

1. 设置环境

进入到项目所在目录

```
conda create -n sfm python==3.7.6
```

```
conda activate sfm
```

```
pip install -r requirements.txt
```

2. 运行脚本

2.1 对 temple 数据集进行预处理

```
python preprocess.py --dataset temple
```

```
INFO: detecting image keypoints...  
100%|██████████████████████████████████████████████████████████████████████████████| 47/47 [00:03<00:00, 14.98it/s]  
INFO: creating pairwise matches between images...  
100%|██████████████████████████████████████████████████████████████████████████████| 1081/1081 [00:07<00:00, 137.55it/s]  
INFO: creating ransac matches...  
100%|██████████████████████████████████████████████████████████████████████████████| 1081/1081 [00:06<00:00, 174.13it/s]  
INFO: creating scene graph...
```

2.2 对 mini-temple 数据集进行预处理

```
python preprocess.py --dataset mini-temple
```

```
(sfm) PS D:\Anaconda3\envs\opencv_gradio\project\homework-04-lab03-sfm-ba-li338> python preprocess.py --dataset mini-temple
INFO: detecting image keypoints...
100%|██████████████████████████████████████| 11/11 [00:01<00:00, 8.04it/s]
INFO: creating pairwise matches between images...
100%|██████████████████████████████████████| 55/55 [00:01<00:00, 37.67it/s]
INFO: creating ransac matches...
100%|██████████████████████████████████████| 55/55 [00:01<00:00, 40.72it/s]
INFO: creating scene graph...
```

2.3 执行不包含捆绑调整的结构从运动中恢复

```
python sfm.py --dataset temple
```

[illegible]

2.4 在 mini-temple 数据集上执行包含捆绑调整的结构从运动中恢复

```
python sfm.py --dataset mini-temple --ba
```

```

100% | 9/9 [00:00<00:00, 14.97it/s]
Iteration    Total nfev    Cost    Cost reduction    Step norm    Optimality
0            1        6.0598e+02        6.74e+01    5.44e-04    1.32e+05
1            12        5.3862e+02        5.04e+00    2.72e-04    2.14e+04
2            14        5.3358e+02        1.20e-01    2.72e-04    1.97e+04
3            15        5.3346e+02        3.13e+00    2.72e-04    4.66e+04
4            16        5.3033e+02        1.29e+00    6.80e-05    1.45e+04
5            17        5.2904e+02        4.80e-01    1.36e-04    1.57e+04
6            18        5.2856e+02        7.14e-01    1.36e-04    2.25e+04
7            19        5.2765e+02        4.08e-01    3.40e-05    1.08e+04
8            20        5.2694e+02        4.78e-01    6.80e-05    7.09e+03
9            21        5.2645e+02        5.26e-01    6.80e-05    1.73e+04
10           22        5.2604e+02        4.78e-01    6.80e-05    2.82e+04
11           23        5.2556e+02        5.18e-01    6.80e-05    2.94e+04
12           24        5.2504e+02        5.26e-01    6.80e-05    2.95e+04
13           25        5.2456e+02        4.68e-01    6.80e-05    3.02e+04
14           26        5.2403e+02        4.76e-01    6.80e-05    2.99e+04
15           27        5.2355e+02        5.10e-01    6.80e-05    3.04e+04
16           28        5.2304e+02        5.10e-01    6.80e-05    3.00e+04
17           29        5.2257e+02        5.10e-01    6.80e-05    3.05e+04
18           30        5.2206e+02        5.10e-01    6.80e-05    3.01e+04
The maximum number of function evaluations is exceeded.
Function evaluations 30, initial cost 6.0598e+02, final cost 5.2206e+02, first-order optimality 3.01e+04.

```

2.5 在 mini-temple 数据集上执行不包含捆绑调整的结构从运动中恢复

python sfm.py --dataset mini-temple

```

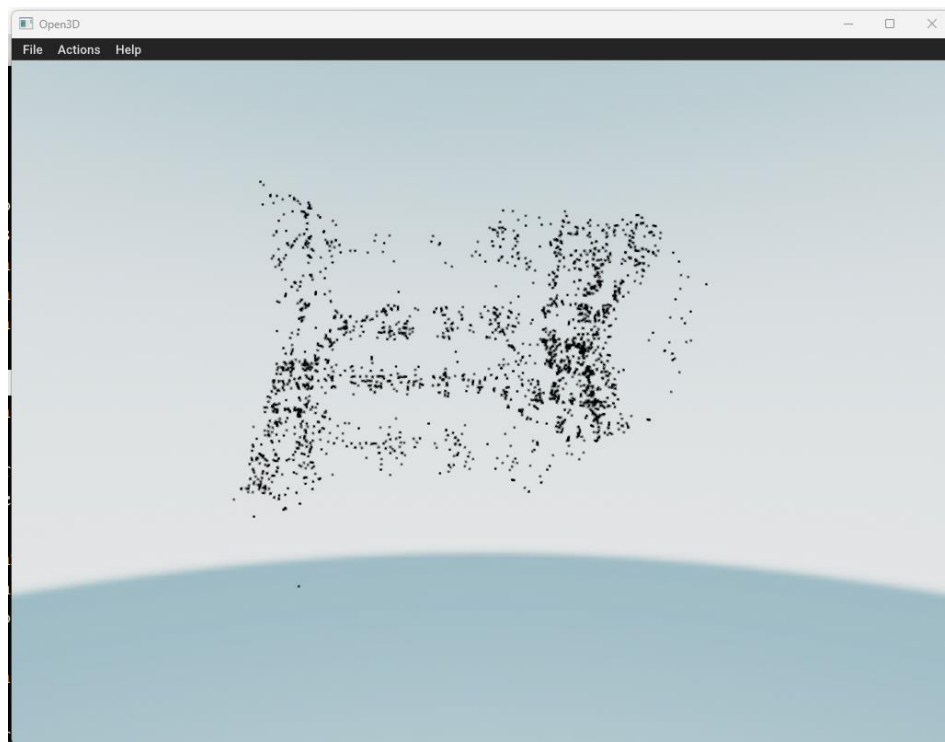
(sfm) PS D:\Anaconda3\envs\opencv_gradio\project\homework-04-lab03-sfm-ba-li338> python sfm.py --dataset mini-temple
100% | 9/9 [00:00<00:00, 9.46it/s]

```

3. 可视化

3.1 从重建中可视化 3D 点云

python visualize.py --dataset mini-temple



3.2 temple 数据集上的重建 3D 点云

```
python visualize.py --dataset temple
```

