int j;
   int nx, ny, nxh, nyh, nxe, nye, nxeh, nnxe, nxyh, nxhy;
   int ny1, ntime, nloop, isign, ierr;
   float qbme, affp, dth;
   double np;
/* declare scalars for MPI code */
   int ntpose = 1;
   int nvp, idproc, kstrt, npmax, kxp, kyp, nypmx, nypmn;
   int nyp, noff, npp, nps, nbmax, ntmax;
/* declare arrays for standard code */
   float *part = NULL, *part2 = NULL, *tpart = NULL;
   float *qe = NULL;
   float *cue = NULL, *fxyze = NULL, *bxyze = NULL;
   float complex *exyz = NULL, *bxyz = NULL;
   float complex *qt = NULL;
   float complex *cut = NULL, *fxyt = NULL, *bxyt = NULL;
   float complex *ffc = NULL;
   int *mixup = NULL;
   float complex *sct = NULL;
   int *ihole = NULL;
   int *npic = NULL;
   float wtot[7], work[7];
   int info[7];
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/* declare arrays for MPI code */
   float complex *bs = NULL, *br = NULL;
   float *sbufl = NULL, *sbufr = NULL, *rbufl = NULL, *rbufr = NULL;
   float *edges = NULL;
   float *scr = NULL;
/* declare and initialize timing data */
   float time;
   struct timeval itime;
   float tdpost = 0.0, tquard = 0.0, ttp = 0.0, tfield = 0.0;
   float tdjpost = 0.0, tpush = 0.0, tsort = 0.0, tmov = 0.0;
   float tfft[2] = \{0.0, 0.0\};
   double dtime;
/* initialize scalars for standard code */
   np = (double) npx*(double) npy;
   nx = 1L << indx; ny = 1L << indy; nxh = nx/2; nyh = ny/2;
   nxe = nx + 2; nye = ny + 2; nxeh = nxe/2; nnxe = ndim*nxe;
  nxyh = (nx > ny ? nx : ny)/2; nxhy = nxh > ny ? nxh : ny;
  ny1 = ny + 1;
  nloop = tend/dt + .0001; ntime = 0;
  qbme = qme;
   affp = (double) nx*(double) ny/np;
  dth = 0.0;
/* nvp = number of distributed memory nodes */
/* initialize for distributed memory parallel processing */
   cppinit2(&idproc,&nvp,argc,argv);
   kstrt = idproc + 1;
/* check if too many processors */
   if (nvp > ny) {
      if (kstrt==1) {
         printf("Too many processors requested: ny, nvp=%d,%d\n",ny,nvp);
      goto L3000;
   }
/* initialize data for MPI code */
   edges = (float *) malloc(idps*sizeof(float));
                                                                        */
/* calculate partition variables: edges, nyp, noff, nypmx
/* edges[0:1] = lower:upper boundary of particle partition
                                                                        */
/* nyp = number of primary (complete) gridpoints in particle partition */
/* noff = lowermost global gridpoint in particle partition
                                                                        */
/* nypmx = maximum size of particle partition, including guard cells
                                                                        */
/* nypmn = minimum value of nyp
                                                                        */
   cpdicomp21(edges,&nyp,&noff,&nypmx,&nypmn,ny,kstrt,nvp,idps);
   if (nypmn < 1) {
      if (kstrt==1) {
         printf("combination not supported nvp, ny =%d,%d\n",ny,nvp);
      goto L3000;
   }
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/* initialize additional scalars for MPI code */
/* kxp = number of complex grids in each field partition in x direction */
  kxp = (nxh - 1)/nvp + 1;
/* kyp = number of complex grids in each field partition in y direction */
  kyp = (ny - 1)/nvp + 1;
/* npmax = maximum number of electrons in each partition */
  npmax = (np/nvp)*1.25;
/* nbmax = size of buffer for passing particles between processors */
  nbmax = 0.1*npmax;
/* ntmax = size of ihole buffer for particles leaving processor */
  ntmax = 2*nbmax;
/* allocate and initialize data for standard code */
   part = (float *) malloc(idimp*npmax*sizeof(float));
   part2 = (float *) malloc(idimp*npmax*sizeof(float));
  qe = (float *) malloc(nxe*nypmx*sizeof(float));
   fxyze = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
   cue = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
