I/O System Characteristics(特性)

- Dependability(可靠性) is important
- Particularly for storage devices
- Performance measures
- Latency (response time,响应时间)
- Throughput (bandwidth, 带宽)
- Desktops & embedded systems
- Mainly interested in response time & diversity(多样 性) of devices
- Servers
- Mainly interested in throughput & expandability(扩展 性) of devices



Chapter 6 — Storage and Other I/O Topics — 3

Dependability(可信度) Measures

- Reliability(可靠度): mean time to failure (MTTF)
- Service interruption: mean time to repair (MTTR)
- Mean time between failures
- MTBF = MTTF + MTTR
- Availability = MTTF / (MTTF + MTTR)
- Improving Availability(可用度)
- Increase MTTF: fault avoidance(避免), fault tolerance(容忍), fault forecasting(预测)
- Reduce MTTR: improved tools and processes for diagnosis(诊断) and repair



Chapter 6 — Storage and Other I/O Topics — 4



M K4 COMPUTER ORGANIZATION AND DESIGN

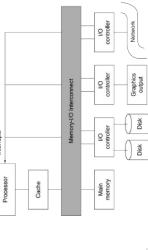
The Hardware/Software Interface

Chapter 6

Storage and Other I/O **Topics**

Introduction

- I/O devices can be characterized by
- Behaviour: input, output, storage
 - Partner: human or machine
- Data rate: bytes/sec, transfers/sec
- I/O bus connections





Chapter 6 — Storage and Other I/O Topics — 2

Disk Access Example

- Given
- 512B sector, 15,000rpm, 4ms average seek time, 100MB/s transfer rate, 0.2ms controller overhead, idle disk
- Average read time
- 4ms seek time
 + ½ / (15,000/60) = 2ms rotational latency
 + 512 / 100MB/s = 0.005ms transfer time
- + 0.2ms controller delay = 6.2ms
- If actual average seek time is 1ms
- Average read time = 3.2ms



Chapter 6 — Storage and Other I/O Topics — 7

 \sum

Flash Storage

- Nonvolatile semiconductor storage
- $100 \times -1000 \times$ faster than disk
- Smaller, lower power, more robust
- But more \$/GB (between disk and DRAM)





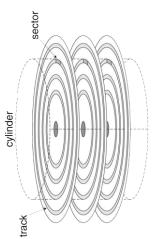




Disk Storage

 Nonvolatile(非易失性), rotating(旋转式) magnetic storage





Chapter 6 — Storage and Other I/O Topics — 5

Disk Sectors and Access

- Each sector(扇区) records
- Sector ID
- Data (512 bytes, 4096 bytes proposed)
- Error correcting code (ECC:纠错码)
- Used to hide defects(缺陷) and recording errors
- Synchronization fields and gaps
- Access to a sector involves(涉及)
- Queuing delay if other accesses are pending
- Seek: move the heads
- Rotational latency Data transfer
- Controller overhead



Chapter 6 — Storage and Other I/O Topics — 6

Bus Types

- Processor-Memory buses
- Short, high speed
- Design is matched to memory organization
- I/O buses
- Longer, allowing multiple connections
- Specified by standards for interoperability
- Connect to processor-memory bus through a bridge



Chapter 6 — Storage and Other I/O Topics — 11

Bus Signals and Synchronization

- Data lines
- Carry address and data
- Multiplexed or separate
- Control lines
- Indicate data type, synchronize transactions
- Synchronous
- Uses a bus clock
- Asynchronous
- Uses request/acknowledge control lines for handshaking



Chapter 6 — Storage and Other I/O Topics — 12

Flash Types

- NOR flash: bit cell like a NOR gate
- Random read/write access
- Used for instruction memory in embedded systems
- NAND flash: bit cell like a NAND gate
- Denser (bits/area), but block-at-a-time access
- Cheaper per GB
- Used for USB keys, media storage, ...
- Flash bits wears out after 1000's of accesses
- Not suitable for direct RAM or disk replacement
- Wear leveling: remap data to less used blocks



Chapter 6 — Storage and Other I/O Topics — 9

Interconnecting Components

- Need interconnections between
 - CPU, memory, I/O controllers
- Bus: shared communication channel
- Parallel set of wires for data and synchronization of data transfer
- Can become a bottleneck
- Performance limited by physical factors
- Wire length, number of connections
- More recent alternative: high-speed serial connections with switches
- Like networks



