

# Template

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# 1 Geo

## 1.1 Geo\_jls

```

int cmp(db k1,db k2){return sign(k1-k2);}
int inmid(db k1,db k2,db k3){return sign(k1-k3)*sign(k2-k3)<=0;}// k3 在 [k1,k2] 内
struct point{
    db x,y;
    point operator + (const point &k1) const{return (point){k1.x+x,k1.y+y};}
    point operator - (const point &k1) const{return (point){x-k1.x,y-k1.y};}
    point operator * (db k1) const{return (point){x*k1,y*k1};}
    point operator / (db k1) const{return (point){x/k1,y/k1};}
    int operator == (const point &k1) const{return cmp(x,k1.x)==0&&cmp(y,k1.y)==0;}
    // 逆时针旋转
    point turn(db k1){return (point){x*cos(k1)-y*sin(k1),x*sin(k1)+y*cos(k1);}
    point turn90(){return (point){-y,x};}
    bool operator < (const point k1) const{
        int a=cmp(x,k1.x);
        if (a==1) return 1; else if (a==1) return 0; else return cmp(y,k1.y)==-1;
    }
    db abs(){return sqrt(x*x+y*y);}
    db abs2(){return x*x+y*y;}
    db dis(point k1){return ((*this)-k1).abs();}
    point unit(){db w=abs(); return (point){x/w,y/w};}
    void scan(){double k1,k2; scanf("%lf%lf",&k1,&k2); x=k1; y=k2;}
    void print(){printf("%.11lf %.11lf\n",x,y);}
    db getw(){return atan2(y,x);}
    point getdel(){if (sign(x)==-1||(sign(x)==0&&sign(y)==-1)) return (*this)*(-1); else return (*this);}
    int getP() const{return sign(y)==1||(sign(y)==0&&sign(x)==-1);}
};

int inmid(point k1,point k2,point k3){return inmid(k1.x,k2.x,k3.x)&&inmid(k1.y,k2.y,k3.y);}
db cross(point k1,point k2){return k1.x*k2.y-k1.y*k2.x;}
db dot(point k1,point k2){return k1.x*k2.x+k1.y*k2.y;}
db rad(point k1,point k2){return atan2(cross(k1,k2),dot(k1,k2));}
// -pi -> pi
int compareangle (point k1,point k2){
    return k1.getP()<k2.getP()||(k1.getP()==k2.getP()&&sign(cross(k1,k2))>0);
}

point proj(point k1,point k2,point q){ // q 到直线 k1,k2 的投影
    point k=k2-k1; return k1+k*(dot(q-k1,k)/k.abs2());
}

point reflect(point k1,point k2,point q){return proj(k1,k2,q)*2-q;}
int clockwise(point k1,point k2,point k3){// k1 k2 k3 逆时针 1 顺时针 -1 否则 0
    return sign(cross(k2-k1,k3-k1));
}

int checkLL(point k1,point k2,point k3,point k4){// 求直线 (L) 线段 (S)k1,k2 和 k3,k4 的交点
    return cmp(cross(k3-k1,k4-k1),cross(k3-k2,k4-k2))!=0;
}

point getLL(point k1,point k2,point k3,point k4){
    db w1=cross(k1-k3,k4-k3),w2=cross(k4-k3,k2-k3); return (k1*w2+k2*w1)/(w1+w2);
}

int intersect(db l1,db r1,db l2,db r2){
    if (l1>r1) swap(l1,r1); if (l2>r2) swap(l2,r2); return cmp(r1,l2)!=-1&&cmp(r2,l1)!=-1;
}

int checkSS(point k1,point k2,point k3,point k4){
    return intersect(k1.x,k2.x,k3.x,k4.x)&&intersect(k1.y,k2.y,k3.y,k4.y)&&
    sign(cross(k3-k1,k4-k1))*sign(cross(k3-k2,k4-k2))<=0&&
    sign(cross(k1-k3,k2-k3))*sign(cross(k1-k4,k2-k4))<=0;
}

db disSP(point k1,point k2,point q){
    point k3=proj(k1,k2,q);
    if (inmid(k1,k2,k3)) return q.dis(k3); else return min(q.dis(k1),q.dis(k2));
}

db disSS(point k1,point k2,point k3,point k4){
    if (checkSS(k1,k2,k3,k4)) return 0;
    else return min(min(disSP(k1,k2,k3),disSP(k1,k2,k4)),min(disSP(k3,k4,k1),disSP(k3,k4,k2)));
}

int onS(point k1,point k2,point q){return inmid(k1,k2,q)&&sign(cross(k1-q,k2-k1))==0;}

struct circle{
    point o; db r;
    void scan(){o.scan(); scanf("%lf",&r);}
    int inside(point k){return cmp(r,o.dis(k));}
};

struct line{
    // p[0]->p[1]
    point p[2];
    line(point k1,point k2){p[0]=k1; p[1]=k2;}
    point& operator [] (int k){return p[k];}
    int include(point k){return sign(cross(p[1]-p[0],k-p[0]))>0;}
    point dir(){return p[1]-p[0];}
    line push(){ // 向外 ( 左边 ) 平移 eps
        const db eps = 1e-6;

```

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    point delta=(p[1]-p[0]).turn90().unit()*eps;
    return {p[0]-delta,p[1]-delta};
}
};
point getLL(line k1,line k2){return getLL(k1[0],k1[1],k2[0],k2[1]);}
int parallel(line k1,line k2){return sign(cross(k1.dir(),k2.dir()))==0;}
int sameDir(line k1,line k2){return parallel(k1,k2)&&sign(dot(k1.dir(),k2.dir()))==1;}
int operator < (line k1,line k2){
    if (sameDir(k1,k2)) return k2.include(k1[0]);
    return compareangle(k1.dir(),k2.dir());
}
int checkpos(line k1,line k2,line k3){return k3.include(getLL(k1,k2));}
vector<line> getHL(vector<line> &L){ // 求半平面交 , 半平面是逆时针方向 , 输出按照逆时针
    sort(L.begin(),L.end()); deque<line> q;
    for (int i=0;i<(int)L.size();i++){
        if (i&&sameDir(L[i],L[i-1])) continue;
        while (q.size()>1&&!checkpos(q[q.size()-2],q[q.size()-1],L[i])) q.pop_back();
        while (q.size()>1&&!checkpos(q[q.size()-1],q[q.size()-2],L[i])) q.pop_front();
        q.push_back(L[i]);
    }
    while (q.size()>2&&!checkpos(q[q.size()-2],q[q.size()-1],q[0])) q.pop_back();
    while (q.size()>2&&!checkpos(q[q.size()-1],q[q.size()-2],q[0])) q.pop_front();
    vector<line>ans; for (int i=0;i<q.size();i++) ans.push_back(q[i]);
    return ans;
}
db closepoint(vector<point>&A,int l,int r){ // 最近点对 , 先要按照 x 坐标排序
    if (r-l<=5){
        db ans=1e20;
        for (int i=l;i<=r;i++) for (int j=i+1;j<=r;j++) ans=min(ans,A[i].dis(A[j]));
        return ans;
    }
    int mid=l+r>>1; db ans=min(closepoint(A,l,mid),closepoint(A,mid+1,r));
    vector<point>B; for (int i=l;i<=r;i++) if (abs(A[i].x-A[mid].x)<=ans) B.push_back(A[i]);
    sort(B.begin(),B.end(),[](point k1,point k2){return k1.y<k2.y;});
    for (int i=0;i<B.size();i++) for (int j=i+1;j<B.size()&&B[j].y-B[i].y<ans;j++) ans=min(ans,B[i].dis(B[j]));
    return ans;
}
int checkposCC(circle k1,circle k2){// 返回两个圆的公切线数量
    if (cmp(k1.r,k2.r)==-1) swap(k1,k2);
    db dis=k1.o.dis(k2.o); int w1=cmp(dis,k1.r+k2.r),w2=cmp(dis,k1.r-k2.r);
    if (w1>0) return 4; else if (w1==0) return 3; else if (w2>0) return 2;
    else if (w2==0) return 1; else return 0;
}
vector<point> getCL(circle k1,point k2,point k3){ // 沿着 k2->k3 方向给出 , 相切给出两个
    point k=proj(k2,k3,k1.o); db d=k1.r*k1.r-(k-k1.o).abs2();
    if (sign(d)==-1) return {};
    point del=(k3-k2).unit()*sqrt(max((db)0.0,d)); return {k-del,k+del};
}
vector<point> getCC(circle k1,circle k2){// 沿圆 k1 逆时针给出 , 相切给出两个
    int pd=checkposCC(k1,k2); if (pd==0||pd==4) return {};
    db a=(k2.o-k1.o).abs2(),cosA=(k1.r*k1.r+a-k2.r*k2.r)/(2*k1.r*sqrt(max(a,(db)0.0)));
    db b=k1.r*cosA,c=sqrt(max((db)0.0,k1.r*k1.r-b*b));
    point k=(k2.o-k1.o).unit(),m=k1.o+k*b,del=k.turn90()*c;
    return {m-del,m+del};
}
vector<point> TangentCP(circle k1,point k2){// 沿圆 k1 逆时针给出
    db a=(k2-k1.o).abs(),b=k1.r*k1.r/a,c=sqrt(max((db)0.0,k1.r*k1.r-b*b));
    point k=(k2-k1.o).unit(),m=k1.o+k*b,del=k.turn90()*c;
    return {m-del,m+del};
}
vector<line> TangentoutCC(circle k1,circle k2){
    int pd=checkposCC(k1,k2); if (pd==0) return {};
    if (pd==1){point k=getCC(k1,k2)[0]; return {(line){k,k}};}
    if (cmp(k1.r,k2.r)==0){
        point del=(k2.o-k1.o).unit().turn90().getdel();
        return {(line){k1.o-del*k1.r,k2.o-del*k2.r},{k1.o+del*k1.r,k2.o+del*k2.r}};
    } else {
        point p=(k2.o*k1.r-k1.o*k2.r)/(k1.r-k2.r);
        vector<point>A=TangentCP(k1,p),B=TangentCP(k2,p);
        vector<line>ans; for (int i=0;i<A.size();i++) ans.push_back((line){A[i],B[i]});
        return ans;
    }
}
vector<line> TangentinCC(circle k1,circle k2){
    int pd=checkposCC(k1,k2); if (pd<=2) return {};
    if (pd==3){point k=getCC(k1,k2)[0]; return {(line){k,k}};}
    point p=(k2.o*k1.r+k1.o*k2.r)/(k1.r+k2.r);
    vector<point>A=TangentCP(k1,p),B=TangentCP(k2,p);
    vector<line>ans; for (int i=0;i<A.size();i++) ans.push_back((line){A[i],B[i]});
    return ans;
}
vector<line> TangentCC(circle k1,circle k2){

```

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    int flag=0; if (k1.r<k2.r) swap(k1,k2),flag=1;
    vector<line>A=TangentoutCC(k1,k2),B=TangentinCC(k1,k2);
    for (line k:B) A.push_back(k);
    if (flag) for (line &k:A) swap(k[0],k[1]);
    return A;
}
db getarea(circle k1,point k2,point k3){
    // 圆 k1 与三角形 k2 k3 k1.o 的有向面积交
    point k=k1.o; k1.o=k1.o-k; k2=k2-k; k3=k3-k;
    int pd1=k1.inside(k2),pd2=k1.inside(k3);
    vector<point>A=getCL(k1,k2,k3);
    if (pd1>=0){
        if (pd2>=0) return cross(k2,k3)/2;
        return k1.r*k1.r*rad(A[1],k3)/2+cross(k2,A[1])/2;
    } else if (pd2>=0){
        return k1.r*k1.r*rad(k2,A[0])/2+cross(A[0],k3)/2;
    } else {
        int pd=cmp(k1.r,disSP(k2,k3,k1.o));
        if (pd<=0) return k1.r*k1.r*rad(k2,k3)/2;
        return cross(A[0],A[1])/2+k1.r*k1.r*(rad(k2,A[0])+rad(A[1],k3))/2;
    }
}
circle getcircle(point k1,point k2,point k3){
    db a1=k2.x-k1.x,b1=k2.y-k1.y,c1=(a1*a1+b1*b1)/2;
    db a2=k3.x-k1.x,b2=k3.y-k1.y,c2=(a2*a2+b2*b2)/2;
    db d=a1*b2-a2*b1;
    point o=(point){k1.x+(c1*b2-c2*b1)/d,k1.y+(a1*c2-a2*c1)/d};
    return (circle){o,k1.dis(o)};
}
circle getScircle(vector<point> A){
    random_shuffle(A.begin(),A.end());
    circle ans=(circle){A[0],0};
    for (int i=1;i<A.size();i++){
        if (ans.inside(A[i])==-1){
            ans=(circle){A[i],0};
            for (int j=0;j<i;j++){
                if (ans.inside(A[j])==-1){
                    ans.o=(A[i]+A[j])/2; ans.r=ans.o.dis(A[i]);
                    for (int k=0;k<j;k++){
                        if (ans.inside(A[k])==-1)
                            ans=getcircle(A[i],A[j],A[k]);
                    }
                }
            }
        }
    }
    return ans;
}
db area(vector<point> A){ // 多边形用 vector<point> 表示 , 逆时针
    db ans=0;
    for (int i=0;i<A.size();i++) ans+=cross(A[i],A[(i+1)%A.size()]);
    return ans/2;
}
int checkconvex(vector<point>A){
    int n=A.size(); A.push_back(A[0]); A.push_back(A[1]);
    for (int i=0;i<n;i++) if (sign(cross(A[i+1]-A[i],A[i+2]-A[i]))==-1) return 0;
    return 1;
}
int contain(vector<point>A,point q){ // 2 内部 1 边界 0 外部
    int pd=0; A.push_back(A[0]);
    for (int i=1;i<A.size();i++){
        point u=A[i-1],v=A[i];
        if (onS(u,v,q)) return 1; if (cmp(u.y,v.y)>0) swap(u,v);
        if (cmp(u.y,q.y)>=0||cmp(v.y,q.y)<0) continue;
        if (sign(cross(u-v,q-v))<0) pd^=1;
    }
    return pd<=1;
}
vector<point> ConvexHull(vector<point>A,int flag=1){ // flag=0 不严格 flag=1 严格
    int n=A.size(); vector<point>ans(n*2);
    sort(A.begin(),A.end()); int now=-1;
    for (int i=0;i<A.size();i++){
        while (now>0&&sign(cross(ans[now]-ans[now-1],A[i]-ans[now-1]))<flag) now--;
        ans[++now]=A[i];
    } int pre=now;
    for (int i=n-2;i>=0;i--){
        while (now>pre&&sign(cross(ans[now]-ans[now-1],A[i]-ans[now-1]))<flag) now--;
        ans[++now]=A[i];
    } ans.resize(now); return ans;
}
db convexDiameter(vector<point>A){
    int now=0,n=A.size(); db ans=0;
    for (int i=0;i<A.size();i++){
        now=max(now,i);
        while (1){

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        db k1=A[i].dis(A[now%n]),k2=A[i].dis(A[(now+1)%n]);
        ans=max(ans,max(k1,k2)); if (k2>k1) now++; else break;
    }
}
return ans;
}
vector<point> convexcut(vector<point>A,point k1,point k2){
    // 保留 k1,k2,p 逆时针的所有点
    int n=A.size(); A.push_back(A[0]); vector<point>ans;
    for (int i=0;i<n;i++){
        int w1=clockwise(k1,k2,A[i]),w2=clockwise(k1,k2,A[i+1]);
        if (w1>=0) ans.push_back(A[i]);
        if (w1*w2<0) ans.push_back(getLL(k1,k2,A[i],A[i+1]));
    }
    return ans;
}
int checkPos(vector<point>A,point k1,point k2){
    // 多边形 A 和直线 ( 线段 )k1→k2 严格相交 , 注释部分为线段
    struct ins{
        point m,u,v;
        int operator < (const ins& k) const {return m<k.m;}
    }; vector<ins>B;
    //if (contain(A,k1)==2||contain(A,k2)==2) return 1;
    vector<point>poly=A; A.push_back(A[0]);
    for (int i=1;i<A.size();i++) if (checkLL(A[i-1],A[i],k1,k2)){
        point m=getLL(A[i-1],A[i],k1,k2);
        if (inmid(A[i-1],A[i],m)/ *&&inmid(k1,k2,m)*/) B.push_back((ins){m,A[i-1],A[i]});
    }
    if (B.size()==0) return 0; sort(B.begin(),B.end());
    int now=1; while (now<B.size()&&B[now].m==B[0].m) now++;
    if (now==B.size()) return 0;
    int flag=contain(poly,(B[0].m+B[now].m)/2);
    if (flag==2) return 1;
    point d=B[now].m-B[0].m;
    for (int i=now;i<B.size();i++){
        if (!(B[i].m==B[i-1].m)&&flag==2) return 1;
        int tag=sign(cross(B[i].v-B[i].u,B[i].m+d-B[i].u));
        if (B[i].m==B[i].u||B[i].m==B[i].v) flag+=tag; else flag+=tag*2;
    }
    //return 0;
    return flag==2;
}
int checkinp(point r,point l,point m){
    if (compareangle(l,r)){return compareangle(l,m)&&compareangle(m,r);}
    return compareangle(l,m)||compareangle(m,r);
}
int checkPosFast(vector<point>A,point k1,point k2){ // 快速检查线段是否和多边形严格相交
    if (contain(A,k1)==2||contain(A,k2)==2) return 1; if (k1==k2) return 0;
    A.push_back(A[0]); A.push_back(A[1]);
    for (int i=1;i+1<A.size();i++)
        if (checkLL(A[i-1],A[i],k1,k2)){
            point now=getLL(A[i-1],A[i],k1,k2);
            if (inmid(A[i-1],A[i],now)==0||inmid(k1,k2,now)==0) continue;
            if (now==A[i]){
                if (A[i]==k2) continue;
                point pre=A[i-1],ne=A[i+1];
                if (checkinp(pre-now,ne-now,k2-now)) return 1;
            } else if (now==k1){
                if (k1==A[i-1]||k1==A[i]) continue;
                if (checkinp(A[i-1]-k1,A[i]-k1,k2-k1)) return 1;
            } else if (now==k2||now==A[i-1]) continue;
            else return 1;
        }
    return 0;
}
// 拆分凸包成上下凸壳凸包尽量都随机旋转一个角度来避免出现相同横坐标
// 尽量特判只有一个点的情况凸包逆时针
void getUDP(vector<point>A,vector<point>&U,vector<point>&D){
    db l=1e100,r=-1e100;
    for (int i=0;i<A.size();i++) l=min(l,A[i].x),r=max(r,A[i].x);
    int wherel,wherer;
    for (int i=0;i<A.size();i++) if (cmp(A[i].x,l)==0) wherel=i;
    for (int i=A.size()-1;i>=0;i--) if (cmp(A[i].x,r)==0) wherer=i-1;
    U.clear(); D.clear(); int now=wherel;
    while (1){D.push_back(A[now]); if (now==wherer) break; now++; if (now>=A.size()) now=0;}
    now=wherel;
    while (1){U.push_back(A[now]); if (now==wherer) break; now--; if (now<0) now=A.size()-1;}
}
// 需要保证凸包点数大于等于 3,2 内部 ,1 边界 ,0 外部
int containCoP(const vector<point>&U,const vector<point>&D,point k){
    db lx=U[0].x,rx=U[U.size()-1].x;
    if (k==U[0]||k==U[U.size()-1]) return 1;

