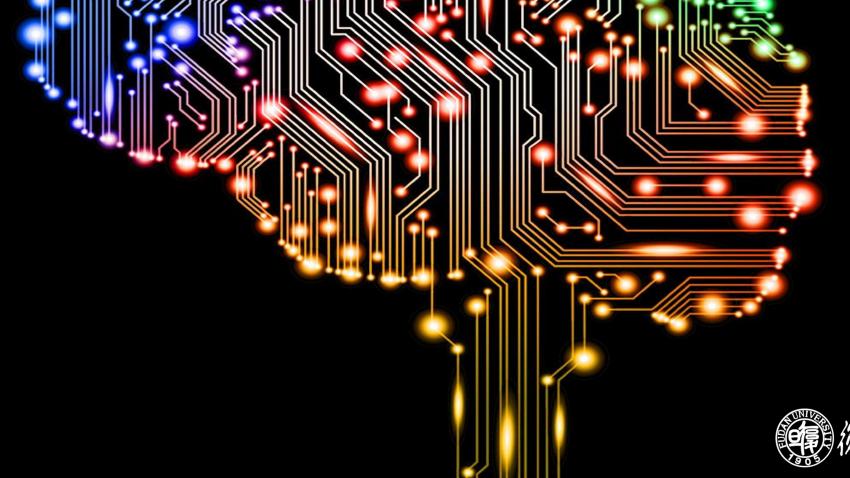
数据驱动的人工智能(2a)机器学习基础

Data Driven Artificial Intelligence

邬学宁 SAP硅谷创新中心 2017 / 02









44 目录

Lecture 1: Artificial Intelligence Overview

Lecture 2: Machine Learning Foundation

Lecture 3: Deep Learning

Lecture 4: Reinforcement Learning

Lecture 5: Probabilistic Graphic Model

Lecture 6: Natural Language Processing

Lecture 7: Industry 4.0 / Exam





44 日程

Linear Regression

Cost Function

Gradient Descent / Normal Equation

Logistic Regression

Perceptron

Machine Learning System Design





4 变量类型

Categorical 类别 (Qualitative 定性)	Numerical 数值 (quantitative 定量)
Nominal 名词性	Interval 区间性
Ordinal 顺序性	Ratio 比例性

Discrete 离散

Continuous 连续





66 回归 / 分类

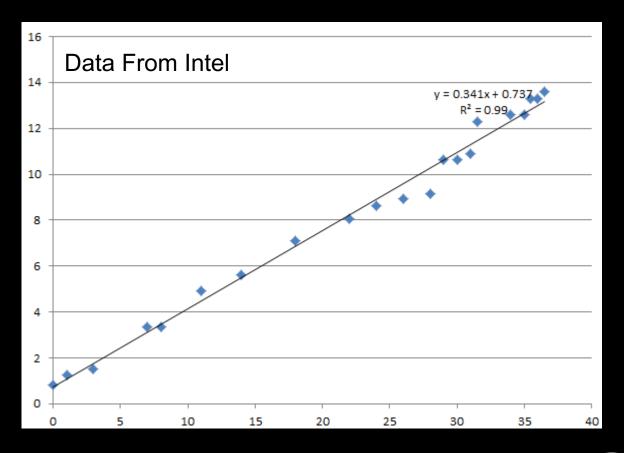
	分类 Classification	回归 Regression	
输出类型	离散 (分类标签)	连续(数值)	
分析目标	Decision Boundary	Best Fit Line	
评价	Accuracy / Confusion Matrix	Mean Squared Error / R ²	





Linear Regression (摩尔定律的线性回归)

Time(years)	e(years) Transistors (1K) log(Transistors)			
0	2.3	0.83		
1	3.5	1.25		
3	4.5	1.50		
7	29	3.37		
8	29	3.37		
11	134	4.90		
14	275	5.62		
18	1200	7.09		
22	3100	8.04		
24	5500	8.61		
26	7500	8.92		
28	9500	9.16		
29	42000	10.65		
30	42000	10.65		
31	55000	10.92		
31.5	220000	12.30		
34	291000	12.58		
35	291000	12.58		
35.5	582000	13.27		
36	582000	13.27		
36.5	820000	13.62		

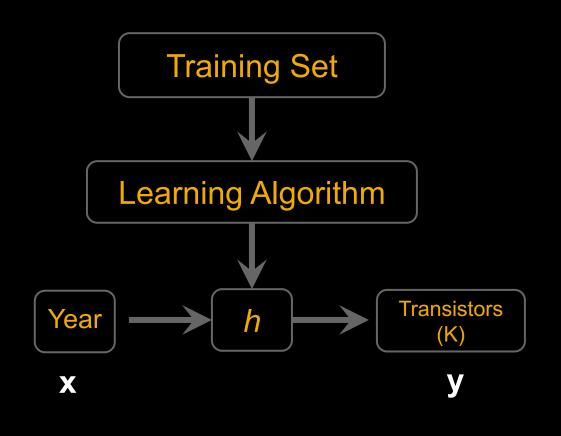






____Univariate Linear Regression 单变量线性回归

Model Representation 模型表达与标记说明



如何表达H?

$$H_{\theta}(\mathbf{x}) = \theta_0 + \theta_1 \mathbf{x} \tag{1}$$

Notation:

 \mathbf{m} = Number of training examples (rows) \mathbf{n} = Number of features (columns) \mathbf{x} 's = "input" variable / features (independent) \mathbf{y} 's = "output" / "target" variable (dependent) Turple ($x^{(i)}$, $y^{(i)}$) represent the i^{th} training example





