

# Homework 4 Solutions: Linear Algebra (2025)

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### Question 1 (20%)

**Problem:** Let  $T_w$  be the reflection of  $\mathbb{R}^3$  about the plane  $W$  in  $\mathbb{R}^3$  with equation  $x + 2y - 3z = 0$  and let

$$\mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix} \right\}.$$

Note that the first two vectors in  $\mathcal{B}$  lie in  $W$  and the third vector is perpendicular (normal) to  $W$ .

**(a) Find  $T_w(\mathbf{v})$  for each vector  $\mathbf{v}$  in  $\mathcal{B}$ .**

**Solution:**

Let  $\mathbf{b}_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}$ , and  $\mathbf{b}_3 = \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$ .

Since  $\mathbf{b}_1$  and  $\mathbf{b}_2$  lie in the plane  $W$ , the reflection leaves them unchanged:

$$T_w(\mathbf{b}_1) = \mathbf{b}_1$$

$$T_w(\mathbf{b}_2) = \mathbf{b}_2$$

Since  $\mathbf{b}_3$  is normal to the plane  $W$ , the reflection maps it to its negative:

$$T_w(\mathbf{b}_3) = -\mathbf{b}_3$$

**(b) Show that  $\mathcal{B}$  is a basis for  $\mathbb{R}^3$ .**

**Solution:**

The set  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$  consists of three vectors in  $\mathbb{R}^3$ . To show they form a basis, we need to show they are linearly independent.

Since  $\mathbf{b}_1$  and  $\mathbf{b}_2$  are non-parallel vectors in  $W$  (they are linearly independent), and  $\mathbf{b}_3$  is normal to  $W$  (and thus not in  $W$ ),  $\mathbf{b}_3$  cannot be written as a linear combination of  $\mathbf{b}_1$  and  $\mathbf{b}_2$ .

Alternatively, we can compute the determinant of the matrix formed by these vectors:

$$\det \begin{bmatrix} -2 & 3 & 1 \\ 1 & 0 & 2 \\ 0 & 1 & -3 \end{bmatrix} = -2(0 - 2) - 3(-3 - 0) + 1(1 - 0) = 4 + 9 + 1 = 14 \neq 0$$

Since the determinant is non-zero, the vectors are linearly independent and form a basis for  $\mathbb{R}^3$ .

**© Find**  $[T_w]_{\mathcal{B}}$ .

**Solution:**

Using the results from (a):

$$[T_w(\mathbf{b}_1)]_{\mathcal{B}} = [\mathbf{b}_1]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$[T_w(\mathbf{b}_2)]_{\mathcal{B}} = [\mathbf{b}_2]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$[T_w(\mathbf{b}_3)]_{\mathcal{B}} = [-\mathbf{b}_3]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$$

Thus, the matrix representation is:

$$[T_w]_{\mathcal{B}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

**(d) Find the standard matrix of  $T_w$ .**

**Solution:**

Let  $A$  be the standard matrix of  $T_w$ . We know that  $A = P[T_w]_{\mathcal{B}}P^{-1}$ , where  $P$  is the transition matrix from  $\mathcal{B}$  to the standard basis, i.e.,  $P = [\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3]$ .

$$P = \begin{bmatrix} -2 & 3 & 1 \\ 1 & 0 & 2 \\ 0 & 1 & -3 \end{bmatrix}$$

Computing  $A$ :

$$A = P \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} P^{-1}$$

Using computational tools, we find:

$$A = \begin{bmatrix} 6/7 & -2/7 & 3/7 \\ -2/7 & 3/7 & 6/7 \\ 3/7 & 6/7 & -2/7 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 6 & -2 & 3 \\ -2 & 3 & 6 \\ 3 & 6 & -2 \end{bmatrix}$$

**(e) Determine an explicit formula for  $T_w \begin{pmatrix} [x_1] \\ [x_2] \\ [x_3] \end{pmatrix}$ .**

**Solution:**

Using the standard matrix  $A$ :

$$T_w \begin{pmatrix} [x_1] \\ [x_2] \\ [x_3] \end{pmatrix} = A \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 6x_1 - 2x_2 + 3x_3 \\ -2x_1 + 3x_2 + 6x_3 \\ 3x_1 + 6x_2 - 2x_3 \end{bmatrix}$$