  bxyze = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
   exyz = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
  bxyz = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
  qt = (float complex *) malloc(nye*kxp*sizeof(float complex));
   fxyt = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
  cut = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
  bxyt = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
   ffc = (float complex *) malloc(nyh*kxp*sizeof(float complex));
  mixup = (int *) malloc(nxhy*sizeof(int));
   sct = (float complex *) malloc(nxyh*sizeof(float complex));
   ihole = (int *) malloc((ntmax+1)*sizeof(int));
   npic = (int *) malloc(nypmx*sizeof(int));
/* allocate and initialize data for MPI code */
  bs = (float complex *) malloc(ndim*kxp*kyp*sizeof(float complex));
  br = (float complex *) malloc(ndim*kxp*kyp*sizeof(float complex));
  sbufl = (float *) malloc(idimp*nbmax*sizeof(float));
  sbufr = (float *) malloc(idimp*nbmax*sizeof(float));
  rbufl = (float *) malloc(idimp*nbmax*sizeof(float));
   rbufr = (float *) malloc(idimp*nbmax*sizeof(float));
   scr = (float *) malloc(ndim*nxe*sizeof(float));
/* prepare fft tables */
  cwpfft2rinit(mixup,sct,indx,indy,nxhy,nxyh);
/* calculate form factors */
   isign = 0;
  cppois23(qt,fxyt,isiqn,ffc,ax,ay,affp,&we,nx,ny,kstrt,nye,kxp,nyh);
/* initialize electrons */
  nps = 1;
  npp = 0;
   cpdistr2h(part,edges,&npp,nps,vtx,vty,vtz,vx0,vy0,vz0,npx,npy,nx,ny,
            idimp,npmax,idps,ipbc,&ierr);
/* check for particle initialization error */
   if (ierr != 0) {
      if (kstrt==1) {
        printf("particle initialization error: ierr=%d\n",ierr);
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}
      goto L3000;
   }
/* initialize transverse electromagnetic fields */
   for (j = 0; j < ndim*nye*kxp; j++) {
      exyz[j] = 0.0 + 0.0*_Complex_I;
      bxyz[j] = 0.0 + 0.0*_Complex_I;
   }
   if (dt > 0.45*ci) {
      if (kstrt==1) {
         printf("Warning: Courant condition may be exceeded!\n");
      }
/* * * * start main iteration loop * * * */
L500: if (nloop <= ntime)
         goto L2000;
/*
      if (kstrt==1) printf("ntime = %i\n",ntime); */
/* deposit current with standard procedure: updates part, cue, ihole */
      dtimer(&dtime,&itime,-1);
      for (j = 0; j < ndim*nxe*nypmx; j++) {
         cue[j] = 0.0;
      if (relativity==1) {
         cppgrjpost21(part,cue,edges,npp,noff,ihole,qme,dth,ci,nx,ny,
                      idimp,npmax,nxe,nypmx,idps,ntmax,ipbc);
      }
      else {
         cppgjpost2l(part,cue,edges,npp,noff,ihole,qme,dth,nx,ny,idimp,
                     npmax,nxe,nypmx,idps,ntmax,ipbc);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tdjpost += time;
/* check for ihole overflow error */
      if (ihole[0] < 0) {</pre>
         ierr = -ihole[0];
         printf("ihole overflow error: ntmax,ih=%d,%d\n",ntmax,ierr);
         cppabort();
         goto L3000;
      }
/* move electrons into appropriate spatial regions: updates part, npp */
      dtimer(&dtime, &itime, -1);
      cppmove2(part,edges,&npp,sbufr,sbufl,rbufr,rbufl,ihole,ny,kstrt,nvp,
               idimp,npmax,idps,nbmax,ntmax,info);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tmov += time;
/* check for particle manager error */
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if (info[0] != 0) {
         ierr = info[0];
         if (kstrt==1) {
            printf("current particle manager error: ierr=%d\n",ierr);
         goto L3000;
      }
/* deposit charge with standard procedure: updates qe */
      dtimer(&dtime,&itime,-1);
      for (j = 0; j < nxe*nypmx; j++) {
         qe[j] = 0.0;
      cppgpost21(part,qe,npp,noff,qme,idimp,npmax,nxe,nypmx);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tdpost += time;
/* add guard cells with standard procedure: updates cue, qe */
      dtimer(&dtime,&itime,-1);
