Statistica - 16^a lezione

25 maggio 2021

Regressione multipla in 13 righe

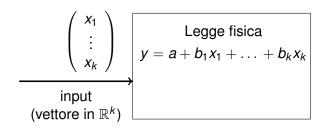
Modello	
Era	Sarà
Y = a + bx + E	$Y = a + b_1 x_1 + \ldots + b_k x_k + E$

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Era	Sarà
r ²	r ² adjusted

Regressione multipla in 13 righe

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Test sui coefficienti	
Erano	Saranno
$H_0: a = 0$ vs. $H_1: a \neq 0$	$H_0: a = 0$ vs. $H_1: a \neq 0$
$H_0: b = 0$ vs. $H_1: b \neq 0$	$H_0: b_i = 0$ vs. $H_1: b_i \neq 0$
	H_0 : tutti i b_i sono 0
	VS.
	H_1 : almeno uno dei b_i non è 0



$$\mathbf{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_k \end{pmatrix} \qquad \text{Legge fisica} \\ y = a + b_1 x_1 + \dots + b_k x_k \\ = a + \mathbf{x}^t \mathbf{b} \\ (a \in \mathbb{R}, \ \mathbf{b} \in \mathbb{R}^k)$$

Legge fisica
$$y = a + b_1 x_1 + \dots + b_k x_k$$
input
$$(vettore in \mathbb{R}^k)$$

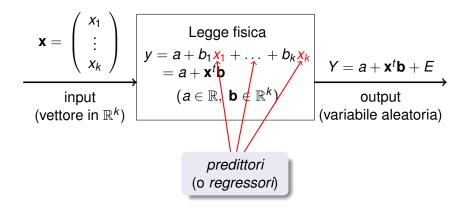
$$(a \in \mathbb{R}, \mathbf{b} \in \mathbb{R}^k)$$

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$$y = a + b_1 x_1 + \dots + b_k x_k$$

$$= a + \mathbf{x}^t \mathbf{b}$$
(vettore in \mathbb{R}^k)
$$(a \in \mathbb{R}, \mathbf{b} \in \mathbb{R}^k)$$

$$(variabile aleatoria)$$

Se facciamo *n* misure:

$$\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n \longrightarrow Y_1, Y_2, \dots, Y_n \text{ con } Y_i = a + \mathbf{x}_i^t \mathbf{b} + E_i$$

Legge fisica
$$y = a + b_1 x_1 + \dots + b_k x_k$$

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Ipotesi fondamentale del modello multilineare:

•
$$E_1, \ldots, E_n$$
 indipendenti $\Leftrightarrow Y_1, \ldots, Y_n$ indipendenti

•
$$E_i \sim N(0, \sigma^2) \ \forall i$$
 $\Leftrightarrow Y_i \sim N(a + \mathbf{x}_i^t \mathbf{b}, \sigma^2) \ \forall i$

Legge fisica
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Parametri incogniti: a, b, σ^2

PROBLEMA: Valutare quanto bene l'iperpiano

$$y = a + b_1x_1 + \ldots + b_kx_k = a + \mathbf{x}^t\mathbf{b}$$

interpola *n* punti $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ assegnati in \mathbb{R}^{k+1}

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$$e_i := y_i - (a + \mathbf{x}_i^t \mathbf{b})$$

i-esimo residuo

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$$L(a, \mathbf{b}) := \sum_{i=1}^{n} e_i^2 = \sum_{i=1}^{n} [y_i - (a + \mathbf{x}_i^t \mathbf{b})]^2$$

funzionale di errore

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i-esimo residuo

funzionale di errore

$$\tilde{\mathbf{x}} = \underbrace{\begin{pmatrix} 1 & x_{11} & \cdots & x_{1k} \\ 1 & x_{21} & \cdots & x_{2k} \\ \cdots & \cdots & \cdots & \cdots \\ 1 & x_{n1} & \cdots & x_{nk} \end{pmatrix}}_{n \times (k+1)} \quad \beta = \underbrace{\begin{pmatrix} a \\ b_1 \\ \vdots \\ b_k \end{pmatrix}}_{(k+1) \times 1}$$