### Question 2 (12%)

**Problem:** Prove the following properties about matrix representations of linear transformations.

**(a) If  $A$  is the standard matrix of  $T$ , then  $[T]_{\mathcal{B}}^{\mathcal{C}} = C^{-1}AB$ .**

**Proof:**

By definition, the columns of  $[T]_{\mathcal{B}}^{\mathcal{C}}$  are coordinate vectors of  $T(\mathbf{b}_j)$  with respect to  $\mathcal{C}$ .

$$[T]_{\mathcal{B}}^{\mathcal{C}} = [[T(\mathbf{b}_1)]_{\mathcal{C}} \dots [T(\mathbf{b}_n)]_{\mathcal{C}}]$$

We know that  $T(\mathbf{x}) = A\mathbf{x}$ . So  $T(\mathbf{b}_j) = A\mathbf{b}_j$ .

The coordinate vector  $[\mathbf{v}]_{\mathcal{C}}$  is obtained by  $C^{-1}\mathbf{v}$ .

Thus,  $[T(\mathbf{b}_j)]_{\mathcal{C}} = C^{-1}A\mathbf{b}_j$ .

Therefore,

$$[T]_{\mathcal{B}}^{\mathcal{C}} = [C^{-1}A\mathbf{b}_1 \dots C^{-1}A\mathbf{b}_n] = C^{-1}A[\mathbf{b}_1 \dots \mathbf{b}_n] = C^{-1}AB$$

**(b)  $[T(\mathbf{v})]_{\mathcal{C}} = [T]_{\mathcal{B}}^{\mathcal{C}}$  for any vector  $\mathbf{v}$  in  $\mathbb{R}^n$ .**

**Proof:**

Let  $[\mathbf{v}]_{\mathcal{B}} = \mathbf{x}$ . Then  $\mathbf{v} = B\mathbf{x}$ .

$$T(\mathbf{v}) = T(B\mathbf{x}) = A(B\mathbf{x}) = (AB)\mathbf{x}$$

We want to find  $[T(\mathbf{v})]_{\mathcal{C}}$ , which is  $C^{-1}T(\mathbf{v})$ .

$$[T(\mathbf{v})]_{\mathcal{C}} = C^{-1}(AB)\mathbf{x} = (C^{-1}AB)\mathbf{x}$$

From part (a),  $[T]_{\mathcal{B}}^{\mathcal{C}} = C^{-1}AB$ .

So,

$$[T(\mathbf{v})]_{\mathcal{C}} = [T]_{\mathcal{B}}^{\mathcal{C}}[\mathbf{v}]_{\mathcal{B}}$$

$$\textcircled{e} [UT]_{\mathcal{B}}^{\mathcal{D}} = [U]_{\mathcal{C}}^{\mathcal{D}}[T]_{\mathcal{B}}^{\mathcal{C}}$$

**Proof:**

Let  $A$  be the standard matrix of  $T$  and  $M$  be the standard matrix of  $U$ .

From (a),  $[T]_{\mathcal{B}}^{\mathcal{C}} = C^{-1}AB$  and  $[U]_{\mathcal{C}}^{\mathcal{D}} = D^{-1}MC$ .

The standard matrix of the composition  $UT$  is  $MA$ .

Using (a) for  $UT$ :

$$[UT]_{\mathcal{B}}^{\mathcal{D}} = D^{-1}(MA)B$$

Now compute the product of the individual representations:

$$[U]_{\mathcal{C}}^{\mathcal{D}}[T]_{\mathcal{B}}^{\mathcal{C}} = (D^{-1}MC)(C^{-1}AB) = D^{-1}M(CC^{-1})AB = D^{-1}MIA = D^{-1}(MA)B$$

Thus,

$$[UT]_{\mathcal{B}}^{\mathcal{D}} = [U]_{\mathcal{C}}^{\mathcal{D}}[T]_{\mathcal{B}}^{\mathcal{C}}$$

### Question 3 (12%)

**Problem:** Find eigenvalues and basis for each eigenspace of  $T$ .

$$T \begin{pmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} -4x_1 + 6x_2 \\ 2x_2 \\ -5x_1 + 5x_2 + x_3 \end{bmatrix}$$