```

```

    if (cmp(k.x, lx) == -1 || cmp(k.x, rx) == 1) return 0;
    int where1 = lower_bound(U.begin(), U.end(), (point){k.x, -1e100}) - U.begin();
    int where2 = lower_bound(D.begin(), D.end(), (point){k.x, -1e100}) - D.begin();
    int w1 = clockwise(U[where1-1], U[where1], k), w2 = clockwise(D[where2-1], D[where2], k);
    if (w1 == 1 || w2 == -1) return 0; else if (w1 == 0 || w2 == 0) return 1; return 2;
}
// d 是方向, 输出上方切点和下方切点
pair<point, point> getTangentCow(const vector<point> &U, const vector<point> &D, point d){
    if (sign(d.x) < 0 || (sign(d.x) == 0 && sign(d.y) < 0)) d = d * (-1);
    point whereU, whereD;
    if (sign(d.x) == 0) return mp(U[0], U[U.size()-1]);
    int l=0, r=U.size()-1, ans=0;
    while (l<r){int mid=l+r>>1; if (sign(cross(U[mid+1]-U[mid], d)) <= 0) l=mid+1, ans=mid+1; else r=mid;}
    whereU=U[ans]; l=0, r=D.size()-1, ans=0;
    while (l<r){int mid=l+r>>1; if (sign(cross(D[mid+1]-D[mid], d)) >= 0) l=mid+1, ans=mid+1; else r=mid;}
    whereD=D[ans]; return mp(whereU, whereD);
}
// 先检查 contain, 逆时针给出
pair<point, point> getTangentCoP(const vector<point> &U, const vector<point> &D, point k){
    db lx=U[0].x, rx=U[U.size()-1].x;
    if (k.x < lx){
        int l=0, r=U.size()-1, ans=U.size()-1;
        while (l<r){int mid=l+r>>1; if (clockwise(k, U[mid], U[mid+1]) == 1) l=mid+1; else ans=mid, r=mid;}
        point w1=U[ans]; l=0, r=D.size()-1, ans=D.size()-1;
        while (l<r){int mid=l+r>>1; if (clockwise(k, D[mid], D[mid+1]) == -1) l=mid+1; else ans=mid, r=mid;}
        point w2=D[ans]; return mp(w1, w2);
    } else if (k.x > rx){
        int l=1, r=U.size(), ans=0;
        while (l<r){int mid=l+r>>1; if (clockwise(k, U[mid], U[mid-1]) == -1) r=mid; else ans=mid, l=mid+1;}
        point w1=U[ans]; l=1, r=D.size(), ans=0;
        while (l<r){int mid=l+r>>1; if (clockwise(k, D[mid], D[mid-1]) == 1) r=mid; else ans=mid, l=mid+1;}
        point w2=D[ans]; return mp(w2, w1);
    } else {
        int where1 = lower_bound(U.begin(), U.end(), (point){k.x, -1e100}) - U.begin();
        int where2 = lower_bound(D.begin(), D.end(), (point){k.x, -1e100}) - D.begin();
        if ((k.x == lx && k.y > U[0].y) || (where1 && clockwise(U[where1-1], U[where1], k) == 1)){
            int l=1, r=where1+1, ans=0;
            while (l<r){int mid=l+r>>1; if (clockwise(k, U[mid], U[mid-1]) == 1) ans=mid, l=mid+1; else r=mid;}
            point w1=U[ans]; l=where1, r=U.size()-1, ans=U.size()-1;
            while (l<r){int mid=l+r>>1; if (clockwise(k, U[mid], U[mid+1]) == 1) l=mid+1; else ans=mid, r=mid;}
            point w2=U[ans]; return mp(w2, w1);
        } else {
            int l=1, r=where2+1, ans=0;
            while (l<r){int mid=l+r>>1; if (clockwise(k, D[mid], D[mid-1]) == -1) ans=mid, l=mid+1; else r=mid;}
            point w1=D[ans]; l=where2, r=D.size()-1, ans=D.size()-1;
            while (l<r){int mid=l+r>>1; if (clockwise(k, D[mid], D[mid+1]) == -1) l=mid+1; else ans=mid, r=mid;}
            point w2=D[ans]; return mp(w1, w2);
        }
    }
}
}
}
struct P3{
    db x, y, z;
    P3 operator + (P3 k1){return (P3){x+k1.x, y+k1.y, z+k1.z};}
    P3 operator - (P3 k1){return (P3){x-k1.x, y-k1.y, z-k1.z};}
    P3 operator * (db k1){return (P3){x*k1, y*k1, z*k1};}
    P3 operator / (db k1){return (P3){x/k1, y/k1, z/k1};}
    db abs2(){return x*x+y*y+z*z;}
    db abs(){return sqrt(x*x+y*y+z*z);}
    P3 unit(){return (*this)/abs();}
    int operator < (const P3 k1) const{
        if (cmp(x, k1.x) != 0) return x < k1.x;
        if (cmp(y, k1.y) != 0) return y < k1.y;
        return cmp(z, k1.z) == -1;
    }
    int operator == (const P3 k1){
        return cmp(x, k1.x) == 0 && cmp(y, k1.y) == 0 && cmp(z, k1.z) == 0;
    }
    void scan(){
        double k1, k2, k3; scanf("%lf%lf%lf", &k1, &k2, &k3);
        x=k1; y=k2; z=k3;
    }
};
P3 cross(P3 k1, P3 k2){return (P3){k1.y*k2.z-k1.z*k2.y, k1.z*k2.x-k1.x*k2.z, k1.x*k2.y-k1.y*k2.x};}
db dot(P3 k1, P3 k2){return k1.x*k2.x+k1.y*k2.y+k1.z*k2.z;}
// p=(3, 4, 5), l=(13, 19, 21), theta=85 ans=(2.83, 4.62, 1.77)
P3 turn3D(db k1, P3 l, P3 p){
    l=l.unit(); P3 ans; db c=cos(k1), s=sin(k1);
    ans.x=p.x*(1.x*1.x*(1-c)+c)+p.y*(1.x*1.y*(1-c)-l.z*s)+p.z*(1.x*1.z*(1-c)+l.y*s);
    ans.y=p.x*(1.x*1.y*(1-c)+l.z*s)+p.y*(1.y*1.y*(1-c)+c)+p.z*(1.y*1.z*(1-c)-l.x*s);
    ans.z=p.x*(1.x*1.z*(1-c)-l.y*s)+p.y*(1.y*1.z*(1-c)+l.x*s)+p.z*(1.x*1.x*(1-c)+c);
    return ans;
}
}

```

```

typedef vector<P3> VP;
typedef vector<VP> VWP;
db Acos(db x){return acos(max(-(db)1,min(x,(db)1)));}
// 球面距离, 圆心原点, 半径 1
db Odist(P3 a,P3 b){db r=Acos(dot(a,b)); return r;}
db r; P3 rnd;
vector<db> solve(db a,db b,db c){
    db r=sqrt(a*a+b*b),th=atan2(b,a);
    if (cmp(c,-r)==-1) return {0};
    else if (cmp(r,c)<=0) return {1};
    else {
        db tr=pi-Acos(c/r); return {th+pi-tr,th+pi+tr};
    }
}
vector<db> jiao(P3 a,P3 b){
    // dot(rd+x*cos(t)+y*sin(t),b) >= cos(r)
    if (cmp(Odist(a,b),2*r)>0) return {0};
    P3 rd=a*cos(r),z=a.unit(),y=cross(z,rnd).unit(),x=cross(y,z).unit();
    vector<db> ret = solve(-(dot(x,b)*sin(r)),-(dot(y,b)*sin(r)),-(cos(r)-dot(rd,b)));
    return ret;
}
db norm(db x,db l=0,db r=2*pi){ // change x into [l,r)
    while (cmp(x,l)==-1) x+=(r-l); while (cmp(x,r)>=0) x--(r-l);
    return x;
}
db disLP(P3 k1,P3 k2,P3 q){
    return (cross(k2-k1,q-k1)).abs()/(k2-k1).abs();
}
db disLL(P3 k1,P3 k2,P3 k3,P3 k4){
    P3 dir=cross(k2-k1,k4-k3); if (sign(dir.abs())==0) return disLP(k1,k2,k3);
    return fabs(dot(dir.unit(),k1-k2));
}
VP getFL(P3 p,P3 dir,P3 k1,P3 k2){
    db a=dot(k2-p,dir),b=dot(k1-p,dir),d=a-b;
    if (sign(fabs(d))==0) return {};
    return {(k1*a-k2*b)/d};
}
VP getFF(P3 p1,P3 dir1,P3 p2,P3 dir2){// 返回一条线
    P3 e=cross(dir1,dir2),v=cross(dir1,e);
    db d=dot(dir2,v); if (sign(abs(d))==0) return {};
    P3 q=p1+v*dot(dir2,p2-p1)/d; return {q,q+e};
}
// 3D Convex Hull Template
db getV(P3 k1,P3 k2,P3 k3,P3 k4){ // get the Volume
    return dot(cross(k2-k1,k3-k1),k4-k1);
}
db rand_db(){return 1.0*rand()/RAND_MAX;}
VP convexHull2D(VP A,P3 dir){
    P3 x={(db)rand(),(db)rand(),(db)rand()}; x=x.unit();
    x=cross(x,dir).unit(); P3 y=cross(x,dir).unit();
    P3 vec=dir.unit()*dot(A[0],dir);
    vector<point>B;
    for (int i=0;i<A.size();i++) B.push_back((point){dot(A[i],x),dot(A[i],y)});
    B=ConvexHull(B); A.clear();
    for (int i=0;i<B.size();i++) A.push_back(x*B[i].x+y*B[i].y+vec);
    return A;
}
namespace CH3{
    VWP ret; set<pair<int,int> >e;
    int n; VP p,q;
    void wrap(int a,int b){
        if (e.find({a,b})==e.end()){
            int c=-1;
            for (int i=0;i<n;i++) if (i!=a&&i!=b){
                if (c==-1||sign(getV(q[c],q[a],q[b],q[i]))>0) c=i;
            }
            if (c!=-1){
                ret.push_back({p[a],p[b],p[c]});
                e.insert({a,b}); e.insert({b,c}); e.insert({c,a});
                wrap(c,b); wrap(a,c);
            }
        }
    }
}
VWP ConvexHull3D(VP _p){
    p=q=_p; n=p.size();
    ret.clear(); e.clear();
    for (auto &i:q) i=i+(P3){rand_db()*1e-4,rand_db()*1e-4,rand_db()*1e-4};
    for (int i=1;i<n;i++) if (q[i].x<q[0].x) swap(p[0],p[i]),swap(q[0],q[i]);
    for (int i=2;i<n;i++) if ((q[i].x-q[0].x)*(q[1].y-q[0].y)>(q[i].y-q[0].y)*(q[1].x-q[0].x)) swap(q[1],q[i]),swap(p[1],p[i]);
    wrap(0,1);
    return ret;
}

