

Diffeomorphic Counterfactuals

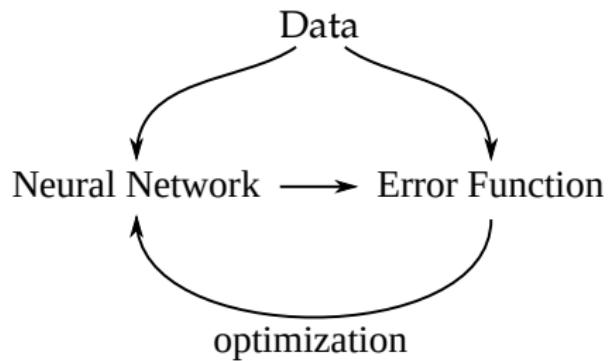
Jan E. Gerken



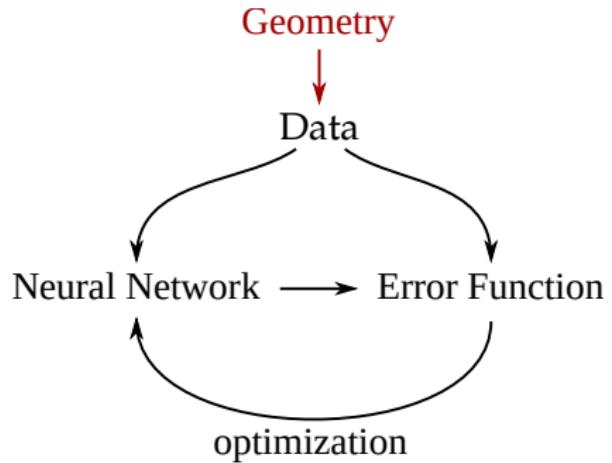
Pollica Workshop 2023
At the interface of physics, mathematics and artificial intelligence

Based on joint work with
Ann-Kathrin Dombrowski, Klaus-Robert Müller and Pan Kessel

