

Multilevel Monte Carlo Solvers for Linear Systems

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Hardware-Based Motivation

- Modern hardware is moving in two directions (Kogge,2011):
 - Lightweight machines
 - Heterogeneous machines
 - Both characterized by low power and high concurrency
- Some issues:
 - Higher potential for both soft and hard failures (DOE,2012)
 - Memory restrictions are expected with a continued decrease in memory/FLOPS
- Potential resolution from Monte Carlo:
 - Soft failures buried within the tally variance
 - Hard failures mitigated by replication
 - Memory savings over conventional methods

Monte Carlo Methods for Discrete Linear Systems

- First proposed by J. Von Neumann and S.M. Ulam in the 1940's
- Earliest published reference in 1950 (Forsythe,1950)
- General lack of publications on applications
- Plagued by slow convergence $\approx \frac{1}{\sqrt{N}}$
- Modern work yielded new applications (Evans,2009) (Evans,2013)

MCSA Iteration

$$\mathbf{r}^k = \mathbf{b} - \mathbf{A}\mathbf{x}^k$$

$$\mathbf{x}^{k+1/2} = \mathbf{x}^k + \mathbf{r}^k$$

$$\mathbf{r}^{k+1/2} = \mathbf{b} - \mathbf{A}\mathbf{x}^{k+1/2}$$

$$\hat{\mathbf{A}}\delta\mathbf{x}^{k+1/2} = \mathbf{r}^{k+1/2}$$

$$\mathbf{x}^{k+1} = \mathbf{x}^{k+1/2} + \delta\mathbf{x}^{k+1/2}$$

- Neumann-Ulam methods bound by the Central Limit Theorem
- Build on Sequential Monte Carlo method (Halton,1962)
- Neumann-Ulam Monte Carlo solver computes the correction
- Decouples MC error from solution error, exponential convergence

Monte Carlo Linear Solver Preliminaries

- Split the linear operator

$$\mathbf{Ax} = \mathbf{b} \quad \rightarrow \quad \mathbf{x} = \mathbf{Hx} + \mathbf{b}$$

$$\mathbf{H} = \mathbf{I} - \mathbf{A}$$

- Generate the *Neumann series*

$$\mathbf{A}^{-1} = (\mathbf{I} - \mathbf{H})^{-1} = \sum_{k=0}^{\infty} \mathbf{H}^k$$

- Require $\rho(\mathbf{H}) < 1$ for convergence

$$\mathbf{A}^{-1}\mathbf{b} = \sum_{k=0}^{\infty} \mathbf{H}^k \mathbf{b} = \mathbf{x}$$

- Expand the Neumann series

$$x_i = \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N h_{i,i_1} h_{i_1,i_2} \cdots h_{i_{k-1},i_k} b_{i_k}$$

- Define a sequence of state transitions

$$\nu = i \rightarrow i_1 \rightarrow \cdots \rightarrow i_{k-1} \rightarrow i_k$$

- Define the *Neumann-Ulam decomposition*¹

$$\mathbf{H} = \mathbf{P} \circ \mathbf{W}$$

¹The Hadamard product $\mathbf{A} = \mathbf{B} \circ \mathbf{C}$ is defined element-wise as $a_{ij} = b_{ij}c_{ij}$.

- Compute row-normalized transition probabilities and weights

$$p_{ij} = \frac{|h_{ij}|}{\sum_j |h_{ij}|}, \quad w_{ij} = \frac{h_{ij}}{p_{ij}}$$

- Generate an expectation value for the solution

$$W_m = w_{i,i_1} w_{i_1,i_2} \cdots w_{i_{m-1},i_m}$$

$$X_\nu(i_0 = i) = \sum_{m=0}^k W_m b_{i_m}$$

Direct Method

- Compute the probability of a particular random walk permutation

$$P_\nu = p_{i,i_1} p_{i_1,i_2} \cdots p_{i_{k-1},i_k}$$

- Generate the estimator

$$E\{X(i_0 = i)\} = \sum_\nu P_\nu X_\nu$$

- Check that we recover the exact solution

$$\begin{aligned} E\{X(i_0 = i)\} &= \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N p_{i,i_1} p_{i_1,i_2} \cdots p_{i_{k-1},i_k} w_{i,i_1} w_{i_1,i_2} \cdots w_{i_{k-1},i_k} b_{i_k} \\ &= x_i \end{aligned}$$