```

```

    }
}
VVP reduceCH(VVP A){
    VVP ret; map<P3,VP> M;
    for (VP nowF:A){
        P3 dir=cross(nowF[1]-nowF[0],nowF[2]-nowF[0]).unit();
        for (P3 k1:nowF) M[dir].pb(k1);
    }
    for (pair<P3,VP> nowF:M) ret.pb(convexHull2D(nowF.se,nowF.fi));
    return ret;
}
// 把一个面变成 ( 点 , 法向量 ) 的形式
pair<P3,P3> getF(VP F){
    return mp(F[0],cross(F[1]-F[0],F[2]-F[0]).unit());
}
// 3D Cut 保留 dot(dir,x-p)>=0 的部分
VVP ConvexCut3D(VVP A,P3 p,P3 dir){
    VVP ret; VP sec;
    for (VP nowF: A){
        int n=nowF.size(); VP ans; int dif=0;
        for (int i=0;i<n;i++){
            int d1=sign(dot(dir,nowF[i]-p));
            int d2=sign(dot(dir,nowF[(i+1)%n]-p));
            if (d1>=0) ans.pb(nowF[i]);
            if (d1*d2<0){
                P3 q=getFL(p,dir,nowF[i],nowF[(i+1)%n])[0];
                ans.push_back(q); sec.push_back(q);
            }
            if (d1==0) sec.push_back(nowF[i]); else dif=1;
            dif+=(sign(dot(dir,cross(nowF[(i+1)%n]-nowF[i],nowF[(i+1)%n]-nowF[i])))==-1);
        }
        if (ans.size()>0&&dif) ret.push_back(ans);
    }
    if (sec.size()>0) ret.push_back(convexHull2D(sec,dir));
    return ret;
}
db vol(VVP A){
    if (A.size()==0) return 0; P3 p=A[0][0]; db ans=0;
    for (VP nowF:A)
        for (int i=2;i<nowF.size();i++)
            ans+=abs(getV(p,nowF[0],nowF[i-1],nowF[i]));
    return ans/6;
}
VVP init(db INF) {
    VVP pss(6,VP(4));
    pss[0][0] = pss[1][0] = pss[2][0] = {-INF, -INF, -INF};
    pss[0][3] = pss[1][1] = pss[5][2] = {-INF, -INF, INF};
    pss[0][1] = pss[2][3] = pss[4][2] = {-INF, INF, -INF};
    pss[0][2] = pss[5][3] = pss[4][1] = {-INF, INF, INF};
    pss[1][3] = pss[2][1] = pss[3][2] = {INF, -INF, -INF};
    pss[1][2] = pss[5][1] = pss[3][3] = {INF, -INF, INF};
    pss[2][2] = pss[4][3] = pss[3][1] = {INF, INF, -INF};
    pss[5][0] = pss[4][0] = pss[3][0] = {INF, INF, INF};
    return pss;
}

```

## 2 Math

### 2.1 FT\_fft\_2D

```

const int _M = 2050, _N = N;
template <class V>
struct FT {
    struct cp { double x, y; } tmp[_M * 2 + 5]; cp aa[_M][_M], bb[_M][_M];
    friend cp operator + (cp &a, cp &b) { return cp{ a.x + b.x, a.y + b.y }; }
    friend cp operator - (cp &a, cp &b) { return cp{ a.x - b.x, a.y - b.y }; }
    friend cp operator * (cp &a, cp &b) { return cp{ a.x*b.x - a.y*b.y, a.x*b.y + a.y*b.x }; }
    cp get(double x) { return cp{ cos(x), sin(x) }; }
    void FFT(cp *a, int n, int op) {
        for (int i = (n >> 1), j = 1; j < n; j++) {
            if (i < j) swap(a[i], a[j]);
            int k; for (k = (n >> 1); k&i; i ^= k, k >>= 1); i ^= k;
        }
        for (int m = 2; m <= n; m <= 1) {
            cp w = get(2 * PI*op / m); tmp[0] = cp{ 1, 0 };
            for (int j = 1; j < (m >> 1); j++) tmp[j] = tmp[j - 1] * w;
            for (int i = 0; i < n; i += m)
                for (int j = i; j < i + (m >> 1); j++) {
                    cp u = a[j], v = a[j + (m >> 1)] * tmp[j - i];
                    a[j] = u + v, a[j + (m >> 1)] = u - v;
                }
        }
    }
}

```



```

    }
    if (op == -1) rep(i, 0, n) a[i] = cp{ a[i].x / n, a[i].y / n };
}
void FFT(cp a[][M], int n, int op) { rep(i, 0, n) FFT(a[i], n, op); }
template <class T>
void Transpose(T a[][M], int n) {
    rep(i, 0, n) rep(j, 0, i) swap(a[i][j], a[j][i]);
}
void Reverse(V a[][M], int n, int m) {
    rep(i, 0, (n - 1 >> 1) + 1) rep(j, 0, m) swap(a[i][j], a[n - 1 - i][j]);
    rep(i, 0, n) rep(j, 0, (m - 1 >> 1) + 1) swap(a[i][j], a[i][m - 1 - j]);
}
void Shift(V a[][M], int n, int m, int p, int q) {
    rep(i, n, n + p) rep(j, m, m + q) a[i - n][j - m] = a[i][j];
}
void In(cp p[][M], int len, V a[][M], int n, int m) {
    rep(i, 0, len) rep(j, 0, len) p[i][j] = cp{ i < n && j < m ? (double)a[i][j] : 0, 0 };
}
void Out(V a[][M], int n, int m, cp p[][M], int len) {
    rep(i, 0, n) rep(j, 0, m) a[i][j] = (V)(p[i][j].x + 0.5) % _p;
}
void Multiply(V A[][M], int n, V B[][M], int m, V C[][M], int &len, int op = 0) {
    if (op) Reverse(A, n, n);
    len = 1; while (len < n + m - 1) len <<= 1;
    In(aa, len, A, n, n), In(bb, len, B, m, m), FFT(aa, len, 1), FFT(bb, len, 1);
    Transpose(aa, len), Transpose(bb, len), FFT(aa, len, 1), FFT(bb, len, 1);
    rep(i, 0, len) rep(j, 0, len) aa[i][j] = aa[i][j] * bb[i][j];
    FFT(aa, len, -1), Transpose(aa, len), FFT(aa, len, -1), Out(C, len, len, aa, len);
    if (op) Shift(C, n - 1, n - 1, m, m), len = m, Reverse(A, n, n);
}
};

inline void Random(int a[][M], int n) {
    rep(i, 0, n) rep(j, 0, n) a[i][j] = rand();
}
}

```

## 2.2 FT\_fft\_2D\_使用说明

```

/*
* FT_fft_2D 使用说明
*
* 【接口说明】
*
* cp get(double x) : 获取一个辐角为 x 的复数
*
* void FFT(cp *a, int n, int op) : 变换接口, 注意: op=1 为正卷积, op=-1 为逆卷积
*
* void FFT(cp a[ ][M], int n, int op) : 行变换接口, 逐行进行正 / 逆变换
*
* void Transpose(T a[ ][M], int n) : 转置接口
*
* void Reverse(V a[ ][M], int n, int m) : 翻转接口
*
* void Shift(V a[ ][M], int n, int m, int p, int q) : 移位接口, 将矩阵 a 的 (n, m) 整体移到 (0, 0) 长度保留 p 和 q (长和宽)
*
* void In(cp p[ ][M], int len, V a[ ][M], int n, int m) : 数据填充接口
*
* void Out(V a[ ][M], int n, int m, cp p[ ][M], int len) : 数据提取接口
*
* void Multiply(V A[ ][M], int n, V B[ ][M], int m, V C[ ][M], int &len, int op=0) :
*
* 乘法接口, 表示 n * n 的矩阵 A 乘上 m * m 的矩阵 B, 结果放到 C 中, 规模为 len * len 且计算并返回到 len 中, op=1 为差卷积
*/

```

## 2.3 FT\_fft 基础版本

```

const int M = N, N = N;
template <class V>
struct FT {
    struct cp { double x, y; } tmp[M * 2 + 5];
    friend cp operator + (cp &a, cp &b) { return cp{ a.x + b.x, a.y + b.y }; }
    friend cp operator - (cp &a, cp &b) { return cp{ a.x - b.x, a.y - b.y }; }
    friend cp operator * (cp &a, cp &b) { return cp{ a.x*b.x - a.y*b.y, a.x*b.y + a.y*b.x }; }
    cp get(double x) { return cp{ cos(x), sin(x) }; }
    vector <cp> aa, bb;
    void FFT(vector <cp> &a, int n, int op) {
        for (int i = (n >> 1), j = 1; j < n; j++) {
            if (i < j) swap(a[i], a[j]);
            int k; for (k = (n >> 1); k & i; i ^= k, k >>= 1); i ^= k;
        }
        for (int m = 2; m <= n; m <<= 1) {
            cp w = get(2 * PI * op / m); tmp[0] = cp{ 1, 0 };

```

```

    for (int j = 1; j < (m >> 1); j++) tmp[j] = tmp[j - 1] * w;
    for (int i = 0; i < n; i += m)
        for (int j = i; j < i + (m >> 1); j++) {
            cp u = a[j], v = a[j + (m >> 1)] * tmp[j - i];
            a[j] = u + v, a[j + (m >> 1)] = u - v;
        }
    if (op == -1) rep(i, 0, n) a[i] = cp{ a[i].x / n, a[i].y / n };
}
vector<V> multiply(vector<V> A, vector<V> B, int op = 0) {
    if (op) reverse(all(A));
    int lena = A.size(), lenb = B.size(), len = 1;
    while (len < lena + lenb) len <= 1;
    aa = vector<cp>(len), bb = vector<cp>(len);
    rep(i, 0, lena) aa[i] = cp{ (double)A[i], 0 };
    rep(i, 0, lenb) bb[i] = cp{ (double)B[i], 0 };
    FFT(aa, len, 1), FFT(bb, len, 1);
    rep(i, 0, len) aa[i] = aa[i] * bb[i];
    FFT(aa, len, -1); A.clear();
    if (!op) rep(i, 0, len) A.pb((ll)(aa[i].x + 0.5)); else
        rep(i, lena - 1, lena + lenb - 2 + 1) A.pb((ll)(aa[i].x + 0.5));
    return A;
}
};

```

## 2.4 NTT\_2D

```

typedef vector<vector<int>> vii;

const int _M = N, _N = N;
template <class V>
struct FT {
    vector<V> aa, bb; int _p, K, _m, N; V w[2][_M * 2 + 5], rev[_M * 2 + 5], tmp, w0;
    inline void Init(int _K, int p) { K = _K, _p = p; }
    ll Pow(ll x, ll k, ll _p) { ll ans = 1; for (; k; k >>= 1, x = x*x%_p) if (k & 1) (ans *= x) %= _p; return ans; }
    inline void get_len(int a, int b, int &len, int &L) { len = 1, L = 0; while (len < a + b) len <= 1, ++L; }
    inline void init_w(int m) {
        N = 1 << m, w0 = Pow(3, (_p - 1) / N, _p); w[0][0] = w[1][0] = 1;
        rep(i, 1, N) w[0][i] = w[1][N - i] = (ll)w[0][i - 1] * w0%_p;
        rep(i, 1, N) rev[i] = (rev[i >> 1] >> 1) | (i & 1) << m - 1;
    }
    inline void FFT(vector<V>& A, int m, int op) {
        if (m != _m) init_w(_m = m);
        rep(i, 0, N) if (i < rev[i]) swap(A[i], A[rev[i]]);
        for (int i = 1; i < N; i <= 1)
            for (int j = 0, t = N / (i << 1); j < N; j += i << 1)
                for (int k = j, l = 0; k < j + i; k++, l += t) {
                    V x = A[k], y = (ll)w[op][l] * A[k + i] % _p;
                    A[k] = (x + y) % _p, A[k + i] = (x - y + _p) % _p;
                }
        if (op) { tmp = Pow(N, _p - 2, _p); rep(i, 0, N) A[i] = 1ll * A[i] * tmp%_p; }
    }
    inline void multiply(const vector<V>& A, const vector<V>& B, vector<V> *C) {
        int lena = A.size(), lenb = B.size(), len = 1, L = 0; aa = A, bb = B;
        get_len(lena, lenb, len, L), aa.resize(len), bb.resize(len);
        FFT(aa, L, 0), FFT(bb, L, 0), (*C).resize(len);
        rep(i, 0, len) (*C)[i] = (ll)aa[i] * bb[i] % _p;
        FFT(*C, L, 1); if (K < len - 1) (*C).resize(K + 1);
    }
};

struct Matrix {
    int n, m; vii a;
    inline void Set_m(int _m, int x = 0) { m = _m; rep(i, 0, n) a[i].resize(m, x); }
    inline void Set_n(int _n) { n = _n, a.resize(n); }
    inline void Set(int _n, int _m, int x = 0) { Set_n(_n), Set_m(_m, x); }
    Matrix(int n = 0, int m = 0, int x = 0) : n(n), m(m) {
        a.clear(), a.resize(n); Set_m(m, x);
    }
    inline void Transpose() {
        Matrix t = Matrix(m, n, 0);
        rep(i, 0, n) rep(j, 0, m) t.a[j][i] = a[i][j];
        *this = t;
    }
    inline void Reverse() {
        Matrix t = Matrix(n, m, 0);
        rep(i, 0, n) rep(j, 0, m) t.a[n - 1 - i][m - 1 - j] = a[i][j];
        *this = t;
    }
    inline void Shift(int x, int y) {
        rep(i, x, n - 1 + x + 1) rep(j, y, m - 1 + y + 1) a[i - x][j - y] = (i < n && j < m) ? a[i][j] : 0;
    }
};

```

```

inline void FFT(FT<int> &T, int len, int op) {
    if (!op) Set_m(1 << len, 0);
    rep(i, 0, n) T.FFT(a[i], len, op);
}
inline void print() const;
inline void Normalize(int _p);
inline void Random();
};

inline void Matrix::print() const {
    printf("\n\n\n\n\n => %d      m => %d\n", n, m);
    debug_arr2(a, n - 1, m - 1);
}

inline void Matrix::Normalize(int _p) {
    rep(i, 0, n) rep(j, 0, m) if (a[i][j] < 0) a[i][j] += _p;
}

inline void Matrix::Random() {
    rep(i, 0, n) rep(j, 0, m) a[i][j] = (rand() << 15) + rand();
}

inline bool operator==(const Matrix &A, const Matrix &B) {
    if (A.n != B.n || A.m != B.m) return 0;
    rep(i, 0, A.n) rep(j, 0, A.m) if (A.a[i][j] != B.a[i][j]) return 0;
    return 1;
}

struct Calculator {
    Matrix aa, bb, cc; FT<int> T; int len, L, _p;
    inline void Init(int p) { _p = p; }
    inline void Multiply(const Matrix &A, const Matrix &B, Matrix &C, int op = 0) {
        aa = A, bb = B; if (op) aa.Reverse(); T.get_len(A.m, B.m, len, L), T.Init(cc.m = A.n + B.n - 1, _p);
        aa.FFT(T, L, 0), bb.FFT(T, L, 0), aa.Transpose(), bb.Transpose(), cc.Set_n(aa.n);
        rep(i, 0, aa.n) T.multiply(aa.a[i], bb.a[i], &cc.a[i]);
        cc.Transpose(), cc.FFT(T, L, 1), cc.Set_m(A.m + B.m - 1), C = cc;
        if (op) C.Shift(A.n - 1, A.m - 1);
    }
    inline void add(int &x, int y) { x += y, x %= _p; }
    inline int mul(int x, int y) { return (ll)x*y%p; }
    inline void Multiply_B(const Matrix &A, const Matrix &B, Matrix &C) {
        C.Set(A.n + B.n - 1, A.m + B.m - 1);
        rep(xa, 0, A.n) rep(ya, 0, A.m) rep(xb, 0, B.n) rep(yb, 0, B.m)
            add(C.a[xa + xb][ya + yb], mul(A.a[xa][ya], B.a[xb][yb]));
    }
    inline void Multiply_B_sub(const Matrix &A, const Matrix &B, Matrix &C) {
        C.Set(A.n + B.n - 1, A.m + B.m - 1);
        rep(xa, 0, A.n) rep(ya, 0, A.m) rep(xb, xa, B.n) rep(yb, ya, B.m)
            add(C.a[xb - xa][yb - ya], mul(A.a[xa][ya], B.a[xb][yb]));
    }
};

