#### Modular neural nets

In the previous exercise, we computed the loss and gradient for a two-layer neural network in a single monolithic function. This isn't very difficult for a small two-layer network, but would be tedious and error-prone for larger networks. Ideally we want to build networks using a more modular design so that we can snap together different types of layers and loss functions in order to quickly experiment with different architectures.

In this exercise we will implement this approach, and develop a number of different layer types in isolation that can then be easily plugged together. For each layer we will implement forward and backward functions. The forward function will receive data, weights, and other parameters, and will return both an output and a cache object that stores data needed for the backward pass. The backward function will recieve upstream derivatives and the cache object, and will return gradients with respect to the data and all of the weights. This will allow us to write code that looks like this:

```
def two_layer_net(X, W1, b1, W2, b2, reg):
    # Forward pass; compute scores
    s1, fc1_cache = affine_forward(X, W1, b1)
    a1, relu_cache = relu_forward(s1)
    scores, fc2_cache = affine_forward(a1, W2, b2)

# Loss functions return data loss and gradients on scores
    data_loss, dscores = svm_loss(scores, y)

# Compute backward pass
    da1, dW2, db2 = affine_backward(dscores, fc2_cache)
    ds1 = relu_backward(da1, relu_cache)
    dX, dW1, db1 = affine_backward(ds1, fc1_cache)

# A real network would add regularization here

# Return loss and gradients
    return loss, dW1, db1, dW2, db2
```

```
In [3]: # As usual, a bit of setup
        import numpy as np
        import matplotlib.pyplot as plt
        from cs231n.gradient_check import eval_numerical_gradient_array, eval_numerica
        l_gradient
        from cs231n.layers import *
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
        # for auto-reloading external modules
        # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipyt
        hon
        %load ext autoreload
        %autoreload 2
        def rel_error(x, y):
          """ returns relative error """
          return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

The autoreload extension is already loaded. To reload it, use: %reload\_ext autoreload

## **Affine layer: forward**

Open the file cs231n/layers.py and implement the affine forward function.

Once you are done we will test your can test your implementation by running the following:

Testing affine\_forward function: difference: 9.76984772881e-10

## Affine layer: backward

Now implement the affine\_backward function. You can test your implementation using numeric gradient checking.

```
In [6]: # Test the affine backward function
        x = np.random.randn(10, 2, 3)
        w = np.random.randn(6, 5)
        b = np.random.randn(5)
        dout = np.random.randn(10, 5)
        dx num = eval numerical gradient array(lambda x: affine forward(x, w, b)[0],
        dw_num = eval_numerical_gradient_array(lambda w: affine_forward(x, w, b)[0],
        w, dout)
        db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0],
        b, dout)
         _, cache = affine_forward(x, w, b)
        dx, dw, db = affine_backward(dout, cache)
        # The error should be less than 1e-10
        print 'Testing affine_backward function:'
        print 'dx error: ', rel_error(dx_num, dx)
        print 'dw error: ', rel_error(dw_num, dw)
        print 'db error: ', rel_error(db_num, db)
        Testing affine_backward function:
        dx error: 6.99811149861e-10
```

#### **ReLU layer: forward**

dw error: 9.14830163174e-11
db error: 2.16251754573e-11

difference: 4.99999979802e-08

Implement the relu forward function and test your implementation by running the following:

#### ReLU layer: backward

Implement the relu\_backward function and test your implementation using numeric gradient checking:

```
In [8]: x = np.random.randn(10, 10)
dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

_, cache = relu_forward(x)
dx = relu_backward(dout, cache)

# The error should be around 1e-12
print 'Testing relu_backward function:'
print 'dx error: ', rel_error(dx_num, dx)

Testing relu_backward function:
dx error: 3.27564222471e-12
```

# Loss layers: Softmax and SVM

You implemented these loss functions in the last assignment, so we'll give them to you for free here. It's still a good idea to test them to make sure they work correctly.

```
In [9]: num_classes, num_inputs = 10, 50
        x = 0.001 * np.random.randn(num_inputs, num_classes)
        y = np.random.randint(num_classes, size=num_inputs)
        dx_num = eval_numerical_gradient(lambda x: svm_loss(x, y)[0], x,
        verbose=False)
        loss, dx = svm_loss(x, y)
        # Test svm_loss function. Loss should be around 9 and dx error should be 1e-9
        print 'Testing svm_loss:'
        print 'loss: ', loss
        print 'dx error: ', rel_error(dx_num, dx)
        dx_num = eval_numerical_gradient(lambda x: softmax_loss(x, y)[0], x, verbose=F
        alse)
        loss, dx = softmax_loss(x, y)
        # Test softmax_loss function. Loss should be 2.3 and dx error should be 1e-8
        print '\nTesting softmax_loss:'
        print 'loss: ', loss
        print 'dx error: ', rel_error(dx_num, dx)
```

Testing svm\_loss: loss: 8.99999185188

dx error: 8.18289447289e-10

Testing softmax\_loss:
loss: 2.30258473372

dx error: 8.68969367873e-09