

Homework 4, for Linear Algebra class@csie.ntnu.edu.tw-2025

1. (20%) Let T_w be the reflection of \mathbb{R}^3 about the plane W in \mathbb{R}^3 with equation $x+2y-3z=0$ and let $\mathcal{B} = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix} \right\}$.

Note that the first two vectors in \mathcal{B} lies W and the third vector is perpendicular (normal) to W (because

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix}^T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = ax + by + cz = 0 \quad \text{where } \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}.$$

- (a) Find $T_w(\mathbf{v})$ for each vector \mathbf{v} in \mathcal{B} .
 - (b) Show that \mathcal{B} is a basis for \mathbb{R}^3 .
 - (c) Find $[T_w]_{\mathcal{B}}$.
 - (d) Find the standard matrix of T_w .
 - (e) Determine an explicit formula for $T_w \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right)$.
2. (12%) (Refer to the definition after this problem.) Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation, and $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}$ and $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_m\}$ be bases for \mathbb{R}^n and \mathbb{R}^m , respectively. Let B and C be the matrices whose columns are the vectors in \mathcal{B} and \mathcal{C} , respectively. Prove the following:
- (a) If A is the standard matrix of T , then $[T]_{\mathcal{B}}^{\mathcal{C}} = C^{-1}AB$.
 - (b) $[T(\mathbf{v})]_{\mathcal{C}} = [T]_{\mathcal{B}}^{\mathcal{C}}[\mathbf{v}]_{\mathcal{B}}$ for any vector \mathbf{v} in \mathbb{R}^n .
 - (c) Let $U: \mathbb{R}^m \rightarrow \mathbb{R}^p$ be linear, and let \mathcal{D} be a basis for \mathbb{R}^p . Then $[UT]_{\mathcal{B}}^{\mathcal{D}} = [U]_{\mathcal{C}}^{\mathcal{D}}[T]_{\mathcal{B}}^{\mathcal{C}}$.

Definition

Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation, and let $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}$ and $\mathcal{C} = \{\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_m\}$ be bases for \mathbb{R}^n and \mathbb{R}^m , respectively. The Matrix $[[T(\mathbf{b}_1)]_{\mathcal{C}}, [T(\mathbf{b}_2)]_{\mathcal{C}}, \dots, [T(\mathbf{b}_n)]_{\mathcal{C}}]$ is called the matrix representation of T with respect to \mathcal{B} and \mathcal{C} . It is denoted by $[T]_{\mathcal{B}}^{\mathcal{C}}$.

3. (12%) Find the eigenvalues of linear operator T and determine a basis for each eigenspace, where

$$T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} -4x_1 + 6x_2 \\ 2x_2 \\ -5x_1 + 5x_2 + x_3 \end{bmatrix}.$$

4. (12%) Given a matrix $A = \begin{bmatrix} -2 & 6 & 3 \\ -2 & -8 & -2 \\ 4 & 6 & -1 \end{bmatrix}$ and its characteristic polynomial $-(t+5)(t+4)(t+2)$,

find, if possible, an invertible matrix P and its diagonal matrix D such that $A = PDP^{-1}$.

5. (10%) Let A be a diagonalizable $n \times n$ matrix. Prove that if the characteristic polynomial of A is $f(t) = a_n t^n + a_{n-1} t^{n-1} + \dots + a_1 t + a_0$, then $f(A) = O$, where $f(A) = a_n A^n + a_{n-1} A^{n-1} + \dots + a_1 A + a_0 I_n$ (This is called the *Cayley-Hamilton theorem*.)
6. (10%) A linear operator T on \mathbb{R}^n is given in the following. Find, if possible, a basis \mathcal{B} for \mathbb{R}^n such that

$[T]_{\mathcal{B}}$ is a diagonal matrix. If no such basis exists, explain why. $T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} 4x_1 - 5x_2 \\ -x_2 \\ -x_3 \end{bmatrix}$.

7. (12%) Given a linear operator T and its characteristic polynomial $f(t)$, determine all the values of the scalar c for which T on \mathcal{R}^3 is not diagonalizable, where $T\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} x_1 + 2x_2 - x_3 \\ cx_2 \\ 6x_1 - x_2 + 6x_3 \end{pmatrix}$ and $f(t) = -(t - c)(t - 3)(t - 4)$.
8. (12%) Let $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ be a basis for \mathcal{R}^3 , and let T be the linear operator on \mathcal{R}^3 defined by $T(a\mathbf{u} + b\mathbf{v} + c\mathbf{w}) = a\mathbf{u} + b\mathbf{v} - c\mathbf{w}$ for all scalars a, b and c .
- (a) Find the eigenvalues of T and determine a basis for each eigenspace.
 - (b) Is T diagonalizable? Justify your answer.