

Seminar 7 (142)

(Ex1) $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $f(x) = (-3x_1 + 2x_2, -5x_1 + 4x_2, 2x_1 - 2x_2 - x_3)$
 Precizați un refer în \mathbb{R}^3 al căreia matricea asociată
 lui f este diagonală

SOL $\mathcal{R}_0 = \{e_1^0, e_2^0, e_3^0\}$ referul canonic din \mathbb{R}^3

$$A = [f]_{\mathcal{R}_0, \mathcal{R}_0} = \begin{pmatrix} -3 & 2 & 0 \\ -5 & 4 & 0 \\ 2 & -2 & -1 \end{pmatrix}$$

Determinăm valorile proprii

$$\begin{aligned} P(\lambda) &= \det(A - \lambda I_3) = \begin{vmatrix} -3-\lambda & 2 & 0 \\ -5 & 4-\lambda & 0 \\ 2 & -2 & 1-\lambda \end{vmatrix} \\ &= (-1-\lambda) \begin{vmatrix} -3-\lambda & 2 \\ -5 & 4-\lambda \end{vmatrix} = (-1-\lambda)(\lambda^2 - \lambda - 2) = \\ &= -(\lambda+1)^2(\lambda-2) = 0 \Rightarrow \begin{cases} \lambda_1 = -1, m_1 = 2 \\ \lambda_2 = 2, m_2 = 1 \end{cases} \end{aligned}$$

⊗ $\lambda_1, \lambda_2 \in \mathbb{R}$

Det. subsp. proprii

$$\begin{aligned} V_{\lambda_1} &= \{x \in \mathbb{R}^3 \mid f(x) = -x\} = \{(x_1, x_1, x_3) \mid x_1, x_3 \in \mathbb{R}\} \\ &= \langle \{(1, 1, 0), (0, 0, 1)\} \rangle \\ \begin{cases} -3x_1 + 2x_2 = -x_1 \\ -5x_1 + 4x_2 = -x_2 \\ 2x_1 - 2x_2 - x_3 = -x_3 \end{cases} &\Rightarrow \begin{cases} x_1 = x_2 \\ \text{rg} \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} = 2 = \max \end{cases} \end{aligned}$$

$\mathcal{R}_1 = \{(1, 1, 0), (0, 0, 1)\}$ refer în V_{λ_1} .

$$\bullet \dim V_{\lambda_1} = 2 = m_1$$

$$V_{\lambda_2} = \{x \in \mathbb{R}^3 \mid f(x) = 2x\} = \{(x_1, \frac{5}{2}x_1, -x_1) \mid x_1 \in \mathbb{R}\}$$

$$\begin{cases} -3x_1 + 2x_2 = 2x_1 \\ -5x_1 + 4x_2 = 2x_2 \\ 2x_1 - 2x_2 - x_3 = 2x_3 \end{cases} \Rightarrow \begin{cases} -5x_1 + 2x_2 = 0 \Rightarrow x_2 = \frac{5}{2}x_1 \\ -5x_1 + 2x_2 = 0 \\ 2x_1 - 2x_2 - x_3 = 2x_3 \Rightarrow x_3 = -x_1 \end{cases}$$

$$V_{\lambda_2} = \langle \{(2, 5, -2)\} \rangle, \mathcal{R}_2 = \{(2, 5, -2)\}, \dim V_{\lambda_2} = 1 = m_2$$

$$\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2 = \{ \overset{e_1}{(1, 1, 0)}, \overset{e_2}{(0, 0, 1)}, \overset{e_3}{(2, 5, -2)} \} \text{ reper în } \mathbb{R}^3$$

$$A' = [f]_{\mathcal{R}, \mathcal{R}} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \begin{cases} f(e_1) = -e_1 \\ f(e_2) = -e_2 \\ f(e_3) = 2e_3 \end{cases}$$

Ex2) $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $f(x) = (4x_1 + x_2 + x_3, x_1 + 4x_2 + x_3, x_1 + x_2 + 4x_3)$
Precizați un reper în raport cu care matricea asociată lui f este diagonală.