```

## 2.5 Poly\_多项式相关

```

#include<bits/stdc++.h>
using namespace std;
#define pb push_back
#define mp make_pair
#define rep(i, a, b) for(int i=(a); i<(b); i++)
#define per(i, a, b) for(int i=(b)-1; i>=(a); i--)
#define fi first
#define se second
#define fe first
#define FI(x) freopen(#x".in", "r", stdin)
#define FO(x) freopen(#x".out", "w", stdout)
typedef pair<int, int> pii;
typedef long long ll;
typedef double ld;
typedef vector<int> vi;

const int P=998244353;
#define SZ 666666
ll w[2][SZ], rev[SZ];
inline ll qp(ll a, ll b) {
    ll ans=1;
    while(b) {
        if(b&1) ans=ans*a%P;
        a=a*a%P;
        b>>=1;
    }
    return ans;
}

```

```

int K;
inline void fftinit(int n) {
    for(K=1; K<n; K<=<=1);
    w[0][0]=w[0][K]=1;
    ll g=qp(3, (P-1)/K);
    for(int i=1; i<K; i++) w[0][i]=w[0][i-1]*g%P;
    for(int i=0; i<=K; i++) w[1][i]=w[0][K-i];
}
inline void fft(int* x, int v) {
    for(int i=0; i<K; i++) x[i]=(x[i]%P+P)%P;
    for(int i=0, j=0; i<K; i++) {
        if(i>j) swap(x[i], x[j]);
        for(int l=K>>1; (j^=l)<1; l>>=1);
    }
    for(int i=2; i<=K; i<=<=1)
        for(int l=0; l<i>>1; l++) {
            register int w=w[v][K/i*1], *p=x+l+(i>>1), *q=x+l, t;
            for(register int j=0; j<K; j+=i) {
                p[j]=(q[j]-(t=(ll)p[j]*w%P)<0)?(q[j]-t+P):(q[j]-t);
                q[j]=(q[j]+t-P>=0)?(q[j]+t-P):(q[j]+t);
            }
        }
    if(!v) return;
    ll rv=qp(K, P-2);
    for(int i=0; i<K; i++) x[i]=x[i]*rv%P;
}
struct poly {
    vector<int> ps;
    inline int cs() {
        return ps.size()-1;
    }
    inline int& operator [] (int x) {
        return ps[x]; //ps.at(x)
    }
    inline void sc(int x) {
        ps.resize(x+1);
    }
    inline void dbg() {
        bool fi=0;
        for(int i=cs(); i>=0; i--) {
            ps[i]=(ps[i]%P+P)%P;
            if(!ps[i]) continue;
            if(ps[i]>P/2) ps[i]-=P;
            if(fi) {
                if(i==0) printf("%d", ps[i]);
                else if(ps[i]==1) printf("+");
                else if(ps[i]==-1) printf("-");
                else printf("%d", ps[i]);
            } else {
                if(i==0) printf("%d", ps[i]);
                else if(ps[i]==1);
                else if(ps[i]==-1) printf("-");
                else printf("%d", ps[i]);
            }
            if(i>1) printf("x^%d", i);
            else if(i==1) printf("x");
            fi=1;
        }
        if(!fi) printf("0");
        putchar(10);
    }
    inline void clr() {
        int p=cs()+1;
        while(p&&!ps[p-1]) --p;
        sc(p-1);
    }
};
namespace PolyMul { int ta[SZ], tb[SZ], tc[SZ];}
inline poly operator * (poly a, poly b) {
    using namespace PolyMul;
    if(a.cs()<180||b.cs()<180) {
        poly g;
        g.sc(a.cs()+b.cs());
        int*G=&g[0], *A=&a[0], *B=&b[0];
        for(int i=0; i<=a.cs(); i++) {
            register int*h=G+i, j=0;
            register ll x=A[i];
            for(; j<=b.cs(); ++j) h[j]=(h[j]+x*(ll)B[j])%P;
        }
        return g;
    }
}
poly c;

```

```

    int t=a.cs()+b.cs();
    c.sc(t);
    fftinit(t+1);
    memset(ta,0,sizeof(int)*K);
    memset(tb,0,sizeof(int)*K);
    memset(tc,0,sizeof(int)*K);
    for(int i=a.cs(); i>=0; i--) ta[i]=a[i];
    for(int i=b.cs(); i>=0; i--) tb[i]=b[i];
    fft(ta,0);
    fft(tb,0);
    for(int i=0; i<K; i++) tc[i]=(ll)ta[i]*tb[i]%P;
    fft(tc,1);
    for(int i=t; i>=0; i--) c[i]=tc[i];
    c.clr();
    return c;
}

namespace PolyInv {
    int ay[SZ],a0[SZ],tmp[SZ];
}

inline void ginv(int t) {
    using namespace PolyInv;
    if(t==1) {
        a0[0]=qp(ay[0],P-2);
        return;
    }
    ginv((t+1)>>1);
    fftinit(t+t+3);
    memset(tmp,0,sizeof(int)*K);
    for(int i=t; i<K; i++) tmp[i]=a0[i]=0;
    for(int i=0; i<t; i++) tmp[i]=ay[i];
    fft(tmp,0);
    fft(a0,0);
    for(int i=0; i<K; i++) a0[i]=(2-(ll)tmp[i]*a0[i])%P*a0[i]%P;
    fft(a0,1);
    for(int i=t; i<K; i++) a0[i]=0;
}

inline poly inv(poly x) {
    using namespace PolyInv;
    poly y;
    y.sc(x.cs());
    for(int i=x.cs(); i>=0; i--) ay[i]=x[i];
    ginv(x.cs()+1);
    for(int i=x.cs(); i>=0; i--) y[i]=a0[i];
    y.clr();
    return y;
}

inline poly operator + (poly a,poly b) {
    poly w;
    w.sc(max(a.cs(),b.cs()));
    for(int i=a.cs(); i>=0; i--) w[i]=a[i];
    for(int i=b.cs(); i>=0; i--) (w[i]+=b[i])%=P;
    return w;
}

inline poly operator - (poly a,poly b) {
    poly w;
    w.sc(max(a.cs(),b.cs()));
    for(int i=a.cs(); i>=0; i--) w[i]=a[i];
    for(int i=b.cs(); i>=0; i--) (w[i]-=b[i])%=P;
    w.clr();
    return w;
}

inline void div(poly a,poly b,poly& d,poly& r) {
    int n=a.cs(),m=b.cs();
    if(n<m) {
        d.sc(0);
        d[0]=0;
        r=a;
        return;
    }
    fftinit(2*n);
    poly aa=a;
    reverse(aa.ps.begin(),aa.ps.end());
    poly bb=b;
    reverse(bb.ps.begin(),bb.ps.end());
    bb.sc(n-m);
    bb=inv(bb);
    d=aa*bb;
    d.sc(n-m);
    reverse(d.ps.begin(),d.ps.end());
    r=a-b*d;
    r.clr();
}

```

```

inline poly operator / (poly a,poly b) {
    poly d,r;
    div(a,b,d,r);
    return d;
}
inline poly operator % (poly a,poly b) {
    a.clr();
    b.clr();
    if(a.cs()<b.cs()) return a;
    poly d,r;
    div(a,b,d,r);
    return r;
}
inline poly dev(poly x) {
    for(int i=1; i<=x.cs(); i++) x[i-1]=(ll)x[i]*i%P;
    x.sc(x.cs()-1);
    return x;
}
inline poly inte(poly x) {
    x.sc(x.cs()+1);
    for(int i=x.cs(); i>=1; i--) x[i]=x[i-1];
    x[0]=0;
    for(int i=x.cs(); i>=1; i--) x[i]=(ll)x[i]*rev[i]%P;
    return x;
}
inline ll qz(poly& a,ll x) {
    ll ans=0;
    for(int i=a.cs(); i>=0; i--) ans=(ans*x+a[i])%P;
    return ans;
}
poly vvs[SZ];
inline void gvs(int m,int* x,int id) {
    if(m==1) {
        vvs[id].sc(1), vvs[id][1]=1, vvs[id][0]=-*x;
        return;
    }
    int hf=m>>1;
    gvs(hf,x,id*2);
    gvs(m-hf,x+hf,id*2+1);
    vvs[id]=vvs[id*2]*vvs[id*2+1];
}
namespace PolyGetv {
    int xs[SZ],anss[SZ];
};
inline void gv(poly f,int m,int* x,int* ans,int id) {
    if(f.cs()<=1000) {
        int c=f.cs(),*F=&f.ps[0];
        for(int i=0; i<m; i++) {
            register ll t=0;
            register int v=x[i];
            for(register int j=c; ~j; --j) t=(t*v+F[j])%P;
            ans[i]=t;
        }
        return;
    }
    int hf=m>>1;
    gv(f%vvs[id*2],hf,x,ans,id*2);
    gv(f%vvs[id*2+1],m-hf,x+hf,ans+hf,id*2+1);
}
inline vector<int> getv(poly a,vector<int> x) {
    using namespace PolyGetv;
    a.clr();
    if(!x.size()) return vector<int>();
    int m=x.size();
    for(int i=0; i<m; i++) xs[i]=x[i];
    gvs(m,xs,1);
    gv(a%vvs[1],m,xs,anss,1);
    vector<int> ans;
    ans.resize(m);
    for(int i=0; i<m; i++) ans[i]=anss[i];
    return ans;
}
namespace PolyIntp {
    int xs[SZ],vs[SZ];
};
inline poly comb(int m,int*v,int id) {
    if(m==1) {
        poly s;
        s.sc(0);
        s[0]=*v;
        return s;
    }
}

```

```

    int hf=m>>1;
    return comb(hf,v,id*2)*vvs[id*2+1]
        +comb(m-hf,v+hf,id*2+1)*vvs[id*2];
}
inline poly intp(vector<int> x,vector<int> y) {
    using namespace PolyIntp;
    int m=x.size();
    for(int i=0; i<m; i++) xs[i]=x[i];
    gvs(m,xs,1);
    gv(dev(vvs[1]),m,xs,vs,1);
    for(int i=0; i<m; i++)
        vs[i]=y[i]*qp(vs[i],P-2)%P;
    return comb(m,vs,1);
}

int n, m, x, y;

int main() {
    ios::sync_with_stdio(0);
    cin.tie(0);
    rev[1]=1;
    for(int i=2; i<SZ; ++i) rev[i]=-rev[P%i]*(1l)(P/i)%P;
    cin >> n;
    vi xx, yy, zz;
    /*for(int i=0,x,y;i<n;++i) {
        cin >> x >> y;
        xx.pb(x),yy.pb(y);
    }
    poly g = intp(xx, yy);
    g.dbg(); */
    poly g;
    g.sc(n);
    rep(i, 0, n+1) cin >> x, g[i] = x;

    for(int i = 0, z; i < m; ++i) cin >> z, zz.pb(z);
    vector<int> vs = getv(g, zz);
    for(int i=0; i<m; ++i)
        cout << ((vs[i]%P+P)%P) << "\n";
}

```

## 2.6 Poly\_扩展版

```

const int _N=200005; ll inv[_N<<2],fac[_N<<2],fac_inv[_N<<2];
inline ll add(ll x,ll y) { x+=y; return x%P; }
inline ll mul(ll x,ll y) { return (ll)x*y%P; }
inline ll Pow(ll x,ll k) { ll ans=1; for (;k>=1,x=x*x%P) if (k&1) (ans*=x)%=P; return ans; }
inline void init_inv(int n) { inv[1]=1; rep(i,2,n+1) inv[i]=mul(P-P/i,inv[P%i]); }
inline void init_fac(int n) {
    fac[0]=fac_inv[0]=1;
    rep(i,1,n+1) fac[i]=mul(fac[i-1],i), fac_inv[i]=mul(fac_inv[i-1],inv[i]);
}

template <class V>
struct FT{
    int n,nn; V w[2][_N<<2],rev[_N<<2],tmp;
    inline int init_len(int _n) { for (n=1; n<=_n; n<=1); return n; }
    inline int Init(int _n) {
        init_len(_n); if (n==nn) return n; nn=n;
        V w0=Pow(3, (P-1)/n); w[0][0]=w[1][0]=1;
        rep(i,1,n) w[0][i]=w[1][n-i]=mul(w[0][i-1],w0);
        rep(i,0,n) rev[i]=(rev[i>>1]>>1)|((i&1)*(n>>1)); return n;
    }
    void FFT(V A[],int op){
        rep(i,0,n) if (i<rev[i]) swap(A[i],A[rev[i]]);
        for (int i=1; i<n; i<=1)
            for (int j=0,t=n/(i<=1); j<n; j+=i<=1)
                for (int k=j,l=0; k<j+i; k++,l+=t) {
                    V x=A[k],y=mul(w[op][l],A[k+i]);
                    A[k]=add(x,y),A[k+i]=add(x-y,P);
                }
            if (op) { tmp=inv[n]; rep(i,0,n) A[i]=mul(A[i],tmp); }
    }
};

template <class V>
struct Calculator{
    FT<V> T; V X[_N<<2],Y[_N<<2],A[_N<<2],B[_N<<2],C[_N<<2];
    inline void Fill(V a[],V b[],int n,int len) {
        if (a!=b) memcpy(a,b,sizeof(V)*n); fill(a+n,a+len,0);
    }
    inline void Add(V a[],int n,V b[],int m,V c[],int t=1) {
        n=max(n,m); rep(i,0,n) c[i]=add(a[i],t*b[i]);
    }
};