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i-esimo residuo

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$$e_i := y_i - (a + \mathbf{x}_i^t \mathbf{b}) = y_i - (\tilde{\mathbf{x}}\boldsymbol{\beta})_i$$
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$$L(a, \mathbf{b}) := \sum_{i=1}^n e_i^2 = \sum_{i=1}^n \left[y_i - (a + \mathbf{x}_i^t \mathbf{b}) \right]^2$$
 funzionale di errore
$$= \sum_i (y_i - (\tilde{\mathbf{x}}\boldsymbol{\beta})_i)^2$$

$$\tilde{\mathbf{x}} = \underbrace{\begin{pmatrix} 1 & \mathbf{x}_1^t \\ 1 & \mathbf{x}_2^t \\ \dots & \dots \\ 1 & \mathbf{x}_n^t \end{pmatrix}}_{n \times (k+1)} \quad \boldsymbol{\beta} = \underbrace{\begin{pmatrix} a \\ \mathbf{b} \\ \mathbf{b} \end{pmatrix}}_{(k+1) \times 1} =: \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{pmatrix}$$

PROBLEMA: Valutare quanto bene l'iperpiano

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$$L(a, \mathbf{b}) := \sum_{i=1}^n e_i^2 = \sum_{i=1}^n \left[y_i - (a + \mathbf{x}_i^t \mathbf{b}) \right]^2$$
 funzionale di errore
$$= \sum_i (y_i - (\tilde{\mathbf{x}}\beta)_i)^2 = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$

$$\tilde{\mathbf{x}} = \begin{pmatrix} 1 & \mathbf{x}_1^t \\ 1 & \mathbf{x}_2^t \\ \dots & \dots \\ 1 & \mathbf{x}_n^t \end{pmatrix} \quad \beta = \begin{pmatrix} a \\ \mathbf{b} \end{pmatrix} =: \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_k \end{pmatrix} \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

$$\mathbf{B} = \left(\begin{array}{c} \mathbf{b} \\ \mathbf{b} \end{array}\right) =: \left(\begin{array}{c} \mathbf{\beta_1} \\ \mathbf{\beta_1} \\ \vdots \\ \mathbf{\beta_k} \end{array}\right)$$

 $(k+1)\times 1$

$$= \underbrace{\left(\begin{array}{c} y_2 \\ \vdots \\ y_n \end{array}\right)}_{n \times 1}$$

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
 rispetto a β : $\nabla_{\beta} L(\beta) = ?????$

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
 rispetto a β :

$$\nabla_{\beta} L(\beta) = -2\tilde{\mathbf{x}}^t(\mathbf{y} - \tilde{\mathbf{x}}\beta)$$

Minimizziamo
$$L(\boldsymbol{\beta}) = \|\mathbf{y} - \tilde{\mathbf{x}}\boldsymbol{\beta}\|^2$$
 rispetto a $\boldsymbol{\beta}$:

$$\nabla_{\beta} L(\beta) = -2\tilde{\mathbf{x}}^t(\mathbf{y} - \tilde{\mathbf{x}}\beta) = -2\tilde{\mathbf{x}}^t\mathbf{y} + 2\tilde{\mathbf{x}}^t\tilde{\mathbf{x}}\beta$$

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$$\stackrel{\text{se } \tilde{\mathbf{x}}^t\tilde{\mathbf{x}} \stackrel{\text{è invertibile}}{\Longrightarrow}}{\Longrightarrow} \beta = (\tilde{\mathbf{x}}^t\tilde{\mathbf{x}})^{-1}\tilde{\mathbf{x}}^t\mathbf{y}$$

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P. es., con k = 1 predittore:

$$\tilde{\mathbf{x}}^t \tilde{\mathbf{x}} = \begin{pmatrix} n & n\bar{x} \\ n\bar{x} & s_{xx} + n\bar{x}^2 \end{pmatrix}$$
 è invertibile $\Leftrightarrow s_{xx} \neq 0$