Ex $\mathcal{R}_0 = \{e_1^0, e_2^0, e_3^0\}$, $A = [f]_{\mathcal{R}_0, \mathcal{R}_0} = \begin{pmatrix} 4 & 1 & 1 \\ 1 & 4 & 1 \\ 1 & 1 & 4 \end{pmatrix}$

$$P(\lambda) = \det(A - \lambda I_3) = \begin{vmatrix} 4-\lambda & 1 & 1 \\ 1 & 4-\lambda & 1 \\ 1 & 1 & 4-\lambda \end{vmatrix} = (6-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ 1 & 4-\lambda & 1 \\ 1 & 1 & 4-\lambda \end{vmatrix} =$$

$$= (6-\lambda) \begin{vmatrix} 1 & 0 & 0 \\ 0 & 3-\lambda & 0 \\ 0 & 0 & 3-\lambda \end{vmatrix} \quad \begin{matrix} e_1' = e_1 + e_2 + e_3 \\ \end{matrix}$$

$$\lambda_1 = 6, m_1 = 1; \quad \lambda_2 = 3, m_2 = 2$$

$$V_{\lambda_1} = \{x \in \mathbb{R}^3 \mid f(x) = 6x\} = \{(x_3, x_3, x_3) \mid x_3 \in \mathbb{R}\} = \langle (1, 1, 1) \rangle$$

$$\begin{cases} 4x_1 + x_2 + x_3 = 6x_1 \\ x_1 + 4x_2 + x_3 = 6x_2 \\ x_1 + x_2 + 4x_3 = 6x_3 \end{cases} \Rightarrow \begin{cases} -2x_1 + x_2 + x_3 = 0 \\ x_1 - 2x_2 + x_3 = 0 \\ x_1 + x_2 - 2x_3 = 0 \end{cases} \quad M = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$\det M = 0$$

$$\begin{cases} -2x_1 + x_2 = -x_3 \\ x_1 - 2x_2 = -x_3 \end{cases} \quad \begin{matrix} 2 \\ 2 \end{matrix}$$

$$x_1 = x_3$$

$$x_2 = -x_3 + 2x_3 = x_3$$

$$-3x_1 \neq -3x_3 \quad \textcircled{+}$$

$$\mathcal{R}_1 = \{(1, 1, 1)\} \text{ reper în } V_{\lambda_1}, \dim V_{\lambda_1} = 1 = m_1$$

$$V_{\lambda_2} = \{x \in \mathbb{R}^3 \mid f(x) = 3x\} = \{(x_1, x_2, -x_1 - x_2) \mid x_1, x_2 \in \mathbb{R}\}$$

$$\begin{cases} 4x_1 + x_2 + x_3 = 3x_1 \\ x_1 + 4x_2 + x_3 = 3x_2 \\ x_1 + x_2 + 4x_3 = 3x_3 \end{cases} \Rightarrow \begin{matrix} x_1 + x_2 + x_3 = 0 \\ x_1 + x_2 + x_3 = 0 \\ x_1 + x_2 + x_3 = 0 \end{matrix} \Rightarrow x_3 = -x_1 - x_2$$

$$V_{\lambda_2} = \langle (1, 0, -1), (0, 1, -1) \rangle, \operatorname{rg} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ -1 & -1 \end{pmatrix} = 2 = \max$$

$$\mathcal{R}_2 = \{(1, 0, -1), (0, 1, -1)\} \text{ reper în } V_{\lambda_2}, \dim V_{\lambda_2} = m_2 = 2.$$

$\mathcal{R} = \mathcal{R}_1 \cup \mathcal{R}_2 = \left\{ \overbrace{(1,1,1)}^{(1,1,1)}, (1,0,-1), (0,1,-1) \right\}$ reper în \mathbb{R}^3 cu

$$A' = [f]_{\mathcal{R}, \mathcal{R}} = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

Ex $f \in \text{End}(\mathbb{R}^3)$

Fre $\lambda_1 = 3, \lambda_2 = -2, \lambda_3 = 1$ valorile proprii ale lui f
si $v_1 = (-3, 2, 1), v_2 = (-2, 1, 0), v_3 = (-6, 3, 1)$ sunt
vectori proprii coresp. valorilor proprii $\lambda_1, \lambda_2, \text{resp } \lambda_3$.

