

Jigsaw Puzzle

Fuzuo Zhang zfz_ll@163.com

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This is an application of **convex relaxation**.

1 Assumption

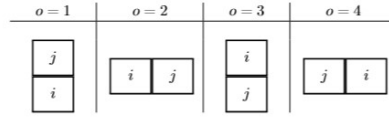


Figure 2: Four different configurations for an oriented pair of matching pieces (i, j, o) . In this paper we assume that the positive x axis points right while the positive y direction points down. From left to right the orientation takes values $o = \{1, 2, 3, 4\}$ respectively.

(a) four orientations

$$\delta_o^x = \begin{cases} 0 & \text{if } o = 1 \\ -1 & \text{if } o = 2 \\ 0 & \text{if } o = 3 \\ 1 & \text{if } o = 4 \end{cases}$$

$$\delta_o^y = \begin{cases} 1 & \text{if } o = 1 \\ 0 & \text{if } o = 2 \\ -1 & \text{if } o = 3 \\ 0 & \text{if } o = 4 \end{cases}$$

(b) desired offset: namely $\delta_0^x = x_i - x_j, \delta_o^y = y_i - y_j$

Figure 1: Assumption

2 Calculation Procedure

2.1 Compute D_{ijo}

We define D_{ijo} to be the MGC distance between pieces i and j with orientation o 1(a). We give the calculation of MGC distance for the example when $o = 2$: Before the formulations, we give the assumption: P :size of the image-block; c :color channel.

$$G_{iL}(p, c) = x_i(p, P, c) - x_i(p, P - 1, c) \quad (1)$$

$$\mu_{iL}(c) = \frac{1}{P} \sum_{p=1}^P G_{iL}(p, c) \quad (2)$$

$$G_{ijLR}(p, c) = x_j(p, 1, c) - x_i(p, P, c) \quad (3)$$

$$D_{LR}(x_i, x_j) = \sum_{p=1}^P (G_{ijLR}(p) - \mu_{iL}) S_{iL}^{-1} (G_{ijLR}(p) - \mu_{iL})^T \quad (4)$$

where the 3×3 covariance S_{iL} is estimated from G_{iL} captures the relationship of the gradients near the edge of the jigsaw piece between the color channels. To avoid numerical problems related to the inversion of S and the inherent issues of quantized pixel values, we include nine "dummy gradients" in the calculations, in the real project, I use $1e - 6 \times [[0, 0, 1], [1, 1, 1], [1, 0, 0]]$.

2.2 Compute w_{ijo}

The matching weight w_{ijo} associated with the oriented pair (i, j, o) can be computed as:

$$w_{ijo} = \frac{\min(\min_{k \neq i}(D_{kjo}), \min_{k \neq j}(D_{iko}))}{D_{ijo}} \quad (5)$$

2.3 Compute $U^{(k)}$

Given the entire set of puzzle pieces $V = \{i | i = 1, \dots, N \times M\}$

$$U^{(0)} = U = \{(i, j, o), \forall i \in V, \forall j \in V, \forall o \in \{0, 1, 2, 3\}\} \quad (6)$$

$$R^{(k)} = \{\forall (i, j, o) \in A^{(k)} : |x_i - x_j - \delta_o^x| \geq 10^{-5}\} \quad (7)$$

$$U^{(k)} = U^{(k-1)} - R^{(k)} \quad (8)$$

2.4 Compute $A^{(k)}$

$$A^{(k)} = \{(i, j, o) \in U^{(k)} : j = \arg \min_{j: (i, j, o) \in U^{(k)}} D_{ijo}\} \quad (9)$$

2.5 Solve Convex Problem

$$\begin{aligned} \arg \min_{x, h} \quad & \sum_{(i, j, o) \in A^{(k)}} w_{ijo} h_{ijo} \\ \text{subject to} \quad & h_{ijo} \geq x_i - x_j - \delta_o^x, \quad (i, j, o) \in A^{(k)} \\ & h_{ijo} \geq -x_i + x_j + \delta_o^x, \quad (i, j, o) \in A^{(k)} \end{aligned} \quad (10)$$

3 Algorithm Procedure

Algorithm 1: LP based Type 1 jigsaw puzzle solver

Input: Scrambled jigsaw puzzle pieces

Output: Assembled image

Initialisation: Generate initial pairwise matches $U^{(0)}$ (6) ;

Compute $A^{(0)}$ according to (9);

Solve (10) to get the initial solution $x^{(0)}, y^{(0)}$;

while *not converged* **do**

 Generate Rejected Matches $R^{(k)}$ using (7);

 Update $U^{(k)}$ (6) by discarding $R^{(k)}$;

 Compute pairwise matches $A^{(k)}$ according to eqrefeq:A;

 Solve (10), get new solution $x^{(k)}, y^{(k)}$

end

Trim and fill as necessary to get rectangular shape

References

- [1] Rui Yu, Chris Russell & Lourdes Agapito. *Solving Jigsaw Puzzles with Linear Programming*. 2015.
- [2] Andrew C. Gallagher & Rochester. *Jigsaw Puzzles with Pieces of Unknown Orientation*. 2012.