

Wisenet Open Platform v4.02

Troubleshooting


v4.02

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Troubleshooting

1. Storing Files on a Flash Memory

You may read and write files under the following path:

```
/mnt/opensdk/apps/<AppName>
```

If you delete an application, the corresponding information stored in the flash memory will be removed as well. If you reboot the camera only without deleting the application, stored files won't be removed but will be available. For information to be saved even after the application is deleted, refer to "Nand Flash Space" under Chapter 6 Others in the SDK API document.

2. Storing Files on a SD Card

Use the following API to check the path for the mounted SD card.

```
Const INT8_N *opensdk_getSDcardStoragePath();
```

For any of the following cases, NULL will be returned.

- No SD card is mounted
- No access right available to the SD card in "IPCameraManifest.xml"

If NULL is returned despite not applicable to cases above, check if the SD card is activated. To activate the SD card from the camera web viewer, select on the menu Basic > Event > Storage, select [SD Card] from the [Storage action setup] list, and choose [On] under the [Record] column.

	Device	Record	Free size	Total size	Status	
<input checked="" type="radio"/>	SD Card	On	29.70 GB	29.71 GB	Recording	Format
<input type="radio"/>	NAS	Off	0 MB	0 MB	None	Format

The space is limited to 80% of the size of the SD card. If the SD card recording is enabled, the space will be shared with a network camera main application.

3. Implementing FTP/Email/JPEG Encoding Function

Regarding FTP/Email/JPEG encoding, you should receive the event after calling `send_event()`.

The behavior scenario is as below:

Open Platform Application Apphelper
`send_event()` -----> processing
`recv_event()` <----- processing result

Event type is `OPENSdk_EVENT_STATUS`.

`TASK_STATUS.TaskName` will be `OPENSdk_FTP_FILE_UPLOAD` for FTP,
`OPENSdk_JPEG_ENCODE` for

JPEG Encoding.

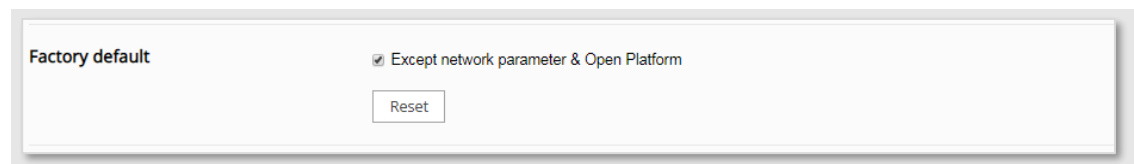
In the case of JPEG encoding, it takes up to 100 ms. If you request it without waiting for the result

notification, it causes memory leaks.

4. Preserving Applications after a Factory Default

During factory default initialization, you may preserve open applications installed and their settings but reset other settings.

If you don't want to remove open applications during factory default initialization, select on the menu `System > Upgrade/Restart` from the web viewer, and select [Except network parameter & open platform] under [Factory default].



If you physically press the reset button on the camera, all settings, including network settings and open platform information, will be initialized to the factory default.

5. Connecting Docker and Ubuntu by using a shared folder

If you create an app by loading a Docker image on Wisenet Open Platform (WOP) 4.01 or above and create a *.cap file (WOP app file) or source code for user OS, use the following commands:

Example 1

In the example, the folder that you want to share on a current directory is 'pwd' and the shared folder is 'mnt'.

```
$> docker run --rm -it -v=`pwd`: /mnt wop:4.01
```

```
$> docker run --rm -it --volume="$PWD:/mnt" wop:4.01
```

Example 2

If you want to display debug_message, add the options below.

```
$> docker run -p 8080:8080 --rm -it --volume="$PWD:/mnt" wop:4.01
```

