

```

class Graph:

    def __init__(self, vertices):

        self.V = vertices

        self.graph = [[0 for _ in range(vertices)] for _ in range(vertices)]

    def is_safe(self, v, colour, c):

        for i in range(self.V):

            if self.graph[v][i] == 1 and colour[i] == c:

                return False

        return True

    def graph_colouring_util(self, m, colour, v):

        if v == self.V:

            return True

        for c in range(1, m+1):

            if self.is_safe(v, colour, c):

                colour[v] = c

                if self.graph_colouring_util(m, colour, v+1):

                    return True

                colour[v] = 0

    def graph_colouring(self, m):

        colour = [0] * self.V

        if not self.graph_colouring_util(m, colour, 0):

            return False

        print("Solution exists. The assigned colours are:")

        for c in colour:

            print(c, end=" ")

        return True

g = Graph(4)

g.graph = [[0, 1, 1, 1],

            [1, 0, 1, 0],

            [1, 1, 0, 1],

            [1, 0, 1, 0]]

```

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m = 3
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g.graph_colouring(m)
```

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arr=[2,4,6,8,10,12,14,18]
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```
print("max is",arr[-1])
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print("min is",arr[0])
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```
def rob(nums):
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```
    def rob_linear(houses):
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        prev,curr=0,0
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        for money in houses:
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            prev,curr=curr,max(curr,prev+money)
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        return curr
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    if len(nums)==1:
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        return nums[0]
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```
    return max(rob_linear(nums[1:]),rob_linear(nums[:-1]))
```

```
print(rob([2,3,2]))
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```
import heapq
```

```
def dijkstra(graph, start):
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    distances = {node: float('infinity') for node in graph}
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    distances[start] = 0
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    queue = [(0, start)]
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    while queue:
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        current_distance, current_node = heapq.heappop(queue)
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        if current_distance > distances[current_node]:
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        continue

    for neighbor, weight in graph[current_node].items():
        distance = current_distance + weight

        if distance < distances[neighbor]:
            distances[neighbor] = distance
            heapq.heappush(queue, (distance, neighbor))

    return distances

graph = {
    'A': {'B': 1, 'C': 4},
    'B': {'A': 1, 'C': 2, 'D': 5},
    'C': {'A': 4, 'B': 2, 'D': 1},
    'D': {'B': 5, 'C': 1}
}

start_node = 'A'
result = dijkstra(graph, start_node)
print(result)

def selection(arr):
    for i in range(len(arr)):
        min=i
        for j in range(i+1,len(arr)):
            if arr[j]<arr[min]:
                min=j
        arr[i],arr[min]=arr[min],arr[i]
    return arr

arr=[5,2,9,1,5,6]
print(selection(arr))

```

```
def kthpositive(arr,k):  
    missing=[]  
    num=1  
    while len(missing)<k:  
        if num not in arr:  
            missing.append(num)  
        num+=1  
    return missing[-1]  
arr=[2,3,4,7,11]  
k=5  
print(kthpositive(arr,k))
```

```
def binary(arr,key):  
    low=0  
    high=len(arr)+1  
    while low<=high:  
        mid=(low+high)//2  
        if arr[mid]<key:  
            low=mid+1  
        elif arr[mid]>key:  
            high=mid-1  
        else:  
            return mid  
arr=[10,20,30,40,50,60]  
key=50  
print(binary(arr,key))
```

```

def combinationSum(candidates, target):
    dp = [[] for _ in range(target + 1)]
    dp[0] = [[]]
    for c in candidates:
        for i in range(c, target + 1):
            dp[i] += [comb + [c] for comb in dp[i - c]]
    return dp[target]

candidates = [2, 3, 6, 7]
target = 7
print(combinationSum(candidates,target))

```

```

def merge_sort(arr):
    if len(arr)>1:
        mid=len(arr)//2
        L=arr[:mid]
        R=arr[mid:]
        merge_sort(L)
        merge_sort(R)
        i=j=k=0
        while i<len(L) and j<len(R):
            if L[i]<R[j]:
                arr[k]=L[i]
                i+=1
            else:
                arr[k]=R[j]
                j+=1
            k+=1
        while i<len(L):
            arr[k]=L[i]

```

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        i+=1
        k+=1
    while j<len(R):
        arr[k]=R[j]
        j+=1
        k+=1
    return arr
arr=[31,23,35,27,11,21,15,28]
print(merge_sort(arr))

```

```

import heapq
def kclosest(points,k):
    max_heap=[]
    for x,y in points:
        dist=-(x*x+y*y)
        if len(max_heap)<k:
            heapq.heappush(max_heap,(dist,x,y))
        else:
            heapq.heappushpop(max_heap,(dist,x,y))
    return [(x,y)for _,x,y in max_heap]
points=[[1,3],[-2,2],[5,8],[0,1]]
k=2
print(kclosest(points,k))

```