Evolution of a Solution

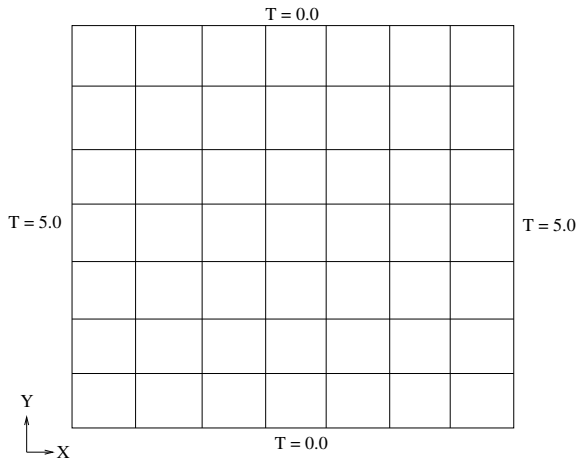


Figure : **Poisson Problem.** *Distributed source of 1.0 in the domain.*

Evolution of a Solution: Direct Method

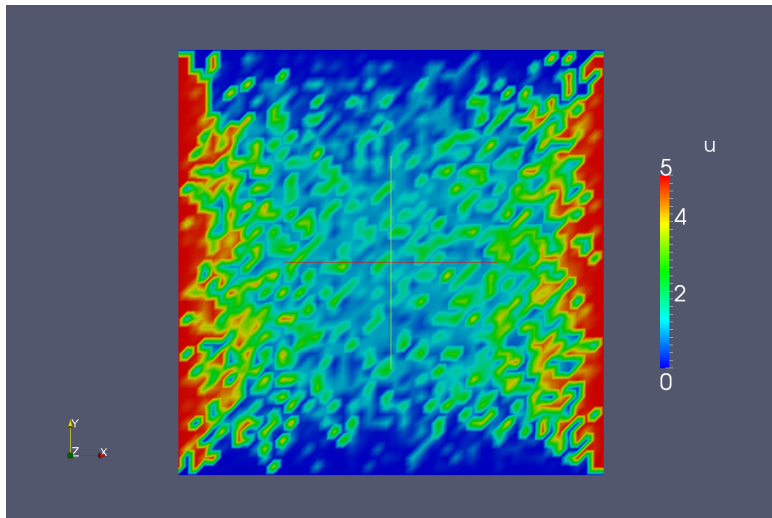


Figure : **Direct solution to Poisson Equation.** 1×10^0 *total histories.*

Evolution of a Solution: Direct Method

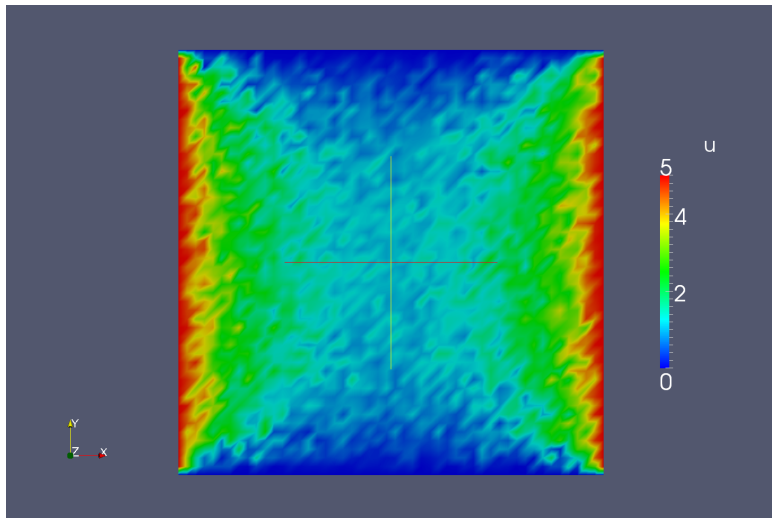


Figure : **Direct solution to Poisson Equation.** 1×10^1 *total histories.*

Evolution of a Solution: Direct Method

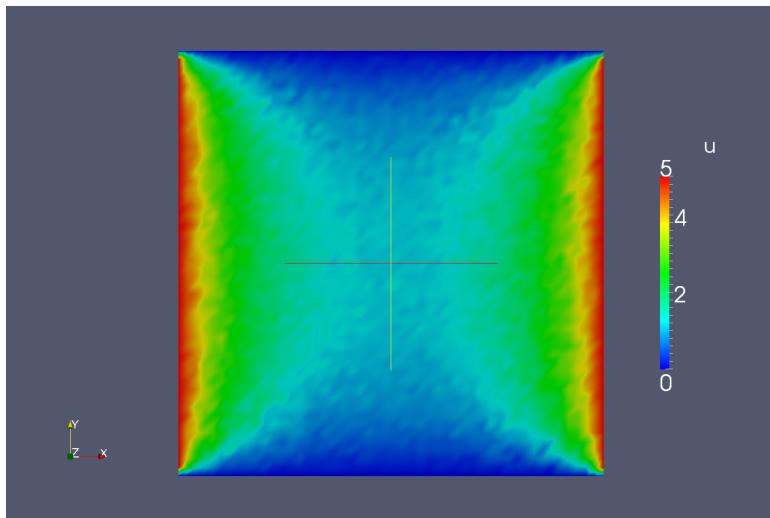


Figure : **Direct solution to Poisson Equation.** 1×10^2 *total histories.*

Evolution of a Solution: Direct Method

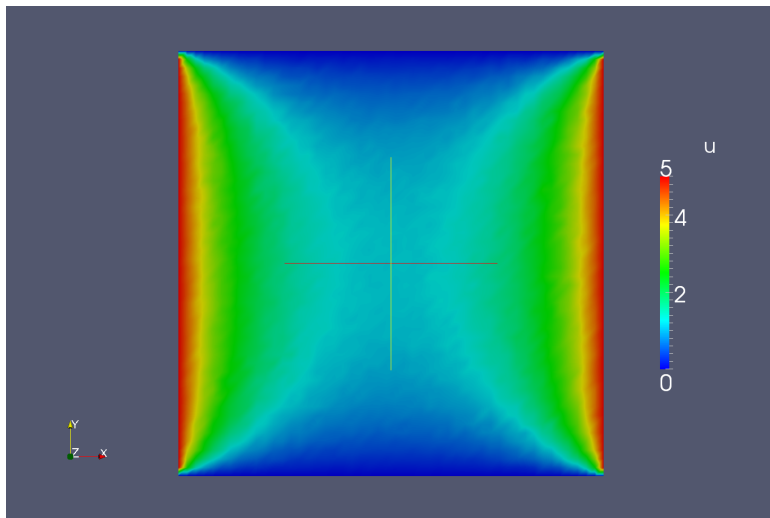


Figure : **Direct solution to Poisson Equation.** 1×10^3 total histories.

- Solve the adjoint linear system

$$\mathbf{A}^T \mathbf{y} = \mathbf{d}$$

$$\mathbf{y} = \mathbf{H}^T \mathbf{y} + \mathbf{d}$$

- Set the adjoint constraint

$$\langle \mathbf{A}^T \mathbf{x}, \mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{A} \mathbf{y} \rangle$$