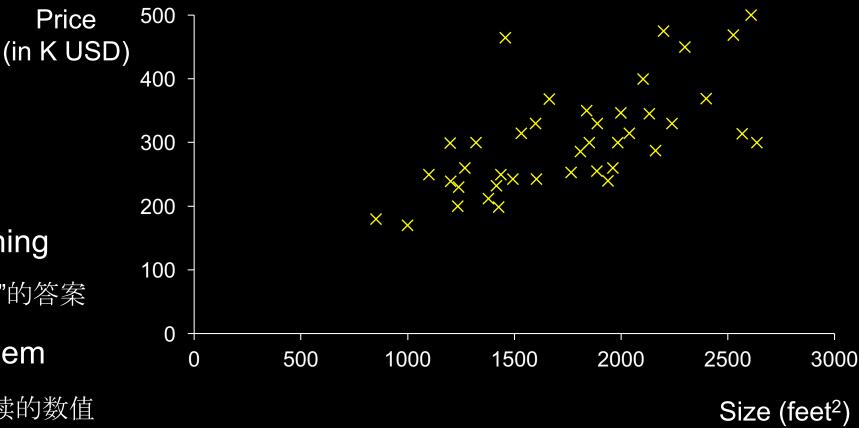
房价训练数据集 (Portland)

Size in feet ²	Price in 1K USD
(x)	(y)
2104	460
1416	232
1534	315
852	178





← 房价训练数据集 (Portland)



Supervised Learning
 给每个数据样本"正确"的答案

Regression Problem

预测目标:房价是连续的数值





┛ 房价训练数据集 (Portland)

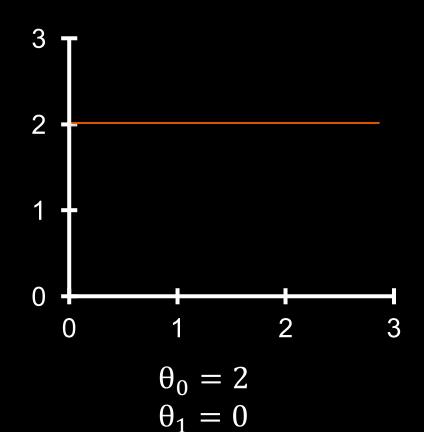
Size in feet ²	Price in 1K USD	
(x)	(y)	Hypothesis: $H_{\theta}(x) = \theta_0 + \theta_1 x$
2104	460	11 1 1 1 1 1 1 1 1 1
1416	232	θ's: Parameters / Weight
1534	315	0 3. I didiffictors / Weight
852	178	如何选择θ 's?

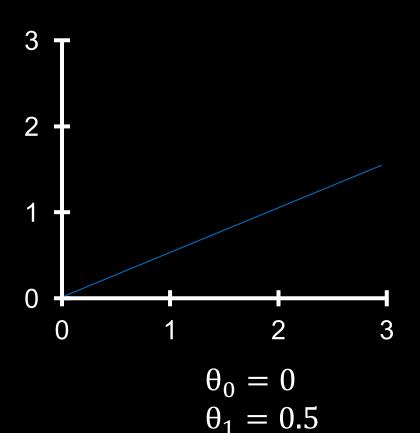


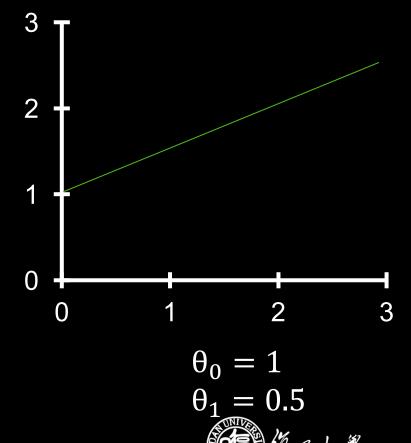


房价训练数据集 (Portland)

Hypothesis: $H_{\theta}(x) = \theta_0 + \theta_1 x$









Cost Function 代价函数 / 损失函数

如何表达模型的误差?

$$\mathcal{J}(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$$
 (2)

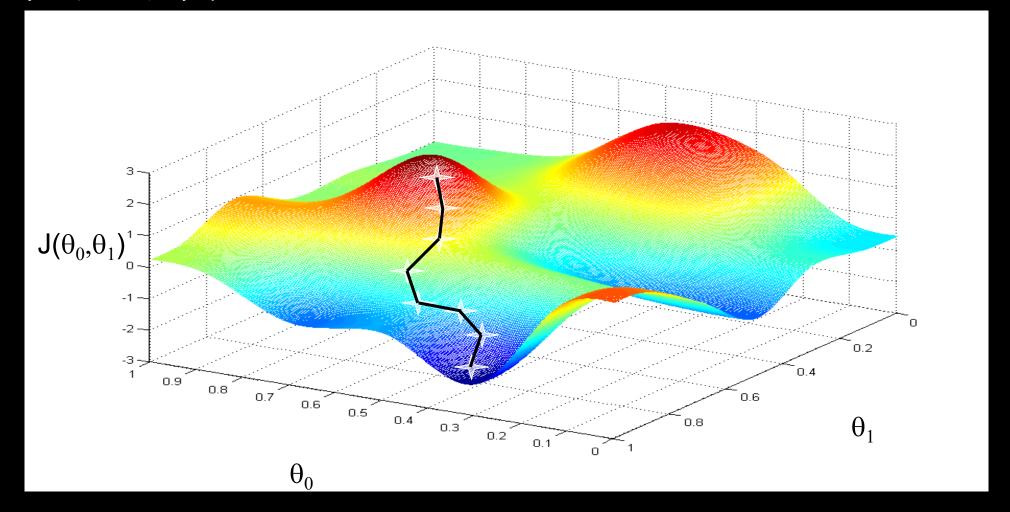
目标: 通过调整 θ_0 , θ_1 , 最小化 J (θ_0, θ_1)

