```
import numpy as np
import pandas as pd
```

Double-click (or enter) to edit

```
1 data=pd.read_csv('/content/Iris.csv')
2 data.columns=['Id','Sepal_len_cm','Sepal_wid_cm','Petal_len_cm','Petal_wid_cm','Species']
3 data.head(10)
```

| | Id | Sepal_len_cm | Sepal_wid_cm | Petal_len_cm | Petal_wid_cm | Species |
|---|----|--------------|--------------|--------------|--------------|-------------|
| 0 | 1 | 5.1 | 3.5 | 1.4 | 0.2 | Iris-setosa |
| 1 | 2 | 4.9 | 3.0 | 1.4 | 0.2 | Iris-setosa |
| 2 | 3 | 4.7 | 3.2 | 1.3 | 0.2 | Iris-setosa |
| 3 | 4 | 4.6 | 3.1 | 1.5 | 0.2 | Iris-setosa |
| 4 | 5 | 5.0 | 3.6 | 1.4 | 0.2 | Iris-setosa |
| 5 | 6 | 5.4 | 3.9 | 1.7 | 0.4 | Iris-setosa |
| 6 | 7 | 4.6 | 3.4 | 1.4 | 0.3 | Iris-setosa |
| 7 | 8 | 5.0 | 3.4 | 1.5 | 0.2 | Iris-setosa |
| 8 | 9 | 4.4 | 2.9 | 1.4 | 0.2 | Iris-setosa |
| 9 | 10 | 4.9 | 3.1 | 1.5 | 0.1 | Iris-setosa |
| | | | | | | |

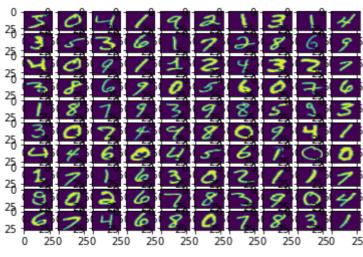
```
1 def activation_func(value): #Tangent Hypotenuse
2  #return (1/(1+np.exp(-value)))
3  return ((np.exp(value)-np.exp(-value))/(np.exp(value)+np.exp(-value)))
```

```
1 def perceptron_train(in_data,labels,alpha):
      X=np.array(in_data)
      y=np.array(labels)
      weights=np.random.random(X.shape[1])
      original=weights
      bias=np.random.random sample()
      for key in range(X.shape[0]):
          a=activation_func(np.matmul(np.transpose(weights),X[key]))
          yn=0
          if a>=0.7:
10
11
              yn=1
          elif a<=(-0.7):
12
13
14
          weights=weights+alpha*(yn-y[key])*X[key]
           print('Iteration '+str(key)+': '+str(weights))
15
      print('Difference: '+str(weights-original))
       return weights
```

https://colab.research.google.com/drive/13YmfGsUiEmNd57Kk9AFGe3mjskqerjpU

```
X=np.array(in_data)
      y=np.zeros(label_shape)
      for key in range(X.shape[1]):
          a=activation_func((weights*X[key]).sum())
          y[key]=0
          if a>=0.7:
               y[key]=1
          elif a < = (-0.7):
10
              y[key]=-1
11
      return y
1 def score(result, labels):
      difference=result-np.array(labels)
      correct_ctr=0
      for elem in range(difference.shape[0]):
          if difference[elem]==0:
               correct ctr+=1
      score=correct_ctr*100/difference.size
      print('Score='+str(score))
1 # Dividing DataFrame "data" into "d_train" (60%) and "d_test" (40%)
2 divider = np.random.rand(len(data)) < 0.70</pre>
3 d_train=data[divider]
4 d_test=data[~divider]
    # Dividing d_train into data and labels/targets
    d_train_y=d_train['Species']
    d_train_X=d_train.drop(['Species'],axis=1)
    # Dividing d_train into data and labels/targets
    d_test_y=d_test['Species']
    d_test_X=d_test.drop(['Species'],axis=1)
 7
    # Learning rate
    alpha = 0.01
    # Train
    weights = perceptron train(d train X, d train y, alpha)
    # Test
    result_test=perceptron_test(d_test_X,d_test_y.shape,weights)
    # Calculate score
    score(result_test,d_test_y)
     Score=28.571428571428573
    import tensorflow as tf
2 import numpy as np
    from tensorflow.keras.models import Sequential
   from tensorflow.keras.layers import Flatten
    from tensorflow.keras.layers import Dense
    from tensorflow.keras.layers import Activation
```

```
import matplotlib.pyplot as plt
 1 (x_train, y_train), (x_test, y_test) = tf.keras.datasets.mnist.load_data()
     Downloading data from <a href="https://storage.googleapis.com/tensorflow/tf-keras-datasets/mn:">https://storage.googleapis.com/tensorflow/tf-keras-datasets/mn:</a>
     11490434/11490434 [============ ] - Os Ous/step
                                                                                                   1 # Cast the records into float values
 2 x_train = x_train.astype('float32')
 3 x_test = x_test.astype('float32')
5 # normalize image pixel values by dividing
6 # by 255
 7 gray_scale = 255
8 x_train /= gray_scale
9 x_test /= gray_scale
10
1 print("Feature matrix:", x_train.shape)
2 print("Target matrix:", x_test.shape)
3 print("Feature matrix:", y_train.shape)
4 print("Target matrix:", y_test.shape)
     Feature matrix: (60000, 28, 28)
     Target matrix: (10000, 28, 28)
     Feature matrix: (60000,)
     Target matrix: (10000,)
1 fig, ax = plt.subplots(10, 10)
 2 k = 0
3 for i in range(10):
       for j in range(10):
           ax[i][j].imshow(x_train[k].reshape(28, 28),
                            aspect='auto')
           k += 1
8 plt.show()
```



```
1 model = Sequential([
   # reshape 28 row * 28 column data to 28*28 rows
   Flatten(input_shape=(28, 28)),
   # dense layer 1
   Dense(256, activation='sigmoid'),
   # dense layer 2
   Dense(128, activation='sigmoid'),
10
11
12
   # output layer
   Dense(10, activation='sigmoid'),
14])
1 model.compile(optimizer='adam',
      loss='sparse_categorical_crossentropy',
      metrics=['accuracy'])
4
1 model.fit(x_train, y_train, epochs=10,
    batch_size=2000,
    validation_split=0.2)
  Epoch 1/10
  Epoch 2/10
  Epoch 3/10
  Epoch 4/10
  Epoch 5/10
  Epoch 6/10
  Epoch 7/10
  Epoch 8/10
  Epoch 9/10
  Epoch 10/10
  <keras.callbacks.History at 0x7fa0595f94d0>
                                          1 results = model.evaluate(x_test, y_test, verbose = 0)
2 print('test loss, test acc:', results)
  test loss, test acc: [0.2749628722667694, 0.9228000044822693]
```

```
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| 6 | 7 | 4.6 | 3.4 | 1.4 | 0.3 | Iris-setosa |
| 7 | 8 | 5.0 | 3.4 | 1.5 | 0.2 | Iris-setosa |
| 8 | 9 | 4.4 | 2.9 | 1.4 | 0.2 | Iris-setosa |
| 9 | 10 | 4.9 | 3.1 | 1.5 | 0.1 | Iris-setosa |
| | | | | | | |

