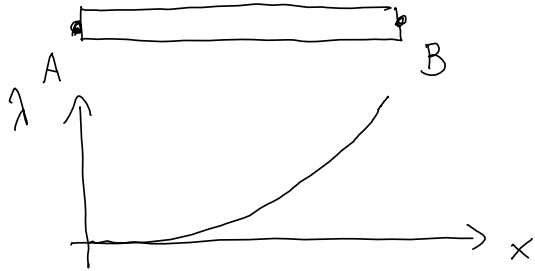


ESERCIZIO 1

$$m = 200 \text{ g}, \quad L = 1 \text{ m}, \quad S = 3 \text{ cm}^2$$

$$\lambda(x) = Hx^2$$



a) calcolo del centro di massa e H

$$x_{cm} = \frac{\int_0^L \lambda x dx}{m} = \frac{\int_0^L \frac{Hx^3}{m} dx}{m} = \frac{HL^4}{4m}$$

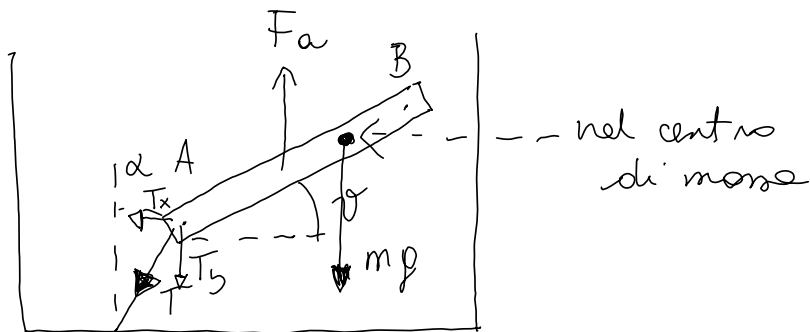
$$m = \int_0^L \lambda dx = \int_0^L Hx^2 dx = HL^3/3$$

$$\hookrightarrow H = \frac{3m}{L^3} = \frac{3 \cdot 0.2 \text{ kg}}{(1 \text{ m})^3} = 0.6 \frac{\text{kg}}{\text{m}^3}$$

$$x_{cm} = \frac{HL^4}{4m} = \frac{3m}{L^3} \frac{L^4}{4m} = \frac{3}{4} L = 75 \text{ cm}$$

(a)

b)



Eq Newton lungo $x \Rightarrow T_x = 0$

$$\Rightarrow \alpha = \arctan\left(\frac{T_x}{T_y}\right) = 0$$

Eq Newton lungo y

$$F_a - mg - T = 0 \quad (T = T_y)$$

$$T = F_a - mg = \rho V g - mg = g(\rho V - m)$$

dato che $T > 0$, $\rho > \frac{m}{V}$

densità media
del corpo

c) 2^a eq cardinale

$$F_a \frac{L}{2} \cos \theta - F_g \frac{3}{4} L \cos \theta = 0 \quad \text{EQUILIBRIO}$$

$$\cos \theta \frac{L}{2} (\rho V - \frac{3}{2} m) g = 0$$

Soluzioni: $\theta = 0$, $\theta = \pi$ sono sempre punti di equilibrio. \forall valore di ρ .

$$\forall \theta, \quad \rho V = \frac{3}{2} m \quad \text{EQUILIBRIO}$$

Se $\rho = \frac{3m}{V} = \frac{3m}{2SL}$, allora si ha equilibrio
statico $\forall \theta$.

$$\rho = \frac{3m}{2SL} = \frac{3 \cdot 0.2 \text{ kg}}{2 \cdot 3 \cdot 10^{-4} \text{ m}^2 \cdot 1 \text{ m}} \\ = 10^3 \frac{\text{kg}}{\text{m}^3}$$

In tal caso:

$$T = \rho(pV - m) = \\ = \frac{3}{2} mg - mg = \frac{1}{2} mg = 0.1 \text{ kg} \cdot 9.81 \frac{\text{m}}{\text{s}^2} \approx 1 \text{ N}$$