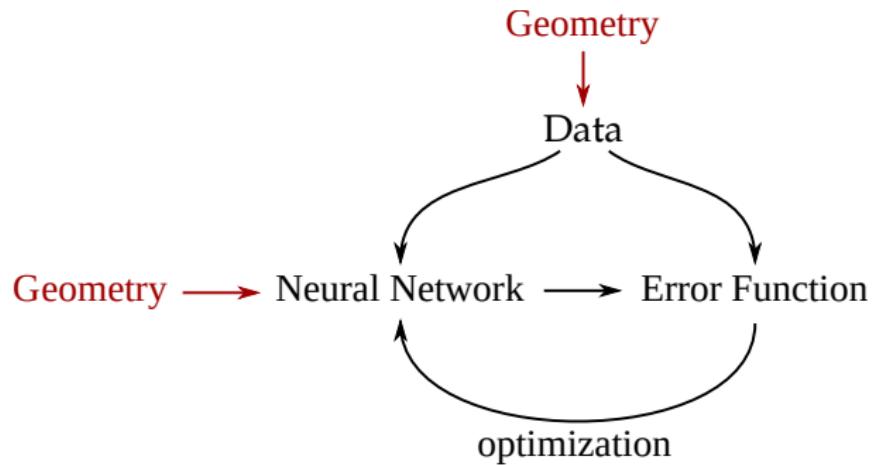
Geometric Deep Learning



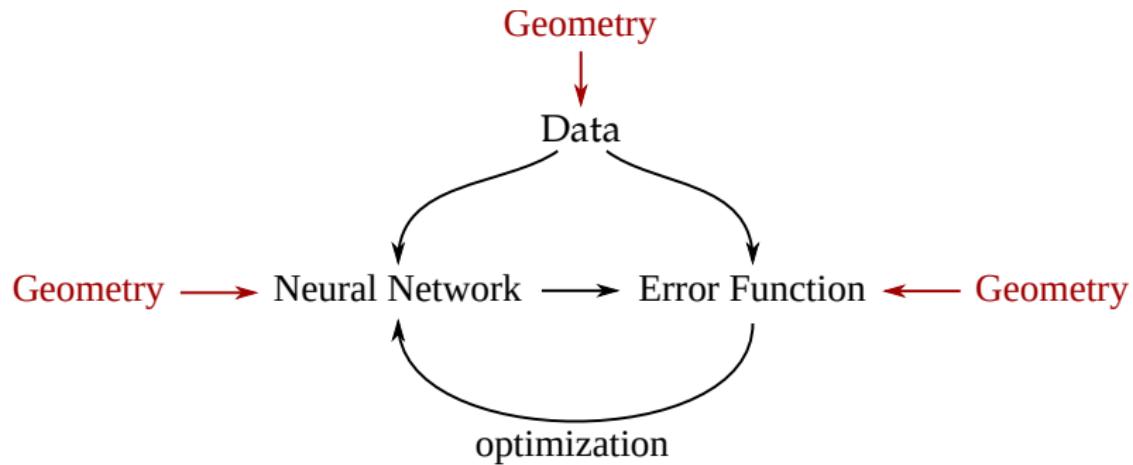
Geometric Deep Learning



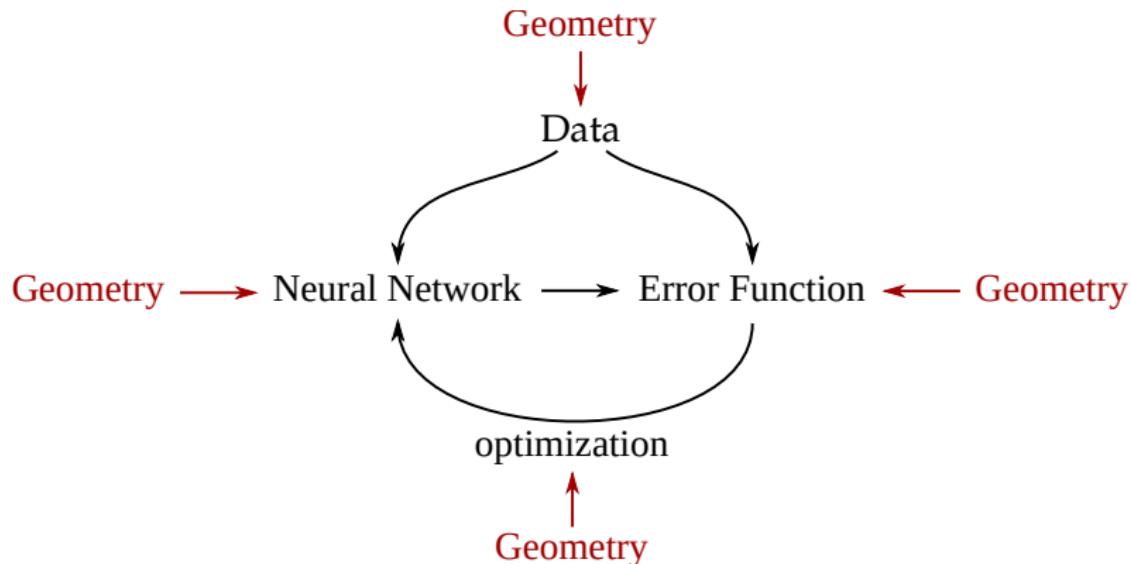
Geometric Deep Learning



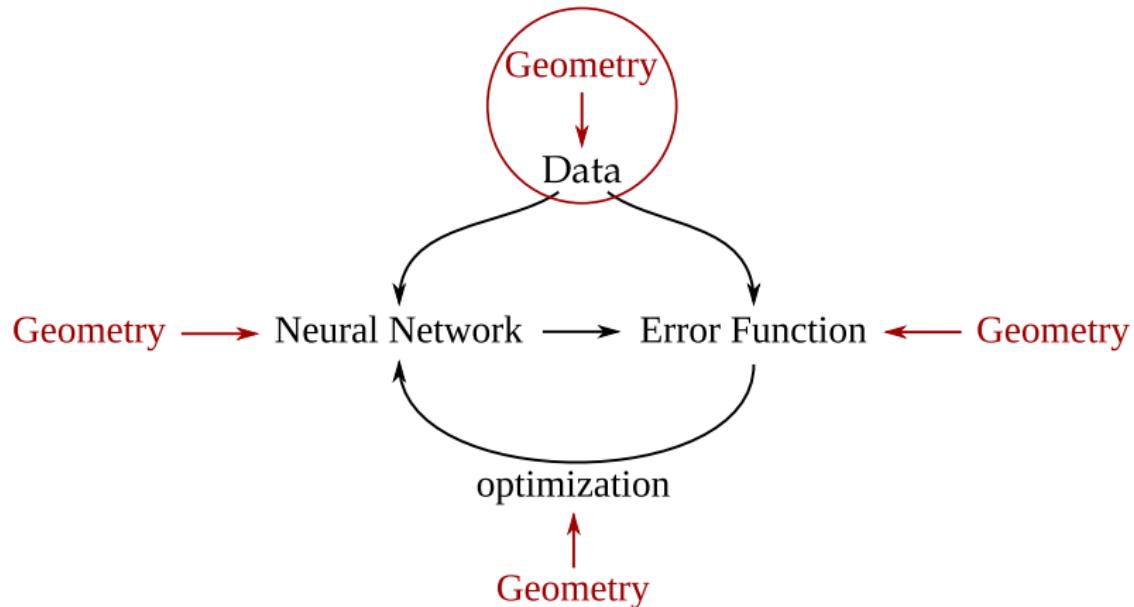
Geometric Deep Learning



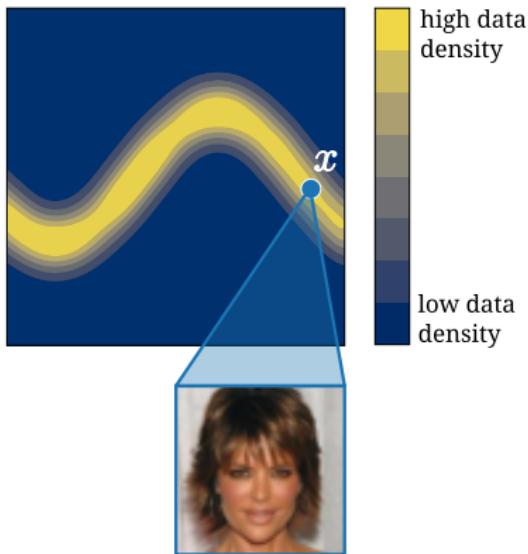
Geometric Deep Learning



Geometric Deep Learning



Geometry of the training data



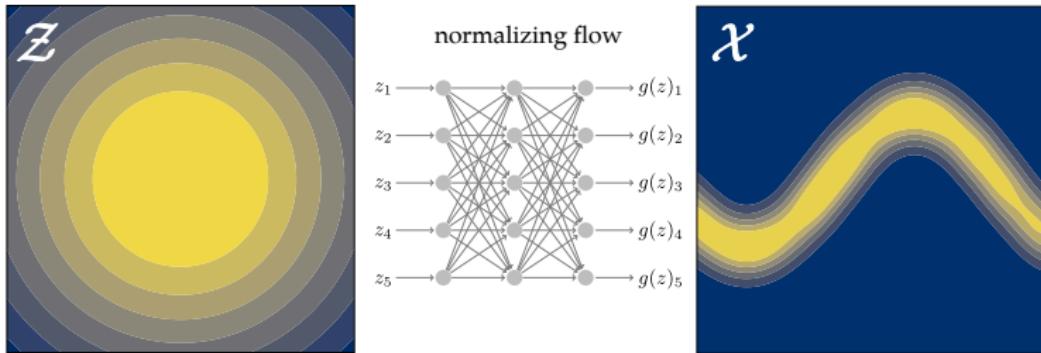
- ▶ Manifold Hypothesis: Data lies on low-dim. submanifold of high-dim. input space
- ▶ E.g. MNIST pictures lie on ~ 30 -dim. submanifold of $28 \times 28 = 784$ dim. input space