$$\langle \mathbf{x}, \mathbf{d} \rangle = \langle \mathbf{y}, \mathbf{b} \rangle$$

Adjoint Method

- Generate the Neumann series for the adjoint operator

$$\mathbf{y} = (\mathbf{I} - \mathbf{H}^T)^{-1} \mathbf{d} = \sum_{k=0}^{\infty} (\mathbf{H}^T)^k \mathbf{d}$$

- Expand the series

$$y_i = \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N h_{i_k, i_{k-1}} \cdots h_{i_2, i_1} h_{i_1, i} d_{i_k}$$

- Pick another constraint to yield the original solution

$$\mathbf{d} = \boldsymbol{\delta}_i, \langle \mathbf{y}, \mathbf{b} \rangle = \langle \mathbf{x}, \boldsymbol{\delta}_i \rangle = x_i$$

Adjoint Method

- Use the adjoint Neumann-Ulam decomposition

$$\mathbf{H}^T = \mathbf{P} \circ \mathbf{W}$$

$$p_{ij} = \frac{|h_{ji}|}{\sum_j |h_{ji}|}, \quad w_{ij} = \frac{h_{ji}}{p_{ij}}$$

- Build the estimator and expectation value

$$X_\nu = \sum_{m=0}^k W_m \delta_{i, i_m}$$

$$\begin{aligned} E\{X_j\} &= \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N b_{i_0} h_{i_0, i_1} h_{i_1, i_2} \cdots h_{i_{k-1}, i_k} \delta_{i_k, j} \\ &= x_j \end{aligned}$$