Să se determine $A = [f]_{\mathcal{R}_0, \mathcal{R}_0}$, $\mathcal{R}_0 = \text{reperul}$
canonic din \mathbb{R}^3 .

SOL $f(v_1) = \lambda_1 v_1 ; f(v_2) = \lambda_2 v_2, f(v_3) = \lambda_3 v_3.$

v_1, v_2, v_3 sunt vect. pr. coresp. la valori pr. dist \Rightarrow

$\Rightarrow \mathcal{R} = \{v_1, v_2, v_3\}$ S.L. $\Rightarrow \mathcal{R}$ reper în \mathbb{R}^3 .

dat $\dim \mathbb{R}^3 = |\mathcal{R}|$

$$A' = [f]_{\mathcal{R}, \mathcal{R}} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathcal{R}_0 = \{e_1, e_2, e_3\} \xrightarrow{C} \mathcal{R} = \{v_1, v_2, v_3\}$$

$$v_1 = (-3, 2, 1) = -3e_1 + 2e_2 + e_3 \quad C = \begin{pmatrix} -3 & -2 & -6 \\ 2 & 1 & 3 \\ 1 & 0 & 1 \end{pmatrix}$$

$$v_2 = (-2, 1, 0) = -2e_1 + e_2$$

$$v_3 = (-6, 3, 1) = -6e_1 + 3e_2 + e_3$$

$$A = [f]_{\mathcal{R}_0, \mathcal{R}_0} \rightsquigarrow A' = [f]_{\mathcal{R}, \mathcal{R}}.$$

(M₁) $A' = C^{-1}AC \Rightarrow A = CA'C^{-1}$

(M₂) $\begin{cases} f(v_1) = f(-3e_1 + 2e_2 + e_3) = -3f(e_1) + 2f(e_2) + f(e_3) = 3(-3, 2, 1) \\ f(v_2) = f(-2e_1 + e_2) = -2f(e_1) + f(e_2) = -2(-2, 1, 0) \\ f(v_3) = f(-6e_1 + 3e_2 + e_3) = -6f(e_1) + 3f(e_2) + f(e_3) = 1(-6, 3, 1) \end{cases}$

$$\text{ec } 1 - \text{ec } 3 : \begin{cases} 3f(e_1) - f(e_2) = (9+6, 6-3, 3-1) = (-3, 3, 2) \\ -2f(e_1) + f(e_2) = (4, -2, 0) \\ f(e_1) = (1, 1, 2) \end{cases} \oplus$$

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$$\begin{cases} f(e_1) = (1, 1, 2) \\ f(e_2) = (4, -2, 0) + 2(1, 1, 2) = (6, 0, 4) \\ f(e_3) = (-9, 6, 3) + 3(1, 1, 2) - 2(6, 0, 4) \\ \quad = (-9+3-12, 6+3, 3+6-8) = (-18, 9, 1) \end{cases}$$

$$\begin{cases} f(e_1) = e_1 + e_2 + 2e_3 \\ f(e_2) = 6e_1 + 4e_3 \\ f(e_3) = -18e_1 + 9e_2 + e_3 \end{cases} \quad A = [f]_{R_0, R_0} = \begin{pmatrix} 1 & 6 & -18 \\ 0 & 0 & 9 \\ 2 & 4 & 1 \end{pmatrix}$$

Ex $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x) = (x_2, x_3, 2x_1 - 5x_2 + 4x_3)$

