Week 10: Search Tree Algorithms 2

Tree Review

Binary search trees ...

- data structures designed for $O(\log n)$ search
- consist of nodes containing item (incl. key) and two links
- can be viewed as recursive data structure (subtrees)
- have overall ordering (data(Left) < root < data(Right))
- insert new nodes as leaves (or as root), delete from anywhere
- have structure determined by insertion order (worst: O(n))
- operations: insert, delete, search, rotate, rebalance, ...

Randomised BST Insertion

Effects of order of insertion on BST shape:

- best case (for at-leaf insertion): keys inserted in pre-order (median key first, then median of lower half, median of upper half, etc.)
- worst case: keys inserted in ascending/descending order
- average case: keys inserted in random order $\Rightarrow O(\log_2 n)$

Tree ADT has no control over order that keys are supplied.

Can the algorithm itself introduce some *randomness*?

In the hope that this randomness helps to balance the tree ...

... Randomised BST Insertion

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How can a computer pick a number at random?

• it cannot

Software can only produce *pseudo random numbers*.

- a pseudo random number is one that is predictable
 - (although it may appear unpredictable)
- \Rightarrow implementation may deviate from expected theoretical behaviour
 - o (more on this in week 12)

... Randomised BST Insertion

• Pseudo random numbers in C:

rand() // generates random numbers in the range 0 .. RAND MAX

where the constant RAND_MAX is defined in stdlib.h (depends on the computer: on the CSE network, RAND_MAX = 2147483647)

To convert the return value of rand() to a number between 0 .. RANGE

• compute the remainder after division by RANGE+1

... Randomised BST Insertion

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Approach: normally do leaf insert, randomly do root insert.

```
insertRandom(tree,item)
Input tree, item
Output tree with item randomly inserted

if tree is empty then
    return new node containing item
end if
// p/q chance of doing root insert
if random number mod q
```

E.g. 30% chance \Rightarrow choose p=3, q=10

... Randomised BST Insertion

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Cost analysis:

- similar to cost for inserting keys in random order: $O(\log_2 n)$
- does not rely on keys being supplied in random order

Approach can also be applied to deletion:

- standard method promotes inorder successor to root
- for the randomised method ...
 - o promote inorder successor from right subtree, OR
 - o promote inorder predecessor from left subtree

Splay Trees

Splay Trees

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A kind of "self-balancing" tree ...

Splay tree insertion modifies insertion-at-root method:

- by considering parent-child-granchild (three level analysis)
- by performing double-rotations based on p-c-g orientation

The idea: appropriate double-rotations improve tree balance.

... Splay Trees

Splay tree implementations also do *rotation-in-search*:

• by performing double-rotations also when searching

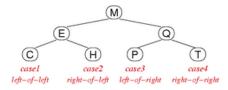
The idea: provides similar effect to periodic rebalance.

⇒ improves balance but makes search more expensive

... Splay Trees

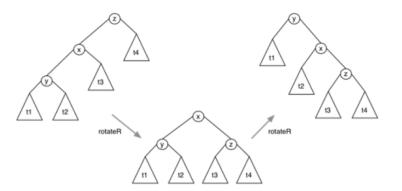
Cases for splay tree double-rotations:

- case 1: grandchild is left-child of left-child \Rightarrow double right rotation from top
- case 2: grandchild is right-child of left-child
- case 3: grandchild is left-child of right-child
- case 4: grandchild is right-child of right-child \Rightarrow double left rotation from top



... Splay Trees

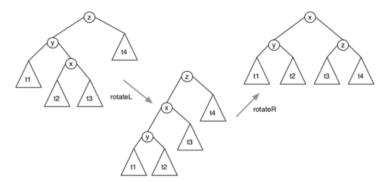
Double-rotation case for left-child of left-child ("zig-zig"):



... Splay Trees

Double-rotation case for right-child of left-child ("zig-zag"):

Note: both rotations at the root (unlike insertion-at-root)



Note: rotate subtree first (like insertion-at-root)

... Splay Trees

Algorithm for splay tree insertion:

```
insertSplay(tree,item):
  Input tree, item
  Output tree with item splay-inserted
  if tree is empty then return new node containing item
  else if item=data(tree) then return tree
  else if item<data(tree) then</pre>
     if left(tree) is empty then
        left(tree)=new node containing item
     else if item<data(left(tree)) then</pre>
            // Case 1: left-child of left-child "zig-zig"
        left(left(tree))=insertSplay(left(left(tree)),item)
        tree=rotateRight(tree)
      else if item>data(left(tree)) then
            // Case 2: right-child of left-child "zig-zag"
        right(left(tree))=insertSplay(right(left(tree)),item)
        left(tree)=rotateLeft(left(tree))
     end if
     return rotateRight(tree)
            // item>data(tree)
     if right(tree) is empty then
         right(tree) = new node containing item
     else if item<data(right(tree)) then</pre>
            // Case 3: left-child of right-child "zag-zig"
        left(right(tree))=insertSplay(left(right(tree)),item)
         right(tree)=rotateRight(right(tree))
```

Exercise #1: Splay Trees

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Insert 18 into this splay tree:





... Splay Trees

Searching in splay trees:

where splay() is similar to insertSplay(),

except that it doesn't add a node ... simply moves item to root if found, or nearest node if not found

Exercise #2: Splay Trees

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If we search for 22 in the splay tree



... how does this affect the tree?