方法: Gradient Descent





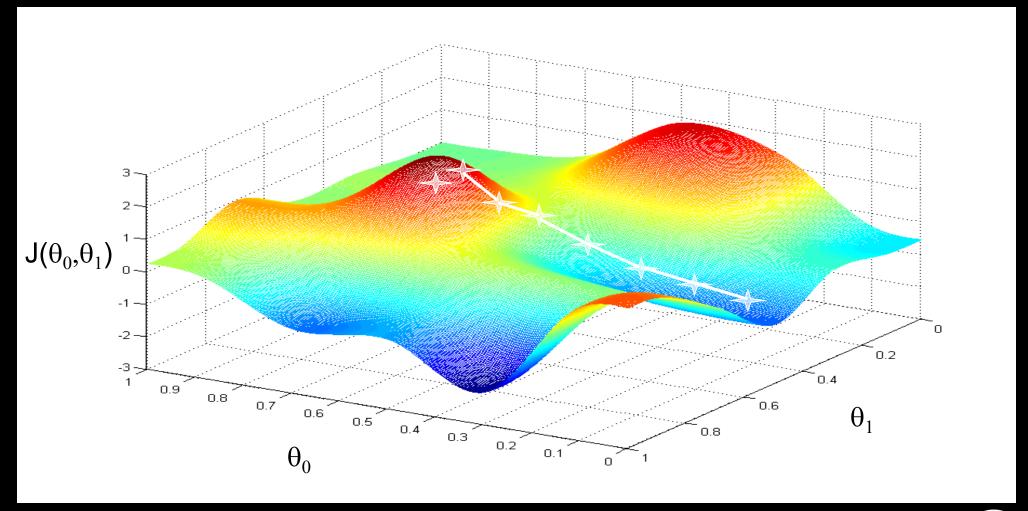
梯度下降 Gradient Descent







梯度下降 Gradient Descent







Gradient Descent

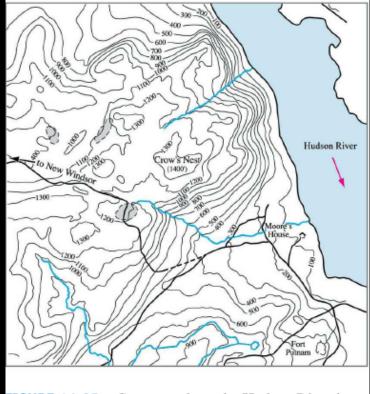
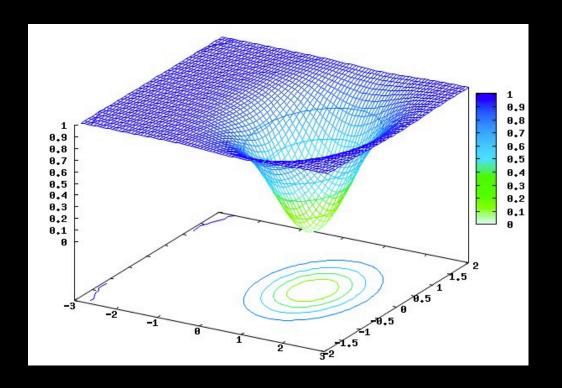


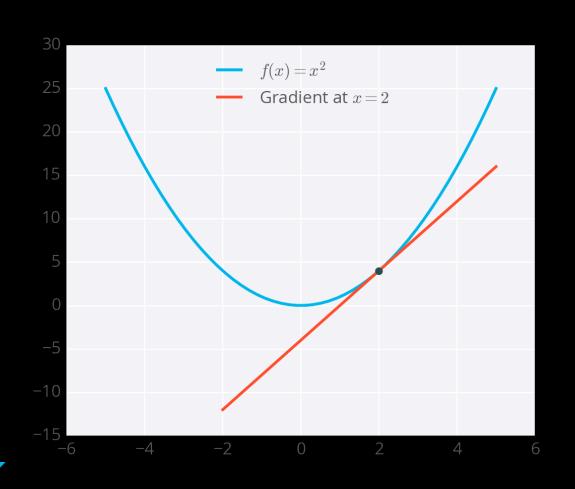
FIGURE 14.25 Contours along the Hudson River in New York show streams, which follow paths of steepest descent, running perpendicular to the contours.