      cppacguard2xl(cue,nyp,nx,ndim,nxe,nypmx);
      cppnacguard2l(cue,scr,nyp,nx,ndim,kstrt,nvp,nxe,nypmx);
      cppaguard2xl(qe,nyp,nx,nxe,nypmx);
      cppnaguard21(qe,scr,nyp,nx,kstrt,nvp,nxe,nypmx);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tguard += time;
/* transform charge to fourier space with standard procedure: updates qt */
/* modifies qe */
      dtimer(&dtime,&itime,-1);
      isign = -1;
      cwppfft2r((float complex *)qe,qt,bs,br,isiqn,ntpose,mixup,sct,&ttp,
                indx, indy, kstrt, nvp, nxeh, nye, kxp, kyp, nypmx, nxhy, nxyh);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfft[0] += time;
      tfft[1] += ttp;
/* transform current to fourier space with standard procedure: updates cut */
/* modifies cue */
      dtimer(&dtime,&itime,-1);
      isign = -1;
      cwppfft2r3((float complex *)cue,cut,bs,br,isiqn,ntpose,mixup,sct,
                 &ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,nxhy,
                 nxyh);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfft[0] += time;
      tfft[1] += ttp;
/* take transverse part of current with standard procedure: updates cut */
      dtimer(&dtime, &itime, -1);
      cppcuperp2(cut,nx,ny,kstrt,nye,kxp);
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dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfield += time;
/* calculate electromagnetic fields in fourier space with standard */
/* procedure: updates exyz, bxyz */
      dtimer(&dtime, &itime, -1);
      if (ntime==0) {
         cippbpoisp23(cut,bxyz,ffc,ci,&wm,nx,ny,kstrt,nye,kxp,nyh);
         wf = 0.0;
         dth = 0.5*dt;
      }
      else {
         cppmaxwel2(exyz,bxyz,cut,ffc,affp,ci,dt,&wf,&wm,nx,ny,kstrt,
                    nye, kxp, nyh);
      }
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfield += time;
/* calculate force/charge in fourier space with standard procedure: */
/* updates fxyt */
      dtimer(&dtime, &itime, -1);
      isign = -1;
      cppois23(qt,fxyt,isign,ffc,ax,ay,affp,&we,nx,ny,kstrt,nye,kxp,
               nyh);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfield += time;
/* add longitudinal and transverse electric fields with standard */
/* procedure: updates fxyt */
      dtimer(&dtime, &itime, -1);
      isign = 1;
      cppemfield2(fxyt,exyz,ffc,isign,nx,ny,kstrt,nye,kxp,nyh);
/* copy magnetic field with standard procedure: updates bxyt */
      isign = -1;
      cppemfield2(bxyt,bxyz,ffc,isign,nx,ny,kstrt,nye,kxp,nyh);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfield += time;
/* transform force to real space with standard procedure: updates fxyze */
/* modifies fxyt */
      dtimer(&dtime,&itime,-1);
      isign = 1;
      cwppfft2r3((float complex *)fxyze,fxyt,bs,br,isign,ntpose,mixup,
                 sct,&ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,
                 nxhy, nxyh);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tfft[0] += time;
      tfft[1] += ttp;
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/* transform magnetic field to real space with standard procedure: */
/* updates bxyze, modifies bxyt */
      dtimer(&dtime,&itime,-1);
      isign = 1;
      cwppfft2r3((float complex *)bxyze,bxyt,bs,br,isign,ntpose,mixup,
                 sct,&ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,
                 nxhy, nxyh);
      dtimer(&dtime,&itime,1);
      time = (float) dtime;
      tfft[0] += time;
      tfft[1] += ttp;
/* copy quard cells with standard procedure: updates fxyze, bxyze */
      dtimer(&dtime,&itime,-1);
      cppncguard21(fxyze,nyp,kstrt,nvp,nnxe,nypmx);
      cppcguard2xl(fxyze,nyp,nx,ndim,nxe,nypmx);
      cppncguard21(bxyze,nyp,kstrt,nvp,nnxe,nypmx);
      cppcguard2xl(bxyze,nyp,nx,ndim,nxe,nypmx);
      dtimer(&dtime,&itime,1);
      time = (float) dtime;
      tguard += time;
/* push particles: updates part, wke, and ihole */
      dtimer(&dtime,&itime,-1);
