

$$[\hat{z}_i, \hat{p}_j] = i\hbar \delta_{ij}$$

$$\psi(\vec{r}) = \langle \vec{r} | \psi \rangle$$

Inf. translation operator on  $|\psi\rangle$

$$|\psi\rangle = \hat{T}(d\vec{r}) |\psi\rangle$$

$$\langle \vec{r} | \hat{T}(d\vec{r}) = \langle \vec{r} | \hat{T}(d\vec{r}) |\psi\rangle$$

$$= \langle \psi | \hat{T}^\dagger(d\vec{r}) | \vec{r} \rangle^*$$

$$\text{um } \hat{T}^\dagger(d\vec{r}) = \hat{T}^\dagger(-d\vec{r}) = \hat{T}(-d\vec{r})$$

$$\langle \vec{r} | \psi \rangle = \langle \psi | \hat{T}^\dagger(d\vec{r}) | \vec{r} \rangle^*$$

$$= \langle \psi | \vec{r} - d\vec{r} \rangle^*$$

$$= \langle \vec{r} - d\vec{r} | \psi \rangle$$

$$\hat{z} |\vec{r}\rangle = \vec{r} |\vec{r}\rangle$$

$$|\hat{x}|x,y,z\rangle = x|x,y,z\rangle$$

$$|\hat{y}|x,y,z\rangle = y|x,y,z\rangle$$

$$\vdots$$

$$\psi'(\vec{r}) = \psi(\vec{r} - d\vec{r})$$

$$= \psi(\vec{r}) - d\vec{r} \cdot \vec{\nabla} \psi(\vec{r})$$

Andererseits:  $\psi'(\vec{r}) = \langle \vec{r} | \hat{T}(d\vec{r}) | \psi \rangle$

$$= \langle \vec{r} | \hat{1} - \frac{i}{\hbar} \hat{p} \cdot d\vec{r} | \psi \rangle$$

$$= \psi(\vec{r}) - \frac{i}{\hbar} d\vec{r} \cdot \langle \vec{r} | \hat{p} | \psi \rangle$$

$$\langle \vec{r} | \hat{p} | \psi \rangle = -i\hbar \vec{\nabla} \psi(\vec{r}) \rightarrow \hat{p} = (i\hbar \frac{\partial}{\partial x}, i\hbar \frac{\partial}{\partial y}, i\hbar \frac{\partial}{\partial z})$$

$\hat{A}, \hat{B}$  hermitisch

$$\langle \psi | \hat{A} | \psi \rangle = \langle \hat{A} \rangle$$

$$\Delta A = \langle (\hat{A} - \langle \hat{A} \rangle)^2 \rangle^{1/2}$$

$$\hat{A} = \hat{A} - \langle \hat{A} \rangle, \hat{B} = \hat{B} - \langle \hat{B} \rangle$$

$$\Delta A \Delta B \geq \frac{1}{2} |\langle [\hat{A}, \hat{B}] \rangle|$$

$$\langle \Delta A^2 \rangle = \langle \hat{A}^2 \rangle, \langle \Delta B^2 \rangle = \langle \hat{B}^2 \rangle$$

$$[\hat{A}, \hat{B}] = [\hat{A}, \hat{B}]$$

Belegk:  $\hat{C}(\lambda) = \hat{A} + i\lambda \hat{B}$

$$\hat{C}^\dagger(\lambda) = \hat{A} - i\lambda \hat{B}$$

$$\langle \hat{C} \hat{C}^\dagger \rangle = \langle \psi | \hat{C} \hat{C}^\dagger | \psi \rangle$$

$$= \langle \psi | \hat{C}^\dagger \hat{C} | \psi \rangle \geq 0$$

$$= \sum_n \langle \psi | \hat{C} | \psi_n \rangle \langle \psi_n | \hat{C}^\dagger | \psi \rangle$$

$$= \sum_n |\langle \psi | \hat{C} | \psi_n \rangle|^2 \geq 0$$

$$\langle (\hat{A} + i\lambda \hat{B})(\hat{A} - i\lambda \hat{B}) \rangle = \langle \hat{A}^2 + \lambda^2 \hat{B}^2 - i\lambda (\hat{A}\hat{B} - \hat{B}\hat{A}) \rangle$$

$$= \langle \Delta A^2 \rangle + \lambda^2 \langle \Delta B^2 \rangle - i\lambda \langle [\hat{A}, \hat{B}] \rangle \geq 0$$

$$= g(\lambda)$$

$$\frac{dg}{d\lambda} = 2\lambda \langle \Delta B^2 \rangle - i\lambda \langle [\hat{A}, \hat{B}] \rangle$$