Example 3

In the example, VirtualBoxMountExample is the OpenApp Folder that is currently being created.

```
root@-VirtualBox:/home/VirtualBoxShared/# docker run --rm -it --
volume="$PWD:/mnt" wop:4.01
root@0994f5fa31d7:/# cd /mnt/
root@0994f5fa31d7:/mnt# ls
VirtualBoxMountExample
root@0994f5fa31d7:/mnt# cd VirtualBoxMountExample/
root@0994f5fa31d7:/mnt/VirtualBoxMountExample# ls
IPCameraManifest.xml Makefile bin html inc res src
root@0994f5fa31d7:/mnt/VirtualBoxMountExample# touch test.ttt
root@0994f5fa31d7:/mnt/VirtualBoxMountExample# exit
exit
root@-VirtualBox:/home/VirtualBoxShared# ls
VirtualBoxMountExample
root@-VirtualBox:/home/VirtualBoxShared# cd VirtualBoxMountExample/
root@-VirtualBox:/home/VirtualBoxShared/VirtualBoxMountExample# ls
IPCameraManifest.xml Makefile bin html inc res src test.ttt
```

Reference

OpenPlatform_v4.01_Programming_Guide.pdf > 2. Developing an Application > 2.2 How to Run Docker Images, Step 4

6. Sample application location

When creating an app by loading a Docker image on Wisenet Open Platform (WOP) 4.01 or above, a test application was created when performing verification in Hanwha Techwin. This is a sample application.

On this page, we are going to describe its source code location and how to create a build.

The sample application is a test application used to create an app by loading a Docker image on Wisenet Open Platform (WOP) 4.01 or above. The build location and build method of the sample application is as below.

Sample application location

```
$> /opt/opensdk/opensdk-4.01/SampleApplication
```

Example

```
oot@20090071-L03:/opt/opensdk/opensdk-4.01/SampleApplication$ ls
test_PTZ test_Storage test_log test_sunapi_api wn7
root@20090071-L03:/opt/opensdk/opensdk-4.01/SampleApplication$ cd wn7/
root@20090071-L03:/opt/opensdk/opensdk-4.01/SampleApplication/wn7$ ls
DynamicCPU_MemoryChange PeopleCounter RawImageTest SNTTest ServerPushMJPEG
test_Email test_FTP
root@20090071-L03:/opt/opensdk/opensdk-4.01/SampleApplication/wn7/$ cd
test_FTP
root@20090071-L03:/opt/opensdk/opensdk-4.01/SampleApplication/wn7/test_FTP#
make clean;make;opensdk_packager
rm -f bin/* src/buffermanager_wn7.o src/test_FTP_wn7.o
src/Opensdk_FTP_wn7.o *.cap
```

7. Connecting to a Docker container in a remote server by using Visual Studio Code in Windows 10

To connect to a docker container on a remote server running Windows 10 in Wisenet Open

Platform (WOP) 4.01, follow the steps below:

Requirements

- Windows10
- Windows Terminal (download from Microsoft Store)
- Container created by running a Docker image on a remote server

How to connect

1 Install WSL and Docker Desktop for windows

- Step 1. After executing Windows terminal as an administrator, enter the following commands in order and reboot.

```
dism.exe /online /enable-feature /featurename:Microsoft-Windows-Subsystem-Linux /all /norestart  
dism.exe /online /enable-feature /featurename:VirtualMachinePlatform /all /norestart
```

- Step 2. Download the Ubuntu distribution version from the Microsoft Store, install, and run it.
- Step 3. Enter `wsl -l` in the Windows terminal to confirm that Ubuntu Linux is installed.
- Step 4. To update the wsl2 Linux kernel, refer to <https://docs.microsoft.com/ko-kr/windows/wsl/install-win10#step-4---download-the-linux-kernel-update-package>.
- Step 5. Enter `wsl -l -v` in the Windows terminal to check the current WSL version.
- Step 6. Enter `wsl -set-default-version 2` to change the default to wsl2.
- Step 7. Download Docker Desktop for Windows from the following link, install, and run it: <https://hub.docker.com/editions/community/docker-ce-desktop-windows>.
- Step 8. After running, check the option to use the WSL2 based engine in the general tab of the settings page, check the Enable integration with my default WSL distro option in the resources tab, and activate Ubuntu-20.04.