I/O Management

- I/O is mediated by the OS
- Multiple programs share I/O resources
- Need protection and scheduling
- I/O causes asynchronous(异步的) interrupts
- Same mechanism as exceptions
- I/O programming is fiddly(麻烦的, 精巧的)
- OS provides abstractions to programs



Chapter 6 — Storage and Other I/O Topics — 15

I/O Commands

- I/O devices are managed by I/O controller hardware
- Transfers data to/from device
- Synchronizes operations with software
- Command registers
- Cause device to do something
- Status registers
- Indicate what the device is doing and occurrence of
- Data registers
- Write: transfer data to a device
- Read: transfer data from a device



Chapter 6 — Storage and Other I/O Topics — 16

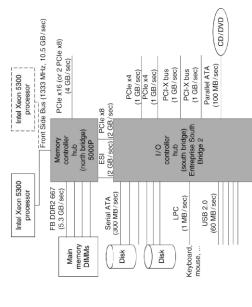
I/O Bus Examples

	Firewire	USB 2.0	PCI Express	Serial ATA	Serial Attached
Intended use	External	External	Internal	Internal	External
Devices per channel	63	127	-	_	4
Data width	4	2	2/lane	4	4
Peak bandwidth	50MB/s or 100MB/s	0.2MB/s, 1.5MB/s, or 60MB/s	250MB/s/lane $1\times, 2\times, 4\times, 8\times, 16\times, 32\times$	300MB/s	300MB/s
Hot pluggable	Yes	Yes	Depends	Yes	Yes
Max length	4.5m	2m	0.5m	1m	8m
Standard	IEEE 1394	USB	PCI-SIG	SATA-10	INCITS TC
		Forum			
(8)					



Chapter 6 — Storage and Other I/O Topics — 13

Typical x86 PC I/O System





Chapter 6 — Storage and Other I/O Topics — 14

Interrupts

- When a device is ready or error occurs
- Controller interrupts CPU
- Interrupt is like an exception
- But not synchronized to instruction execution
- Can invoke handler between instructions
- Cause information often identifies the interrupting device
- Priority interrupts
- Devices needing more urgent attention get higher priority
- Can interrupt handler for a lower priority interrupt



Chapter 6 — Storage and Other I/O Topics — 19

I/O Data Transfer

- Polling and interrupt-driven I/O
- CPU transfers data between memory and I/O data registers
- Time consuming for high-speed devices
- Direct memory access (DMA)
- OS provides starting address in memory
- I/O controller transfers to/from memory autonomously
- Controller interrupts on completion or error



Chapter 6 — Storage and Other I/O Topics — 20

| I/O Register Mapping

- Memory mapped I/O
- Registers are addressed in same space as memory
- Address decoder distinguishes between them
- OS uses address translation mechanism to make them only accessible to kernel
- I/O instructions
- Separate instructions to access I/O registers
- Can only be executed in kernel mode
- Example: x86



Chapter 6 — Storage and Other I/O Topics — 17

Polling(轮询)

- Periodically check I/O status register
- If device ready, do operation
- If error, take action
- Common in small or low-performance realtime embedded systems
- Predictable timing
- Low hardware cost
- In other systems, wastes CPU time



I/O vs. CPU Performance

Amdahl's Law

Don't neglect I/O performance as parallelism increases compute performance

Example

- Benchmark takes 90s CPU time, 10s I/O time
- Double the number of CPUs/2 years
- I/O unchanged

Year	CPU time	I/O time	Elapsed time	% I/O time
won	s06	10s	100s	10%
+2	45s	10s	s <u>2</u> 9	18%
+4	23s	10s	338	31%
9+	11s	10s	21s	47%



Chapter 6 — Storage and Other I/O Topics — 23

Concluding Remarks

I/O performance measures

- Throughput, response time
- Dependability and cost also important
- Buses used to connect CPU, memory, I/O controllers
- Polling, interrupts, DMA
- I/O benchmarks
- TPC, SPECSFS, SPECWeb

DMA/Cache Interaction

- If DMA writes to a memory block that is cached
- Cached copy becomes stale
- If write-back cache has dirty block, and DMA reads memory block
- Reads stale data
- Need to ensure cache coherence
- Flush blocks from cache if they will be used for DMA
- Or use non-cacheable memory locations for I/O



Chapter 6 — Storage and Other I/O Topics — 21

Measuring I/O Performance

- I/O performance depends on
- Hardware: CPU, memory, controllers, buses
- Software: operating system, database management system, application
- Workload: request rates and patterns
- I/O system design can trade-off between response time and throughput
- Measurements(测量,量度) of throughput often done with constrained response-time



Σ Σ