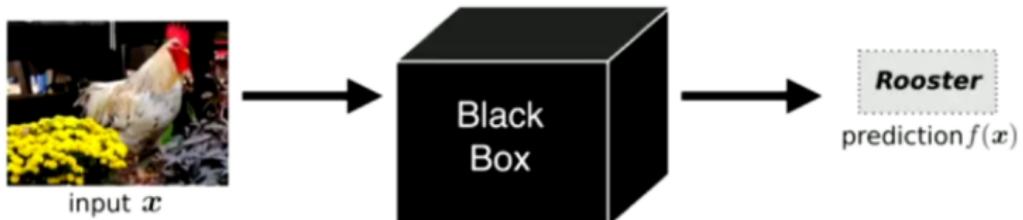
Learned diffeomorphisms

[Dinh, Krueger, Bengio, 2014]

- ▶ How to characterize the data manifold?
- ▶ Can learn a diffeomorphism between a simple distribution and data distribution

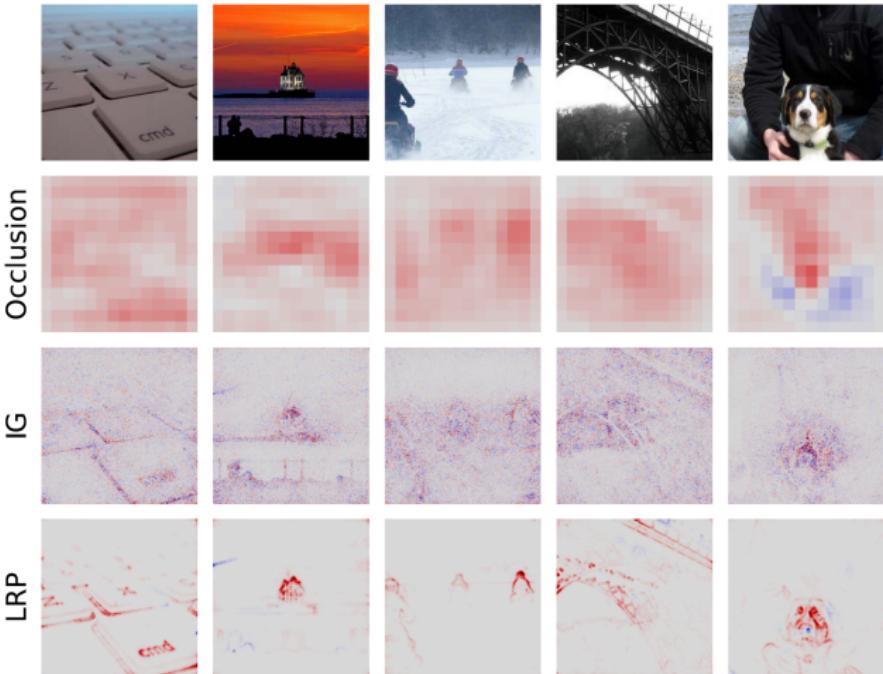


- ▶ Diffeomorphism is given by another neural network, a *normalizing flow*
- ▶ Get access to the data manifold in a functional form
- ▶ Connections to shape matching [Jansson, Modin, 2022]
- ▶ Connections to optimal transport [Chen, Karlsson, Ringh, 2021]
[Bauer, Joshi, Modin, 2017]
[Onken, Fung, Li, Ruthotto 2020]



