#### SAGNIK BASU 113EC0199

#### **QUESTION**

# **Communication Channel Equalizer using Perceptron**

Design a perceptron/ adaline with suitable activation function for communication channel equalization as detailed in the accompanying document.

#### **MATLAB CODE**

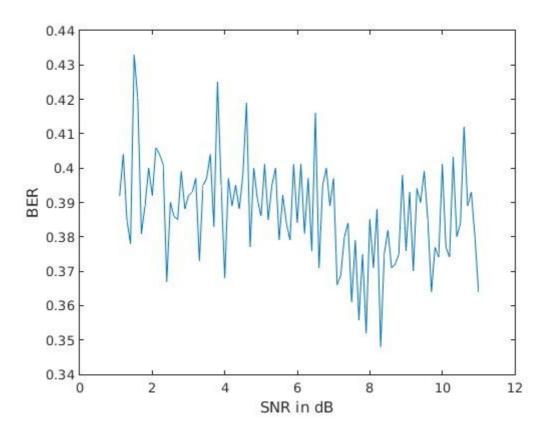
```
clc:
clear all;
close all;
c=input('Channel order');
experiments =50.0;
samples=1000;
x=2*rand(1,samples)-1;
inp=zeros(1,samples);
for i=1:length(x) %%generation of inputs
  if(x(i) < 0)
    inp(i)=-1;
  else if(x(i)>0)
       inp(i)=1;
    else
       inp(i)=0;
    end
  end
end
%noise=2*rand(1,samples)-1; %%noise(bias)
%%channel 1
%y1=inp+noise;
SNR=20;
y1=awgn(inp,SNR);
weights=2*(rand(1,c))-1;
bias=2*rand(1,1)-1; %%bias for the perceptron
y=zeros(1,samples);
output=zeros(1,samples);
error=zeros(1,samples);
```

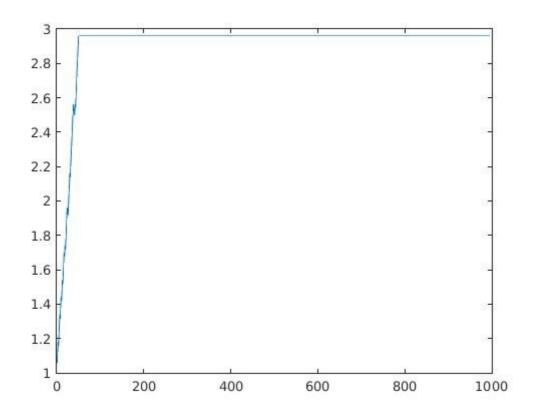
```
err train=zeros(1,samples);
%%final_err_train=0;
for j=1:samples-c
                     %% input1(:,j)=input(:,r);
y(1,j)=y1(1,j:j+c-1)*(transpose(weights))+bias;
                     \%out(1,j) = (1/(1+exp(-y(1,j))));
                     \%\%e=d_out(r)-out(j);
output(1,j)=hardlims(y(1,j));
%MSE Calculation for 50 experiments
final_err_mse2=0;
for k=1:experiments
   y_mse2(1,k)=y1(1,k:k+c-1)*(transpose(weights))+bias;
   output mse2(1,k)=hardlims(y(1,k));
   error_mse2(1,k)=inp(1,k)-output(1,k);
   final err mse2=final err mse2+error mse2(1,k)*error mse2(1,k);
end
mse_2(j)=final_err_mse2/experiments;
%%training
error(1,j) = inp(1,j) - output(1,j);
%%err_train(j)=error(1,j)*error(1,j);
bias=bias+error(1,j);
weights=weights+error(1,j)*y1(1,k:k+c-1);
weights array(j,:)=weights;
%%weights final(j,:,k)= weights;
%%bias final(j,1,k) = bias;
%error(j,1,k) = e;
end
%%Testing
testing size=1000;
y test=2*rand(1,testing size)-1;
input=zeros(1,50);
final err=0;
mse=zeros(1,50);
SNR=1;
for k=1:100
  y test=2*rand(1,testing size)-1;
  input=zeros(1,testing size);
for i=1:length(y test)
                       %%generation of inputs
  if(y_test(i)<0)
     input(i)=-1;
  else if(y_test(i)>0)
       input(i)=1;
     else
       input(i)=0;
     end
  end
end
final err=0;
```

```
SNR arr(k)=SNR+k/10;
y1=awgn(input,SNR_arr(k));
BER=0;
for i=1:testing_size-c+1
  \label{eq:y1_test(1,i)=y1(1,i:i+c-1)*(transpose(weights))+bias;} \\ percp_out(1,i)=hardlims(y1\_test(1,i)); \\
  error_test(i)=percp_out(1,i)-input(1,i);
  if(error_test(i)==0)
  else
     BER=BER+1;
  end
  %final err=final err+error test(i)*error test(i);
BER_arr(\bar{k})=BER/1000;
%mse(k)=final_err/1000.0;
end
%axis([-3 3 -3 3]);
%w1=-bias/weights(1,1);
%w2=-bias/weights(1,2);
%plot([w1,0],[0,w2]);
%hold on;
%plotpv(inp,inp);
%hold on;
%plotpc(weights,bias);
```