... Splay Trees

Why take into account both child and grandchild?

- · moves accessed node to the root
- moves every ancestor of accessed node roughly halfway to the root

⇒ better amortized cost than insert-at-root

... Splay Trees

- assume that we "splay" for both insert and search
- consider: m insert+search operations, n nodes
- Theorem. Total number of comparisons: average $O((n+m) \cdot log(n+m))$

Gives good overall (amortized) cost.

Analysis of splay tree performance:

- insert cost not significantly different to insert-at-root
- search cost increases, but ...
 - improves balance on each search

o moves frequently accessed nodes closer to root

But ... still has worst-case search cost O(n)

Real Balanced Trees

Better Balanced Binary Search Trees

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So far, we have seen ...

- randomised trees ... make poor performance unlikely
- occasional rebalance ... fix balance periodically
- splay trees ... reasonable amortized performance
- but both types still have O(n) worst case

Ideally, we want both average/worst case to be $O(\log n)$

- AVL trees ... fix imbalances as soon as they occur
- 2-3-4 trees ... use varying-sized nodes to assist balance
- red-black trees ... isomorphic to 2-3-4, but binary nodes

AVL Trees

AVL Trees

Invented by Georgy Adelson-Velsky and Evgenii Landis

Approach:

- insertion (at leaves) may cause imbalance
- repair balance as soon as we notice imbalance
- repairs done locally, not by overall tree restructure

A tree is unbalanced when: abs(height(left)-height(right)) > 1

This can be repaired by at most two rotations:

- if left subtree too deep ...
 - o if data inserted in left-right grandchild ⇒ left-rotate left subtree
 - o rotate right
- if right subtree too deep ...
 - o if data inserted in right-left grandchild ⇒ right-rotate right subtree
 - rotate left

Problem: determining height/depth of subtrees may be expensive.

... AVL Trees 25/61

Implementation of AVL insertion

```
insertAVL(tree,item):
   Input tree, item
   Output tree with item AVL-inserted
  if tree is empty then
      return new node containing item
  else if item=data(tree) then
      return tree
  else
      if item<data(tree) then</pre>
         left(tree)=insertAVL(left(tree),item)
      else if item>data(tree) then
         right(tree)=insertAVL(right(tree),item)
      end if
      if height(left(tree))-height(right(tree)) > 1 then
         if item>data(left(tree)) then
            left(tree)=rotateLeft(left(tree))
         end if
         tree=rotateRight(tree)
      else if height(right(tree))-height(left(tree)) > 1 then
         if item<data(right(tree)) then</pre>
            right(tree)=rotateRight(right(tree))
         end if
         tree=rotateLeft(tree)
      end if
     return tree
   end if
```

Exercise #3: AVL Trees 26/61

Insert 27 into the AVL tree





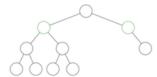
What happens when you insert 24 now?

You may like the animation at www.cs.usfca.edu/~galles/visualization/AVLtree.html

... AVL Trees 28/61

Analysis of AVL trees:

- trees are *height*-balanced; subtree depths differ by +/-1
- average/worst-case search performance of $O(\log n)$
- require extra data to be stored in each node ("height")
- may not be weight-balanced; subtree sizes may differ

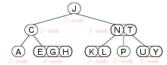


2-3-4 Trees

2-3-4 Trees 30/61

2-3-4 trees have three kinds of nodes

- 2-nodes, with two children (same as normal BSTs)
- 3-nodes, two values and three children
- 4-nodes, three values and four children



... 2-3-4 Trees

2-3-4 trees are ordered similarly to BSTs







In a balanced 2-3-4 tree:

- all leaves are at same distance from the root
- 2-3-4 trees grow "upwards" by splitting 4-nodes.