- ▶ Neural network classifiers lack inherent interpretability
- ▶ This is in contrast to more traditional methods like linear- or physical models
- ▶ For safety-critical applications this poses a serious challenge in practice
- ▶ Research progress can also be impeded
- ▶ Need explanations which provide insight into the neural network decisions

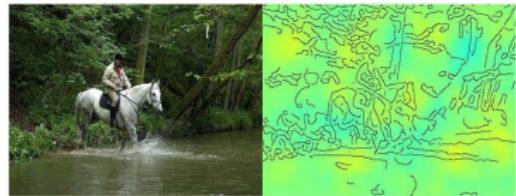
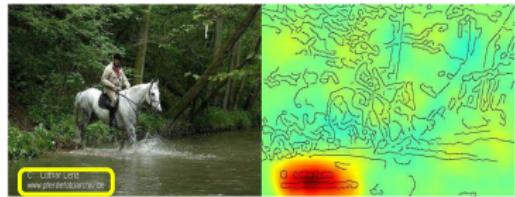
Saliency maps



Clever Hans Effect

[Lapuschkin et al., Nat Commun 2019]

Horse-picture from Pascal VOC data set



Source tag present
↓

Classified
as horse

Artificial picture of a car



No source
tag present
↓

Not classified
as horse

Clever Hans



Counterfactual explanations

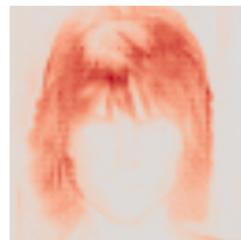
- ▶ **Counterfactual of a sample:** Data point close to original but with different classification
- ▶ Difference between original and counterfactual reveals features which led to classification
- ▶ Example from CelebA dataset, classified as not-blonde:



original x



counterfactual x'



$|x - x'|$

Adversarial Examples

- ▶ Small perturbations can lead to misclassifications

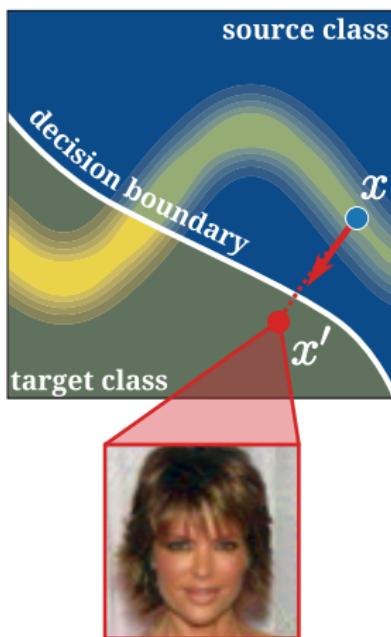
$$p_{\text{blonde}} \left(\begin{array}{c} \text{Image of a woman with dark hair} \end{array} \right) = 0.01 \quad \text{but} \quad p_{\text{blonde}} \left(\begin{array}{c} \text{Image of a woman with blonde hair} \end{array} \right) = 0.99$$

Adversarial Examples

- ▶ Small perturbations can lead to misclassifications

$$p_{\text{blonde}} \left(\begin{array}{c} \text{original image} \\ \text{of a blonde woman} \end{array} \right) = 0.01 \quad \text{but} \quad p_{\text{blonde}} \left(\begin{array}{c} \text{image} \\ \text{perturbed by noise} \end{array} \right) = 0.99$$

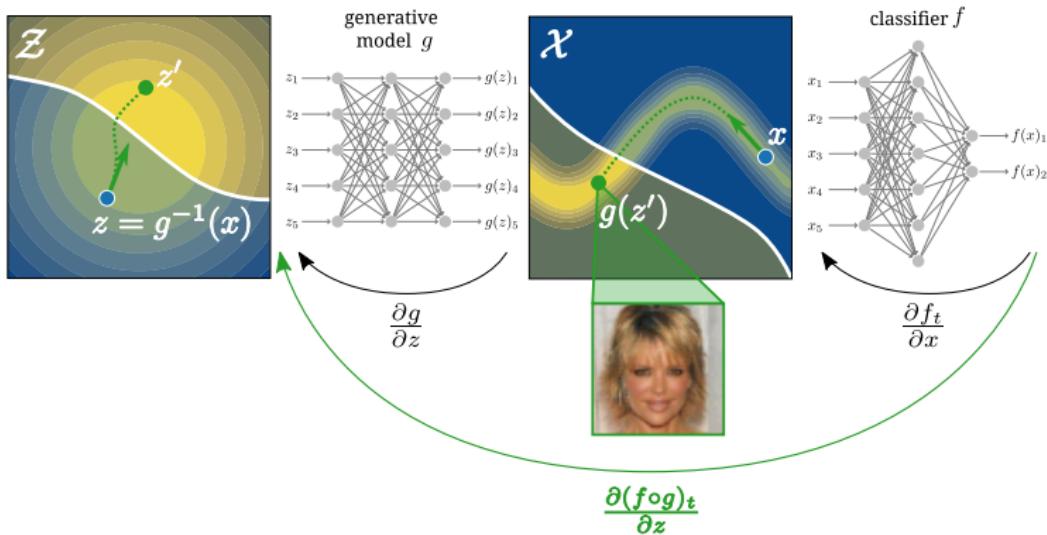
- ▶ Reason: Classifier only trained on the data manifold



