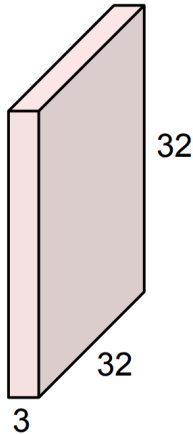


CNN architecture

Convolution layer

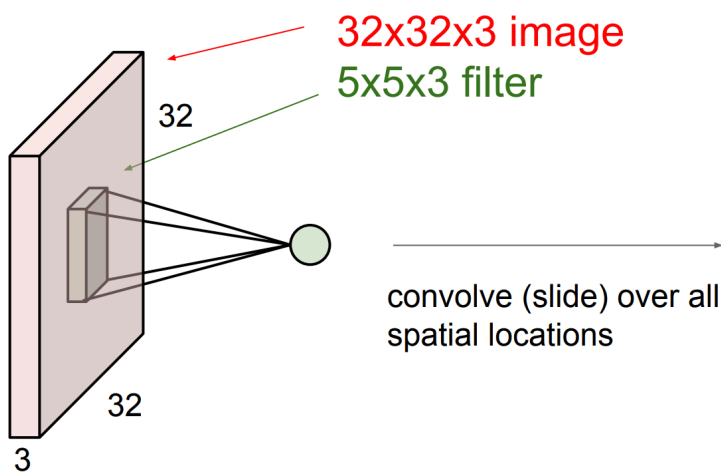
32x32x3 image



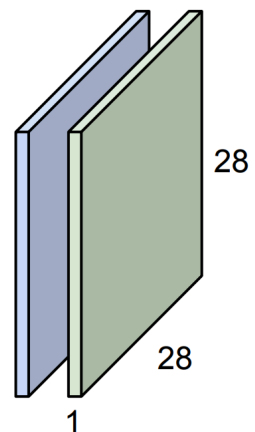
5x5x3 filter



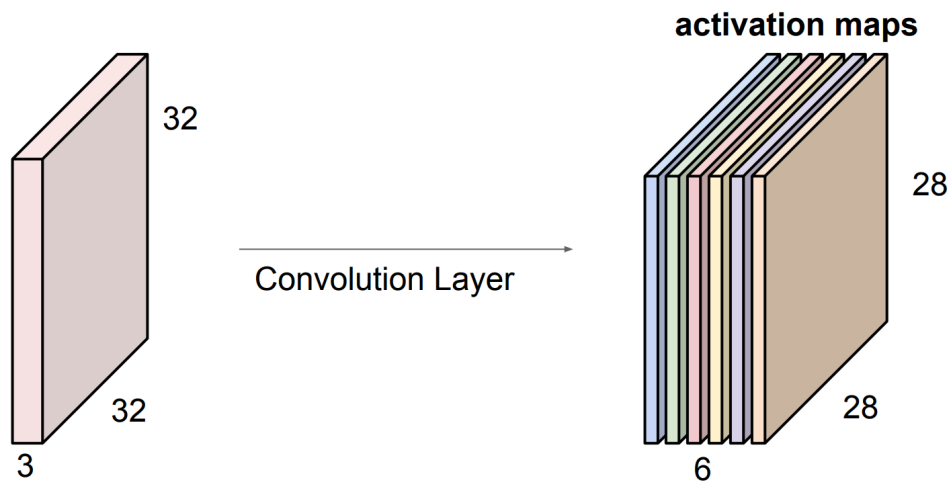
Convolve the filter with the image
i.e. “slide over the image spatially,
computing dot products”



activation maps



For example, if we had 6 5x5 filters, we'll get 6 separate activation maps:



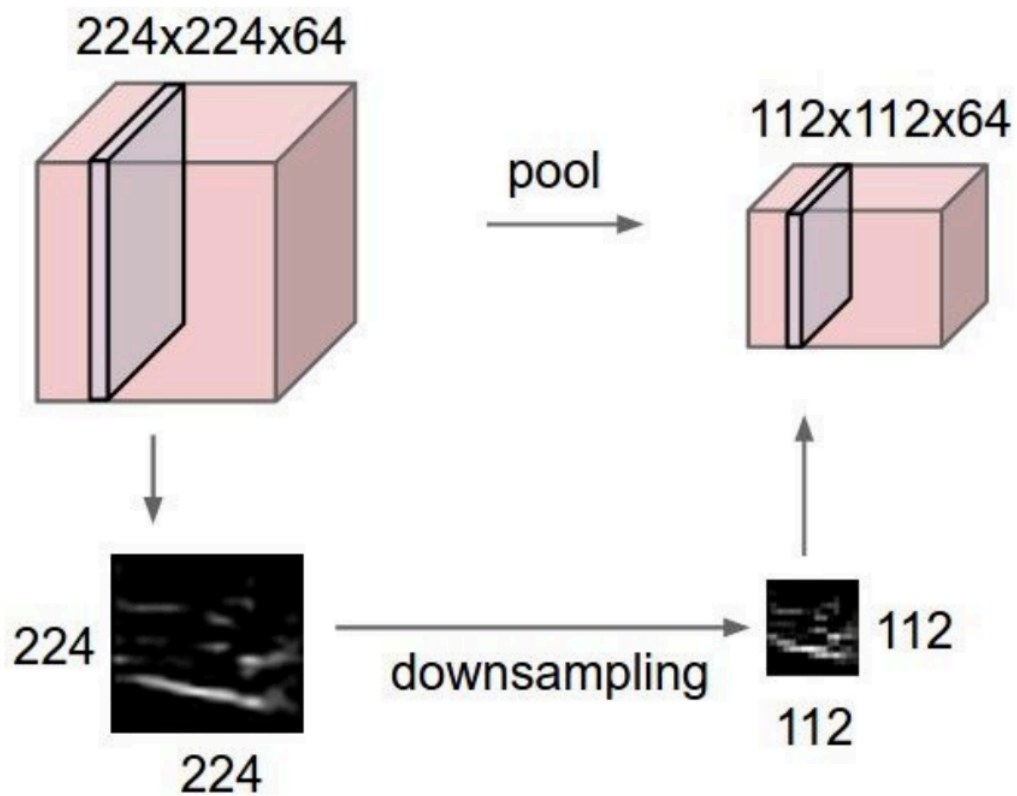
We stack these up to get a “new image” of size 28x28x6!

CONV layers with stride 1, filters of size $F \times F$, and zero-padding with $(F-1)/2$.

- $F = 3 \Rightarrow$ zero pad with 1
- $F = 5 \Rightarrow$ zero pad with 2
- $F = 7 \Rightarrow$ zero pad with 3

Pooling layer

- makes the representations smaller and more manageable
- operates over each activation map independently



MAX POOLING