```

```

}
inline void Dot_Mul(V a[],V b[],int len,V c[]) {
    rep(i,0,len) c[i]=mul(a[i],b[i]);
}
inline void Dot_Mul(V a[],int len,V v,V c[]) {
    rep(i,0,len) c[i]=mul(a[i],v);
}
inline void Mul(V a[],int n,V b[],int m,V c[]) {
    int len=T.Init(n+m-1); Fill(X,a,n,len),Fill(Y,b,m,len);
    T.FFT(X,0),T.FFT(Y,0),Dot_Mul(X,Y,len,c),T.FFT(c,1);
}
inline void Int(V a[],int n,V b[]) {
    per(i,0,n) b[i+1]=mul(a[i],inv[i+1]); b[0]=0;
}
inline void Der(V a[],int n,V b[]) {
    rep(i,1,n) b[i-1]=mul(a[i],i); b[n-1]=0;
}
inline void Inv(V a[],int n,V b[]) {
    if (n==1) { b[0]=Pow(a[0],P-2),b[1]=0; return; }
    Inv(a,(n+1)>>1,b); int len=T.Init(2*n-1);
    Fill(X,a,n,len),Fill(b,b,n,len),T.FFT(X,0),T.FFT(b,0);
    rep(i,0,len) b[i]=mul(b[i],2-mul(b[i],X[i]));
    T.FFT(b,1),Fill(b,b,n,len);
}
inline void Log(V a[],int n,V b[]) {
    static V A[_N<<2],B[_N<<2];
    Der(a,n,A),Inv(a,n,B),Mul(A,n,B,n,b);
    Int(b,n,b),Fill(b,b,n,T.n);
}
inline void Exp(V a[],int n,V b[]) {
    if (n==1) { b[0]=exp(a[0]),b[1]=0; return; }
    Exp(a,(n+1)>>1,A),Log(A,n,B),Add(a,n,B,n,B,-1);
    (B[0]+=1)%=P,Mul(A,n,B,n,b),Fill(b,b,n,T.n);
}
inline void Sqrt(V a[],int n,V b[]) {
    if (n==1) { b[0]=sqrt(a[0]),b[1]=0; return; }
    Sqrt(a,(n+1)>>1,b),Inv(b,n,B),Mul(a,n,B,n,B);
    Add(b,n,B,n,b),Dot_Mul(b,n,inv[2],b),Fill(b,b,n,T.n);
}
inline void Power(V a[],int n,ll k,V b[]) {
    Log(a,n,C),Dot_Mul(C,n,k,C),Exp(C,n,b),Fill(b,b,n,T.n);
}
inline V Lagrange(V a[],int n,int k) {
    Inv(a,n,A),Power(A,n,k,B); return mul(B[k-1],inv[k]);
}
inline void Div(V a[],int n,V b[],int m,V d[],V r[]) {
    int len=T.init_len(2*n-1); Fill(A,a,n,len),Fill(B,b,m,len);
    reverse(A,A+n),reverse(B,B+m),Inv(B,n-m+1,Y);
    Mul(A,n,Y,n,d),Fill(d,d,n-m+1,len),reverse(d,d+n-m+1);
    reverse(B,B+m),Fill(A,d,n-m+1,len);
    Mul(A,n,B,n,r),Add(a,n,r,n,r,-1),Fill(r,r,n,len);
}
inline void Sinh(V a[],int n,V b[]) {
    Exp(a,n,b); for (int i=0; i<n; i+=2) b[i]=0;
}
inline void Cosh(V a[],int n,V b[]) {
    Exp(a,n,b); for (int i=1; i<n; i+=2) b[i]=0;
}
inline void Dirichlet_Mul(V a[],int n,V b[],int m,V c[],int L) {
    int len=min((ll)n*m,L); Fill(c,c,0,L+1);
    rep(i,1,n+1) for (int j=1; j<=m && (ll)i*j<=len; j++)
        c[i*j]=add(c[i*j],mul(a[i],b[j]));
}
inline void Der_k(V a[],int n,int k,V b[]) {
    Der(a,n,b); rep(i,1,k) Der(b,n,b);
}
inline void Int_k(V a[],int n,int k,V b[]) {
    Int(a,n,b); rep(i,1,k) Int(b,n,b);
}
inline void Grow(V a[],int n,V b[]) {
    rep(i,0,n) b[i]=mul(a[i],i);
}
inline void Grow_k(V a[],int n,int k,V b[]) {
    rep(i,0,n) b[i]=mul(a[i],Pow(i,k));
}
inline void Shl(V a[],int n,int k,V b[]) {
    rep(i,k,n) b[i-k]=a[i]; Fill(b,b,n-k,n);
}
inline void Shr(V a[],int n,int k,V b[]) {
    per(i,k,n) b[i]=a[i-k]; Fill(b,b,0,k);
}
inline void To_egf(V a[],int n,V b[]) { Dot_Mul(a,fac,n,b); }

```



```

inline void To_ogf(V a[],int n,V b[]) { Dot_Mul(a,fac_inv,n,b); }
inline void Bin_Mul(V a[],int n,V b[],int m,V c[]) {
    static V A[_N<<2],B[_N<<2];
    To_ogf(a,n,A),To_ogf(b,m,B),Mul(A,n,B,m,c),To_egf(c,T.n,c);
}
inline void POW(V a[],int n,ll k,V b[],int t=0) {
    if (k*t>=n || !k) { Fill(b,b,0,n),b[0]=!k; return; }
    if (t) Shl(a,n,t,a); Power(a,n-t,k,b),Shr(b,n,k*t,b);
}
inline void Reverse(V a[],int n,V b[]) { reverse_copy(a,a+n,b); }
inline void Init_Com_Num_H_B(V a[],int n,ll k) {
    a[0]=1; rep(i,1,n) a[i]=mul(a[i-1],inv[i]*(k-i+1)%P);
}
inline void Init_Com_Num_L_B(V a[],int n,ll k) {
    a[0]=1; rep(i,1,n) a[i]=mul(a[i-1],inv[i]*(k+i)%P);
}
inline void Pre_Sum(V a[],int n,V b[]) {
    b[0]=a[0]; rep(i,1,n) b[i]=add(b[i-1],a[i]);
}
inline void Pre_Sum_k(V a[],int n,ll k,V b[]) {
    Init_Com_Num_L_B(b,n,k-1),Mul(a,n,b,n,b);
}
inline void Fly(V a[],int n,ll k,V b[]) {
    k%=P; for (int i=0,t=1; i<n; ++i,t=mul(t,k)) b[i]=mul(a[i],t);
}
inline void Crossify(V a[],int n) { Fly(a,n,-1,a); }
inline void Diff(V a[],int n,V b[]) {
    rep(i,0,n-1) b[i]=a[i+1]-a[i]; b[n-1]=-a[n-1];
}
inline void Diff_k(V a[],int n,int k,V b[]) {
    Init_Com_Num_H_B(b,k+1,k),Crossify(b,k+1),Mul(a,n,b,k+1,b),Shl(b,n+k,k,b);
}
inline void Get_all_one(V a[],int n) { rep(i,0,n) a[i]=1; }
inline void Get_exp_x(V a[],int n) { Fill(a,fac_inv,n,n); }
inline void Get_log_1_add_x(V a[],int n) {
    a[0]=0; int t=1; rep(i,1,n) a[i]=t*inv[i],t=-t;
}
inline void Init_Bell_Num(V a[],int n) {
    Get_exp_x(C,n),C[0]=0,Exp(C,n,a),To_egf(a,n,a);
}
inline void Init_Bernoulli_Num(V a[],int n) {
    Get_exp_x(C,n+1),Shl(C,n+1,1,C),Inv(C,n,a),To_egf(a,n,a);
}
inline V Get_Num_Power_Sum(ll n,int k) {
    n%=P; V ans=0; static V C[_N<<2];
    Init_Com_Num_H_B(C,k+2,k+1),Init_Bernoulli_Num(B,k+1);
    for (int i=1,t=n*(k&1?-1:1); i<=k+1; ++i,t=mul(t,-n))
        ans=add(ans,mul(C[i],B[k+1-i])*t%P);
    ans=mul(ans,inv[k+1]); return ans;
}
inline void Init_Stirling_Num_2_H_B(V a[],int n,ll k) {
    k%=P-1; static V A[_N<<2],B[_N<<2];
    rep(i,0,n) A[i]=(i&1)?-1:1,B[i]=Pow(i,k);
    Bin_Mul(A,n,B,n,a),To_ogf(a,n,a);
}
inline void Init_Stirling_Num_2_L(V a[],int n,int k) {
    static V A[_N<<2]; Get_exp_x(A,n+k),A[0]=0,POW(A,n+k,k,a,1);
    Dot_Mul(a,n+k,fac_inv[k],a),To_egf(a,n+k,a),Shl(a,n+k,k,a);
}
inline void Init_Stirling_Num_1_L(V a[],int n,int k) {
    static V A[_N<<2]; Get_log_1_add_x(A,n+k),POW(A,n+k,k,a,1);
    Dot_Mul(a,n+k,((k&1)?-1:1)*fac_inv[k],a);
    To_egf(a,n+k,a),Crossify(a,n+k),Shl(a,n+k,k,a);
}
inline void Mod_p(V a[],int n) {
    rep(i,0,n) a[i]=(a[i]%P+P)%P;
}
};

```

## 2.7 Poly\_标准版

```

const int _N=200005; ll inv[_N<<2];
inline ll add(ll x,ll y) { x+=y; return x%P; }
inline ll mul(ll x,ll y) { return (ll)x*y%P; }
inline ll Pow(ll x,ll k) { ll ans=1; for (;k>=1,x=x*x%P) if (k&1) (ans*=x)%=P; return ans; }
inline void init_inv(int n) { inv[1]=1; rep(i,2,n+1) inv[i]=mul(P-P/i,inv[P%i]); }

template <class V>
struct FT{
    int n,nn; V w[2][_N<<2],rev[_N<<2],tmp;
    inline int init_len(int _n) { for (n=1; n<=_n; n<=1); return n; }
    inline int Init(int _n) {

```

```

    init_len(_n); if (n==nn) return n; nn=n;
    V w0=Pow(3, (P-1)/n); w[0][0]=w[1][0]=1;
    rep(i,1,n) w[0][i]=w[1][n-i]=mul(w[0][i-1],w0);
    rep(i,0,n) rev[i]=(rev[i>>1]>>1)|((i&1)*(n>>1)); return n;
}
void FFT(V A[],int op){
    rep(i,0,n) if (i<rev[i]) swap(A[i],A[rev[i]]);
    for (int i=1; i<n; i<=1)
        for (int j=0,t=n/(i<=1); j<n; j+=i<=1)
            for (int k=j,l=0; k<j+i; k++,l+=t) {
                V x=A[k],y=mul(w[op][l],A[k+i]);
                A[k]=add(x,y),A[k+i]=add(x-y,P);
            }
    if (op) { tmp=inv[n]; rep(i,0,n) A[i]=mul(A[i],tmp); }
}
};

```

```

template <class V>
struct Calculator{
    FT<V> T; V X[_N<<2],Y[_N<<2],A[_N<<2],B[_N<<2],C[_N<<2];
    inline void Fill(V a[],V b[],int n,int len) {
        if (a!=b) memcpy(a,b,sizeof(V)*n); fill(a+n,a+len,0);
    }
    inline void Add(V a[],int n,V b[],int m,V c[],int t=1) {
        n=max(n,m); rep(i,0,n) c[i]=add(a[i],t*b[i]);
    }
    inline void Dot_Mul(V a[],V b[],int len,V c[]) {
        rep(i,0,len) c[i]=mul(a[i],b[i]);
    }
    inline void Dot_Mul(V a[],int len,V v,V c[]) {
        rep(i,0,len) c[i]=mul(a[i],v);
    }
    inline void Mul(V a[],int n,V b[],int m,V c[]) {
        int len=T.Init(n+m-1); Fill(X,a,n,len),Fill(Y,b,m,len);
        T.FFT(X,0),T.FFT(Y,0),Dot_Mul(X,Y,len,c),T.FFT(c,1);
    }
    inline void Int(V a[],int n,V b[]) {
        per(i,0,n) b[i+1]=mul(a[i],inv[i+1]); b[0]=0;
    }
    inline void Der(V a[],int n,V b[]) {
        rep(i,1,n) b[i-1]=mul(a[i],i); b[n-1]=0;
    }
    inline void Inv(V a[],int n,V b[]) {
        if (n==1) { b[0]=Pow(a[0],P-2),b[1]=0; return; }
        Inv(a,(n+1)>>1,b); int len=T.Init(2*n-1);
        Fill(X,a,n,len),Fill(b,b,n,len),T.FFT(X,0),T.FFT(b,0);
        rep(i,0,len) b[i]=mul(b[i],2-mul(b[i],X[i]));
        T.FFT(b,1),Fill(b,b,n,len);
    }
    inline void Log(V a[],int n,V b[]) {
        static V A[_N<<2],B[_N<<2];
        Der(a,n,A),Inv(a,n,B),Mul(A,n,B,n,b);
        Int(b,n,b),Fill(b,b,n,T.n);
    }
    inline void Exp(V a[],int n,V b[]) {
        if (n==1) { b[0]=exp(a[0]),b[1]=0; return; }
        Exp(a,(n+1)>>1,A),Log(A,n,B),Add(a,n,B,n,B,-1);
        (B[0] +=1)%P,Mul(A,n,B,n,b),Fill(b,b,n,T.n);
    }
    inline void Sqrt(V a[],int n,V b[]) {
        if (n==1) { b[0]=sqrt(a[0]),b[1]=0; return; }
        Sqrt(a,(n+1)>>1,b),Inv(b,n,B),Mul(a,n,B,n,B);
        Add(b,n,B,n,b),Dot_Mul(b,n,inv[2],b),Fill(b,b,n,T.n);
    }
    inline void Power(V a[],int n,ll k,V b[]) {
        Log(a,n,C),Dot_Mul(C,n,k,C),Exp(C,n,b),Fill(b,b,n,T.n);
    }
    inline V Lagrange(V a[],int n,int k) {
        Inv(a,n,A),Power(A,n,k,B); return mul(B[k-1],inv[k]);
    }
    inline void Div(V a[],int n,V b[],int m,V d[],V r[]) {
        int len=T.init_len(2*n-1); Fill(A,a,n,len),Fill(B,b,m,len);
        reverse(A,A+n),reverse(B,B+m),Inv(B,n-m+1,Y);
        Mul(A,n,Y,n,d),Fill(d,d,n-m+1,len),reverse(d,d+n-m+1);
        reverse(B,B+m),Fill(A,d,n-m+1,len);
        Mul(A,n,B,n,r),Add(a,n,r,n,r,-1),Fill(r,r,n,len);
    }
    inline void Sinh(V a[],int n,V b[]) {
        Exp(a,n,b); for (int i=0; i<n; i+=2) b[i]=0;
    }
    inline void Cosh(V a[],int n,V b[]) {
        Exp(a,n,b); for (int i=1; i<n; i+=2) b[i]=0;
    }

```

```

}
inline void Dirichlet_Mul(V a[],int n,V b[],int m,V c[],int L) {
    int len=min((ll)n*m,L); Fill(c,c,0,L+1);
    rep(i,1,n+1) for (int j=1; j<=m && (ll)i*j<=len; j++)
        c[i*j]=add(c[i*j],mul(a[i],b[j]));
}
};