Să se arate că f nu este diagonalizabil

Sol R_0 reper canonic $A = [f]_{R_0, R_0} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{pmatrix}$

$$P(\lambda) = \det(A - \lambda I_3) = 0 \Rightarrow \begin{vmatrix} -\lambda & 1 & 0 \\ 0 & -\lambda & 1 \\ 2 & -5 & 4-\lambda \end{vmatrix} = 0$$

$$\lambda^3 - \sigma_1 \lambda^2 + \sigma_2 \lambda - \sigma_3 = 0$$

$$\sigma_1 = \text{Tr} A = 4, \quad \sigma_2 = \begin{vmatrix} 0 & 1 \\ -5 & 4 \end{vmatrix} + \begin{vmatrix} 0 & 0 \\ 2 & 4 \end{vmatrix} + \begin{vmatrix} 0 & 1 \\ 0 & 0 \end{vmatrix} = 5$$

$$\sigma_3 = \det(A) = \begin{vmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{vmatrix} = - \begin{vmatrix} 0 & 1 \\ 2 & 4 \end{vmatrix} = 2$$

$$\lambda^3 - 4\lambda^2 + 5\lambda - 2 = 0 \Rightarrow \lambda^3 - \lambda^2 - 3\lambda^2 + 3\lambda + 2\lambda - 2 = 0$$

$$(\lambda-1)(\lambda^2-3\lambda+2) = 0 \Rightarrow (\lambda-1)^2(\lambda+2) = 0$$

$$\lambda_1 = 1, m_1 = 2; \quad \lambda_2 = -2, m_1 = 1$$

$$V_{\lambda_1} = \{x \in \mathbb{R}^3 \mid f(x) = x\} = \{(x_2, x_2, x_2) \mid x_2 \in \mathbb{R}\} = \langle \{(1, 1, 1)\} \rangle$$

$$\begin{cases} x_2 = x_1 \\ x_3 = x_2 \end{cases}$$

$$2x_1 - 5x_2 + 4x_3 = x_3 \Rightarrow 2x_1 - 5x_2 + 3x_3 = 0$$

$$\dim V_{\lambda_1} = 1 \neq \frac{m_1}{2} \Rightarrow f \text{ nu e diagonalizabil}$$

Forme biliniare

Ex1

$g: \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$ formă biliniară antisimetrică
 $R_0 = \{e_1, e_2\}$ reper canonic și $g(e_1, e_2) = 5$
 Care este matricea asociată lui g în raport cu
 reperul canonic?

SOL
 (CBS) $g: V \times V \rightarrow \mathbb{K}$ s.n. formă biliniară \Leftrightarrow liniară în
 ambeli argumente.

simetrică: $g(x, y) = g(y, x) \Leftrightarrow G = G^T$

antisimetrică: $g(x, y) = -g(y, x) \Leftrightarrow G = -G^T$

$R = \{e_1, \dots, e_n\}$ reper în V

$$G = (g_{ij})_{i,j=1,\dots,n}, \quad g_{ij} = g(e_i, e_j); \quad g(x, y) = \sum_{i,j=1}^n g_{ij} x_i y_j$$

$$G = \begin{pmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} = -G^T \rightarrow G = \begin{pmatrix} 0 & g_{12} \\ -g_{12} & 0 \end{pmatrix} = \begin{pmatrix} 0 & 5 \\ -5 & 0 \end{pmatrix}$$

$$g_{12} = g(e_1, e_2) = 5$$

$$g(x, y) = \sum_{i,j=1}^2 g_{ij} x_i y_j = 5x_1 y_2 - 5x_2 y_1$$

Ex2 $g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, \quad g(x, y) = x_1 y_1 - x_2 y_2 - x_1 y_3 - x_3 y_1 + 2x_2 y_3 + 2x_3 y_2$

a) $g \in L^s(\mathbb{R}^3, \mathbb{R}^3; \mathbb{R})$ (formă biliniară, simetrică)

b) Precizați matricea G asociată lui g în raport cu
 reperul canonic R_0

c) $\ker g = ?$ Este p nedegenerată?

d) Să se afle matricea G' asociată lui g în raport
 cu reperul $R' = \{e'_1 = (1, 1, 1), e'_2 = (1, 2, 1), e'_3 = (0, 0, 1)\}$.

e) Să se afle forma pătratică $Q: \mathbb{R}^3 \rightarrow \mathbb{R}$
 asociată lui g .