Evolution of a Solution: Adjoint Method

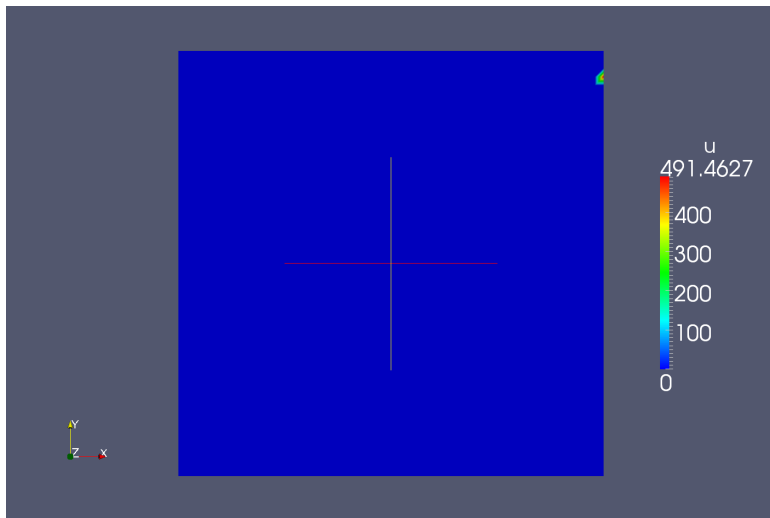


Figure : **Adjoint solution to Poisson Equation.** 1×10^0 *total histories.*

Evolution of a Solution: Adjoint Method

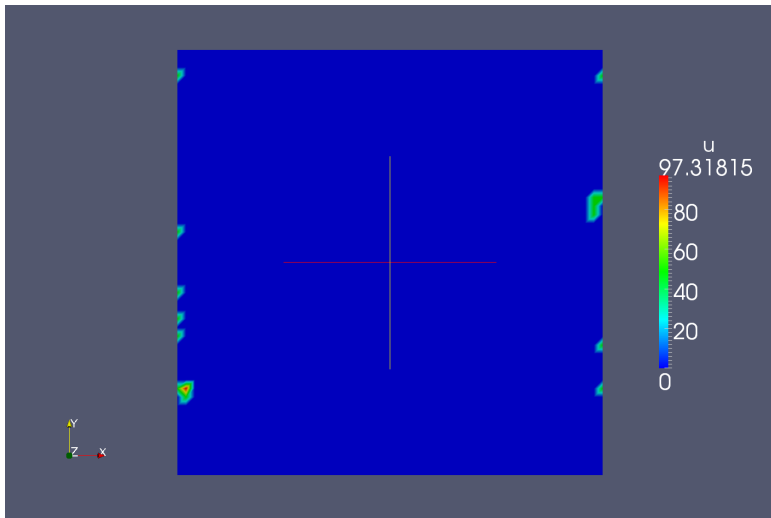


Figure : **Adjoint solution to Poisson Equation.** 1×10^1 total histories.

Evolution of a Solution: Adjoint Method

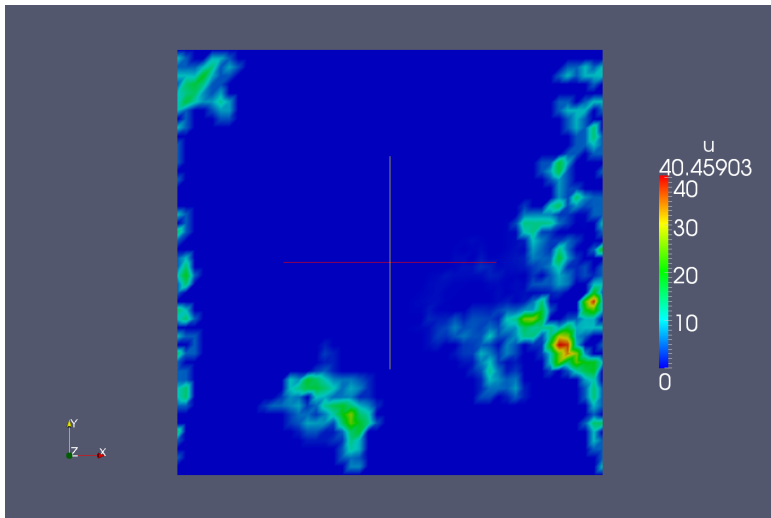


Figure : **Adjoint solution to Poisson Equation.** 1×10^2 total histories.

