# Multivariate Gaussian Classifier

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## Bayes' Rule

We can use the Bayes' rule to find an expression for the class with the highest probability

 $p(\omega_j|x) = \frac{p(x|\omega_j)P(\omega_j)}{p(x)} \tag{1}$ 

where the probability of being class  $\omega_j$  given x is equal to the probability of x given  $\omega_j$  times the prior probability of being class  $\omega_j$ . This whole thing is over the probability of x, but we're going to argue that we don't need that in a moment. The prior probability of  $\omega_j$  or  $P(\omega_j)$  could be defined differently for each class although in this case we will be assuming the classes are equally likely or  $\frac{1}{\#_{classes}}$ .

## Gaussian Density

Any probability can be used to make  $p(x|\omega_j)$ , but we want to use the multivariate Gaussian density.

$$p(\vec{x}|\omega_j) = \frac{1}{\sqrt{(2\pi)^d |\Sigma_j|}} e^{-\frac{1}{2}(\vec{x} - \vec{\mu_j})^{\mathsf{T}} \Sigma_j^{-1} (\vec{x} - \vec{\mu_j})}$$
(2)

where,  $\vec{\mu_j}$  is the mean vector for class j for d features. Giving,

$$\vec{\mu_j} = \begin{bmatrix} \mu_j^1 \\ \mu_j^2 \\ \vdots \\ \mu_j^n \end{bmatrix}$$
 (3)

And  $\Sigma_j$  is the covariance matrix for class j,  $|\Sigma_j|$  is its determinant, and  $\Sigma_j^{-1}$  is its inverse.

#### The Discriminant Function

From (1) we get the discriminant function

$$g_j(x) = p(\omega_j | \vec{x}) = \frac{p(\vec{x} | \omega_j) P(\omega_j)}{p(x)}$$
(4)

but we can ignore p(x) since this is only a normalizing factor and simplify the discriminant function by tossing it out since it won't change which class has the highest probability which is all we care about.

$$g_j(x) = p(\vec{x}|\omega_j)P(\omega_j) \tag{5}$$

#### **Our Discriminant Function**

Before presenting our combined Gaussian density and Bayes' rule discriminant function we will want to simplify using the knowledge that

$$\ln(N \cdot M) = \ln(N) + \ln(M) \tag{6}$$

when applied to our simplified Bayes' rule classifier

$$g_i(\vec{x}) = \ln(p(\vec{x}|\omega_i)P(\omega_i)) \tag{7}$$

$$= \ln(p(\vec{x}|\omega_i)) + \ln(P(\omega_i)) \tag{8}$$

Now we can use this newly acquired knowledge to eliminate the exponent yielding a simplified multivariate Gaussian Classifier

$$g_j(\vec{x}) = -\frac{1}{2}(\vec{x} - \vec{\mu_j})^{\mathsf{T}} \Sigma_j^{-1}(\vec{x} - \vec{\mu_j}) - \frac{d}{2} \ln 2\pi - \frac{1}{2} \ln |\Sigma_j| + \ln P(\omega_j)$$
 (9)

### **Special Cases**

Equation (9) can sometimes be simplified given specific knowledge about the covariance matrices.

## Case 1: $\Sigma_j = \sigma^2 I$

The features are uncorrelated (independent) and have the same variance. Recalling (9) we can discard everything that is common for all classes, so we get

$$g_j(x) = -\frac{||\vec{x} - \vec{\mu_j}||^2}{2\sigma^2} + \ln P(\omega_j)$$
 (10)

where,

$$||\vec{x} - \vec{\mu_j}||^2 = (\vec{x} - \vec{\mu_j})^{\mathsf{T}} (\vec{x} - \vec{\mu_j})$$
(11)

which is the Euclidian distance. This is known as a minimum distance classifier.

#### Case 2: Common covariance matrix

Again, recalling (9), but instead of  $\Sigma_j = \sigma^2 I$  we have  $\Sigma_j = \Sigma$ . Since the covariance matrices are equal we can reduce the discriminant function to

$$g_j(\vec{x}) = -\frac{1}{2}(\vec{x} - \vec{\mu_j})^{\mathsf{T}} \Sigma_j^{-1}(\vec{x} - \vec{\mu_j}) + \ln P(\omega_j)$$
 (12)

$$(\vec{x} - \vec{\mu_j})^{\mathsf{T}} \Sigma_j^{-1} (\vec{x} - \vec{\mu_j}) \tag{13}$$

equation (13) is the Mahalanobis distance.