SOL

a) • g simetrică: $g(x,y) = g(y,x), \forall x,y \in \mathbb{R}^3$

$$g(x,y) = x_1 y_1 - x_2 y_2 - x_1 y_3 - x_3 y_1 + 2x_2 y_3 + 2x_3 y_2$$

• g liniară în primul arg.

$$g(ax+by, z) = ag(x,z) + bg(y,z)$$

$$(ax_1+by_1) \cdot z_1 - (ax_2+by_2) z_2 - (ax_1+by_1) z_3 - (ax_3+by_3) z_1 + 2(ax_2+by_2) z_3 + 2(ax_3+by_3) z_2 =$$

$$= ag(x,z) + bg(y,z)$$

$\Rightarrow g$ liniară și în al doilea arg.

$$\Rightarrow g \in L^s(\mathbb{R}^3, \mathbb{R}^3; \mathbb{R})$$

b)

$$G = \begin{pmatrix} 1 & 0 & -1 \\ 0 & -1 & 2 \\ -1 & 2 & 0 \end{pmatrix}$$

$$g(x,y) = X^T G Y$$

$$X = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, Y = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$$

$$g(e_i, e_j) = g_{ij}$$

$$g_{11} = g(e_1, e_1) = g((1,0,0), (1,0,0)) = 1, \dots, g_{33} = 0$$

$$c) \text{Ker } g = \{x \in \mathbb{R}^3 \mid g(x,y) = 0, \forall y \in \mathbb{R}^3\}$$

$$g \text{ nedegenerată} \Leftrightarrow \text{Ker } g = \{0_{\mathbb{R}^3}\} \Leftrightarrow G \in GL(3, \mathbb{R})$$

$$\det G = \begin{vmatrix} 1 & 0 & -1 \\ 0 & -1 & 2 \\ -1 & 2 & 0 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & -1 & 2 \\ -1 & 2 & -1 \end{vmatrix} = 1 - 4 = -3 \neq 0$$

(SAU)

$$\begin{cases} g(x, e_1) = 0 \\ g(x, e_2) = 0 \\ g(x, e_3) = 0 \end{cases} \Rightarrow \begin{cases} g((x_1, x_2, x_3), (1, 0, 0)) = x_1 - x_3 = 0 \\ g((x_1, x_2, x_3), (0, 1, 0)) = -x_2 + 2x_3 = 0 \\ g((x_1, x_2, x_3), (0, 0, 1)) = -x_1 + 2x_2 = 0 \end{cases}$$

$$G = \begin{pmatrix} 1 & 0 & -1 \\ 0 & -1 & 2 \\ -1 & 2 & 0 \end{pmatrix} \det G \neq 0 \Rightarrow x_1 = x_2 = x_3 = 0 \Rightarrow x = 0_{\mathbb{R}^3}$$

$$d) \mathcal{R}_0 = \{e_1, e_2, e_3\} \xrightarrow{-\frac{1}{C}} \mathcal{R}' = \{e'_1 = (1, 1, 1), e'_2 = (1, 2, 1), e'_3 = (0, 0, 1)\}$$

$$\begin{matrix} \downarrow \\ G \end{matrix} \quad \begin{matrix} \downarrow \\ G' \end{matrix}; C = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$G' = C^T G C$$

$$G' = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & -1 & 2 \\ -1 & 2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 1 & 1 & 1 \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 0 & -1 \\ 1 & 0 & 2 \\ 1 & 3 & 0 \end{pmatrix} \Rightarrow G' = \begin{pmatrix} 2 & 3 & 1 \\ 3 & 3 & 3 \\ 1 & 3 & 0 \end{pmatrix}$$