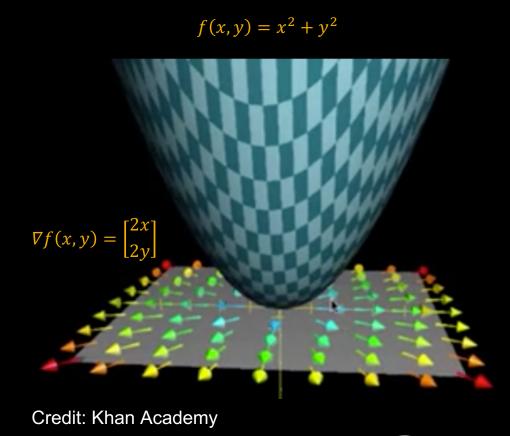






Gradient is the direction of steepest ascent 梯度是最陡峭的上升方向







Gradient Recap

$$f(x,y) = x^2 \sin y$$

$$\frac{\partial f}{\partial x} = 2x \sin y$$

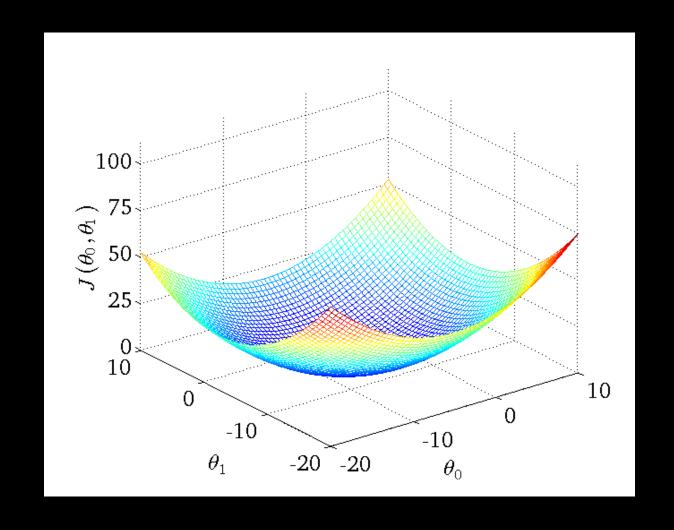
$$\frac{\partial f}{\partial y} = x^2 \cos y$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$

$$\nabla f(x,y) = \begin{bmatrix} 2x \sin y \\ x^2 \cos y \end{bmatrix}$$





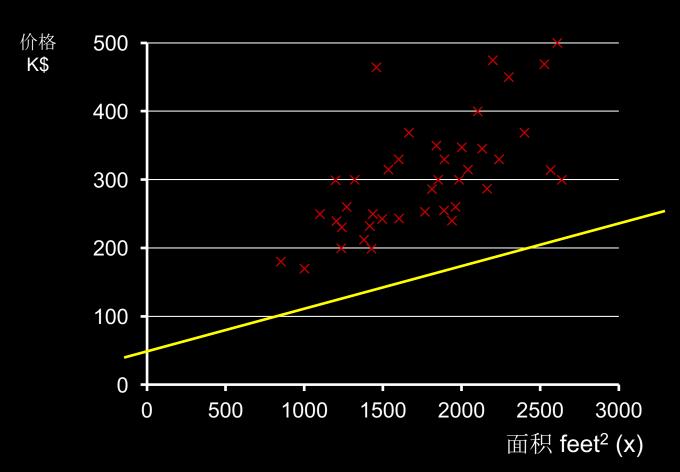


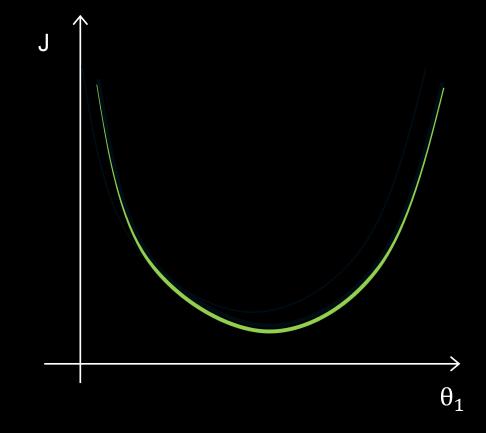




44 代价函数

关于参数 θ_1 的代价函数







$$h_{\theta}(\mathsf{x}) = 50 + 0.1\mathsf{x}$$



44 代价函数

问题:对于某代价函数 $\mathcal{J}(\theta_0,\theta_1)$:

我们希望能 minimize $\mathcal{J}(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2$

步骤:

- 从某任意值的 θ_0, θ_1 开始
- 不断改变 θ_0, θ_1 以降低 $J(\theta_0, \theta_1)$
- 直到最小值停止



4 调整参数

$$\theta_j := \theta_j - \text{learning_rate * gradient_of_}\theta_j$$

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} \mathcal{J}(\theta_0, \theta_1) \quad (j = 0, 1)$$
 (3)

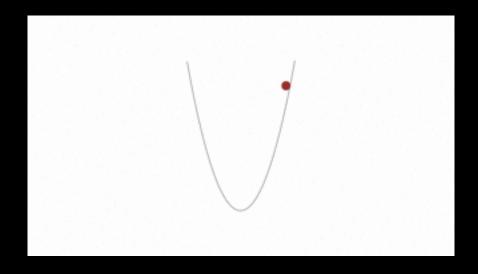




Learning Rate 学习率



理想情况收敛 Convergence



学习率过大导致发散 Divergence

- 经验值:0.1到0.0001之间,很多时候在0.001到0.0001之间;
- 当越逼近(局部)最优解时,梯度越小,参数更新的步幅也越小,因此,可能无需手动缩小步幅。



$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} \mathcal{J}(\theta_0, \theta_1) \quad (j = 0, 1)$$



$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} \mathcal{J} (\theta_0, \theta_1)$$

先计算 $\frac{\partial}{\partial \theta_i} \mathcal{J}(\theta_0, \theta_1)$,我们先计算只有一个数据样本的情况,即m=1的情况:

$$\frac{\partial}{\partial \theta_{j}} \mathcal{J} = \frac{\partial}{\partial \theta_{j}} \left(\frac{1}{2} (h_{\theta}(x) - y)^{2} \right)$$

$$= 2 \cdot \frac{1}{2} \cdot (h_{\theta}(x) - y) \cdot \frac{\partial}{\partial \theta_{j}} (h_{\theta}(x) - y)$$

$$= (h_{\theta}(x) - y) \cdot \frac{\partial}{\partial \theta_{j}} \left(\sum_{i=0}^{n} \theta_{i} x_{i} - y \right)$$

$$= (h_{\theta}(x) - y) \cdot x_{j}$$





∠ LMS算法 (Widrow-Hoff Learning Rule)

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} \mathcal{J} (\theta_0, \theta_1)$$

$$\theta_j := \theta_j + (y - h_{\theta}(x)) \cdot x_j$$

显然:参数更新的幅度(Magnitude)与误差 $(y - h_{\theta}(x))$ 呈正比。





∠ LMS算法 (Widrow-Hoff Learning Rule)