Evolution of a Solution: Adjoint Method

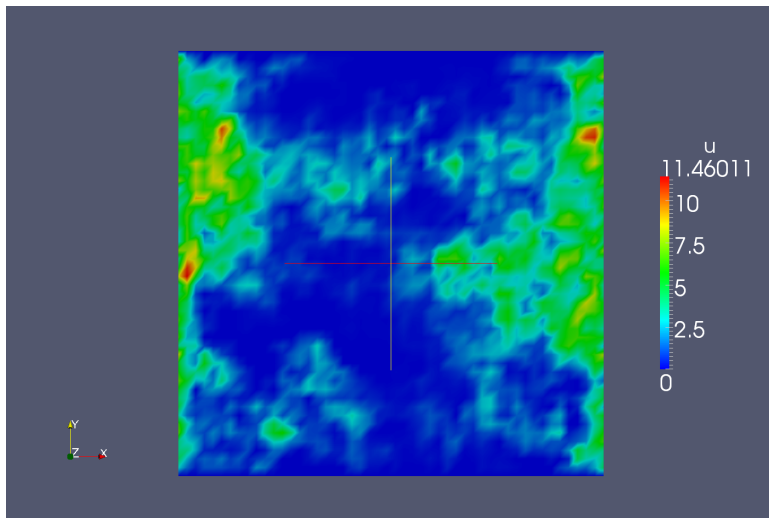


Figure : **Adjoint solution to Poisson Equation.** 1×10^3 *total histories.*

Evolution of a Solution: Adjoint Method

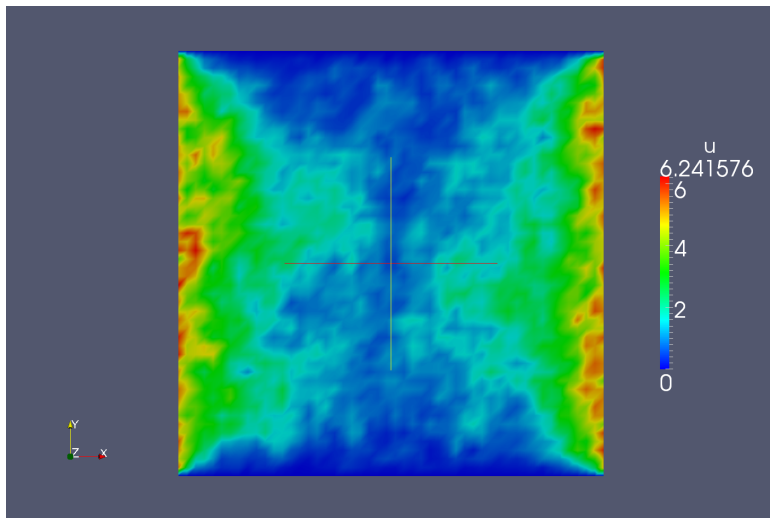


Figure : **Adjoint solution to Poisson Equation.** 1×10^4 total histories.

Evolution of a Solution: Adjoint Method

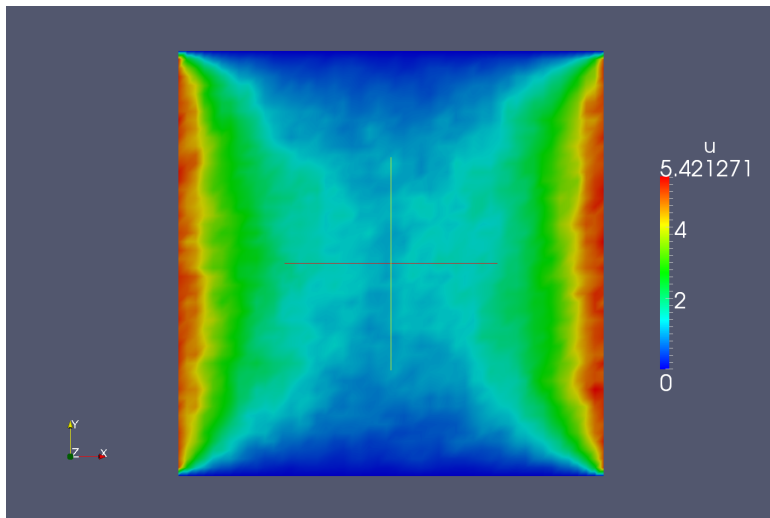


Figure : **Adjoint solution to Poisson Equation.** 1×10^5 total histories.

