✓ 4.1 Defining a Neural Network

```
1 import torch
 2 import torch.nn as nn
4 # Define a simple neural network
 5 class SimpleNN(nn.Module):
6
      def __init__(self):
          super(SimpleNN, self).__init__()
7
8
          # Define layers
          self.fc1 = nn.Linear(3, 5) # Input layer to hidden layer
9
10
          self.fc2 = nn.Linear(5, 1) # Hidden layer to output layer
11
      def forward(self, x):
12
          # Define forward pass
13
          x = torch.relu(self.fc1(x)) # Apply ReLU activation
14
15
          x = self.fc2(x)
16
          return x
17
18 # Instantiate the network
19 net = SimpleNN()
20 print(net)
→ SimpleNN(
      (fc1): Linear(in_features=3, out_features=5, bias=True)
      (fc2): Linear(in_features=5, out_features=1, bias=True)
4.2 Loss Function
1 # Define Mean Squared Error loss function
2 criterion = nn.MSELoss()
4.3 Optimizer
 1 import torch.optim as optim
3 # Define an optimizer
 4 optimizer = optim.SGD(net.parameters(), lr=0.01)
4.4 Preparing Data
1 # Example training data
 2 inputs = torch.tensor([[1.0, 2.0, 3.0], [4.0, 5.0, 6.0], [7.0, 8.0, 9.0]], dtype=torch.float32)
 3 targets = torch.tensor([[1.0], [2.0], [3.0]], dtype=torch.float32)
 5 # Create a DataLoader
 6 from torch.utils.data import DataLoader, TensorDataset
8 dataset = TensorDataset(inputs, targets)
9 data_loader = DataLoader(dataset, batch_size=2, shuffle=True)
```

4.5 Training Loop

```
1 # Training loop
 2 \text{ num\_epochs} = 100
 3 for epoch in range(num epochs):
       for batch_inputs, batch_targets in data_loader:
           # Zero the gradient buffers
 6
           optimizer.zero_grad()
 7
 8
           # Forward pass
q
           outputs = net(batch_inputs)
10
           # Compute loss
11
           loss = criterion(outputs, batch_targets)
12
13
           # Backward pass
14
15
           loss.backward()
16
           # Update weights
17
           optimizer.step()
18
19
       if anach % 10 -- 0.
4.6 Evaluating the Model
 1 # Example test data
 2 test_inputs = torch.tensor([[10.0, 11.0, 12.0]], dtype=torch.float32)
 3 test_targets = torch.tensor([[4.0]], dtype=torch.float32)
5 # Forward pass on test data
 6 with torch.no_grad():
       test_outputs = net(test_inputs)
 8
       test_loss = criterion(test_outputs, test_targets)
10 print(f"Test Loss: {test_loss.item()}")
11
→ Test Loss: 2.29196302825585e-05
```

Exercises

- 1. Define a More Complex Network: Create a deeper network with more layers and different activation functions. Experiment with different layer sizes and configurations.
- 2. Experiment with Different Loss Functions: Try using a different loss function, such as Cross Entropy Loss, and modify the network for a classification task.
- 3. Optimize with Different Optimizers: Compare the performance of different optimizers (e.g., SGD vs. Adam) on the same task. Adjust learning rates and observe the effects.
- 4. Add Regularization: Implement L2 regularization by adding a penalty to the loss function. Experiment with dropout layers to prevent overfitting.
- 5. Data Augmentation: Use data augmentation techniques to artificially increase the size of the training set. Implement these techniques and observe their effects on model performance.