
Pseudocode

邱欣欣

May 27, 2015

1. Pseudocode

Algorithm 1 Space-based Depth-First Search (SDFS)

Input: The feature points P , their number n and connectivity matrix M in the binary skeleton image.

Output: The cycles with their feature points and connectivities in the binary skeleton image.

```
1: for each point  $a_i \in P$  do
2:   for each point  $b_j \in P$  and connects to  $a_i$  do
3:     clear  $CyclePath$  for initialization
4:     add points  $a_i$  and  $b_j$  to  $CyclePath$  in turn
5:   while  $n--$  do
6:      $p_0 \leftarrow CyclePath(end - 1)$ 
7:      $p_1 \leftarrow CyclePath(end)$ 
8:     calculate vector  $V_{p_1p_0} = V_{p_0} - V_{p_1}$ 
9:     for each point  $p_{2_k} \in P$  and connects to  $p_1$  do
10:      if  $V_{p_1p_0} \times V_{p_1p_{2_k}} \geq 0$  then
11:        add  $p_{2_k}$  to  $RightHandPoints$ 
12:      else
13:        add  $p_{2_k}$  to  $LeftHandPoints$ 
14:      end if
15:    end for
16:    if  $RightHandPoints$  is not empty then
17:      for each point  $p_{2_m}$  in  $RightHandPoints$  do
18:        calculate  $\theta_{p_0p_1p_{2_m}} = \arccos \frac{V_{p_1p_0} \cdot V_{p_1p_{2_m}}}{|V_{p_1p_0}| |V_{p_1p_{2_m}}|}$ 
19:      end for
20:      add  $p_2$  determined by  $\min(\theta_{p_0p_1p_{2_m}})$  to  $CyclePath$ 
21:    else
22:      for each point  $p_{2_n}$  in  $LeftHandPoints$  do
23:        calculate  $\theta_{p_0p_1p_{2_n}} = \arccos \frac{V_{p_1p_0} \cdot V_{p_1p_{2_n}}}{|V_{p_1p_0}| |V_{p_1p_{2_n}}|}$ 
24:      end for
25:      add  $p_2$  determined by  $\min(\theta_{p_0p_1p_{2_n}})$  to  $CyclePath$ 
26:    end if
27:    if  $CyclePath$ 's point number is greater than 2 and last point is the same as first point then
28:      if  $checkCyclePath(p_0, p_1, p_2, \dots)$  then
29:        output  $CyclePath(p_0, p_1, p_2, \dots) \Rightarrow Cycles$ 
30:        break
31:      end if
32:    end if
33:  end while
34: end for
35: end for
36: remove the duplicated  $CyclePaths$  from  $Cycles$ 
```