Evolution of a Solution: Adjoint Method

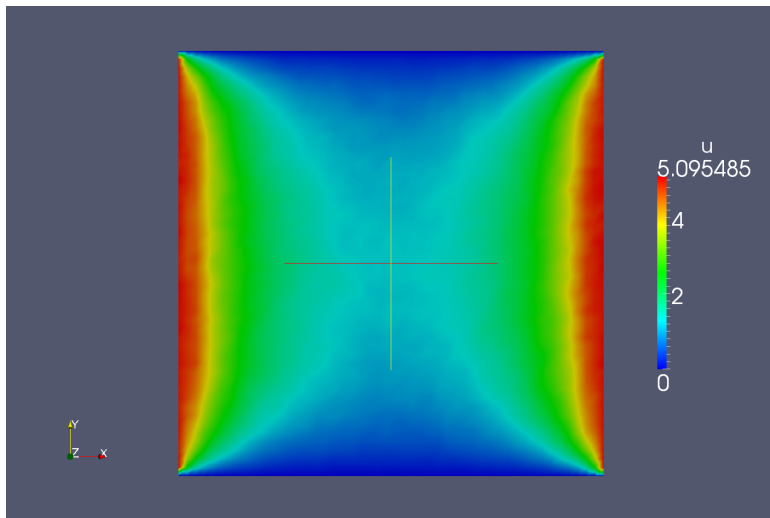


Figure :
histories.

Adjoint solution to Poisson Equation. 1×10^6 total

Evolution of a Solution: Adjoint Method

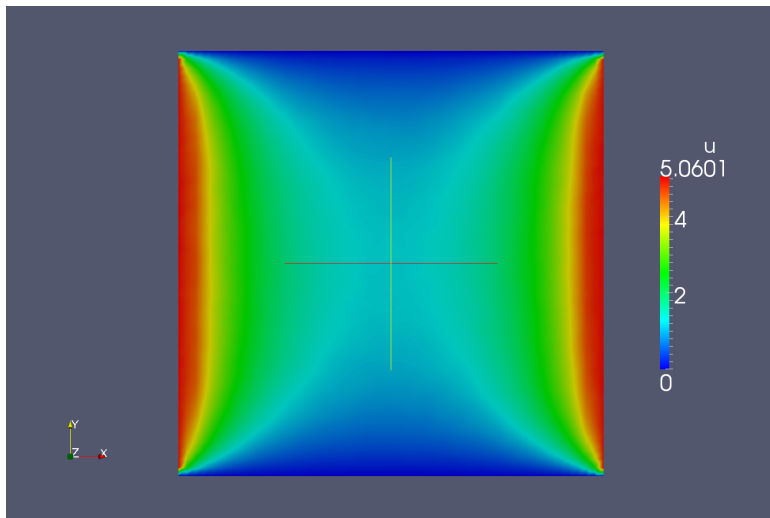


Figure :
histories.

Adjoint solution to Poisson Equation. 1×10^7 total

Model Problem

Choose a simple homogeneous problem with Dirichlet conditions:

$$\nabla^2 x = 0, \quad \mathbf{x}_1 = 0, \quad \mathbf{x}_N = 0$$

Second order finite difference:

$$(\nabla \mathbf{u})_i = \frac{\mathbf{u}_{i-1} - 2\mathbf{u}_i + \mathbf{u}_{i+1}}{h^2}$$

Monte Carlo requires $\rho(\mathbf{H})$ - scale by the diagonal:

$$\mathbf{M}^{-1} \mathbf{A} \mathbf{x} = \mathbf{0}$$

Choose initial guess to be some Fourier mode

$$\mathbf{x}_i^0 = \sin \left(\frac{ik\pi}{N} \right)$$

Error Analysis

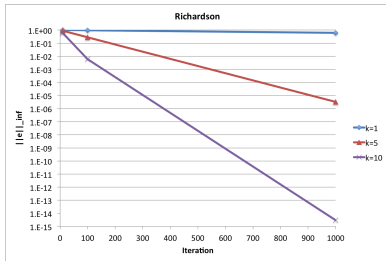


Figure : Convergence of Richardson's iteration. *Better for larger wave numbers.*