**Solution:**

The standard matrix of  $T$  is:

$$A = \begin{bmatrix} -4 & 6 & 0 \\ 0 & 2 & 0 \\ -5 & 5 & 1 \end{bmatrix}$$

The characteristic polynomial is  $\det(A - \lambda I)$ :

$$\det \begin{bmatrix} -4 - \lambda & 6 & 0 \\ 0 & 2 - \lambda & 0 \\ -5 & 5 & 1 - \lambda \end{bmatrix} = (2 - \lambda) \det \begin{bmatrix} -4 - \lambda & 0 \\ -5 & 1 - \lambda \end{bmatrix} = (2 - \lambda)(-4 - \lambda)(1 - \lambda)$$

The eigenvalues are  $\lambda = 2, -4, 1$ .

**For  $\lambda = 2$ :**

$$A - 2I = \begin{bmatrix} -6 & 6 & 0 \\ 0 & 0 & 0 \\ -5 & 5 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$x_1 = x_2, x_3 = 0$ . Basis:  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$ .

**For  $\lambda = -4$ :**

$$A + 4I = \begin{bmatrix} 0 & 6 & 0 \\ 0 & 6 & 0 \\ -5 & 5 & 5 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 \\ -1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$x_2 = 0, x_1 = x_3$ . Basis:  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$ .

**For  $\lambda = 1$ :**

$$A - I = \begin{bmatrix} -5 & 6 & 0 \\ 0 & 1 & 0 \\ -5 & 5 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$x_1 = 0, x_2 = 0, x_3$  is free. Basis:  $\left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ .

#### Question 4 (12%)

**Problem:** Given  $A = \begin{bmatrix} -2 & 3 & 6 \\ -2 & -8 & -2 \\ 6 & -1 & 4 \end{bmatrix}$  and characteristic polynomial  $-(t+5)(t+4)(t+2)$ , find  $P$  and  $D$ .

#### Solution:

There is a discrepancy in the problem statement. The characteristic polynomial of the matrix  $A$  as given is  $f(\lambda) = -(\lambda^3 + 6\lambda^2 - 56\lambda - 356)$ , which has non-integer roots (approximately 5.36, -3.11, -8.24). The provided polynomial  $-(t+5)(t+4)(t+2)$  has roots -5, -4, -2, which do not match the matrix.

As it is impossible to find a matrix  $P$  of eigenvectors for the provided polynomial without the correct corresponding matrix, and the matrix provided does not have simple integer eigenvalues suitable for manual diagonalization (and likely has a typo), we conclude that the problem cannot be solved as stated due to the contradiction.

If the matrix were such that its eigenvalues were -2, -4, -5, we would find the eigenvectors for each to form  $P$  and set  $D = \text{diag}(-2, -4, -5)$ .

#### Question 5 (10%)

**Problem:** Prove Cayley-Hamilton theorem for diagonalizable matrix  $A$ :  $f(A) = O$ .

**Proof:**

Since  $A$  is diagonalizable, there exists an invertible matrix  $P$  and a diagonal matrix  $D$  such that  $A = PDP^{-1}$ .

The characteristic polynomial is  $f(t)$ . Let  $\lambda_1, \dots, \lambda_n$  be the eigenvalues of  $A$ . These are the diagonal entries of  $D$ .

We compute  $f(A)$ :

$$f(A) = a_n A^n + \cdots + a_0 I = a_n (PDP^{-1})^n + \cdots + a_0 I$$

Since  $(PDP^{-1})^k = PD^k P^{-1}$ , we have:

$$f(A) = P(a_n D^n + \cdots + a_0 I)P^{-1} = Pf(D)P^{-1}$$

The matrix  $f(D)$  is a diagonal matrix with entries  $f(\lambda_i)$  on the diagonal.

$$f(D) = \text{diag}(f(\lambda_1), \dots, f(\lambda_n))$$

Since each  $\lambda_i$  is a root of the characteristic polynomial  $f(t)$ , we have  $f(\lambda_i) = 0$  for all  $i$ . Thus,  $f(D)$  is the zero matrix.

$$f(A) = P \cdot O \cdot P^{-1} = O$$

### Question 6 (10%)

**Problem:** Determine if  $T$  is diagonalizable, where  $T \begin{pmatrix} [x_1] \\ [x_2] \\ [x_3] \end{pmatrix} = \begin{bmatrix} 4x_1 - 5x_2 \\ -x_2 \\ -x_3 \end{bmatrix}$ .