```

## 2.8 一维 FFT\_单模式串\_模式串带通配符匹配

```

struct cp { double x, y; };
inline cp operator + (cp &a, cp &b) { return cp{ a.x + b.x,a.y + b.y }; }
inline cp operator - (cp &a, cp &b) { return cp{ a.x - b.x,a.y - b.y }; }
inline cp operator * (cp &a, cp &b) { return cp{ a.x*b.x - a.y*b.y,a.x*b.y + a.y*b.x }; }
inline cp get(double x) { return cp{ cos(x),sin(x) }; }
inline ostream& operator<<(ostream &out, const cp &t) { out << "(" << t.x << "," << t.y << ")"; return out; }

const int _M = 1 << 18, _N = N;
struct FT {
    cp tmp[_M * 2 + 5], aa[_M], bb[_M];
    void FFT(cp *a, int n, int op) {
        for (int i = (n >> 1), j = 1; j < n; j++) {
            if (i < j) swap(a[i], a[j]);
            int k; for (k = (n >> 1); k&i; i ^= k, k >>= 1); i ^= k;
        }
        for (int m = 2; m <= n; m <= 1) {
            cp w = get(2 * PI*op / m); tmp[0] = cp{ 1,0 };
            for (int j = 1; j < (m >> 1); j++) tmp[j] = tmp[j - 1] * w;
            for (int i = 0; i < n; i += m)
                for (int j = i; j < i + (m >> 1); j++) {
                    cp u = a[j], v = a[j + (m >> 1)] * tmp[j - i];
                    a[j] = u + v, a[j + (m >> 1)] = u - v;
                }
        }
        if (op == -1) rep(i, 0, n) a[i] = cp{ a[i].x / n,a[i].y / n };
    }
    void In(cp p[], int len, cp a[], int n) {
        rep(i, 0, len) p[i] = i < n ? a[i] : cp{ 0,0 };
    }
    void Out(int a[], int n, cp p[], int len) {
        rep(i, 0, n) a[i] = (int)(p[i].x + eps);
    }
    void Shift(int a[], int n, int p) { rep(i, n, n + p) a[i - n] = a[i]; }
    void Multiply(cp A[], int n, cp B[], int m, int C[], int &len, int op = 0) {
        if (op) reverse(A, A + n);
        len = 1; while (len < n + m - 1) len <= 1;
        In(aa, len, A, n), In(bb, len, B, m), FFT(aa, len, 1), FFT(bb, len, 1);
        rep(i, 0, len) aa[i] = aa[i] * bb[i];
        FFT(aa, len, -1), Out(C, n + m - 1, aa, len);
        if (op) Shift(C, n - 1, m), len = m, reverse(A, A + n);
    }
};

void Build(cp A[], int n, char s[], int M, int op, int cc = 'a') {
    rep(i, 0, n) A[i] = (s[i] == '?') ? cp{ 0,0 } : get(2 * PI / M*(s[i] - cc)*op);
}

int n, m, len, tot = 0, tt; char s[N], t[N]; FT T; cp A[_M], B[_M]; int C[_M]; vi ans;

int main() {
    //file_put();

    scanf("%s%s", s, t), n = strlen(s), m = strlen(t);
    rep(i, 0, m) tot += (t[i] != '?');
    Build(A, n, s, 26, 1), Build(B, m, t, 26, -1);
    T.Multiply(B, m, A, n, C, len, 1);
    //debug_arr(C,len-1);
    rep(i, 0, n - m + 1) if (C[i] >= tot) ans.pb(i);
    printf("%d\n", tt = ans.size());
    rep(i, 0, tt) printf("%d\n", ans[i]);

    return 0;
}

```

## 2.9 二维 FFT\_单模式串\_模式串带通配符匹配

```

struct cp { double x, y; };
inline cp operator + (cp &a, cp &b) { return cp{ a.x + b.x,a.y + b.y }; }
inline cp operator - (cp &a, cp &b) { return cp{ a.x - b.x,a.y - b.y }; }
inline cp operator * (cp &a, cp &b) { return cp{ a.x*b.x - a.y*b.y,a.x*b.y + a.y*b.x }; }
inline cp get(double x) { return cp{ cos(x),sin(x) }; }
inline ostream& operator<<(ostream &out, const cp &t) { out << "(" << t.x << "," << t.y << ")"; return out; }

```

```

const int _M = 2048, _N = N;
template <class V>
struct FT {
    cp tmp[_M * 2 + 5], aa[_M][_M], bb[_M][_M];
    void FFT(cp *a, int n, int op) {
        for (int i = (n >> 1), j = 1; j < n; j++) {
            if (i < j) swap(a[i], a[j]);
            int k; for (k = (n >> 1); k & i; i ^= k, k >>= 1); i ^= k;
        }
        for (int m = 2; m <= n; m <<= 1) {
            cp w = get(2 * PI * op / m); tmp[0] = cp{ 1, 0 };
            for (int j = 1; j < (m >> 1); j++) tmp[j] = tmp[j - 1] * w;
            for (int i = 0; i < n; i += m)
                for (int j = i; j < i + (m >> 1); j++) {
                    cp u = a[j], v = a[j + (m >> 1)] * tmp[j - i];
                    a[j] = u + v, a[j + (m >> 1)] = u - v;
                }
        }
        if (op == -1) rep(i, 0, n) a[i] = cp{ a[i].x / n, a[i].y / n };
    }
    void FFT(cp a[][_M], int n, int op) { rep(i, 0, n) FFT(a[i], n, op); }
    template <class T>
    void Transpose(T a[][_M], int n) {
        rep(i, 0, n) rep(j, 0, i) swap(a[i][j], a[j][i]);
    }
    void Reverse(V a[][_M], int n, int m) {
        rep(i, 0, (n - 1 >> 1) + 1) rep(j, 0, m) swap(a[i][j], a[n - 1 - i][j]);
        rep(i, 0, n) rep(j, 0, (m - 1 >> 1) + 1) swap(a[i][j], a[i][m - 1 - j]);
    }
    void Shift(int a[][_M], int n, int m, int p, int q) {
        rep(i, n, n + p) rep(j, m, m + q) a[i - n][j - m] = a[i][j];
    }
    void In(cp p[][_M], int len, V a[][_M], int n, int m) {
        rep(i, 0, len) rep(j, 0, len) p[i][j] = i < n & j < m ? a[i][j] : cp{ 0, 0 };
    }
    void Out(int a[][_M], int n, int m, cp p[][_M], int len) {
        rep(i, 0, n) rep(j, 0, m) a[i][j] = (int)(p[i][j].x + eps);
    }
    void Multiply(V A[][_M], int n, V B[][_M], int m, int C[][_M], int &len, int op = 0) {
        if (op) Reverse(A, n, n);
        len = 1; while (len < n + m - 1) len <<= 1;
        In(aa, len, A, n, n), In(bb, len, B, m, m), FFT(aa, len, 1), FFT(bb, len, 1);
        Transpose(aa, len), Transpose(bb, len), FFT(aa, len, 1), FFT(bb, len, 1);
        rep(i, 0, len) rep(j, 0, len) aa[i][j] = aa[i][j] * bb[i][j];
        FFT(aa, len, -1), Transpose(aa, len), FFT(aa, len, -1), Out(C, len, len, aa, len);
        if (op) Shift(C, n - 1, n - 1, m, m), len = m, Reverse(A, n, n);
    }
};

void Build(cp A[][_M], int n, int m, char s[][405], int M, int op, int cc = 'a') {
    rep(i, 0, n) rep(j, 0, m) A[i][j] = (s[i][j] == '?') ? cp{ 0, 0 } : get(2 * PI / M * (s[i][j] - cc) * op);
}

int n1, n2, m1, m2, nn, mm, len, tot = 0; char s[405][405], t[405][405]; FT<cp> T; cp A[_M][_M], B[_M][_M]; int C[_M][_M];

int main() {
    //file_put();

    scanf("%d%d", &n1, &m1);
    rep(i, 0, n1) scanf("%s", s[i]);
    scanf("%d%d", &n2, &m2), nn = n1 + n2, mm = m1 + m2;
    rep(i, 0, n2) scanf("%s", t[i]);
    rep(i, 0, n2) rep(j, 0, m2) tot += (t[i][j] != '?');
    Build(A, n1, m1, s, 26, 1), Build(B, n2, m2, t, 26, -1);
    rep(i, 0, nn) rep(j, 0, mm) {
        if (i < n1 && j < m1) continue;
        A[i][j] = A[i % n1][j % m1];
    }
    //debug_arr2(A, nn - 1, mm - 1);
    //debug_arr2(B, n2 - 1, m2 - 1);
    T.Multiply(B, max(n2, m2), A, max(nn, mm), C, len, 1);
    //debug_arr2(C, len - 1, len - 1);
    rep(i, 0, n1) {
        rep(j, 0, m1) printf("%c", "01"[C[i][j] >= tot]);
        printf("\n");
    }

    return 0;
}

```

## 2.10 分治 FFT

```

const int M = 1 << 17 << 1;

int f[M], a[M], b[M], T, n, ok, len, ans[M], g[M];
stack<pii> sta;

struct NTT{
    static const int M = ::M, G = 3, P = 998244353; //P = C*2^k + 1
    int N, na, nb, a[M], b[M], w[2][M], rev[M];
    ll kpow(ll a, int b){
        ll c = 1;
        for (; b >= 1; a = a * a % P) if (b & 1) c = c * a % P;
        return c;
    }
    void FFT(int *a, int f){
        rep(i, 0, N) if (i < rev[i]) swap(a[i], a[rev[i]]);
        for (int i = 1; i < N; i <= 1)
            for (int j = 0, t = N / (i <= 1); j < N; j += i <= 1)
                for (int k = 0, l = 0, x, y; k < i; k++, l += t)
                    x = (ll) w[f][l] * a[j+k+i] % P, y = a[j+k], a[j+k] = (y+x) % P, a[j+k+i] = (y-x+P) % P;
        if (f) for (int i = 0, x = kpow(N, P-2); i < N; i++) a[i] = (ll)a[i] * x % P;
    }
    void work(){
        rep(i, 0, N){
            int x = i, y = 0;
            for (int k = 1; k < N; x>=1, k<=1) (y<=1) |= x&1;
            rev[i] = y;
        }
        w[0][0] = w[1][0] = 1;
        for (int i = 1, x = kpow(G, (P-1) / N), y = kpow(x, P-2); i < N; i++)
            w[0][i] = (ll)x * w[0][i-1] % P, w[1][i] = (ll)y * w[1][i-1] % P;
    }
    void doit(int *a, int *b, int na, int nb){ // [0, na)
        for (N = 1; N < na + nb - 1; N <= 1);
        rep(i, na, N) a[i] = 0;
        rep(i, nb, N) b[i] = 0;
        work(), FFT(a, 0), FFT(b, 0);
        rep(i, 0, N) a[i] = (ll)a[i] * b[i] % P;
        FFT(a, 1);
        //rep(i, 0, N) cout << a[i] << endl;
    }
} ntt;

//f[i] = f[i-1] \cdot (i-1) + \sum_{j=2}^{n-2} {f[j] \cdot f[n-j] \cdot (j-1)}

//f[L, mid] * g[L, mid] -> [mid+1, R]
//f[L, mid] * g[L, min(L-1, R-1)] -> [mid+1, R]
//f[1, min(L-1, R-L)] * g[L, mid] -> [mid+1, R]

void solve(int l, int r) {
    if (l == r) {
        f[l] = add(mul(f[l-1], l-1), f[l]);
        return;
    }
    int mid = l + r >> 1;
    solve(l, mid);
    if (r >= l * 2) {
        int ed = min(mid, r-1);
        rep(i, 1, ed+1) a[i-1] = mul(f[i], i-1);
        rep(i, 1, ed+1) b[i-1] = f[i];
        ntt.doit(a, b, ed-1+1, ed-1+1);
        rep(i, max(2 * l, mid+1), r+1) if (i <= 2 * ed) f[i] = add(f[i], a[i-2 * l]); else break;
    }
    if (l + 2 <= r && l + l - 1 >= mid + 1) {
        int ed = min(l-1, r-1);
        rep(i, 1, mid+1) a[i-1] = mul(f[i], i-1);
        rep(i, 2, ed+1) b[i-2] = f[i];
        ntt.doit(a, b, mid+1-1, ed+1-2);
        rep(i, max(l+2, mid+1), r+1) if (i <= mid+ed) f[i] = add(f[i], a[i-1-2]); else break;
        rep(i, 1, mid+1) a[i-1] = f[i];
        rep(i, 2, ed+1) b[i-2] = mul(f[i], i-1);
        ntt.doit(a, b, mid+1-1, ed+1-2);
        rep(i, max(l+2, mid+1), r+1) if (i <= mid+ed) f[i] = add(f[i], a[i-1-2]); else break;
    }
    solve(mid+1, r);
}

int main() {
    freopen("a.in", "r", stdin);
    ios::sync_with_stdio(0);

```

```

cin.tie(0);
//cout << setiosflags(ios::fixed);
//cout << setprecision(2);
cin >> T >> n;
f[0] = 1; f[1] = 2;
solve(2, n);
rep(cas, 0, T) {
    ok = 1;
    while (!sta.empty()) sta.pop();
    rep(i, 1, n+1) {
        cin >> len;
        int tmp = 1, cnt = 0;
        if (!ok) continue;
        while (!sta.empty() && sta.top().fi - sta.top().se >= i - len) {
            cnt++; tmp = mul(tmp, ans[sta.top().fi]); sta.pop();
        }
        if (!sta.empty() && i - len + 1 <= sta.top().fi) ok = 0;
        sta.push(mp(i, len));
        ans[i] = mul(tmp, f[cnt]);
    }
    if (!ok || sz(sta) > 1) cout << 0 << endl; else cout << ans[n] << endl;
}
return 0;
}
}

```

## 2.11 扩展卢卡斯

```

namespace exlucas {
const int N = 1e6;
typedef long long ll;
ll n, m, p;
inline ll power(ll a, ll b, const ll p = LLONG_MAX) {
    ll ans = 1;
    while (b) {
        if (b & 1)
            ans = ans * a % p;
        a = a * a % p;
        b >>= 1;
    }
    return ans;
}
ll fac(const ll n, const ll p, const ll pk) {
    if (!n)
        return 1;
    ll ans = 1;
    for (int i = 1; i < pk; i++)
        if (i % p)
            ans = ans * i % pk;
    ans = power(ans, n / pk, pk);
    for (int i = 1; i <= n % pk; i++)
        if (i % p)
            ans = ans * i % pk;
    return ans * fac(n / p, p, pk) % pk;
}
ll exgcd(const ll a, const ll b, ll &x, ll &y) {
    if (!b) {
        x = 1, y = 0;
        return a;
    }
    ll xx, yy, g = exgcd(b, a % b, xx, yy);
    x = yy;
    y = xx - a / b * yy;
    return g;
}
ll inv(const ll a, const ll p) {
    ll x, y;
    exgcd(a, p, x, y);
    return (x % p + p) % p;
}
ll C(const ll n, const ll m, const ll p, const ll pk) {
    if (n < m)
        return 0;
    ll f1 = fac(n, p, pk), f2 = fac(m, p, pk), f3 = fac(n - m, p, pk), cnt = 0;
    for (ll i = n; i; i /= p)
        cnt += i / p;
    for (ll i = m; i; i /= p)
        cnt -= i / p;
    for (ll i = n - m; i; i /= p)
        cnt -= i / p;
    return f1 * inv(f2, pk) % pk * inv(f3, pk) % pk * power(p, cnt, pk) % pk;
}
ll a[N], c[N];
}

```

```

int cnt;
inline ll CRT() {
    ll M = 1, ans = 0;
    for (int i = 0; i < cnt; i++)
        M *= c[i];
    for (int i = 0; i < cnt; i++)
        ans = (ans + a[i] * (M / c[i]) % M * inv(M / c[i], c[i]) % M) % M;
    return ans;
}
ll exlucas(const ll n, const ll m, ll p) {
    ll tmp = sqrt(p);
    for (int i = 2; p > 1 && i <= tmp; i++) {
        ll tmp = 1;
        while (p % i == 0)
            p /= i, tmp *= i;
        if (tmp > 1)
            a[cnt] = C(n, m, i, tmp), c[cnt++] = tmp;
    }
    if (p > 1)
        a[cnt] = C(n, m, p, p), c[cnt++] = p;
    return CRT();
}
int work() {
    ios::sync_with_stdio(false);
    cin >> n >> m >> p;
    cout << exlucas(n, m, p);
    return 0;
}
}