2 SSH-remote connection in Visual Studio Code

- Step 1. Install the remote development extension in Visual Studio Code
- Step 2. Execute the command below on the Ubuntu server where the container is running.

```
sudo apt-get update  
sudo apt-get upgrade  
sudo apt-get install ssh
```

```
sudo apt-get install openssh-server
sudo nano /etc/ssh/sshd_config
sudo service ssh status
sudo service ssh start
sudo ufw enable
sudo ufw allow 22
sudo ufw reload
```

Step 3. SSH-remote connection in Visual Studio Code

```
sc config ssh-agent start=auto
net start ssh-agent
```

Step 4. Run PowerShell on Windows and enter the command below.

```
ssh-keygen -t rsa -b 4096
```

Step 5. After entering Get-Content ..ssh\id_rsa.pub, save the output to /root/.ssh/authorized_keys on the Ubuntu server and change the permission by chmod 644 /root/.ssh/authorized_keys.

Step 6. After pressing F1 in Visual Studio Code and clicking Remote-SSH: Connect to Host, run Configure SSH Hosts to open the config file and enter the IdentityFile information under the server to be used as below.

```
Host 192.168.38.80
    HostName 192.168.38.80
    User simba
    IdentityFile ~/.ssh/id_rsa
```

Step 7. Click Remote-SSH: Connect to Host in Visual Studio Code to connect to the Ubuntu server.

Step 8. In Visual Studio Code, press F1 and click Preferences: Open Settings (JSON) to open the settings.json file and enter the following contents at the bottom.

```
"docker.host": "ssh://simba@192.168.38.80"
```

Step 9. Enter sudo usermod -aG docker on the Ubuntu server.

```
sudo usermod -aG docker simba
```

Step 10. Press F1 in Visual Studio Code and click Remote-Containers: Attach to Running Container to display a list of containers that are running on the Ubuntu server. Choose the one you want and wait.

Step 11. If a segmentation fault occurs during project build (make clean; make), refer to 9. WOP Docker Malfunction (page 9) to disable the WSL2 option.

8. Port forwarding for multi-SOC cameras

Port number 8080 used by cameras with a single SOC should not be used with multiple SOCs.

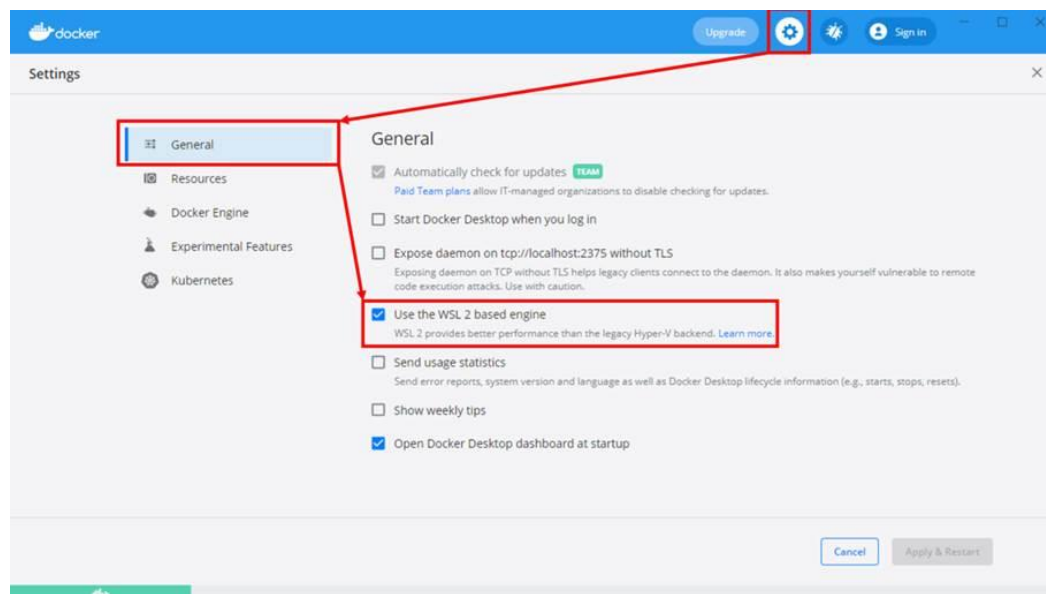
Channel	Old	New	Output
CH1	http://192.168.38.188:8080/dashboard/	http://192.168.38.188:10005/	Connection OK
CH2	http://192.168.38.188:8080/dashboard/	http://192.168.38.188:10006/	Connection OK
CH3	http://192.168.38.188:8080/dashboard/	http://192.168.38.188:10007/	Connection OK
CH4	http://192.168.38.188:8080/dashboard/	http://192.168.38.188:10008/	Connection OK