... 2-3-4 Trees 32/61

Possible 2-3-4 tree data structure:

... 2-3-4 Trees

Searching in 2-3-4 trees:

```
Search(tree,item):
  Input tree, item
  Output address of item if found in 2-3-4 tree
         NULL otherwise
  if tree is empty then
     return NULL
  else
     i=0
     while i<tree.order-1 ^ item>tree.data[i] do
        i=i+1 // find relevant slot in data[]
     end while
     if item=tree.data[i] then  // item found
         return address of tree.data[i]
                // keep looking in relevant subtree
     else
        return Search(tree.child[i],item)
     end if
  end if
```

... 2-3-4 Trees 34/61

2-3-4 tree searching cost analysis:

- as for other trees, worst case determined by height h
- 2-3-4 trees are always balanced \Rightarrow height is $O(\log n)$

- worst case for height: all nodes are 2-nodes same case as for balanced BSTs, i.e. $h \approx log_2 n$
- best case for height: all nodes are 4-nodes balanced tree with branching factor 4, i.e. $h = log_4 n$

Insertion into 2-3-4 Trees

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Starting with the root node:

repeat

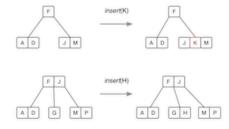
- if current node is full (i.e. contains 3 items)
 - split into two 2-nodes
 - o promote middle element to parent
 - if no parent \Rightarrow middle element becomes the new root 2-node
 - o go back to parent node
- if current node is a leaf
 - o insert Item in this node, order++
- if current node is not a leaf
 - go to child where Item belongs

until Item inserted

... Insertion into 2-3-4 Trees

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Insertion into a 2-node or 3-node:



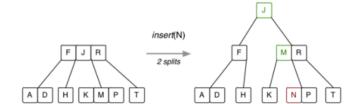
Insertion into a 4-node (requires a split):



... Insertion into 2-3-4 Trees

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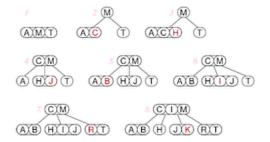
Splitting the root:



... Insertion into 2-3-4 Trees

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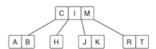
Building a 2-3-4 tree ... 7 insertions:

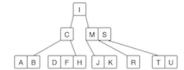


Exercise #4: Insertion into 2-3-4 Tree

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Show what happens when D, S, F, U are inserted into this tree:





... Insertion into 2-3-4 Trees

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Insertion algorithm:

insert(tree,item):
| Input 2-3-4 tree, item

```
Output tree with item inserted
node=root(tree), parent=NULL
repeat
  if node.order=4 then
      promote = node.data[1]
                                  // middle value
      nodeL = new node containing node.data[0]
      nodeR = new node containing node.data[2]
      if parent=NULL then
         make new 2-node root with promote, nodeL, nodeR
      else
         insert promote,nodeL,nodeR into parent
         increment parent.order
      end if
      node=parent
   end if
   if node is a leaf then
      insert item into node
      increment node.order
  else
      parent=node
      if item<node.data[0] then</pre>
         node=node.child[0]
      else if item<node.data[1] then</pre>
         node=node.child[1]
      else
         node=node.child[2]
      end if
   end if
until item inserted
```

... Insertion into 2-3-4 Trees

Variations on 2-3-4 trees ...

Variation #1: why stop at 4? why not 2-3-4-5 trees? or *M*-way trees?

- allow nodes to hold up to M-1 items, and at least M/2
- if each node is a disk-page, then we have a *B-tree* (databases)
- for B-trees, depending on Item size, M > 100/200/400

Variation #2: don't have "variable-sized" nodes

- use standard BST nodes, augmented with one extra piece of data
- implement similar strategy as 2-3-4 trees → red-black trees.

Red-Black Trees

Red-Black Trees 44/61

Red-black trees are a representation of 2-3-4 trees using BST nodes.

- each node needs one extra value to encode link type
- but we no longer have to deal with different kinds of nodes

Link types:

- red links ... combine nodes to represent 3- and 4-nodes
- black links ... analogous to "ordinary" BST links (child links)

Advantages:

- standard BST search procedure works unmodified
- get benefits of 2-3-4 tree self-balancing (although deeper)

Red-Black Trees 45/61

Definition of a red-black tree

• a BST in which each node is marked red or black

- no two red nodes appear consecutively on any path
- a red node corresponds to a 2-3-4 sibling of its parent
- a black node corresponds to a 2-3-4 child of its parent

Balanced red-black tree

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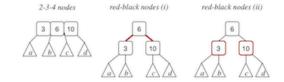
• all paths from root to leaf have same number of black nodes

Insertion algorithm: avoids worst case O(n) behaviour

Search algorithm: standard BST search

... Red-Black Trees 46/61

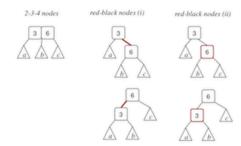
Representing 4-nodes in red-black trees:



Some texts colour the links rather than the nodes.

