

# Solution guide for LA Homework 3@ csie.ntnu.edu.tw-2025

1. (16 %) Find generating sets for the range and null space ...

ANS: The standard matrix of L.T.  $T$  is  $A = [T(\mathbf{e}_1) \ T(\mathbf{e}_2) \ T(\mathbf{e}_3)] = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & 2 & 1 \end{bmatrix}$ . The reduced row echelon form of  $A$  is  $R = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ .

(i)  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right\}$  (or simply  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 2 \end{bmatrix} \right\}$ ) is a generating set for the range of  $T$ .

(ii)  $\left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\}$  is a generating set for the null space of  $T$ .

2. (12%) Given a linear transformation  $T$  ..., (a) Find a basis ...; (b) If the null space ..., find a basis for ...

ANS:

(a) The standard matrix of  $T$  is  $A = \begin{bmatrix} -2 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \end{bmatrix}$ . The reduced row echelon form of  $A$  is  $R = \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ .

The range of  $T$  equals the column space of  $A$ . Hence the set of pivots of  $A$ ,  $\{\mathbf{a}_1, \mathbf{a}_2\} = \left\{ \begin{bmatrix} -2 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 2 \\ 3 \end{bmatrix} \right\}$

is a basis for the range of  $T$ .

(b) The null space of  $T$  is the same as the null space of  $A$ ,  $\{\mathbf{x} \in \mathbb{R}^4; A\mathbf{x} = 0\}$ . The vector form of the general solution of  $A\mathbf{x} = 0$  is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix}.$$

Hence  $\left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$  is a basis for the null space of  $T$ .

3. (12%) Let  $\mathcal{L} = \dots$  Find a basis for the subspace  $V$  ...

ANS:

$$\left[ \begin{array}{ccccc} 0 & 1 & -1 & -3 & 1 \\ 0 & -1 & 1 & 3 & 2 \\ 1 & -3 & 1 & -1 & -1 \\ 0 & 2 & -2 & -6 & 1 \end{array} \right] \rightarrow \text{a row echelon form: } \left[ \begin{array}{ccccc} 1 & -3 & 1 & -1 & 1 \\ 0 & -1 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right].$$

Then,  $\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 2 \\ 1 \end{bmatrix} \right\}$  is a basis for the subspace  $V$  that contains  $\mathcal{L}$

4. (12%) Given a linearly independent subset ..., find a basis for the subspace  $V$  ...

ANS: From the pivot columns of the augmented matrix  $\left[ \begin{array}{ccccc} -1 & 5 & 1 & 1 & 0 \\ -1 & -9 & -2 & -1 & 1 \\ 6 & -2 & 0 & -2 & -2 \\ -7 & -1 & 1 & 3 & 10 \end{array} \right]$  which has a row

echelon form  $R = \left[ \begin{array}{ccccc} -1 & 5 & 1 & 1 & 0 \\ 0 & -14 & -3 & -2 & 1 \\ 0 & 0 & 12/7 & 8/7 & 52/7 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$ , we therefore get the basis  $\left\{ \begin{bmatrix} -1 \\ -1 \\ 6 \\ -7 \end{bmatrix}, \begin{bmatrix} 5 \\ -9 \\ -2 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

for the subspace  $V$  that contains the subset  $\mathcal{L}$

5. (12%) For the linear ... determine (a)the dimension ... ; (b)the dimension of the null ... ; (c)whether ...

ANS: (a) 3; (b) 0; (c) both one-to-one and onto (bijective or bijection)

(The standard matrix of  $T$  is  $A = \left[ \begin{array}{ccc} -1 & -1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 0 \end{array} \right]$  which has the row echelon form  $\left[ \begin{array}{ccc} -1 & -1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{array} \right]$ .

Thus, rank  $A=3$ .)

6. (12%) Find the unique representation of  $\mathbf{u} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$  as a linear combination ....

ANS:

By Theorem 4.11,  $[\mathbf{u}]_{\mathcal{B}} = B^{-1}\mathbf{u}$ , where  $B = [\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3]$ .

Therefore,  $[\mathbf{u}]_{\mathcal{B}} = \begin{bmatrix} 1 & 1 & 0 \\ -1 & 0 & 1 \\ 2 & 2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \dots = \begin{bmatrix} -2a - b + c \\ 3a + b - c \\ -2a + c \end{bmatrix}$ .

That is,  $\mathbf{u} = (-2a - b + c)\mathbf{b}_1 + (3a + b - c)\mathbf{b}_2 + (-2a + c)\mathbf{b}_3$

7. (12 %) Let  $\mathcal{B}=\{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$  ... (a) Show that.... (b)Determine the matrix... (c)What is the relationship

ANS:

(a) Let  $B=[\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3]$ . The reduced row echelon form of  $B$  is  $R_B=I_3$ . Since rank  $R_B=3$ ,  $\mathcal{B}$  is a linearly independent subset of  $\mathbb{R}^3$  containing 3 vectors.

(b)  $A=[B^{-1}\mathbf{e}_1 \ B^{-1}\mathbf{e}_2 \ B^{-1}\mathbf{e}_3]=B^{-1}I_3=B^{-1}=\begin{bmatrix} -3 & -1 & 2 \\ -4 & -1 & 2 \\ 3 & 1 & -1 \end{bmatrix}$

(c)  $A=B^{-1}$  as shown in (b).

8. (12%) Let  $\mathcal{A} = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n\}$  be a basis for  $\mathbb{R}^n$ ..., compute  $[\mathbf{v}]_{\mathcal{B}}$ .

ANS:

Let  $A = [\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_n]$  and  $B = [\mathbf{u}_1 \ \mathbf{u}_1 + \mathbf{u}_2 \ \dots \ \mathbf{u}_1 + \mathbf{u}_n]$ .

$$\text{Then, } B = A \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

$$\text{Since } [\mathbf{v}]_{\mathcal{B}} = B^{-1}\mathbf{v} = \left( A \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \right)^{-1} \mathbf{v} =$$

$$\left( \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \right)^{-1} A^{-1} \mathbf{v} = \begin{bmatrix} 1 & -1 & -1 & \cdots & -1 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} [\mathbf{v}]_{\mathcal{A}} =$$

$$\begin{bmatrix} 1 & -1 & -1 & \cdots & -1 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} a_1 - a_2 - \cdots - a_n \\ a_2 \\ \vdots \\ a_n \end{bmatrix}.$$