**Solution:**

The standard matrix is  $A = \begin{bmatrix} 4 & -5 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ .

Since  $A$  is upper triangular, the eigenvalues are the diagonal entries:

$$\lambda_1 = 4, \lambda_2 = -1, \lambda_3 = -1.$$

Algebraic multiplicities:  $\lambda = 4$  is 1,  $\lambda = -1$  is 2.

We check the geometric multiplicity of  $\lambda = -1$ .

$$A - (-1)I = \begin{bmatrix} 5 & -5 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

The system  $x_1 - x_2 = 0$  has two free variables ( $x_2$  and  $x_3$ ). Thus the dimension of the eigenspace is 2.

Since the geometric multiplicity (2) equals the algebraic multiplicity (2) for  $\lambda = -1$ , and the multiplicities match for  $\lambda = 4$  (both 1), the operator  $T$  is **diagonalizable**.

A basis  $\mathcal{B}$  can be formed by the union of basis vectors for the eigenspaces:

$$\text{For } \lambda = -1: \text{ Basis } \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

$$\text{For } \lambda = 4: \text{ Basis } \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}.$$

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

### Question 7 (12%)

**Problem:** Find  $c$  for which  $T$  is not diagonalizable.

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & c & 0 \\ 6 & -1 & 6 \end{bmatrix}, f(t) = -(t - c)(t - 3)(t - 4).$$

**Solution:**

The eigenvalues are  $c, 3, 4$ .

$T$  is diagonalizable if the geometric multiplicity equals the algebraic multiplicity for every eigenvalue.

If  $c, 3, 4$  are distinct ( $c \neq 3$  and  $c \neq 4$ ),  $T$  is diagonalizable.

We check the cases where eigenvalues are repeated:

**Case 1:**  $c = 3$ .

Eigenvalues are  $3, 3, 4$ . Algebraic multiplicity of  $\lambda = 3$  is 2.

We check the rank of  $A - 3I$ :

$$A - 3I = \begin{bmatrix} -2 & 2 & -1 \\ 0 & 0 & 0 \\ 6 & -1 & 3 \end{bmatrix}$$

Row 3 is not a multiple of Row 1 (independent). The rank is 2.

Geometric multiplicity =  $3 - \text{Rank} = 3 - 2 = 1$ .

Since  $1 < 2$ ,  $T$  is **not diagonalizable** for  $c = 3$ .

**Case 2:**  $c = 4$ .

Eigenvalues are  $4, 4, 3$ . Algebraic multiplicity of  $\lambda = 4$  is 2.

We check the rank of  $A - 4I$ :

$$A - 4I = \begin{bmatrix} -3 & 2 & -1 \\ 0 & 0 & 0 \\ 6 & -1 & 2 \end{bmatrix}$$

Row 3 is not a multiple of Row 1. Rank is 2.

Geometric multiplicity =  $3 - 2 = 1$ .

Since  $1 < 2$ ,  $T$  is **not diagonalizable** for  $c = 4$ .

**Answer:**  $c = 3$  and  $c = 4$ .

**Question 8 (12%)**

**Problem:**  $T(a\mathbf{u} + b\mathbf{v} + c\mathbf{w}) = a\mathbf{u} + b\mathbf{v} - c\mathbf{w}$  for basis  $\mathcal{B} = \{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ .

**(a) Find eigenvalues and basis for each eigenspace.**

**Solution:**

From the definition:

$$T(\mathbf{u}) = 1\mathbf{u}$$

$$T(\mathbf{v}) = 1\mathbf{v}$$

$$T(\mathbf{w}) = -1\mathbf{w}$$

The eigenvalues are  $\lambda = 1$  and  $\lambda = -1$ .

Eigenspace for  $\lambda = 1$ : Spanned by  $\{\mathbf{u}, \mathbf{v}\}$ .

Eigenspace for  $\lambda = -1$ : Spanned by  $\{\mathbf{w}\}$ .

**(b) Is  $T$  diagonalizable?**

**Solution:**

Yes. The sum of dimensions of the eigenspaces is  $2 + 1 = 3$ , which equals the dimension of the space  $\mathbb{R}^3$ .

Also, the matrix representation relative to  $\mathcal{B}$  is diagonal: 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}.$$