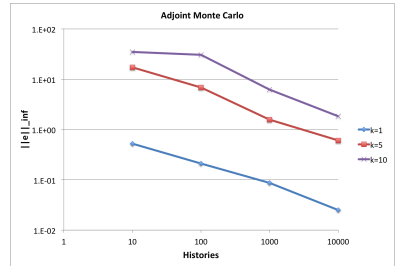


Figure : Convergence of the adjoint Monte Carlo method. *Better for smaller wave numbers.*

- A multilevel scheme means larger errors at coarser levels
- More samples required at the coarser levels
- Potential reduction in run time if the coarse level problems are fast

Error Analysis

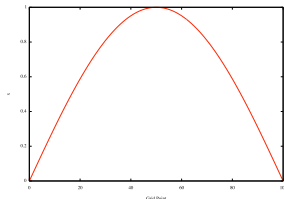


Figure : $k = 1$.

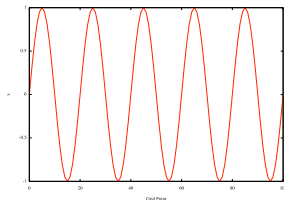


Figure : $k = 10$.

Wave Number	Time per History (s)
1	1
5	0.85
10	0.83

Table : Normalized average time per history.

- $\sigma(A)$ dictates the characteristics of the Markov chain
- Random walks are shorter for larger k
- N dictates the convergence of the Monte Carlo method
- More samples required to resolve fine structures

Multilevel Monte Carlo Methods

- Formalized for integral equations (Heinrich,2001)
- Expanded for time-dependent finance calculations (Giles,2008)
- Recent work includes Bayesian inference techniques for stochastic PDEs in ground water flow (Cliffe,2011) (Teckentrup,2013)
- Idea is to leverage multigrid ideas to reduce variance

Multilevel Expectation

Start first with the standard Monte Carlo estimator for the solution vector:

$$\hat{\mathbf{x}} = \frac{1}{N} \sum_{m=1}^N \mathbf{x}^m$$

Consider L levels with level 0 the finest L the coarsest:

$$E(\mathbf{x}_0) = E(\mathbf{x}_L) + E(\mathbf{x}_{L-1} - \mathbf{x}_L) + E(\mathbf{x}_{L-2} - \mathbf{x}_{L-1}) + \cdots + E(\mathbf{x}_0 - \mathbf{x}_1)$$

Reduce to a sum:

$$\hat{\mathbf{y}}_l = \frac{1}{N_l} \sum_{m=1}^{N_l} (\mathbf{x}_l^m - \mathbf{x}_{l+1}^m)$$

Build a correction estimator for a given level l :

$$\hat{\mathbf{y}}_l = \frac{1}{N_l} \sum_{m=1}^{N_l} (x_l^m - x_{l+1}^m)$$

Leaving a final multilevel estimator of:

$$\hat{\mathbf{x}} = \sum_{l=0}^L \hat{\mathbf{y}}_l$$

Critical observation: x_l^m and x_{l+1}^m must be constructed from the *same* Markov chain

Constructing Multilevel Estimates

Define a *prolongation operator*, \mathbf{P}_l , and a *restriction operator*, \mathbf{R}_l , with variational conditions:

$$\mathbf{R} = {}_c\mathbf{P}^T$$

$$\mathbf{A}_{l+1} = \mathbf{R}_l \mathbf{A}_l \mathbf{P}_l$$

Use to build the multilevel estimate:

$$E(\mathbf{x}_l - \mathbf{x}_{l+1}) = (\mathbf{I} - \mathbf{P}_l \mathbf{R}_l) \hat{\mathbf{x}}_l$$

where $\hat{\mathbf{x}}_l$ is constructed from the standard adjoint estimator at level l