对于 m个训练样本:

循环至收敛 {

$$\theta_{j} := \theta_{j} + \alpha \cdot \frac{1}{m} \cdot \sum_{i=1}^{m} (y^{(i)} - h_{\theta}(x^{(i)})) \cdot x_{j}^{(i)}$$

显然:

- 参数更新的幅度(Magnitude)与误差 $(y h_{\theta}(x))$ 呈正比;
- 每次循环中,都逼历所有的训练样本,因此被称为Batch Gradient Descent





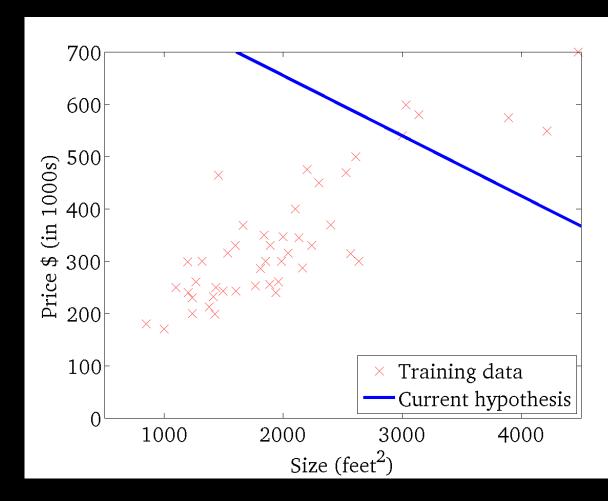
$$\theta_0 := \theta_0 + \alpha \cdot \frac{1}{m} \cdot \sum_{i=1}^m (y^{(i)} - h_{\theta}(x^{(i)}))$$

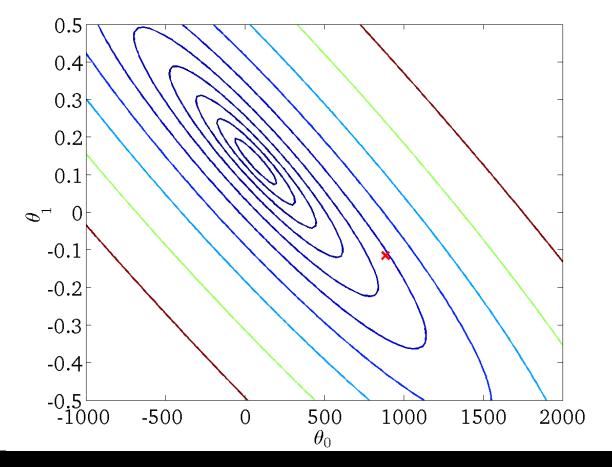
$$\theta_1 := \theta_1 + \alpha \cdot \frac{1}{m} \cdot \sum_{i=1}^m (y^{(i)} - h_{\theta}(x^{(i)})) \cdot x^{(i)}$$