```

## 2.12 拟阵交

```

#include<bits/stdc++.h>
#define MAXN 65
#define MAXM 6005
#define INF 1000000000
#define MOD 1000000007
#define F first
#define S second
using namespace std;
typedef long long ll;
typedef pair<int,int> P;
int color[MAXN];
ll val[MAXN];
int n,m,tot,tot2;
struct LinearMatroid{
    ll basis[62];
    void clear() { memset(basis,0,sizeof(basis));}
    void add(ll x) {
        for(int j=60;j>=0;j--) {
            if(!(x&(1LL<<j))) continue;
            if(!basis[j]) {
                basis[j]=x;
                return;
            }
            else x^=basis[j];
        }
    }
    bool test(ll x) {
        for(int j=60;j>=0;j--) {
            if(!(x&(1LL<<j))) continue;
            if(!basis[j]) return true; else x^=basis[j];
        }
        return false;
    }
};

struct ColorfulMatroid {
    int cnt[125];
    void clear() { memset(cnt,0,sizeof(cnt)); }
    void add(int x) { cnt[x]++; }
    bool test(int x) { return (cnt[x]==0); }
};

template <typename MT1, typename MT2>
struct MatroidIntersection {
    int n;
    MatroidIntersection(int _n):n(_n){}
    int pre[MAXN],id[MAXN];
    bool vis[MAXN],sink[MAXN],has[MAXN];
    queue<int> que;
    void clear_all() {

```

```

    memset(vis, false, sizeof(vis));
    memset(sink, false, sizeof(sink));
    memset(pre, 0, sizeof(pre));
    while(queue.size()) queue.pop();
}
vector<int> getcur() {
    vector<int> ret;
    for(int i=1; i<=n; i++) if(has[i]) ret.push_back(i);
    return ret;
}
void enqueue(int v, int p) {
    vis[v]=true; pre[v]=p;
    queue.push(v);
}
vector<int> run() {
    MT1 mt1; MT2 mt2;
    memset(has, false, sizeof(has));
    while(true) {
        vector<int> cur=getcur();
        int cnt=0;
        for(int i=1; i<=n; i++) if(has[i]) id[i]=cnt++;
        MT1 allmt1; MT2 allmt2; allmt1.clear(); allmt2.clear();
        vector<MT1> vmt1(cur.size()); vector<MT2> vmt2(cur.size());
        for(auto &x:vmt1) x.clear(); for(auto &x:vmt2) x.clear();
        clear_all();
        for(auto x:cur) allmt1.add(val[x]), allmt2.add(color[x]);
        for(int i=0; i<(int)cur.size(); i++)
            for(int j=0; j<(int)cur.size(); j++) {
                if(i==j) continue;
                vmt1[i].add(val[cur[j]]);
                vmt2[i].add(color[cur[j]]);
            }
        for(int i=1; i<=n; i++) {
            if(has[i]) continue;
            if(allmt1.test(val[i])) {queue.push(i); vis[i]=true;}
        }
        for(int i=1; i<=n; i++) {
            if(has[i]) continue;
            if(allmt2.test(color[i])) sink[i]=true;
        }
        int last=-1;
        while(queue.size()) {
            int v=queue.front(); queue.pop();
            if(sink[v]) {last=v; break;}
            for(int i=1; i<=n; i++) {
                if(vis[i]) continue;
                if(has[i]==has[v]) continue;
                if(has[v]) {
                    if(vmt1[id[v]].test(val[i])) enqueue(i, v);
                }
                else {
                    if(vmt2[id[i]].test(color[v])) enqueue(i, v);
                }
            }
        }
        if(last==-1) return cur;
        while(last) {
            has[last]^=1;
            last=pre[last];
        }
    }
}
};
//Pick Your Own Nim
//In real cases, Linear Matroid Need Optimization to Pass
int main() {
    scanf("%d", &n);
    for(int i=0; i<n; i++) {
        ll x;
        scanf("%lld", &x);
        val[++tot]=x; color[tot]=++tot2;
    }
    scanf("%d", &m);
    for(int i=0; i<m; i++) {
        int k;
        scanf("%d", &k);
        tot2++;
        for(int j=0; j<k; j++) {
            ll x;
            scanf("%lld", &x);
            val[++tot]=x; color[tot]=tot2;
        }
    }
}

```



```

    }
    MatroidIntersection<LinearMatroid,ColorfulMatroid> matint(tot);
    vector<int> res=matint.run();
    if(res.size()<n+m) {puts("-1"); return 0;}
    else {
        vector<ll> ans;
        int last=n;
        for(auto x:res) {
            if(color[x]>last) {
                ans.push_back(val[x]);
                last=color[x];
            }
        }
        for(auto x:ans) printf("%lld\n",x);
    }
    return 0;
}

```

## 2.13 拟阵交\_带权

```

#pragma GCC optimize(3)
#include<bits/stdc++.h>
#define MAXN 85
#define MAXM 205
#define INF 1000000000
#define MOD 1000000007
#define F first
#define S second
using namespace std;
typedef long long ll;
typedef pair<int,int> P;
int c[MAXN],k[MAXN],color[MAXM],u[MAXM],v[MAXM],w[MAXM],cost[MAXM];
ll val[MAXM];
int T,n,m,tot,tot2;
struct LinearMatroid
{
    ll basis[62];
    void clear()
    {
        memset(basis,0,sizeof(basis));
    }
    void add(ll x)
    {
        for(int j=60;j>=0;j--)
        {
            if(!(x&(1LL<<j))) continue;
            if(!basis[j])
            {
                basis[j]=x;
                return;
            }
            else x^=basis[j];
        }
    }
    bool test(ll x)
    {
        for(int j=60;j>=0;j--)
        {
            if(!(x&(1LL<<j))) continue;
            if(!basis[j]) return true; else x^=basis[j];
        }
        return false;
    }
};
struct ColorfulMatroid
{
    int cnt[125];
    void clear()
    {
        memset(cnt,0,sizeof(cnt));
    }
    void add(int x)
    {
        cnt[x]++;
    }
    bool test(int x)
    {
        return (cnt[x]==0);
    }
};

struct GraphMatroid

```

```

{
    vector<int> G[MAXN];
    bool vis[MAXN];
    bool exist[MAXN];
    void dfs(int v)
    {
        vis[v]=true;
        for(auto to:G[v]) if(!vis[to]) dfs(to);
    }
    bool test(vector<int> &vec)
    {
        for(int i=1;i<=n+1;i++) G[i].clear();
        memset(vis,false,sizeof(vis));
        memset(exist,true,sizeof(exist));
        for(auto x:vec) exist[x]=false;
        for(int i=1;i<=tot;i++)
        {
            if(exist[i])
            {
                G[u[i]].push_back(v[i]);
                G[v[i]].push_back(u[i]);
            }
        }
        dfs(1);
        for(int i=1;i<=n+1;i++) if(!vis[i]) return false;
        return true;
    }
};

struct PartitionMatroid
{
    int cnt[125];
    bool test(vector<int> &vec)
    {
        memset(cnt,0,sizeof(cnt));
        for(auto x:vec) cnt[color[x]]++;
        for(int i=1;i<=m;i++) if(cnt[i]>c[i]-k[i]) return false;
        return true;
    }
};

template <typename MT1, typename MT2>
struct MatroidIntersection
{
    int n,S,T;
    MatroidIntersection(int _n):n(_n){}
    int pre[MAXM],id[MAXM],d[MAXM];
    bool inque[MAXM],sink[MAXM],has[MAXM];
    vector<int> g[MAXN];
    queue<int> que;
    void clear_all()
    {
        for(int i=1;i<=n+2;i++)
        {
            inque[i]=false;
            sink[i]=false;
            pre[i]=0;
            d[i]=-INF;
            if(has[i]) cost[i]=w[i]; else cost[i]=-w[i];
            g[i].clear();
        }
        while(que.size()) que.pop();
    }
    void add_edge(int u,int v)
    {
        g[u].push_back(v);
    }
    vector<int> getcur()
    {
        vector<int> ret;
        for(int i=1;i<=n;i++) if(has[i]) ret.push_back(i);
        return ret;
    }
    void enqueue(int v,int p)
    {
        pre[v]=p;
        if(!inque[v])
        {
            inque[v]=true;
            que.push(v);
        }
    }
};

```

```

}
pair<vector<int>,ll> run()
{
    ll ans=0;
    MT1 mt1; MT2 mt2;
    memset(has,false,sizeof(has));
    S=n+1; T=n+2;
    while(true)
    {
        clear_all();
        for(int i=1;i<=n;i++)
        {
            if(!has[i])
            {
                cost[i]=w[i];
                has[i]^=1;
                vector<int> tmp=getcur();
                if(mt1.test(tmp)) add_edge(S,i);
                if(mt2.test(tmp)) add_edge(i,T);
                has[i]^=1;
            }
            else cost[i]=-w[i];
        }
        for(int i=1;i<=n;i++)
        {
            if(!has[i])
            {
                for(int j=1;j<=n;j++)
                {
                    if(has[j])
                    {
                        has[i]^=1; has[j]^=1;
                        vector<int> tmp=getcur();
                        if(mt1.test(tmp)) add_edge(j,i);
                        if(mt2.test(tmp)) add_edge(i,j);
                        has[i]^=1; has[j]^=1;
                    }
                }
            }
        }
        d[S]=0; que.push(S); inque[S]=true;
        cost[S]=cost[T]=0;
        int counter=0;
        while(que.size())
        {
            counter++;
            int u=que.front(); que.pop();
            for(auto to:g[u])
                if(d[to]<d[u]+cost[to])
                {
                    d[to]=d[u]+cost[to];
                    enqueue(to,u);
                }
            inque[u]=false;
        }
        if(!pre[T]) return make_pair(getcur(),ans);
        ans+=d[T];
        int last=pre[T];
        while(last!=S)
        {
            has[last]^=1;
            last=pre[last];
        }
    }
}
};
//hdu 6636 Milk Candy
int main()
{
    scanf("%d",&T);
    while(T--)
    {
        tot=0;
        scanf("%d%d",&n,&m);
        int sum=0;
        ll ans=0;
        for(int i=1;i<=m;i++)
        {
            scanf("%d%d",&c[i],&k[i]);
            sum+=c[i]-k[i];
            for(int j=1;j<=c[i];j++)
            {

```

```

        int l, r, cost;
        scanf("%d%d%d", &l, &r, &cost);
        color[++tot] = i; u[tot] = l; v[tot] = r + 1; w[tot] = cost;
        ans += cost;
    }
}
MatroidIntersection<GraphMatroid, PartitionMatroid> matint(tot);
auto res = matint.run();
GraphMatroid gm; PartitionMatroid pm;
if((int)res.F.size() != sum || !gm.test(res.F) || !pm.test(res.F)) puts("-1"); else printf("%lld\n", ans - res.S);
}
return 0;
}

```

## 3 String

### 3.1 PAM\_优化转移\_偶回文切割方案数

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N], dep[N], id[N], no[N], last, n, p, cur, now; int df[N], slink[N], pre[N]; ll
    ans, dp[N], res[N];
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; }
    inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
    inline void I(int c) {
        c -= 'a', s[++n] = c, cur = get_fail(last);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])][c];
            next[cur][c] = now;
            dep[now] = dep[fail[now]] + 1; //...
        }
        last = next[cur][c], cnt[last]++; id[n] = last, no[last] = n;
        df[last] = len[last] - len[fail[last]];
        slink[last] = (df[last] == df[fail[last]]) ? slink[fail[last]] : fail[last]; //...
    }
    inline void Insert(char s[], int op = 0, int _n = 0) {
        if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
    inline void Q() {
        rep(i, 0, n + 2) dp[i] = 0; dp[0] = 1;
        rep(i, 1, n + 1) for (int t = id[i]; len[t] > 0; t = slink[t]) {
            res[t] = dp[i - len[slink[t]] - df[t]];
            if (df[t] == df[fail[t]]) (res[t] += res[fail[t]]) %= P;
            if (!odd(i)) (dp[i] += res[t]) %= P;
        }
        printf("%I64d\n", dp[n]);
    }
};
/* 【题目】

codeforces 932G 求原串偶数段的段式回文切割的方案数目首尾间隔取字母构成新串，转化为求偶回文切割方案数（每段长度为偶数）

*/

```

### 3.2 PAM\_优化转移\_最小回文切割段数

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N], dep[N], id[N], no[N], last, n, p, cur, now; int df[N], slink[N], dp[N], res
    [N]; ll ans;
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; }
    inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
    inline void I(int c) {
        c -= 'a', s[++n] = c, cur = get_fail(last);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])][c];
            next[cur][c] = now;
            dep[now] = dep[fail[now]] + 1; //...
        }
        last = next[cur][c], cnt[last]++; id[n] = last, no[last] = n;
        df[last] = len[last] - len[fail[last]];
        slink[last] = (df[last] == df[fail[last]]) ? slink[fail[last]] : fail[last]; //...
    }
    inline void Insert(char s[], int op = 0, int _n = 0) {

```

```

    if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
}
inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
inline int Q() {
    rep(i, 0, n + 2) dp[i] = oo; dp[0] = 0;
    rep(i, 1, n + 1) {
        for (int t = id[i]; len[t] > 0; t = slink[t]) {
            res[t] = dp[i - len[slink[t]] - df[t]];
            if (df[t] == df[fail[t]]) res[t] = min(res[t], res[fail[t]]);
            dp[i] = min(dp[i], res[t] + 1);
        }
    }
    return dp[n];
}
};

```

/\*【题目】求给定串的最小回文切割段数【注意】如果要求段的长度为奇数或偶数，在

1.  $dp$ 赋值语句前限制，请不要乱改自动机[]如果要求段数为奇数或偶数，
2. 和开二维  $dpresdp[i]$  表示段数为偶数的答案][0]

\*/

### 3.3 PAM\_单串\_支持双端插入

```

const int M = 26;
struct PAM {
    int ss[2 * N], *s, len[N], next[N][M], fail[N], cnt[N], dep[N], id[N], no[N], last[2], n[2], p, cur, now, t; ll sum_cnt, ans;
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { s = ss + N; new_node(p = 0), new_node(s[0] = s[1] = -1), fail[last[0] = last[1] = n[1] = 0] = n[0] = 1; /*...*/ sum_cnt = 0; }
    inline int get_fail(int x, int op) { int t = op * 2 - 1; for (; s[n[op] - t*(len[x] + 1)] != s[n[op]]; x = fail[x]); return x; }
    inline void I(int c, int op) {
        c -= 'a', t = op * 2 - 1, s[n[op] += t] = c, s[n[op] + t] = -1, cur = get_fail(last[op], op);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur], op)][c];
            next[cur][c] = now;
            dep[now] = dep[fail[now]] + 1; /*...
        }
        last[op] = next[cur][c], cnt[last[op]]++;
        if (len[last[op]] == n[1] - n[0] + 1) last[op ^ 1] = last[op];
        id[n[op]] = last[op]; no[last[op]] = n[op] + (len[last[op]] - 1) * !op; /*...
        sum_cnt += dep[last[op]];
    }
    inline void Insert(char s[], int back = 1, int op = 0, int _n = 0) {
        if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i], back); else per(i, 0, _n) I(s[i], back);
    }
    inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
    inline void Q() { /*count();*/ }
};