ESERCIZIO 2

$$r = 20 \text{ cm} = 0.2 \text{ m}$$

$$n = 4 \text{ mol} \quad \text{biatomico}$$

$$p = 1 \text{ atm} \quad T_1 = 20^\circ \text{C}$$

$$a) \quad pV = nRT = pSh_0 = p\pi r^2 h_0$$

$$h_0 = \frac{nRT_1}{\pi r^2 p} = \frac{4 \text{ mol} \cdot 8.314 \frac{\text{J}}{\text{mol K}} \cdot 293.15 \text{ K}}{\pi (0.2)^2 \text{ m}^2 \cdot 101325 \frac{\text{Pa}}{\text{m}^2}} = 0.766 \text{ m} = 76.6 \text{ cm}$$

$$b) \quad \text{trasf. rev. isobara}$$

$$T_2 = 0^\circ \text{C} = 273.15 \text{ K}$$

$$h_2 = \frac{nRT_2}{\pi r^2 p} = \frac{h_0}{T_1} \cdot T_2 = 76.6 \text{ cm} \cdot \frac{273.15}{293.15} = 0.713 \text{ m} = 71.3 \text{ cm} \quad \Delta h = -5.3 \text{ cm}$$

$$\Delta S_{\text{univ}} = 0 \quad (\text{trasf. rev.})$$

$$\Delta S_{\text{scambi}} + \Delta S_{\text{pos}} = 0$$

$$\delta Q_{\text{isobara}} = nC_p dT$$

$$\delta S = \frac{\delta Q}{T} = \frac{nC_p dT}{T}$$

$$\Delta S_{\text{pos}} = nC_p \ln\left(\frac{T_2}{T_1}\right)$$

$$\begin{aligned}\Delta S_{\text{gas}} &= n \cdot \frac{7}{2} R \ln \left(\frac{T_2}{T_1} \right) = \\ &= \frac{4 \text{ mol}}{2} \cdot 7 \cdot 8.314 \frac{\text{J}}{\text{mol K}} \ln \left(\frac{273.15}{293.15} \right) \\ &= -8.225 \text{ J/K}\end{aligned}$$

$$\Delta S_{\text{surroundings}} = -\Delta S_{\text{gas}} = 8.225 \text{ J/K}$$

(c) ISOCORA IRREVERSIBLE

$$\begin{aligned}P_f &= \frac{nRT_1}{\pi r^2 h_2} = \frac{nRT_1}{\pi r^2} \frac{\cancel{h_1^2} P}{nRT_2} = \\ &= 1 \text{ atm} \cdot \frac{293.15}{273.15} = 1.0732 \text{ atm}\end{aligned}$$

$$\Delta S_{\text{univ}} = \Delta S_{\text{gas}} + \Delta S_{\text{surp}}$$

$$\Delta S_{\text{gas}} = n C_V \ln \left(\frac{T_1}{T_2} \right) = n \frac{5}{2} R \ln \left(\frac{T_1}{T_2} \right)$$

$$\begin{aligned}\Delta S_{\text{surp}} &= \frac{\hat{Q}_1}{T_1} \quad \begin{array}{l} \hat{Q}_1 \text{ calore fornito da } T_1 \\ \text{al gas, pari a } \hat{Q}_1 = -nC_V \Delta T \end{array} \\ &= -nC_V \left(\frac{T_1 - T_2}{T_1} \right) = nC_V \left(-1 + \frac{T_2}{T_1} \right)\end{aligned}$$

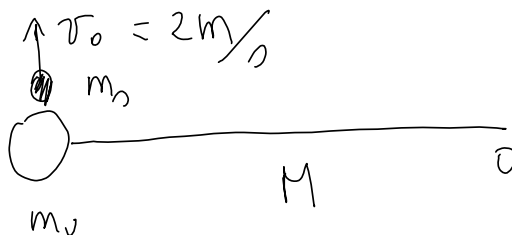
$$\begin{aligned}
 \Delta S_{\text{univ}} &= n \frac{5}{2} R \left[\ln \left(\frac{T_1}{T_2} \right) - 1 + \frac{T_2}{T_1} \right] = \\
 &= \frac{83.14 \text{ J}}{\text{K}} \left[\ln \left(\frac{293.15}{273.15} \right) - 1 + \frac{273.15}{293.15} \right] = \\
 &= 0.2 \frac{\text{J}}{\text{K}} > 0
 \end{aligned}$$