9. WOP Docker Malfunction

When developing an application using Docker on Wisenet Open Platform (WOP) 4.01 or above, seq.fault may occur if the WSL2 option is on. We recommend turning off the WSL2 option in Docker. To disable the WSL2 option, follow the steps below:

Disabling the WSL2 option

- Step 1. Click the Docker settings button.
- Step 2. Uncheck 'Use the WSL 2 based engine' in the General menu.
- Step 3. Restart Docker.



Running error example

```
$docker load -i wop_4.01.tar
$docker run --rm -it wop:4.01 /bin/bash
$docker ps 로 container 확인함(다른 terminal에서)
# cd /opt/opensdk/opensdk-4.01/SampleApplication/PeopleCounter/
# make
Building file: src/mjpegServer.cpp
Invoking: Cross G++ Compiler
/opt/opensdk//opensdk-4.01/armv7-wn7-linux-gnueabi/f/bin/armv7-wn7-linux-
gnueabi/f-g++ -O2 -g -Wall -fmessage-length=0 -c -o 'src/mjpegServer_wn7.o'
'src/mjpegServer.cpp' -I/opt/opensdk//opensdk-4.01/armv7-wn7-linux-
gnueabi/f/bin/./armv7-wn7-linux-gnueabi/f/sysroot/usr/include/ -
I/opt/opensdk//opensdk-4.01/common/inc/ -Iinc/
make: *** [Makefile:153: src/mjpegServer_wn7.o] Segmentation fault
```

10. Port forwarding for Remote Debug Viewer

If Remote Debug Viewer does not work normally, check whether the Remote Debug Viewer port is open.

Setting port forwarding

From Docker

When creating a container, use the “-p” option to port forward the host port.

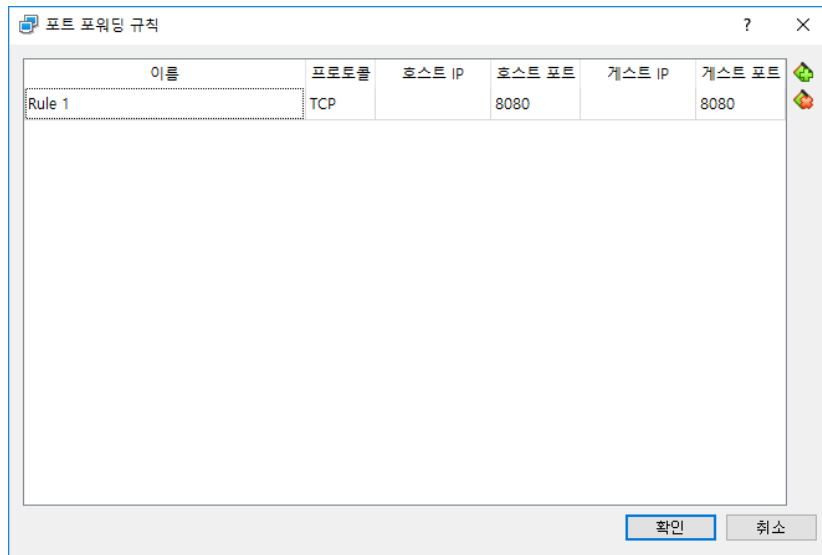
Ex) When setting the receiving port to 8080

```
# docker run -p 8080:8080 --rm -it --volume="$PWD:/mnt" wop:4.02
```

From VirtualBox

You need to port forward on network settings from VirtualBox.

