view_frames Result

Recorded at time: 1636078200.961

dog_base

dog map Broadcaster: /stdr_gmapping_node Broadcaster: /dog_to_scan Average rate: 20.202 Hz Average rate: 10.191 Hz Most recent transform: 1636078201.031 (-0.070 sec old) Most recent transform: 1636078200.990 (-0.029 sec old) Buffer length: 4.950 sec Buffer length: 4.906 sec odom laser Broadcaster: /dog_driver_node Average rate: 9.917 Hz Most recent transform: 1636078200.865 (0.096 sec old) Buffer length: 4.840 sec