

# Padding & Strides in CNN

- Critical hyperparameters in CNN
- **Padding** = Adding extra pixels (usually zeros) around the input image to **control the size** of the output.
- **Stride** = Number of pixels the filter **moves (or "jumps")** each time it slides over the input.

## ● A. Padding: Adding Extra Pixels Around Image

0	0	0	0	0	0	0
0	7	2	3	3	8	0
0	4	5	3	8	4	0
0	3	3	2	8	4	0
0	2	8	7	2	7	0
0	5	4	4	5	4	0
0	0	0	0	0	0	0

? Why Padding?

When a filter moves over the image, it only works where the filter **fully fits** inside the image. So:

- Output size **shrinks**.
- Edge pixels get **less attention**.

**Padding helps:**

- **Preserve size** of input.
- **Capture edge features** better.

## How Padding Works?

Let's say you have:

**Input Image (5×5):**

`padding=" valid "` (Default)

$$\text{Output Size} = \left\lfloor \frac{\text{Input Size} - \text{Kernel Size}}{\text{Stride}} \right\rfloor + 1$$

```
[1 2 3 4 5
 6 7 8 9 10
11 12 13 14 15
16 17 18 19 20
21 22 23 24 25]
```

**Apply padding = 1, it becomes:**

`padding=" same "` : 🙌

```
[0 0 0 0 0 0 0
 0 1 2 3 4 5 0
 0 6 7 8 9 10 0]
```

```
0 11 12 13 14 15 0
0 16 17 18 19 20 0
0 21 22 23 24 25 0
0 0 0 0 0 0 0]
```

- This keeps the **output size same** after convolution.

$$\text{Output Size} = \left\lfloor \frac{\text{Input Size}}{\text{Stride}} \right\rfloor$$

## Padding in Keras:

```
model = Sequential()

model.add(Conv2D(32, kernel_size=(3,3), padding='same', activation='relu', input_shape=(28,28,1)))
model.add(Conv2D(32, kernel_size=(3,3), padding='same', activation='relu'))
model.add(Conv2D(32, kernel_size=(3,3), padding='same', activation='relu'))

model.add(Flatten())

model.add(Dense(128, activation='relu'))
model.add(Dense(10, activation='softmax'))
```

## B. Stride: How Much the Filter Moves Each Step

- By default, a filter moves **1 pixel at a time** (stride = 1).

## ? Why Stride?

- When we only want high level features
- We want to make the output smaller.
- Lower computing power
- We want to skip some positions for **speed** or **feature reduction**.

## How Stride Works?

### Example:

- Input:  $6 \times 6$
- Filter:  $3 \times 3$
- Stride = 1  $\rightarrow$  output =  $4 \times 4$
- Stride = 2  $\rightarrow$  output =  $2 \times 2$

## Stride in Keras:

```
model = Sequential()

model.add(Conv2D(32, kernel_size=(3,3), padding='same', strides=(2,2), activation='relu', input_shape=(28,28,1)))
model.add(Conv2D(32, kernel_size=(3,3), padding='same', strides=(2,2), activation='relu'))
model.add(Conv2D(32, kernel_size=(3,3), padding='same', strides=(2,2), activation='relu'))

model.add(Flatten())

model.add(Dense(128, activation='relu'))
model.add(Dense(10, activation='softmax'))
```

**strides=(2,2)  $\rightarrow$  Horizontal movement = 2 pixels, vertical movement=2 pixels**

## Trivia & Insights

- Large padding + stride = keeps model shallow but efficient.
- **Strided convolutions** can be used **instead of pooling**.
- Padding is like giving the image **"invisible margins"** so filters can slide fully even at the edge.
- Stride is like telling the filter: **"jump ahead this many pixels"**.