$$x = \sum_{i=1}^3 x'_i e'_i, y = \sum_{j=1}^3 y'_j e'_j$$

$$g(x, y) = 2x'_1 y'_1 + 3x'_1 y'_2 + x'_1 y'_3 + 3x'_2 y'_1 + 3x'_2 y'_2 + 3x'_2 y'_3 + x'_3 y'_1 + 3x'_3 y'_2$$

$$\textcircled{\text{obs}} g'_{ij} = g(e'_i, e'_j), \forall i, j = \overline{1, 3}$$

$$g'_{11} = g(e'_1, e'_1) = g((1, 1, 1), (1, 1, 1)) = 1 + 1 + 1 + 1 + 2 + 2 = 2$$

$$g(x, y) = x_1 y_1 - x_2 y_2 - x_1 y_3 - x_3 y_1 + 2x_2 y_3 + 2x_3 y_2$$

$$e) \frac{24}{24} Q: V \rightarrow \mathbb{K} \text{ a.n. } \underline{\text{formă pătratică}} \Leftrightarrow$$

$$\exists g: V \times V \rightarrow \mathbb{K} \text{ formă biliniară simetrică}$$

$$\text{at } Q(x) = g(x, x)$$

$$Q(x) = g(x, x) = x_1^2 - x_2^2 - 2x_1 x_3 + 4x_2 x_3$$

(Ex) $f \in \text{End}(\mathbb{R}^3)$, $g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$ formă biliniară
 Fie $g_f: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$, $g_f(x, y) = g(f(x), y)$, $\forall x, y \in \mathbb{R}^3$

a) g_f formă biliniară

b) Dacă $G = \begin{pmatrix} 2 & 1 & 0 \\ 0 & -1 & 0 \\ -2 & -1 & -1 \end{pmatrix}$ este matricea asociată
 lui g în rap. cu \mathcal{R}_0 și $A = \begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & -1 \\ 1 & 0 & 1 \end{pmatrix} = [f]_{\mathcal{R}_0, \mathcal{R}_0}$,
 să se determine matricea asociată lui g_f în
 raport cu \mathcal{R}_0 .

SOL a) $g_f: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$, $g_f(x, y) = g(f(x), y)$

$$\bullet g_f(ax+by, z) = g(f(ax+by), z) = g(a f(x) + b f(y), z) \\ = a g(f(x), z) + b g(f(y), z) = a g_f(x, z) + b g_f(y, z)$$

$$\bullet g_f(x, ay+bz) = g(f(x), ay+bz) = a g(f(x), y) + b g(f(x), z) \\ = a g_f(x, y) + b g_f(x, z)$$

$$b) g_f(e_i, e_j) = g(\underline{f(e_i)}, e_j) = g\left(\sum_{k=1}^3 a_{ki} e_k, e_j\right) =$$

$$\tilde{g}_{ij} = \sum_{k=1}^3 a_{ki} g(e_k, e_j) \Rightarrow$$

$$\tilde{g}_{ij} = \sum_{k=1}^3 a_{ki} g_{kj} \Rightarrow \tilde{G} = A^T G$$

$$= \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 0 \\ 0 & -1 & 0 \\ -2 & -1 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & -1 \\ -2 & -2 & 0 \\ 0 & 1 & -1 \end{pmatrix}$$

Obs $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$, $f(x) = (x_1 - x_2 + x_3, x_2 - x_3, x_1 + x_3)$

$$\bullet g: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, g(x, y) = 2x_1 y_1 + x_1 y_2 - x_2 y_2 - 2x_3 y_1 - x_3 y_2 - x_3 y_3$$

$$\bullet g_f: \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}, g_f(x, y) = -x_1 y_3 - 2x_2 y_1 - 2x_2 y_2 + x_3 y_2 - x_3 y_3.$$