显然:参数更新的幅度(Magnitude)与误差 $(y - h_{\theta}(x))$ 呈正比。



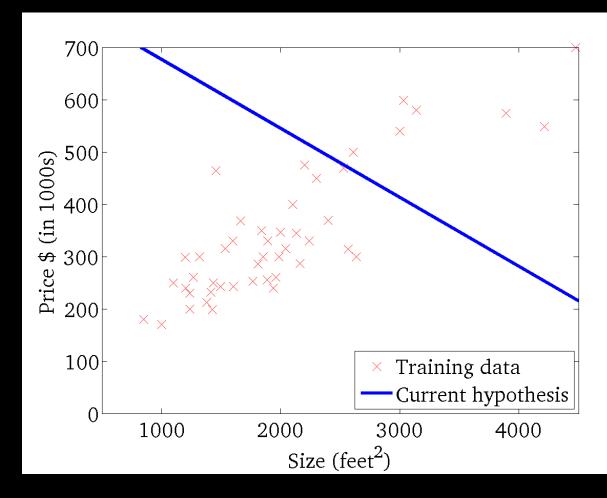


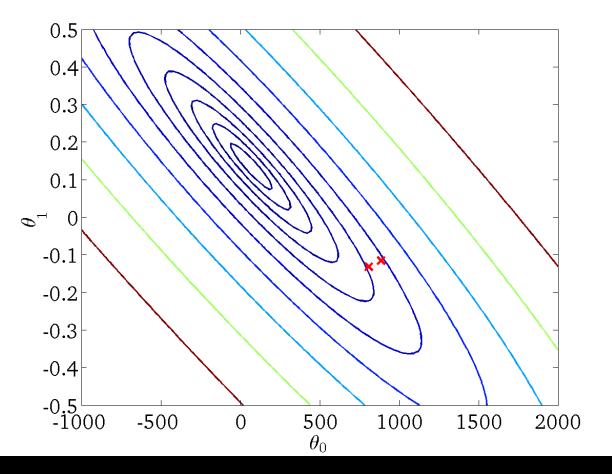






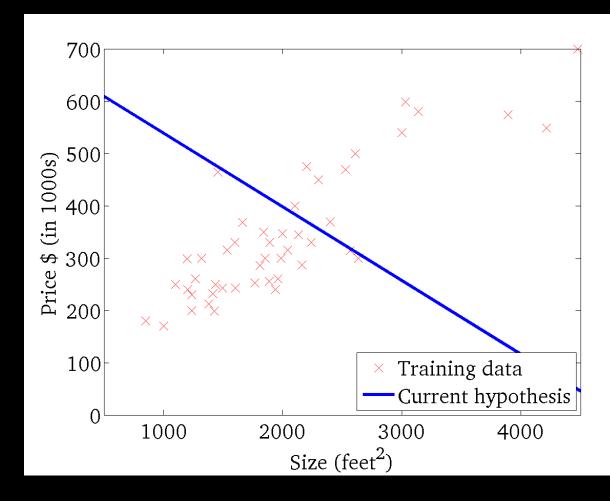


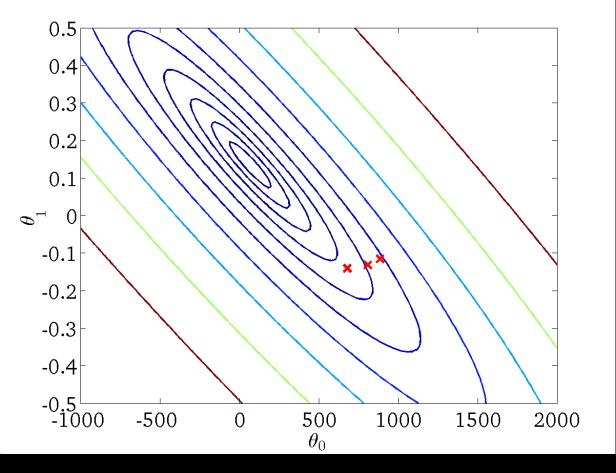






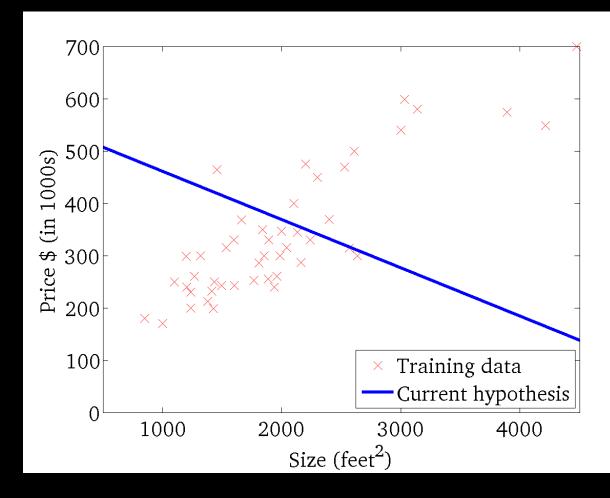


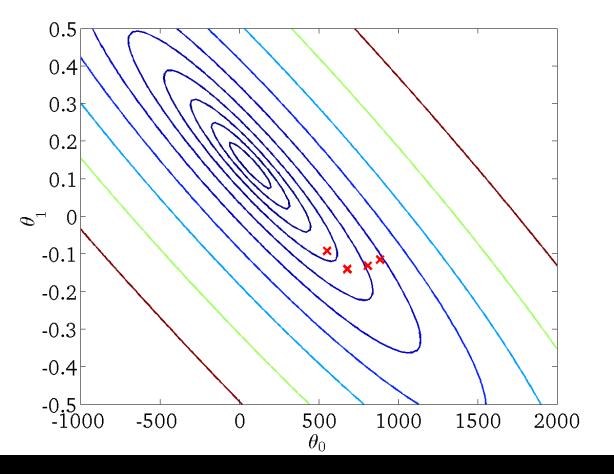








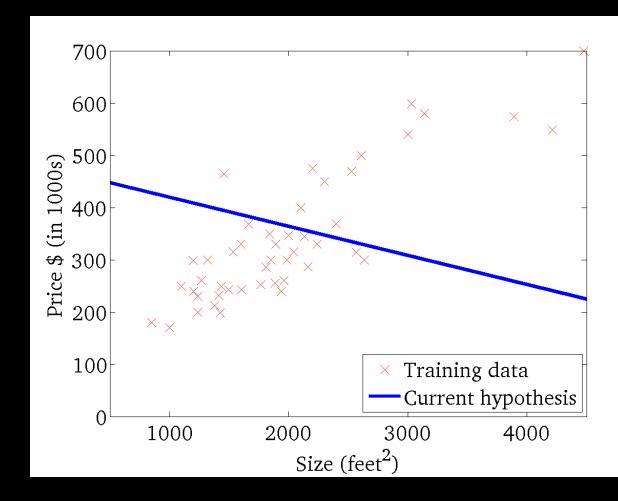


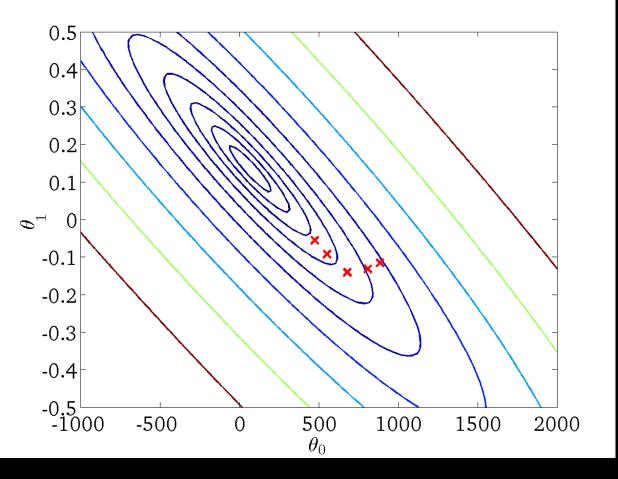






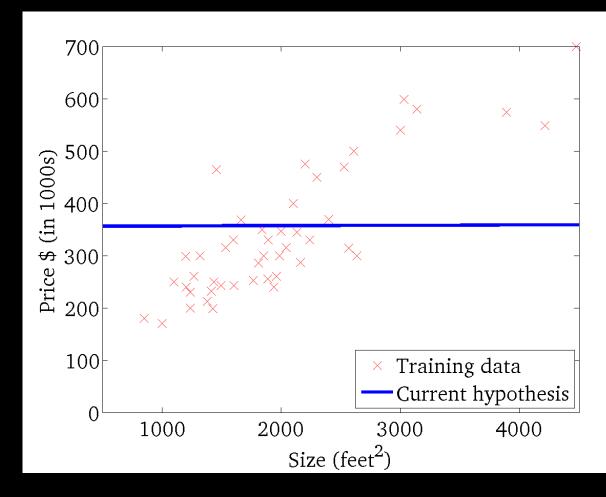
丝性回归/梯度下降