      wke = 0.0;
      if (relativity==1) {
         cppgrbpush231(part,fxyze,bxyze,edges,npp,noff,ihole,qbme,dt,
                       dth,ci,&wke,nx,ny,idimp,npmax,nxe,nypmx,idps,
                       ntmax,ipbc);
      }
      else {
        cppgbpush231(part,fxyze,bxyze,edges,npp,noff,ihole,qbme,dt,dth,
                      &wke,nx,ny,idimp,npmax,nxe,nypmx,idps,ntmax,ipbc);
      dtimer(&dtime, &itime, 1);
      time = (float) dtime;
      tpush += time;
/* check for ihole overflow error */
      if (ihole[0] < 0) {
         ierr = -ihole[0];
        printf("ihole overflow error: ntmax,ih=%d,%d\n",ntmax,ierr);
        cppabort();
        goto L3000;
      }
/* move electrons into appropriate spatial regions: updates part, npp */
      dtimer(&dtime,&itime,-1);
      cppmove2(part,edges,&npp,sbufr,sbufl,rbufr,rbufl,ihole,ny,kstrt,nvp,
               idimp,npmax,idps,nbmax,ntmax,info);
      dtimer(&dtime,&itime,1);
      time = (float) dtime;
      tmov += time;
/* check for particle manager error */
      if (info[0] != 0) {
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ierr = info[0];
         if (kstrt==1) {
            printf("push particle manager error: ierr=%d\n",ierr);
         goto L3000;
      }
/* sort particles for standard code: updates part */
      if (sortime > 0) {
         if (ntime%sortime==0) {
            dtimer(&dtime, &itime, -1);
            cppdsortp2yl(part,part2,npic,npp,noff,nyp,idimp,npmax,nypmx);
/* exchange pointers */
            tpart = part;
            part = part2;
            part2 = tpart;
            dtimer(&dtime, &itime, 1);
            time = (float) dtime;
            tsort += time;
         }
      }
/* energy diagnostic */
      wt = we + wf + wm;
      wtot[0] = wt;
      wtot[1] = wke;
      wtot[2] = 0.0;
      wtot[3] = wke + wt;
      wtot[4] = we;
      wtot[5] = wf;
      wtot[6] = wm;
      cppsum(wtot,work,7);
      wke = wtot[1];
      we = wtot[4];
      wf = wtot[5];
      wm = wtot[6];
      if (ntime==0) {
         if (kstrt==1) {
            wt = we + wf + wm;
            printf("Initial Total Field, Kinetic and Total Energies:\n");
            printf("%e %e %e\n",wt,wke,wke+wt);
            printf("Initial Electrostatic, Transverse Electric and \
Magnetic Field Energies:\n");
            printf("%e %e %e\n",we,wf,wm);
         }
      }
      ntime += 1;
      goto L500;
L2000:
/* * * * end main iteration loop * * * */
   if (kstrt==1) {
      printf("ntime, relativity = %i,%i\n",ntime,relativity);
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printf("MPI nodes nvp = %i\n",nvp);
     wt = we + wf + wm;
      printf("Final Total Field, Kinetic and Total Energies:\n");
      printf("%e %e %e\n",wt,wke,wke+wt);
      printf("Final Electrostatic, Transverse Electric and Magnetic \
Field Energies:\n");
      printf("%e %e %e\n",we,wf,wm);
      printf("\n");
      printf("deposit time = %f\n",tdpost);
      printf("current deposit time = %f\n",tdjpost);
      tdpost += tdjpost;
      printf("total deposit time = %f\n",tdpost);
      printf("quard time = %f\n",tquard);
      printf("solver time = %f\n",tfield);
      printf("fft and transpose time = %f,%f\n",tfft[0],tfft[1]);
      printf("push time = %f\n",tpush);
     printf("particle move time = %f\n",tmov);
      printf("sort time = %f\n",tsort);
      tfield += tguard + tfft[0];
      printf("total solver time = %f\n",tfield);
      time = tdpost + tpush + tmov + tsort;
      printf("total particle time = %f\n",time);
     wt = time + tfield;
      printf("total time = %f\n",wt);
     printf("\n");
     wt = 1.0e+09/(((float) nloop)*((float) np));
      printf("Push Time (nsec) = %f\n",tpush*wt);
      printf("Deposit Time (nsec) = %f\n",tdpost*wt);
      printf("Sort Time (nsec) = %f\n",tsort*wt);
     printf("Total Particle Time (nsec) = %f\n",time*wt);
   }
L3000:
   cppexit();
   return 0;
}
```