ESERCIZIO 3

$$m_v = 80 \text{ kg}$$

$$M = 210 \text{ kg}$$

$$R = 1.5 \text{ m}$$



(a) CONSERV. MOMENTO ANGOLARE \rightarrow rispetto al polo in \$O\$

$$-m_v v_0 R + m_v \omega R R + \underbrace{I_{\text{arte}}^O}_{\frac{1}{12} m R^2 + M \left(\frac{R}{2}\right)^2} \omega = 0$$

$$\omega \left(m_v R^2 + \frac{1}{3} m R^2 \right) = m_v v_0 R \quad \frac{m R^2 + 3 m R^2}{12} = \frac{1}{3} m R^2$$

$$\omega = \frac{m_v v_0}{R \left(m_v + \frac{M}{3} \right)} = \frac{80 \text{ kg} \cdot \frac{2 \text{ m}}{\text{s}}}{1.5 \text{ m} \left(80 \text{ kg} + 70 \text{ kg} \right)} = \frac{1}{5} \cdot \frac{1}{1.5} = \frac{2}{15} \frac{\text{rad}}{\text{s}}$$

(b) $v_0 = \frac{2 \text{ m}}{\text{s}}$

$$v_v = \omega R = \frac{2 \cdot 1.5 \text{ m}}{15} \frac{\text{rad}}{\text{s}} = \frac{0.2 \text{ m}}{\text{s}}$$

la velocità relativa è $2.2 \frac{m}{s}$

(c) Si conserva il momento angolare

$$mR^2 \omega + I_{\text{asta}}^0 \omega = \omega_f I_{\text{asta}}^0$$

$$\omega_f = \omega + \frac{mR^2 \omega}{I_{\text{asta}}^0} = \omega \left(1 + \frac{mR^2}{I_{\text{asta}}^0} \right)$$

$$= \omega \left(1 + \frac{mR^2}{\frac{1}{3}MR^2} \right) = \omega \left(1 + \frac{3m}{M} \right) =$$

$$= \omega \left(1 + \frac{240 \text{ kg}}{210 \text{ kg}} \right) =$$

$$= \omega \left(1 + \frac{8}{7} \right) = \frac{15}{7} \omega$$

$$= \frac{15}{7} \cdot \frac{2}{15} \frac{\text{rad}}{s} = \frac{2}{7} \frac{\text{rad}}{s}$$

(d) lavoro di due corpi per portarmi

$$L = \Delta E_k$$

$$E_k^{mix} = \frac{1}{2} (m_v R^2 + I_{axe}^0) \omega^2 =$$

$$\begin{aligned}
 E_k^{fun} &= \frac{1}{2} I_{axe}^0 \omega_f^2 = \\
 &= \frac{1}{2} I_{axe}^0 \left[\omega^2 + \frac{m_v^2 R^4 \omega^2}{I_{axe}^2} + \frac{2 \omega^2 m_v R^2}{I_{axe}} \right] = \\
 &= \frac{1}{2} I_{axe}^0 \omega^2 + \frac{1}{2} \frac{m_v^2 R^4 \omega^2}{I_{axe}} + \omega^2 m_v R^2
 \end{aligned}$$

$$\begin{aligned}
 \Delta E_k &= E_k^{fun} - E_k^{mix} = \frac{1}{2} m_v R^2 \omega^2 + \frac{1}{2} m_v R^2 \left(\frac{m_v R^2}{I_{axe}^0} \right) \omega^2 \\
 &= \frac{1}{2} m_v R^2 \omega \omega_f = \\
 &= 40 \text{ kg} \cdot (1.5)^2 \text{ m}^2 \cdot \frac{2}{15} \cdot \frac{2}{7} \cdot \frac{1}{2} = \\
 &= \boxed{3.43 \text{ J}}
 \end{aligned}$$