Minimum versch. =  $\frac{i}{2} \frac{\langle [\hat{A}, \hat{B}] \rangle}{\langle \Delta B^2 \rangle}$  (pure imaginary)

$$\Rightarrow g(\lambda_0) = \langle \Delta A^2 \rangle + \frac{1}{4} \frac{\langle [\hat{A}, \hat{B}] \rangle^2}{\langle \Delta B^2 \rangle} \geq 0$$

$$\Rightarrow \langle \Delta A^2 \rangle \langle \Delta B^2 \rangle \geq \frac{1}{4} \langle [\hat{A}, \hat{B}] \rangle^2$$

$\Delta A \Delta B \geq \frac{1}{2} |\langle [\hat{A}, \hat{B}] \rangle|$

$\hat{A} = \hat{x}, \hat{B} = \hat{p}_x$   
 $[\hat{A}, \hat{B}] = i\hbar \rightarrow \Delta x \Delta p_x \geq \frac{1}{2} \hbar$

Inf. rotation:  $\delta \vec{r} = (\delta \varphi) \vec{n}$   
 $\rightarrow$  symmetrie-operator

$$\hat{R}(\delta \vec{r}) = \hat{1} - \frac{i}{\hbar} \vec{L} \cdot \delta \vec{r}$$

$$= \hat{1} - \frac{i}{\hbar} \vec{L} \cdot \vec{n} \delta \varphi$$

$\vec{L}$  rotation around  $x$ -axis

$$\hat{R}^\dagger(\delta \vec{r}) = \hat{R}^\dagger(\delta \vec{r}) = \hat{R}(-\delta \vec{r})$$

$$\langle \vec{r} | \hat{R}(\delta \vec{r}) | \psi \rangle = \langle \hat{R}(-\delta \vec{r}) \vec{r} | \psi \rangle = \langle \vec{r} - \delta \vec{r} \times \vec{r} | \psi \rangle$$

$$= \psi(\vec{r} - \delta \vec{r} \times \vec{r})$$

$$\vec{r}' = \vec{r} + \delta \vec{r} \times \vec{r}$$

$$\cong \psi(\vec{r}) - (\delta \vec{r} \times \vec{r}) \cdot \vec{\nabla} \psi(\vec{r})$$

$$= \psi(\vec{r}) - \delta \vec{r} \cdot (\vec{r} \times \vec{\nabla}) \psi(\vec{r})$$

$$\langle \vec{r} | \hat{R}(\delta \vec{r}) | \psi \rangle = \langle \vec{r} | \hat{1} - \frac{i}{\hbar} \delta \varphi \vec{L} \cdot \vec{n} | \psi \rangle$$

$$= \psi(\vec{r}) - \frac{i}{\hbar} \delta \varphi \langle \vec{r} | \vec{L} | \psi \rangle$$

$$\rightarrow \langle \vec{r} | \vec{L} | \psi \rangle = -i\hbar (\vec{r} \times \vec{\nabla}) \psi(\vec{r})$$

$$\vec{L} = \vec{r} \times \vec{p}$$

$$\hat{L}_x = \hat{y}\hat{p}_z - \hat{z}\hat{p}_y \quad [\hat{L}_x, \hat{L}_y] = [\hat{y}\hat{p}_z - \hat{z}\hat{p}_y, \hat{z}\hat{p}_x - \hat{x}\hat{p}_z]$$

$$\hat{L}_y = \hat{z}\hat{p}_x - \hat{x}\hat{p}_z \quad = -[\hat{y}\hat{p}_z, \hat{z}\hat{p}_x] + [\hat{z}\hat{p}_y, \hat{x}\hat{p}_z] - [\hat{z}\hat{p}_y, \hat{z}\hat{p}_x] - [\hat{y}\hat{p}_z, \hat{x}\hat{p}_z]$$

$$\hat{L}_z = \hat{x}\hat{p}_y - \hat{y}\hat{p}_x \quad = i\hbar \hat{L}_z$$

$$[\hat{L}_i, \hat{L}_j] = i\hbar \epsilon_{ijk} \hat{L}_k$$