Number of samples at each level should be determined from the estimated variance. For simplicity:

$$N_l = 2^{-3(L-l)/2} N$$

Multilevel Monte Carlo Solver

Algorithm 1 Multilevel Monte Carlo Method

```
1: for  $l = 0 \dots L$  do
2:    $\mathbf{P}_l = P(\mathbf{A}_l)$  {Build the prolongation and restriction operators for
   the  $l^{th}$  level.}
3:    $\mathbf{R}_l = c\mathbf{P}_l^T$ 
4:    $\mathbf{r}_l = \mathbf{b}_l - \mathbf{A}_l \mathbf{x}_l^0$  {Build the  $l^{th}$  level residual.}
5:    $\mathbf{d}_l = \hat{\mathbf{A}}_l^{-1} \mathbf{r}_l$  {Solve the  $l^{th}$  level problem with adjoint Monte Carlo}
6:   if  $l \neq L$  then
7:      $\mathbf{d}_l = (\mathbf{I} - \mathbf{P}_l \mathbf{R}_l) \mathbf{d}_l$  {Apply the multilevel tally}
8:      $\mathbf{A}_{l+1} = \mathbf{R}_l \mathbf{A}_l \mathbf{P}_l$  {Construct the next level.}
9:      $\mathbf{x}_{l+1}^0 = \mathbf{R}_l \mathbf{x}_l^0$ 
10:     $\mathbf{b}_{l+1} = \mathbf{R}_l \mathbf{b}_l$ 
11:   end if
12: end for
13: for  $l = L \dots 1$  do
14:    $\mathbf{d}_{l-1} = \mathbf{d}_{l-1} + \mathbf{P}_l \mathbf{d}_l$  {Collapse the tallies to the finest grid}
15: end for
16:  $\mathbf{x} = \mathbf{x}^0 + \mathbf{d}_0$ 
```


Numerical Experiments

- Solve the model problem on grid size 1024 and $N = 10,000$
- Geometric multigrid operators from Briggs' multigrid tutorial, $M = 2$
- Algebraic multigrid operators from ML, $M \approx 3$

Measure performance with a *figure of merit*:

$$FOM = \frac{1}{\|\mathbf{e}\|_{\infty}^2 T}$$

Geometric Multigrid Results

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	0.022	119.1	1
2	13,535	0.026	72.0	1.14
3	14,785	0.035	33.2	1.38
4	15,226	0.039	13.7	2.63
5	15,382	0.027	5.5	13.86
6	15,437	0.036	2.3	19.21
7	15,456	0.045	0.98	28.00
8	15,462	0.081	0.41	20.66
9	15,464	0.267	0.17	11.72

Table : $k = 1$.

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	0.668	101.6	1
2	13,535	0.381	60.0	5.21
3	14,785	0.396	28.0	10.34
4	15,226	0.599	11.9	10.64
5	15,382	0.638	4.7	23.60
6	15,437	1.052	1.8	23.15
7	15,456	1.070	0.67	59.16
8	15,462	1.180	0.23	144.10
9	15,464	2.130	0.10	99.95

Table : $k = 5$.

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	1.81	98.6	1
2	13,535	1.67	59.6	1.94
3	14,785	2.41	27.1	2.05
4	15,226	3.20	11.5	2.74
5	15,382	1.85	4.93	19.14
6	15,437	3.89	1.95	10.95
7	15,456	3.79	0.78	28.68
8	15,462	7.08	0.30	21.62
9	15,464	11.7	0.11	21.45

Table : $k = 10$.

- There is a limit to the number of levels
- Too few samples on the fine grid drive up the error

Algebraic Multigrid Results

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	0.022	119.1	1
2	11,924	0.037	31.9	1.28
3	12,294	0.055	7.6	2.40
4	12,365	0.051	1.8	11.76
5	12,378	0.094	0.5	12.01

Table : $k = 1$.

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	0.668	101.6	1
2	11,924	0.834	30.8	2.12
3	12,294	1.140	7.5	4.63
4	12,365	0.975	1.6	29.09
5	12,378	2.240	0.4	25.10

Table : $k = 5$.

Levels	Samples	$\ e\ _\infty$	Time (s)	RFOM
1	10,000	1.81	98.6	1
2	11,924	2.33	30.0	1.99
3	12,294	3.19	7.6	4.20
4	12,365	3.31	1.8	16.29
5	12,378	9.98	0.5	7.21

Table : $k = 10$.

- Algebraic operators are also effective
- $M \approx 3$ is an ad hoc estimate
- need variance estimates instead

- Multilevel Monte Carlo methods can be an effective variance reduction technique by reducing the computation time needed to reach a particular error
- More formal analysis of convergence in the context of linear systems is required
- For large problems, density of A_l for coarse levels increases computational complexity of the Monte Carlo - consider non-Galerkin and sparsification approaches
- Future work includes addition of variance estimation to properly select N_l

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