Counterfactuals

[Dombrowski, JG, Müller, Kessel, 2022]

- ▶ Can use normalizing flows to optimize along the data manifold \Rightarrow *counterfactuals*



$$z^{(i+1)} = z^{(i)} + \lambda \frac{\partial (f \circ g)_t}{\partial z}(z^{(i)})$$

Gradient ascent in base space

- ▶ Gradient ascent in Z for class k of the classifier f with learning rate λ :

$$z^{(t+1)} = z^{(t)} + \lambda \frac{\partial(f \circ g)_k}{\partial z}(z^{(t)})$$

- ▶ Using change-of-variable under the flow:

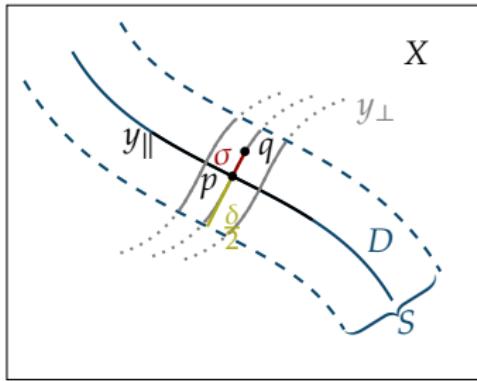
Theorem

Gradient ascent in the base space Z is given by

$$x^{(t+1)} = x^{(t)} + \lambda \gamma^{-1}(x^{(t)}) \frac{\partial f_k}{\partial x}(x^{(t)}) + O(\lambda^2)$$

where $\gamma^{-1}(x) = \left(\frac{\partial g}{\partial z} \frac{\partial g}{\partial z}^T \right)(g^{-1}(x))$ is the inverse of the induced metric on X from Z under the flow g .

Data coordinates



- ▶ Assume that data lies in a region $S = \text{supp}(p)$ around data manifold D , in data coordinates x^α

$$S_x = \left\{ x_D + x_\delta \mid x_D \in D_x, x_\delta^\alpha \in \left(-\frac{\delta}{2}, \frac{\delta}{2} \right) \right\}$$

with $\delta \ll 1$.

- ▶ Define normal coordinates y^μ in a neighborhood of D

Gradient ascent in y -coordinates

- By choosing $\{n_i\}$ orthogonal wrt γ , the inverse induced metric takes the form

$$\gamma^{\mu\nu}(y) = \begin{pmatrix} \gamma_D^{-1}(y) & & & \\ & \gamma_{\perp 1}^{-1} & & \\ & & \ddots & \\ & & & \gamma_{\perp N_X - N_D}^{-1} \end{pmatrix}^{\mu\nu}.$$

- The gradient ascent update $g^\alpha(z^{(i+1)}) = g^\alpha(z^{(i)}) + \lambda \gamma^{\alpha\beta} \frac{\partial f_t}{\partial x^\beta} + O(\lambda^2)$ becomes

$$\gamma^{\alpha\beta} \frac{\partial f_t}{\partial x^\beta} = \frac{\partial x^\alpha}{\partial y_\parallel^\mu} \gamma_D^{\mu\nu} \frac{\partial f_t}{\partial y_\parallel^\nu} + \frac{\partial x^\alpha}{\partial y_\perp^i} \gamma_{\perp i}^{-1} \frac{\partial f_t}{\partial y_\perp^i}$$

- For $\gamma_{\perp i}^{-1} \rightarrow 0$ and $\frac{\partial x}{\partial y_\perp}$ bounded we have

$$\gamma^{\alpha\beta} \frac{\partial f_t}{\partial x^\beta} \rightarrow \frac{\partial x^\alpha}{\partial y_\parallel^\mu} \gamma_D^{\mu\nu} \frac{\partial f_t}{\partial y_\parallel^\nu}$$

and hence the update step points along the data manifold.

\Rightarrow In this case, obtain counterfactuals, not adversarial examples!