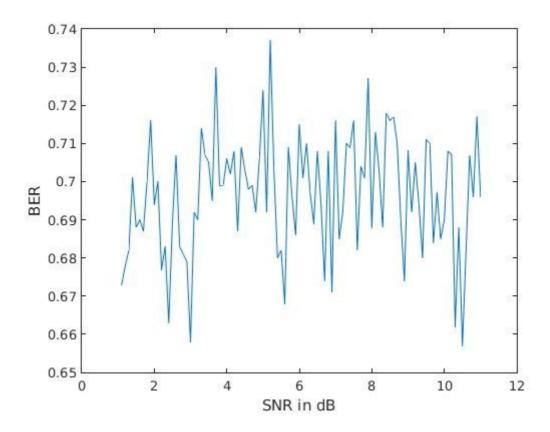
#### FIGURES (MSE Plot and BER Plot)

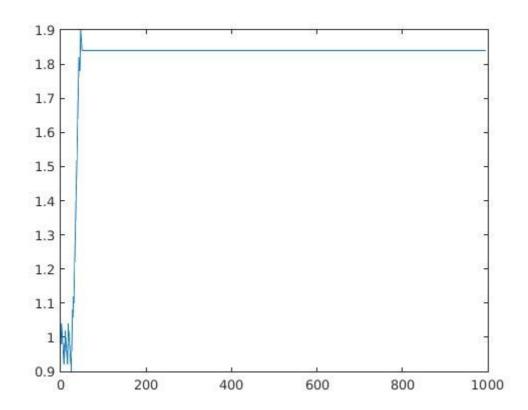
## 1) Channel Order =4



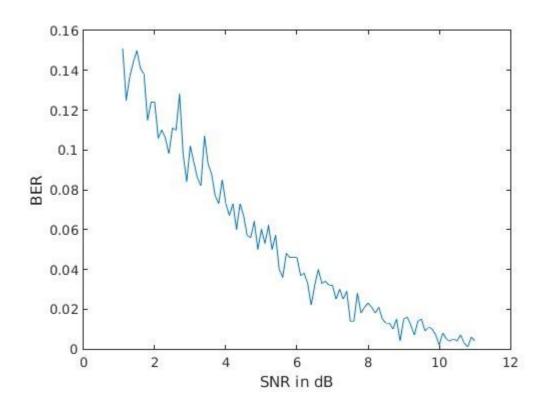


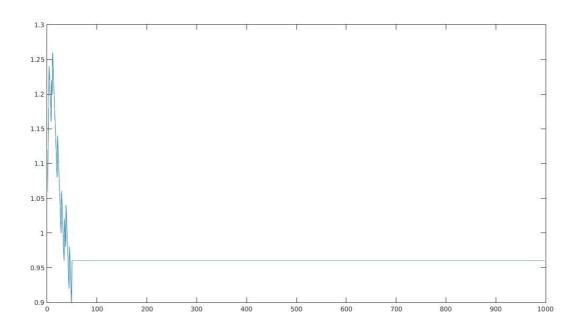
## Channel Order =3





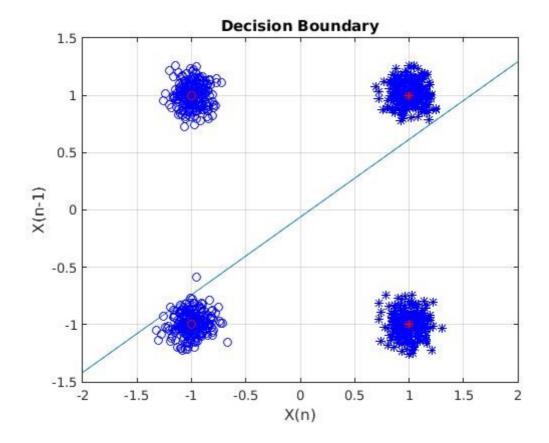
## 3)Channel Order =2



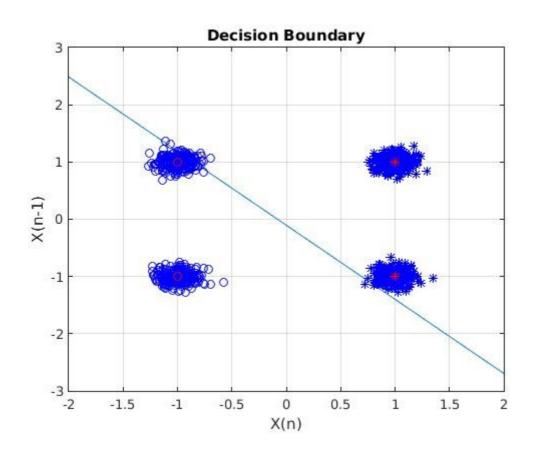


#### **Decision Boundary for various SNR**

$$1) SNR = 5 Db$$



#### 2) SNR =10 Db



## 3)SNR = 15 Db