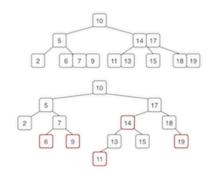
... Red-Black Trees 47/61

Representing 3-nodes in red-black trees (two possibilities):



... Red-Black Trees 48/61

Equivalent trees (one 2-3-4, one red-black):



... Red-Black Trees 49/61

Red-black tree implementation:

```
typedef enum {RED,BLACK} Colour;
typedef struct node *RBTree;
typedef struct node {
  int data; // actual data
    Colour colour; // relationship to parent
    RBTree left; // left subtree
    RBTree right; // right subtree
} node;

#define colour(tree) ((tree)->colour)
#define isRed(tree) ((tree)!= NULL && (tree)->colour == RED)
RED = node is part of the same 2-3-4 node as its parent (sibling)
```

BLACK = node is a child of the 2-3-4 node containing the parent

... Red-Black Trees

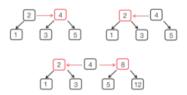
New nodes are always red:

```
RBTree newNode(Item it) {
   RBTree new = malloc(sizeof(Node));
   assert(new != NULL);
   data(new) = it;
   colour(new) = RED;
   left(new) = right(new) = NULL;
   return new;
}
```

... Red-Black Trees 51/61

Node.colour allows us to distinguish links

- black = parent node is a "real"parent
- red = parent node is a 2-3-4 neighbour



... Red-Black Trees 52/61

Search method is standard BST search:

Red-Black Tree Insertion

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- need to recall direction of last branch (L or R)
- need to recall whether parent link is red or black
- splitting/promoting implemented by rotateLeft/rotateRight
- several cases to consider depending on colour/direction combinations

... Red-Black Tree Insertion

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High-level description of insertion algorithm:

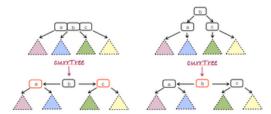
```
insertRB(tree,item,inRight):
  Input tree, item, inRight indicating direction of last branch
  Output tree with it inserted
   if tree is empty then
      return newNode(item)
   end if
   if left(tree) and right(tree) both are RED then
      split 4-node
   end if
   recursive insert cases (cf. regular BST)
  re-arrange links/colours after insert
   return modified tree
insertRedBlack(tree,item):
   Input red-black tree, item
  Output tree with item inserted
  tree=insertRB(tree,item,false)
  colour(tree)=BLACK
```

... Red-Black Tree Insertion

return tree

-black free filsertion

Splitting a 4-node, in a red-black tree:



Algorithm:

```
if isRed(left(currentTree)) and isRed(right(currentTree)) then
   colour(currentTree)=RED
   colour(left(currentTree))=BLACK
   colour(right(currentTree))=BLACK
end if
```

... Red-Black Tree Insertion 56/61

Simple recursive insert (a la BST):



Algorithm:

Not affected by colour of tree node.

... Red-Black Tree Insertion

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Re-arrange after insert (step 1): "normalise" direction of successive red links



Algorithm:

if inRight and currentTree is red and left(currentTree) is red then
 currentTree=rotateRight(currentTree)
end if

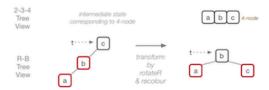
Symmetrically,

if not inRight and both currentTree and right(currentTree) are red
 ⇒ left rotate currentTree

... Red-Black Tree Insertion

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Re-arrange after insert (step 2): two successive red links = newly-created 4-node



Algorithm:

if isRed(left(currentTree)) and isRed(left(left(currentTree))) then
 currentTree=rotateRight(currentTree)
 colour(currentTree)=BLACK
 colour(right(currentTree))=RED
end if

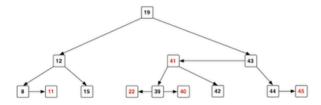
Symmetrically,

• if both right(currentTree) and right(right(currentTree)) are red
⇒ left rotate currentTree, then re-colour currentTree and left(currentTree)

... Red-Black Tree Insertion

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Example of insertion, starting from empty tree:



Red-black Tree Performance

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Cost analysis for red-black trees:

- tree is well-balanced; worst case search is $O(\log_2 n)$
- insertion affects nodes down one path; max #rotations is $2 \cdot h$ (where h is the height of the tree)

Only disadvantage is complexity of insertion/deletion code.

Note: red-black trees were popularised by Sedgewick.

Summary 61/61

- Randomised insertion
- Self-adjusting trees
 - Splay trees
 - AVL trees
 - 2-3-4 trees
 - · Red-black trees
- Suggested reading:
 - o Sedgewick, Ch.13.1-13.4

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