```
1 from sklearn.neural_network import MLPClassifier
2 from sklearn.datasets import make_classification
3 from sklearn.model_selection import train_test_split
4 X, y = make_classification(n_samples=100, random_state=1)
5 X_train, X_test, y_train, y_test = train_test_split(X, y, stratify=y,random_state=1)
6 clf = MLPClassifier(random_state=1, max_iter=300).fit(X_train, y_train)
7 clf.predict_proba(X_test[:1])
8 clf.predict(X_test[:5, :])
9 clf.score(X_test, y_test)
0.88
```

1 clf

MLPClassifier(max iter=300, random state=1)

```
1 import tkinter as tk
2 from tkinter import *
3 import cv2
4 from PIL import Image, ImageTk
5 import os
6 import numpy as np
7
```

```
9 global last frame1
10 last_frame1 = np.zeros((480, 640, 3), dtype=np.uint8)
11 global last frame2
12 last_frame2 = np.zeros((480, 640, 3), dtype=np.uint8)
13 global cap1
14 global cap2
15 cap1 = cv2.VideoCapture(-1)
16 cap2 = cv2.VideoCapture(-1)
17
18 def show_vid():
      if not cap1.isOpened():
20
           print("cant open the camera1")
21
       flag1, frame1 = cap1.read()
22
       frame1 = cv2.resize(frame1,(100,100))
       if flag1 is None:
23
24
           print ("Major error!")
       elif flag1:
25
26
           global last_frame1
           last_frame1 = frame1.copy()
28
           pic = cv2.cvtColor(last_frame1, cv2.COLOR_BGR2RGB)
29
           img = Image.fromarray(pic)
           imgtk = ImageTk.PhotoImage(image=img)
30
           lmain.imgtk = imgtk
           lmain.configure(image=imgtk)
           lmain.after(10, show_vid)
34
36 if __name__ == '__main__':
       root=tk.Tk()
       lmain = tk.Label(master=root)
       lmain2 = tk.Label(master=root)
40
       lmain.pack(side = LEFT)
       lmain2.pack(side = RIGHT)
       root.title("Lane-line detection")
       root.geometry("900x700+100+10")
       exitbutton = Button(root, text='Quit',fg="red",command= root.destroy).pack(side = BOTTOM
       show vid()
       root.mainloop()
48
       cap.release()
```

```
Traceback (most recent call last)
<ipython-input-1-2d2e8826dcdc> in <module>
     36 if __name__ == '__main__':
           root=tk.Tk()
---> 37
           lmain = tk.Label(master=root)
     38
           lmain2 = tk.Label(master=root)
/usr/lib/python3.7/tkinter/__init__.py in __init__(self, screenName, baseName,
className, useTk, sync, use)
   2021
                        baseName = baseName + ext
   2022
               interactive = 0
-> 2023
               self.tk = _tkinter.create(screenName, baseName, className,
interactive, wantobjects, useTk, sync, use)
               if useTk:
                   self. loadtk()
   2025
TclError: no display name and no $DISPLAY environment variable
```

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