The induced metric for well-trained generative models

Theorem (Diffeomorphic Counterfactuals)

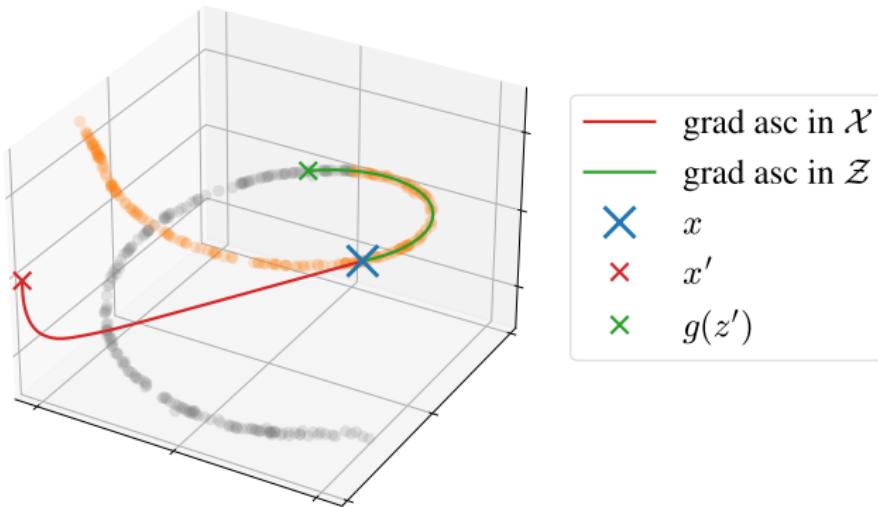
For $\epsilon \in (0, 1)$ and g a normalizing flow with Kullback–Leibler divergence $\text{KL}(p, q) < \epsilon$,

$$\gamma_{\perp_i}^{-1} \rightarrow 0 \quad \text{as} \quad \delta \rightarrow 0$$

for all $i \in \{1, \dots, N_X - N_D\}$.

\Rightarrow For well-trained generative models, the gradient ascent update in Z stays on the data manifold

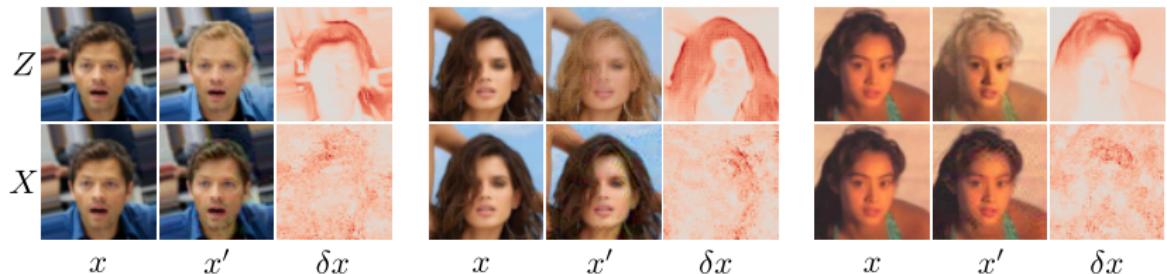
Toy example



Diffeomorphic Counterfactuals with CelebA

- ▶ Classifier: Binary CNN trained on *blonde/not blonde* attribute (test accuracy: 94%)
- ▶ Flow: Glow
- ▶ Task: Change classification from *not blonde* to *blonde*

[Kingma et al., NeurIPS 2018]



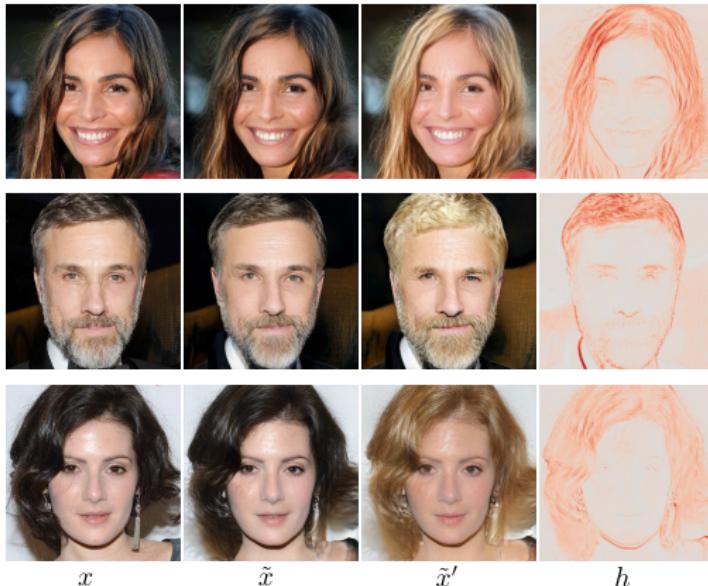
- ▶ Top row: Counterfactual computed in base space
- ▶ Bottom row: Adversarial example computed in data space

Approximately Diffeomorphic Counterfactuals with CelebA-HQ

- ▶ For general generating models, inversion not exact ($\tilde{x} = g(z_0) \neq x_0$)
- ▶ Approximate diffeomorphic counterfactuals can be generated for high-dimensional datasets (1024×1024 pixels for CelebA-HQ)
- ▶ Use StyleGAN trained on CelebA-HQ
- ▶ Use HyperStyle inversion of StyleGAN to find initial latent

[Karras et al., IEEE/CVF 2019]

[Alaluf et al., CVPR 2022]