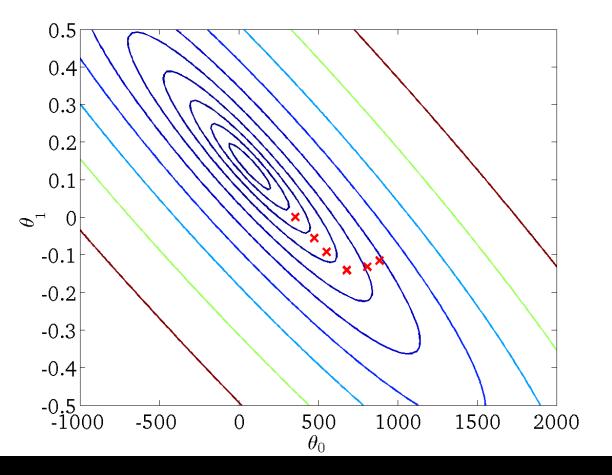






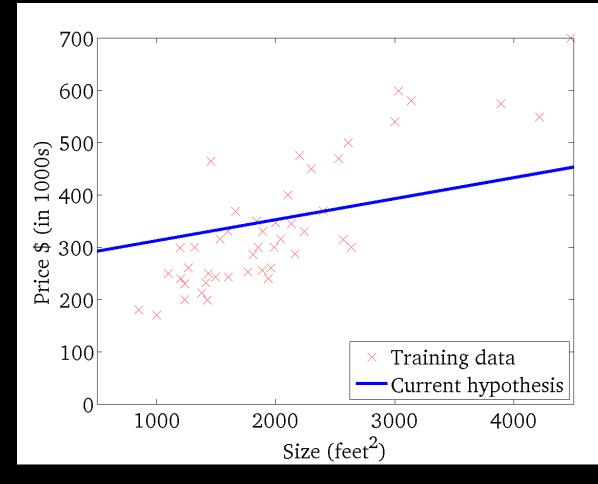


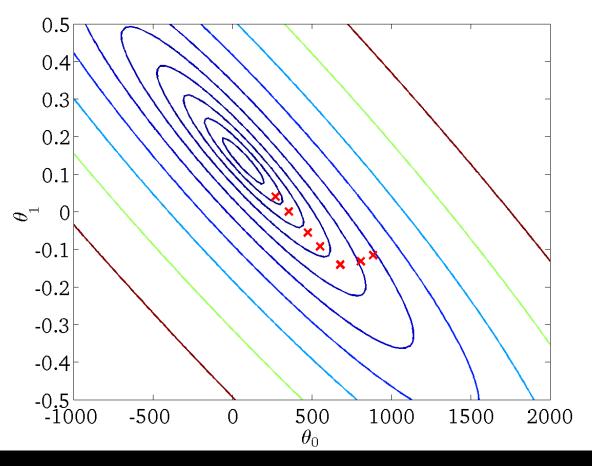






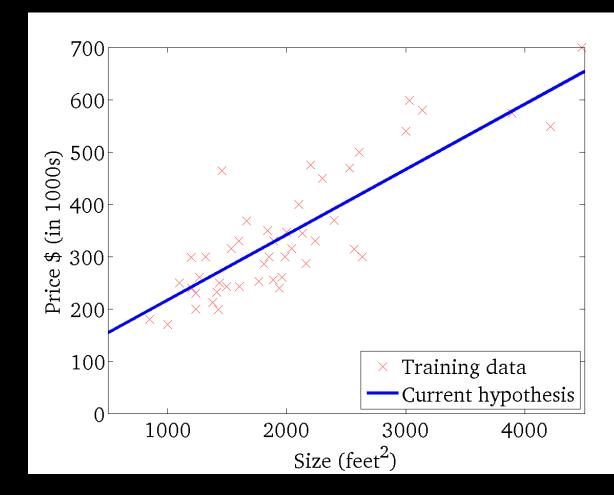


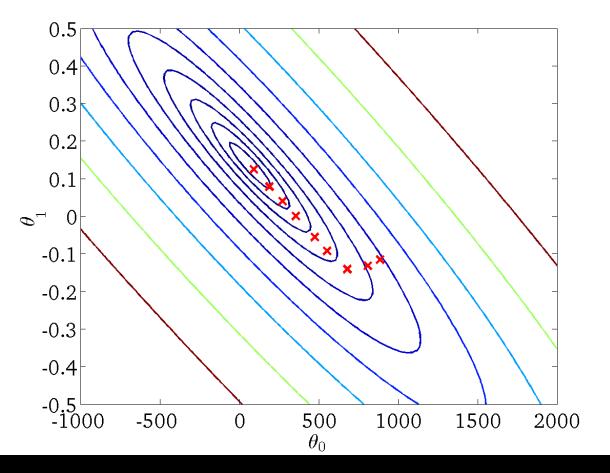












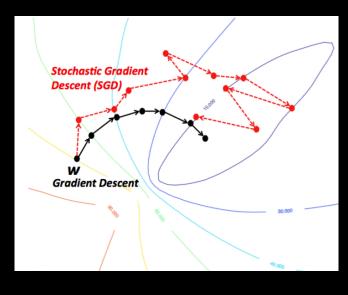




随机梯度下降 Stochastic Gradient Descent

- 1. 对训练样本的数据进行随机重排序
- 2. 利用单个训练样本就可以进行权重更新

```
Loop { for i=1 to m, \{ \theta_j := \theta_j + \alpha \left(y^{(i)} - h_{\theta}(x^{(i)})\right) x_j^{(i)} \qquad (for every j). \}}
```