Altrimenti: collinearità

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
 rispetto a β :
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$$y = \hat{\beta}_0 + \hat{\beta}_1 x_1 + \ldots + \hat{\beta}_k x_k = (1 \mathbf{x}^t) \hat{\beta}$$
 iperpiano dei minimi quadrati (LSH)

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Come nel caso semplice:

$$\hat{y}_i := (1 \mathbf{x}_i^t) \hat{\boldsymbol{\beta}}$$

output dell'LSH

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
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 iperpiano dei minimi quadrati (LSH)

Come nel caso semplice:

$$\hat{\mathbf{y}}_i := (\mathbf{1} \ \mathbf{x}_i^t) \hat{\boldsymbol{\beta}}$$
 $\hat{\mathbf{e}}_i := \mathbf{v}_i - \hat{\mathbf{v}}_i$

output dell'LSH residui dell'LSH

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
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Come nel caso semplice:

$$\hat{y}_i := (1 \mathbf{x}_i^t)\hat{\beta}$$
 $\hat{e}_i := y_i - \hat{y}_i$
 $ss_r := \sum_i (\bar{y} - \hat{y}_i)^2$

output dell'LSH residui dell'LSH varianza spiegata

Minimizziamo
$$L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$$
 rispetto a β :
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$$\stackrel{\text{se } \tilde{\mathbf{x}}^t\tilde{\mathbf{x}} \stackrel{\text{è invertibile}}{\Longrightarrow}}{\beta} = (\tilde{\mathbf{x}}^t\tilde{\mathbf{x}})^{-1}\tilde{\mathbf{x}}^t\mathbf{y} =: \hat{\beta}$$

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Minimizziamo $L(\beta) = \|\mathbf{y} - \tilde{\mathbf{x}}\beta\|^2$ rispetto a β : $\nabla_{\beta} L(\beta) = -2\tilde{\mathbf{x}}^t(\mathbf{y} - \tilde{\mathbf{x}}\beta) = -2\tilde{\mathbf{x}}^t\mathbf{y} + 2\tilde{\mathbf{x}}^t\tilde{\mathbf{x}}\beta \equiv 0$

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$$ss_e = L(\hat{\beta}) = \min_{\beta} L(\beta)$$

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$$L_{k}(\beta) = \sum_{i} (y_{i} - \beta_{0} - \beta_{1}x_{i,1} - \dots - \beta_{k}x_{i,k})^{2} \qquad \beta \in \mathbb{R}^{k+1}$$

$$L_{k+1}(\beta') = \sum_{i} (y_{i} - \beta'_{0} - \beta'_{1}x_{i,1} - \dots - \beta'_{k+1}x_{i,k+1})^{2} \qquad \beta' \in \mathbb{R}^{k+2}$$

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$$L_k(\beta) \equiv L_{k+1} \begin{pmatrix} \beta \\ 0 \end{pmatrix}$$

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$$L_{k}(\beta) \equiv L_{k+1} \begin{pmatrix} \beta \\ 0 \end{pmatrix} \Rightarrow \min_{\beta} L_{k}(\beta) \geq \min_{\beta'} L_{k+1}(\beta')$$

OVERFITTING = ridurre ss_e aumentando i regressori:

$$ss_{e} = L(\hat{\beta}) = \min_{\beta} L(\beta)$$

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Perciò si preferisce usare l'r²-adjusted

$$r_A^2 := 1 - \frac{ss_e}{ss_t} \frac{n-1}{n-1-k}$$

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$$ss_{e} = L(\hat{\beta}) = \min_{\beta} L(\beta)$$

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Perciò si preferisce usare l'r²-adjusted

$$r_A^2 := 1 - \frac{ss_e}{ss_t} \frac{n-1}{n-1-k} \begin{cases} \leq r^2 \\ \text{decrescente in } k \end{cases}$$