1. Settings > Network > Advanced > Port Forwarding



2. Enter the following commands on the Linux shell.

```
root@wisenet-
VirtualBox:/home/wisenet/Window/SampleApplication_cv2x/test_SDmount#
RemoteDebugger -i 192.168.38.185 -p 80 -u admin -w 5tkatjd! -d 8080 -a
test_SDmount
flag_uname 1 flag_password 1
../src/main.cpp:125 Control is here. URL is http://192.168.38.185:80/stw-
cgi/opensdk.cgi?msubmenu=debug&action=set&AppID=test_SDmount&Enable=True&Port=
8080
../src/main.cpp:135 Control is here. camera credentials are admin:5tkatjd!
curl response: OK
../src/main.cpp:75 Control is here. Debug mode is set to ON
Data: test_SDmount one_shot

Data: test_SDmount : one_shot
Data: test_SDmount opensdk_startSDcardUse err : 2
```

3. On the test app, the code should be entered as follows:

Ex) File

```
/opt/opensdk/opensdk-4.01/SampleApplication/test_SDmount/src/test_SDmount.cpp
```

```
void one_shot(void)
{
    debug_message("one_shot\n");
    ...

    err = OPENSdk::RECORD::opensdk_startSDcardUse(sd_number, type);
```

```
debug_message("opensdk_startSDcardUse err : %d", static_cast<int>(err));  
...
```

11. The number of threads running

Basically, 3 main threads run at the same time. One is for encoded video, one for raw video, and one for the other events (FD, MD, VA, and so on).

Each thread sends data. If your code stays in `recv_event()` while processing raw video, you cannot receive raw video events anymore. Encoded video events can still be received.

12. Viewable area of encoding video and raw video

Encoding video and raw video do not have the same viewable area. They have different viewable areas.

For example, SNB-5004 (1.3MP camera) captures video with a 5:4 ratio, SNB-6004 (2MP camera) with 16:9, and SNB-7004 (3MP camera) with 4:3.

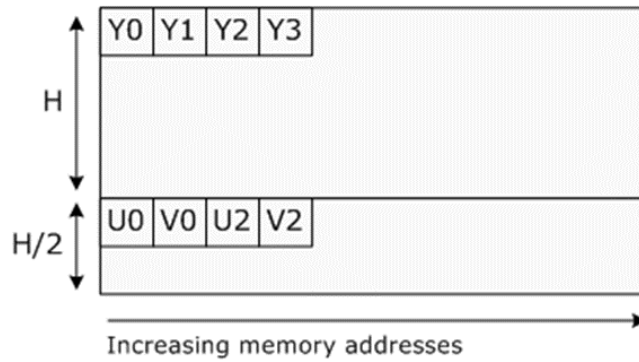
In order to create different resolutions from the original image, in the case of encoding, we just remove a part of the viewable range. For raw video, we do scaling.

13. Viewing the YUV420 video format

Y and UV are separated and concatenated in the memory.

The Y plane consists of serial Y data, from Y0 to Yn-1, and UV is interleaved in the plane, as U0 V0 U1 V1.

Please refer to the following (H stands for height):



14. Logs of the Open Platform Web interface

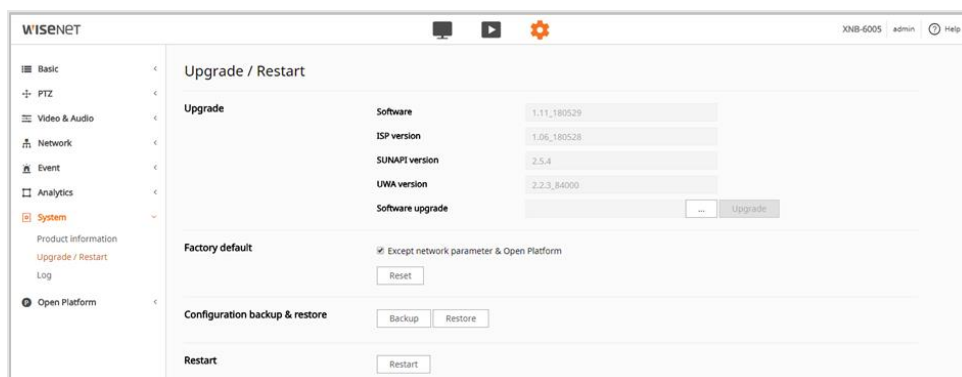
There is no support for web-related logs on opensdk.

The web developer of the camera development team also debugs using the logs provided by the browser.