```

/\*注:

- 1) 支持在线维护本质不同回文串个数  $p-2$  , 所有回文串个数  $sum\_cnt$  , 每个回文串出现的一次起点下标 ( 不保证最左最右 )
- 2) 注意  $id[x]$  是不准确的

\*/

/\*

```

6
1 a
1 b
2 a
2 c
3
4
8
1 a
2 a
2 a
1 a
3
1 b
3
4

```

```

4
5
4
5
11
1 左 2 右
3 p-2
4 sum_cnt
*/

```

### 3.4 PAM\_单串\_支持撤销\_单加 log

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N], id[N], no[N], pre[N], qlink[N], dep[N], last, n, p, cur, now; ll ans;
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; qlink[p] = 0; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; /* ... */ }
    inline bool ok(int x, int y, int d = 0) { return s[n - len[x] - d] == s[n - len[y]]; }
    inline int get_fail(int x) { for (; !ok(x, 0, 1); x = qlink[x]) if (ok(fail[x], 0, 1)) return fail[x]; return x; }
    inline void I(int c) {
        c -= 'a', s[++n] = c, cur = get_fail(last);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])][c];
            next[cur][c] = now; pre[now] = cur;
            dep[now] = dep[fail[now]] + 1; //...
            if (len[now] > 1) qlink[now] = ok(fail[now], fail[fail[now]]) ? qlink[fail[now]] : fail[fail[now]];
        }
        last = next[cur][c], cnt[last]++; id[n] = last, no[last] = n; //...
    }
    inline void D() { if (p <= 1) return; if (!cnt[last]) next[pre[last]][s[n]] = 0, --p; last = id[--n]; }
    inline void Insert(char s[], int op = 0, int _n = 0) {
        if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
    inline void Q() { /*count();*/ }
};

/*注:

```

- 1) 此模板如果不使用回退操作，总复杂度仍为线性，单次插入不超过  $\log(n)$ ，回退操作总是常数
- 2) 若有回退操作，总复杂度退化；使用可持久化线段树优化的 *dLink* 链接，单次插入可降为  $\log$  字符集

```

*/

```

### 3.5 PAM\_单串\_支持撤销\_单加可退化

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N], dep[N], id[N], no[N], pre[N], last, n, p, cur, now; ll ans;
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; }
    inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
    inline void I(int c) {
        c -= 'a', s[++n] = c, cur = get_fail(last);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])][c];
            next[cur][c] = now; pre[now] = cur;
            dep[now] = dep[fail[now]] + 1; //...
        }
        last = next[cur][c], cnt[last]++; id[n] = last, no[last] = n; //...
    }
    inline void D() { if (p <= 1) return; if (!cnt[last]) next[pre[last]][s[n]] = 0, --p; last = id[--n]; }
    inline void Insert(char s[], int op = 0, int _n = 0) {
        if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
    inline void Q() { /*count();*/ }
};

```

### 3.6 PAM\_多串模式

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N][11], dep[N], id[N], no[N], last, n, p, cur, now, str_cnt, d0; ll ans;

```

```

inline int new_node(int _l) { mem(next[p], 0); mem(cnt[p], 0); dep[p] = 0, len[p] = _l; return p++; }
inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; str_cnt = 0; d0 = -1; }
inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
inline void I(int c) {
    if (c < 0) { s[++n] = c; last = 1; return; }
    c -= 'a', s[++n] = c, cur = get_fail(last);
    if (!next[cur][c]) {
        now = new_node(len[cur] + 2);
        fail[now] = next[get_fail(fail[cur])][c];
        next[cur][c] = now;
        dep[now] = dep[fail[now]] + 1; //...
    }
    last = next[cur][c], cnt[last][str_cnt]++; id[n] = last, no[last] = n; //...
}
inline void Insert(char s[], int op = 0, int _n = 0) {
    if (str_cnt) I(-d0); if (!_n) _n = strlen(s);
    if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]); ++str_cnt;
}
inline void count() { per(i, 0, p) rep(j, 0, str_cnt) cnt[fail[i]][j] += cnt[i][j]; }
inline ll Q() { count(); /* ... */ }
};

```

### 3.7 PAM\_标准版本

```

const int M = 26;
struct PAM {
    int s[N], len[N], next[N][M], fail[N], cnt[N], dep[N], id[N], no[N], last, n, p, cur, now; ll ans;
    inline int new_node(int _l) { mem(next[p], 0); cnt[p] = dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; }
    inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
    inline void I(int c) {
        c -= 'a', s[++n] = c, cur = get_fail(last);
        if (!next[cur][c]) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])][c];
            next[cur][c] = now;
            dep[now] = dep[fail[now]] + 1; //...
        }
        last = next[cur][c], cnt[last]++; id[n] = last, no[last] = n; //...
    }
    inline void Insert(char s[], int op = 0, int _n = 0) {
        if (!_n) _n = strlen(s); if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void count() { per(i, 0, p) cnt[fail[i]] += cnt[i]; }
    inline void Q() { /*count();*/ }
};

```

### 3.8 PAM\_空间压缩\_单链表

```

struct Link {
    struct node { int id, x; node *nxt; }; node *head, *p; Link() { head = NULL; }
    void I(int id, int x) { head = new node{ id,x,head }; }
    int F(int id) { for (p = head; p; p = p->nxt) if (p->id == id) return p->x; return 0; }
};

struct PAM {
    int s[N], len[N], fail[N], cnt[N][3], dep[N], id[N], no[N], last, n, p, cur, now, str_cnt, d0, tt; Link next[N]; ll ans;
    inline int new_node(int _l) { mem(cnt[p], 0); dep[p] = 0, len[p] = _l; return p++; }
    inline void Init() { new_node(p = 0), new_node(s[0] = -1), fail[last = n = 0] = 1; str_cnt = 0; d0 = -1; }
    inline int get_fail(int x) { for (; s[n - len[x] - 1] != s[n]; x = fail[x]); return x; }
    inline void I(int c) {
        if (c < 0) { s[++n] = c; last = 1; return; }
        c -= 'a', s[++n] = c, cur = get_fail(last); tt = now = 0;
        if (!(tt = next[cur].F(c))) {
            now = new_node(len[cur] + 2);
            fail[now] = next[get_fail(fail[cur])].F(c);
            next[cur].I(c, now);
            dep[now] = dep[fail[now]] + 1; //...
        }
        last = tt + now, cnt[last][str_cnt]++; id[n] = last, no[last] = n; //...
    }
    inline void Insert(char s[], int op = 0, int _n = 0) {
        if (str_cnt) I(-d0); if (!_n) _n = strlen(s);
        if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]); ++str_cnt;
    }
    inline void count() { per(i, 0, p) rep(j, 0, str_cnt) cnt[fail[i]][j] += cnt[i][j]; }
    inline ll Q() { count(); /* ... */ }
};

```

### 3.9 SAM\_多串模式\_串运行\_树上合并\_map

```

struct SAM {
    static const int M = 26; ll dp[N << 1], ans; map<int, int> SS[N << 1];
    int go[N << 1][M], pre[N << 1], step[N << 1], rr[N << 1], temp[N << 1], toop[N << 1], id[N << 1], dep[N << 1], str_cnt,
    cnt, S, T, n, p, q, nq;
    inline int h(int c) { return c - 'a'; }
    inline int new_node(int _s, int c) { step[++cnt] = _s, pre[cnt] = dep[cnt] = 0, rr[cnt] = c; /* */mem(go[cnt], 0); return
    cnt; }
    inline void Init() { n = cnt = str_cnt = 0, S = T = new_node(0, 0); }
    inline void I(int c) {
        ++n, c = h(c), p = T; if (!go[p][c]) T = new_node(step[T] + 1, c);
        for (; p && !go[p][c]; p = pre[p]) go[p][c] = T;
        if (!p) pre[T] = S; else {
            q = go[p][c]; int &X = (p == T ? T : pre[T]);
            if (step[p] + 1 == step[q]) X = q; else {
                nq = new_node(step[p] + 1, c);
                rep(j, 0, M) go[nq][j] = go[q][j];
                for (; p && go[p][c] == q; p = pre[p]) go[p][c] = nq;
                pre[nq] = pre[q], X = pre[q] = nq;
            }
        }
        id[n] = T; SS[T][str_cnt]++; //...
    }
    inline void Insert(const char s[], int _n = 0, int op = 0) {
        if (!_n) _n = strlen(s); ++str_cnt; T = S;
        if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void Go(int &p, int c) { while (p && !go[p][c]) p = pre[p]; if (p) p = go[p][c], ans += dp[p]; }
    inline int Run(const char s[], int _n = 0, int op = 0) {
        if (!_n) _n = strlen(s); int pos = S, p = op * (_n - 1), q = (op ? -1 : _n); op = 1 - 2 * op; ans = 0;
        for (int i = p; i != q; i += op) if (pos) Go(pos, h(s[i])); else break; return pos;
    }
    inline int get_dep(int x) { return (!x || dep[x]) ? dep[x] : dep[x] = get_dep(pre[x]) + 1; }
    inline void Toop() {
        rep(i, 0, n + 1) temp[i] = 0; rep(i, 1, cnt + 1) temp[get_dep(i)]++;
        rep(i, 1, n + 1) temp[i] += temp[i - 1]; per(i, 1, cnt + 1) toop[temp[dep[i]] - 1] = i;
    }
    inline void Merge(int x, int y) { rep_it(it, SS[y]) SS[x][it->fir] += it->sec; }
    inline void Count() { per(i, 1, cnt + 1) Merge(pre[toop[i]], toop[i]); }
    inline void Q() {
        Toop(), Count(); rep(i, 1, cnt + 1) if (SS[i].size() >= k) dp[i] = step[i] - step[pre[i]]; else dp[i] = 0;
        rep(i, 1, cnt + 1) dp[toop[i]] += dp[pre[toop[i]]]; rep(i, 1, str_cnt + 1) Run(st[i].c_str()), printf("%lld ", ans);
    } //...
};

```

### 3.10 SAM\_广义\_trie 树

```

struct SAM {
    static const int M = 26; int go[N << 1][M], pre[N << 1], step[N << 1], rr[N << 1], temp[N << 1], toop[N << 1], num[N <<
    1], dep[N << 1], cnt, S, n, p, q, nq; ll dp[N << 1], ans = 0;
    inline int h(int c) { return c - 'a'; }
    inline int new_node(int _s, int c) { step[++cnt] = _s, pre[cnt] = num[cnt] = 0, rr[cnt] = c; /* */mem(go[cnt], 0); return
    cnt; }
    inline void Init() { n = cnt = 0, S = new_node(0, 0); }
    inline int I(int T, int c) {
        if (go[T][c = h(c)] && step[go[T][c]] == step[T] + 1) return go[T][c];
        ++n, p = T, T = new_node(step[T] + 1, c);
        for (; p && !go[p][c]; p = pre[p]) go[p][c] = T;
        if (!p) pre[T] = S; else {
            q = go[p][c];
            if (step[p] + 1 == step[q]) pre[T] = q; else {
                nq = new_node(step[p] + 1, c);
                rep(j, 0, M) go[nq][j] = go[q][j];
                for (; p && go[p][c] == q; p = pre[p]) go[p][c] = nq;
                pre[nq] = pre[q], pre[T] = pre[q] = nq;
            }
        }
        num[T]++; return T; //...
    }
    inline void Go(int &p, int c) { while (p && !go[p][c]) p = pre[p]; if (p) p = go[p][c], ans += dp[p]; }
    inline int Run(const char s[], int _n = 0, int op = 0) {
        if (!_n) _n = strlen(s); int pos = S, p = op * (_n - 1), q = (op ? -1 : _n); op = 1 - 2 * op; ans = 0;
        for (int i = p; i != q; i += op) if (pos) Go(pos, h(s[i])); else break; return pos;
    }
    inline int get_dep(int x) { return (!x || dep[x]) ? dep[x] : dep[x] = get_dep(pre[x]) + 1; }
    inline void Toop() {
        rep(i, 0, n + 1) temp[i] = 0; rep(i, 1, cnt + 1) temp[get_dep(i)]++;
        rep(i, 1, n + 1) temp[i] += temp[i - 1]; per(i, 1, cnt + 1) toop[temp[dep[i]] - 1] = i;
    }
    inline void Count() { per(i, 1, cnt + 1) num[pre[toop[i]]] += num[toop[i]]; }
    inline ll Q() {
        /* Toop(); Count(); */ //ll ans = 0; rep(i, 1, cnt + 1) ans += step[i] - step[pre[i]]; return ans; //...
    }
};

```



```

    }
};

const int _N = 1e5 + 5, _M = 1e5 + 5;
struct Tu {
    int head[_N], nxt[_M * 2], e[_M * 2], id[_N], n, tot; ll v[_N], w[_M * 2]; SAM M;
    inline void Init(int _n) { n = _n, mem(head, 0), tot = 0; M.Clear(); id[0] = M.S; }
    inline void I(int x, int y, ll _w = 0) { e[++tot] = y, w[tot] = _w; nxt[tot] = head[x], head[x] = tot; }
    void dfs(int x, int f) {
        id[x] = M.I(id[f], v[x]);
        for (int i = head[x]; i; i = nxt[i]) if (e[i] != f) dfs(e[i], x);
    }
    inline void Q() { /* */ }
};

// 此版本注意:  $N=2*M*V$ (结点数)

```

### 3.11 SAM\_标准版

```

struct SAM {
    static const int M = 26; int go[N << 1][M], pre[N << 1], step[N << 1], rr[N << 1], temp[N << 1], toop[N << 1], num[N << 1], id[N << 1], cnt, S, T, n, p, q, nq;
    inline int h(int c) { return c - 'a'; }
    inline int new_node(int _s, int c) { step[++cnt] = _s, pre[cnt] = num[cnt] = 0, rr[cnt] = c; /* */ mem(go[cnt], 0); return cnt; }
    inline void Init() { n = cnt = 0, S = T = new_node(0, 0); }
    inline void I(int c) {
        ++n, c = h(c), p = T, T = new_node(step[T] + 1, c);
        for (; p && !go[p][c]; p = pre[p]) go[p][c] = T;
        if (!p) pre[T] = S; else {
            q = go[p][c];
            if (step[p] + 1 == step[q]) pre[T] = q; else {
                nq = new_node(step[p] + 1, c);
                rep(j, 0, M) go[nq][j] = go[q][j];
                for (; p && go[p][c] == q; p = pre[p]) go[p][c] = nq;
                pre[nq] = pre[q], pre[T] = pre[q] = nq;
            }
        }
        num[id[n] = T]++; //...
    }
    inline void Insert(char s[], int _n = 0, int op = 0) {
        if (!_n) _n = strlen(s);
        if (!op) rep(i, 0, _n) I(s[i]); else per(i, 0, _n) I(s[i]);
    }
    inline void Toop() {
        rep(i, 0, n + 1) temp[i] = 0; rep(i, 1, cnt + 1) temp[step[i]]++;
        rep(i, 1, n + 1) temp[i] += temp[i - 1]; rep(i, 1, cnt + 1) toop[temp[step[i]] - 1] = i;
    }
    inline void Count() { per(i, 1, cnt + 1) num[pre[toop[i]]] += num[toop[i]]; }
    inline int Q() { Toop(); return 0; } //...
};

// rr[] 表示 right 集合, 用来维护需要量

```