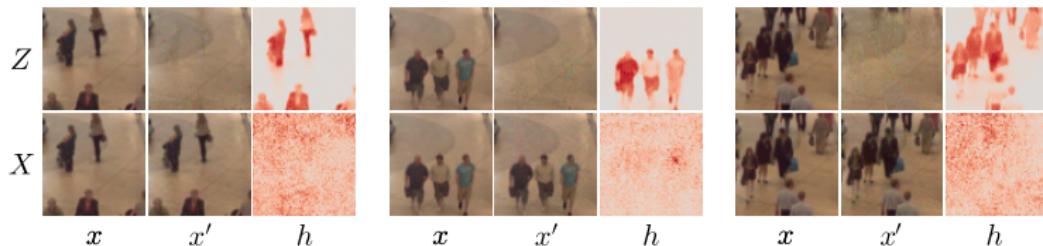


Diffeomorphic Counterfactuals for regression

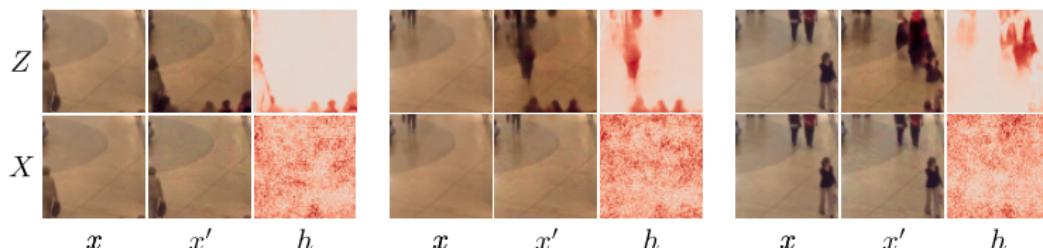
- ▶ Consider crowd-counting dataset of mall images
- ▶ Count number of people in the image
- ▶ Flow: Glow
- ▶ Optimize for low number of people

[Ribera et al., CVPR 2019]

[Kingma et al., NeurIPS 2018]



- ▶ Optimize for high number of people



Paper

Diffeomorphic Counterfactuals with Generative Models

arXiv: 2206.05075

Accepted at IEEE PAMI



Thank you!

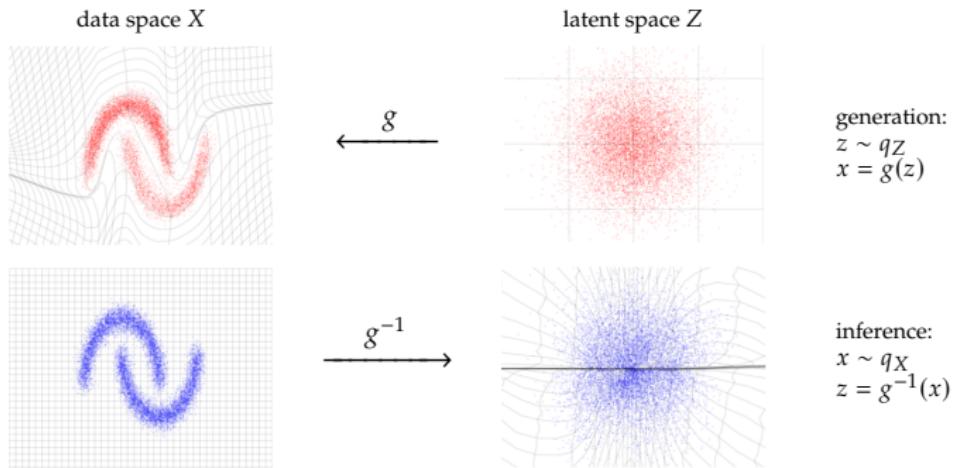
Appendix

Normalizing flows

- ▶ Generative model g which maps base space Z to data space X *bijectively*, i.e. it is a *diffeomorphism*
- ▶ Probability distribution q_Z in Z is simple, e.g. uniform or normal
- ▶ Probability distribution q_X in X is given by change of variables

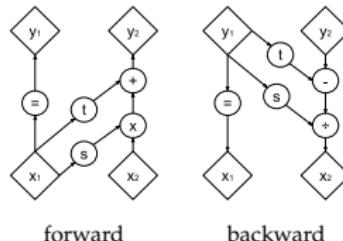
$$q_X(x) = q_Z(g^{-1}(x)) \left| \det \frac{\partial z}{\partial x} \right|$$

- ▶ Train by maximizing log-likelihood $\log q_X$ of train data



- ▶ g is realized as a neural network with bijective building blocks
- ▶ Network needs to be easily invertible and have a tractable Jacobian determinant
- ▶ RealNVP uses *affine coupling layers*

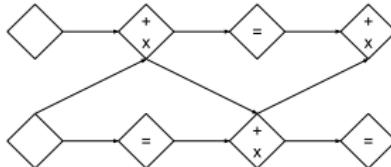
$$\begin{aligned}y_{1:d} &= x_{1:d} \\y_{d+1:D} &= x_{d+1:D} \odot \exp(s(x_{1:d})) + t(x_{1:d}) \\s, t : \mathbb{R}^d &\rightarrow \mathbb{R}^{D-d} \quad (\text{deep CNNs})\end{aligned}$$



