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# Pseudocode

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**Algorithm 1** Space-based Depth-First Search (SDFS)

**Input:** The feature points  $P$ , their number  $n$  and connectivity matrix  $M$  in the binary skeleton image.

**Output:** The cycles with their feature points and connectivities in the binary skeleton image.

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1: for each point  $a_i \in P$  do
2:   for each point  $b_j \in P$  and connects to  $a_i$  do
3:     clear CyclePath for initialization
4:     add points  $a_i$  and  $b_j$  to CyclePath in turn
5:     while  $n--$  do
6:        $p_0 \leftarrow \text{CyclePath}(\text{end} - 1)$ 
7:        $p_1 \leftarrow \text{CyclePath}(\text{end})$ 
8:       calculate vector  $V_{p_1p_0} = V_{p_0} - V_{p_1}$ 
9:       for each point  $p_{2_k} \in P$  and connects to  $p_1$  do
10:        if  $V_{p_1p_0} \cdot x \times V_{p_1p_{2_k}} \cdot y - V_{p_1p_0} \cdot y \times V_{p_1p_{2_k}} \cdot x > 0$  then
11:          add  $p_{2_k}$  to RightHandPoints
12:        else if  $V_{p_1p_0} \cdot x \times V_{p_1p_{2_k}} \cdot y - V_{p_1p_0} \cdot y \times V_{p_1p_{2_k}} \cdot x < 0$  then
13:          add  $p_{2_k}$  to LeftHandPoints
14:        else
15:          record  $p_{2_k}$  to LinePoint
16:        end if
17:      end for
18:      if RightHandPoints is not empty then
19:        for each point  $p_{2_m}$  in RightHandPoints do
20:          calculate  $\theta_{p_0p_1p_{2_m}} = \arccos \frac{V_{p_1p_0} \cdot V_{p_1p_{2_m}}}{|V_{p_1p_0}| |V_{p_1p_{2_m}}|}$ 
21:        end for
22:        add  $p_{2_m}$  determined by  $\min(\theta_{p_0p_1p_{2_m}})$  to CyclePath
23:      else if LeftHandPoints is not empty then
24:        for each point  $p_{2_n}$  in LeftHandPoints do
25:          calculate  $\theta_{p_0p_1p_{2_n}} = \arccos \frac{V_{p_1p_0} \cdot V_{p_1p_{2_n}}}{|V_{p_1p_0}| |V_{p_1p_{2_n}}|}$ 
26:        end for
27:        add  $p_{2_n}$  determined by  $\min(\theta_{p_0p_1p_{2_n}})$  to CyclePath
28:      else
29:        add LinePoint to CyclePath
30:      end if
31:      if CyclePath's point number is greater than 2 and last point is the same as first point then
32:        if checkCyclePath( $p_0, p_1, p_2, \dots$ ) then
33:          output CyclePath( $p_0, p_1, p_2, \dots$ )  $\Rightarrow$  Cycles
34:          break
35:        end if
36:      end if
37:    end while
38:  end for
39: end for
40: remove the duplicated CyclePaths from Cycles
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