15. Backing up the camera settings

To back up the current settings

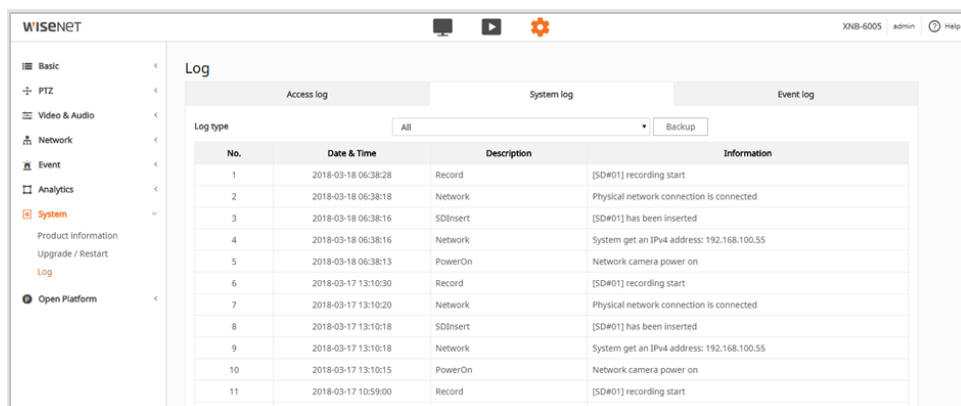
- Step 1. In the camera web viewer, click [Backup].
- Step 2. A backup file named “model name Config.bin” will be created.



16. How to check log files

You can check the system logs or event logs.

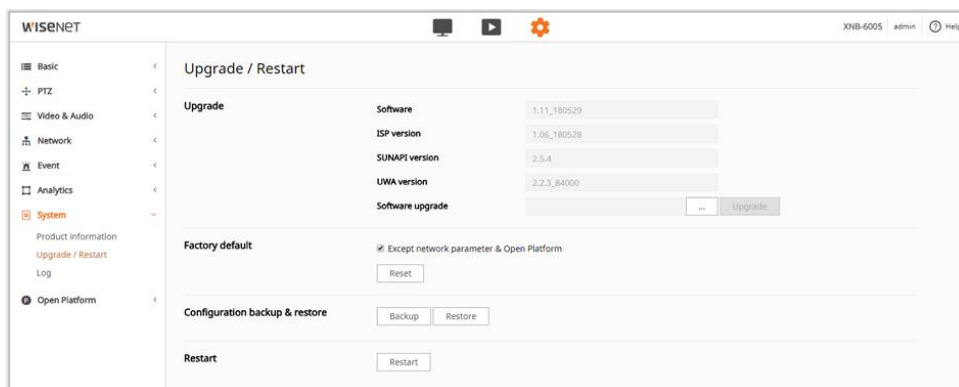
- Step 1. From the Setup menu of the camera web viewer, select the [System] tab
- Step 2. Click [Log].
- Step 3. Click on the [Backup] button to save all the log data for the currently selected mode in the “time stamp value created by camera in modelname-mode-camera.txt” file in the download folder of the browser



17. Checking the camera firmware version

The supported features are listed below.

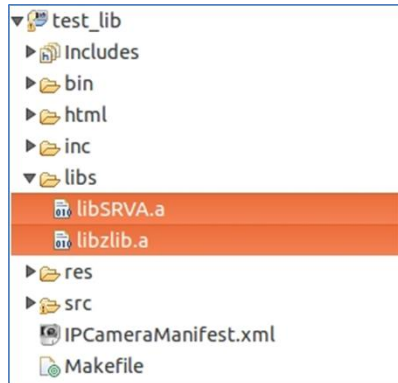
- Step 1. From the Setup menu of the camera web viewer, select the [System] tab
- Step 2. Click [Upgrade / Restart].



18. Adding a library file in Open Platform

To add a library file in Open Platform,

- Step 1. Build the library you want to use with the Hanwha openplatform tool chain.
Since the space provided for the Open SDK is about 18 MB, you need to build it with only the necessary parts.
- Step 2. Add the library file to any folder in your application (default: / libs)



- Step 3. Add library-specific options to the Makefile

```
#lib5_begin
LIBS5 = -Llibs -lapphelper_wn5 -lzlib -lsrva
#lib5_end
```