- ▶ The Jacobian is given by

$$\frac{\partial y}{\partial x^T} = \begin{bmatrix} 1_d & 0 \\ \frac{\partial y_{d+1:D}}{\partial x_{1:d}^T} & \text{diag}(\exp(s(x_{1:d}))) \end{bmatrix} \Rightarrow \left| \frac{\partial y}{\partial x^T} \right| = \exp \left(\sum_j s(x_{1:d})_j \right)$$

- ▶ Alternate the parts which are modified from layer to layer



- ▶ RealNVP uses multi-scale architecture

The induced metric for well-trained generative models

Theorem (Diffeomorphic Counterfactuals)

For $\epsilon \in (0, 1)$ and g a normalizing flow with Kullback–Leibler divergence $\text{KL}(p, q) < \epsilon$,

$$\gamma_{\perp i}^{-1} \rightarrow 0 \quad \text{as} \quad \delta \rightarrow 0$$

for all $i \in \{1, \dots, N_X - N_D\}$.

Theorem (Approximately Diffeomorphic Counterfactuals)

If $g : Z \rightarrow X$ is a generative model with $D \subset g(Z)$ and image $g(Z)$ which extends in any non-singular orthogonal direction y_{\perp}^i to regions outside of D of low probability $p(x) \ll 1$,

$$\gamma_{\perp i}^{-1} \rightarrow 0$$

for $\delta \rightarrow 0$ for all non-singular orthogonal directions y_{\perp}^i .

⇒ For well-trained generative models, the gradient ascent update in Z stays on the data manifold

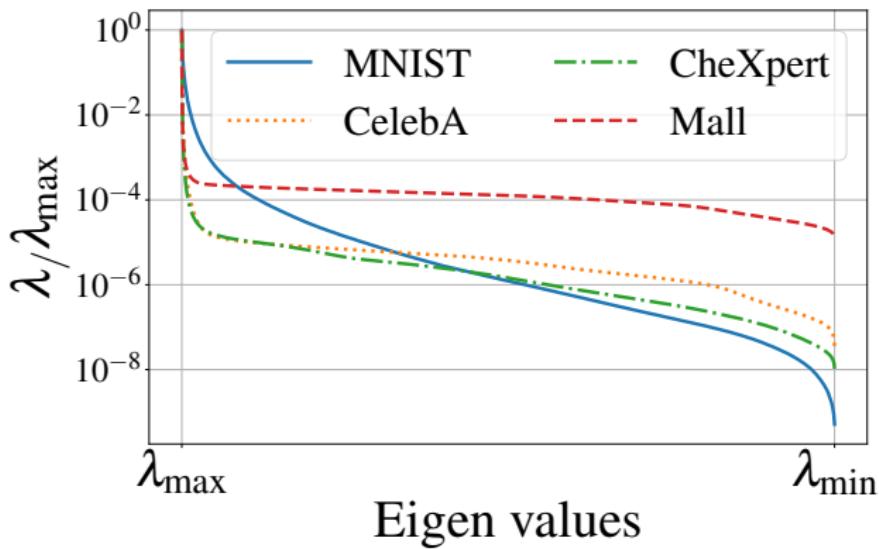
Sketch of proof (flow-case)

- For flows g with $\text{KL}(p, q) < \epsilon$, almost all probability mass is concentrated in $S = \text{supp}(p)$

$$\begin{aligned} 0 < 1 - \epsilon &< \int_{S_x} q_X(x) dx \\ &= \int_{S_x} q_Z(g^{-1}(x)) \left| \frac{\partial z^a}{\partial x^\alpha} \right| dx \\ &= \int_{D_y} \sqrt{|\gamma_D|} \prod_{i=1}^{N_X-N_D} \int_{-\delta/2}^{\delta/2} \sqrt{|\gamma_{\perp_i}|} q_Z(z(y)) dy_\perp^i dy_\parallel \end{aligned}$$

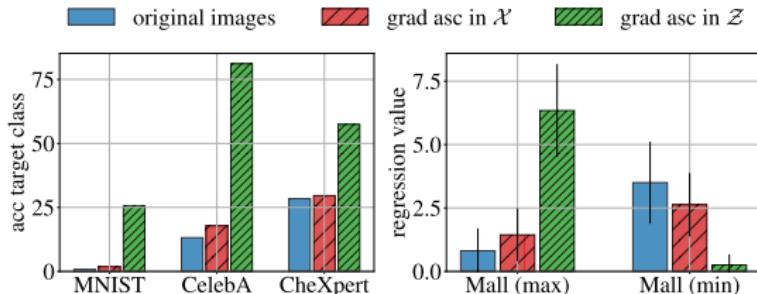
- When $\delta \rightarrow 0$, the integration domain shrinks to zero, but the value of the integral is bounded from below
- Hence, the metric γ_{\perp_i} has to diverge, i.e. $\gamma_{\perp_i}^{-1} \rightarrow 0$.

Eigenvalue spectrum of Jacobian



Quantitative evaluation

- Diffeomorphic Counterfactuals generalize to SVMs, adversarials do not



- The ground truth classes for the ten nearest neighbors matches the target values of the counterfactuals more often for Diffeomorphic Counterfactuals than for adversarials