Source: https://wikidocs.net/3413

思想:以随机梯度替代真正的梯度。在足够多步后,真正梯度的 均值≈随机梯度均值。

优点:简单,计算量小,对于大 数据量有用

缺点:稳定性欠缺一些







Mini-Batch Gradient Descent

```
Say b = 10, m = 1000.
Repeat {
   for i = 1, 11, 21, 31, \dots, 991 {
    \theta_j := \theta_j - \alpha \frac{1}{10} \sum_{k=1}^{i+9} (h_\theta(x^{(k)}) - y^{(k)}) x_j^{(k)}
              (for every j = 0, \ldots, n)
```





Multivariate Linear Regression

Model Representation

$$H_{\theta}(x) = \theta_0 + \theta_1 x_1 + \bullet \bullet \bullet + \theta_n x_n$$

= $\sum_{i=0}^n \theta_i x_i = \theta^T \bullet X$ (x₀=1)





Multivariate Linear Regression

Multiple features

Size (feet²)	Number of bedrooms	Number of floors	Age of home (years)	Price (\$1000)
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178

Credit: Andrew Ng

Notation:

- n = number of features
- $x^{(i)}$ = input (features) of the ith training example.



• $x_j^{(i)}$ = value of feature j in ith training example.



Multivariate Linear Regression

Multiple features (多变量线性回归)

Model:

$$h_{\theta}(\mathbf{x}) = \theta_0 x_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n \qquad (x_0 = 1)$$
$$= \theta^T x$$

Parameters: $\overline{\theta_0}$, $\overline{\theta_1}$, \cdots , $\overline{\theta_n}$

Cost Function: $\mathcal{J}(\theta_0, \theta_1, \dots, \theta_n) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$

Gradient Descent: (学迭代至收敛)

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} \mathcal{J}(\theta_0, \theta_1, \cdots, \theta_n)$$





Multivariate Linear Regression

Gradient Descent (梯度下降)

ひ迭代至收敛,每 Iteration / epoch 内使用矢量表达避免循环

$$\theta_{j} := \theta_{j} - \alpha \frac{\partial}{\partial \theta_{j}} \mathcal{J}(\theta_{0}, \theta_{1}, \cdots, \theta_{n})$$

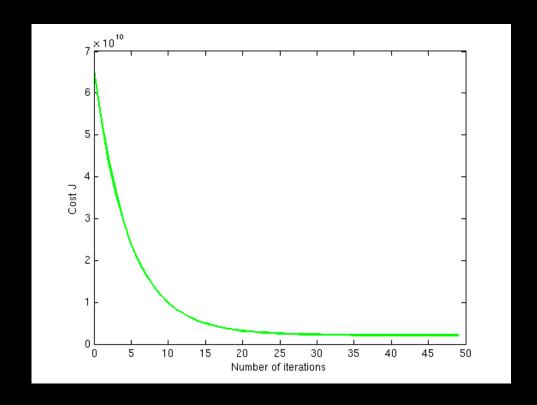
$$= \theta_{j} - \alpha \frac{1}{m} \sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)}) x^{(i)}$$

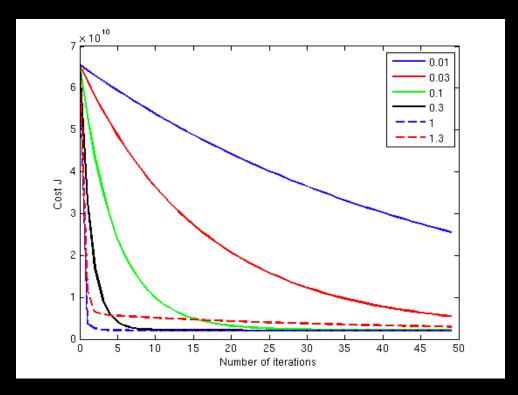
- 程序运行期间,需监控代价函数,确保其不但不断下降,而且还不至于太慢
- 合理选择α学习率
- Declare $\mathcal{J}(\boldsymbol{\theta})$ is convergence if decreases by less than 10^{-3} in one iteration





Learning Rate & Cost

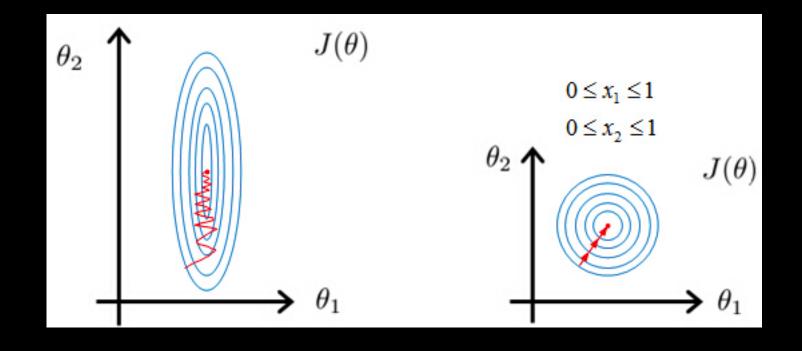








Feature Scaling



公式:
$$x' := \frac{x - x_{min}}{x_{max} - x_{min}}$$
 或 $x' := \frac{x - \overline{x}}{\sigma(x)}$







Thank you!

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