

SIGVerse interaction trough Robot Operating System

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26 août 2015

Introduction
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More functionnalities
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Conclusion
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Goal

RoboCup

RoboCup competition, how to participate





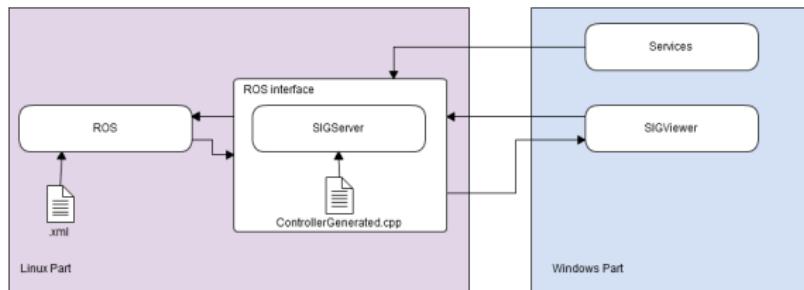
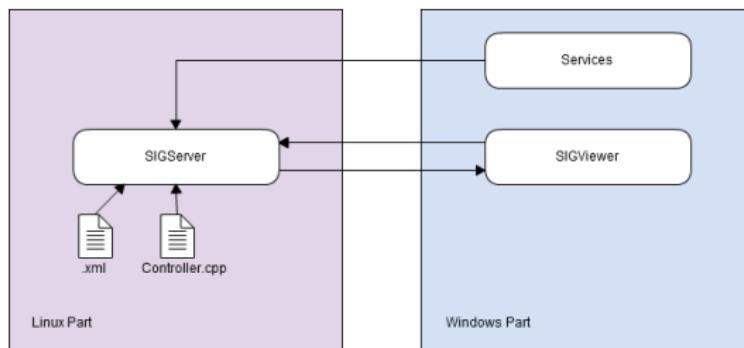
SIGVerse



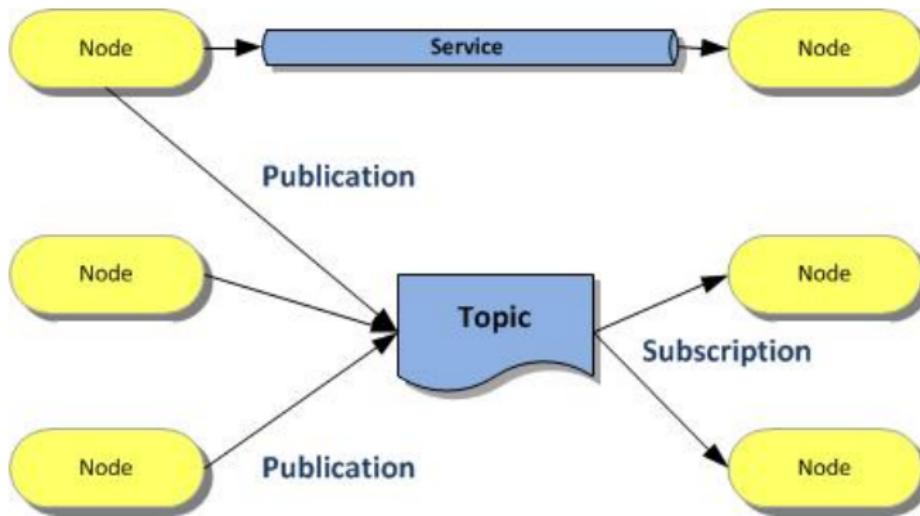
Goal

- C++
- Dynamique SIGVerse
- Japanese documentation
- Problem of SIGVerse (no restart without relaunch simulation)
- Robotic world : Robot Operating System

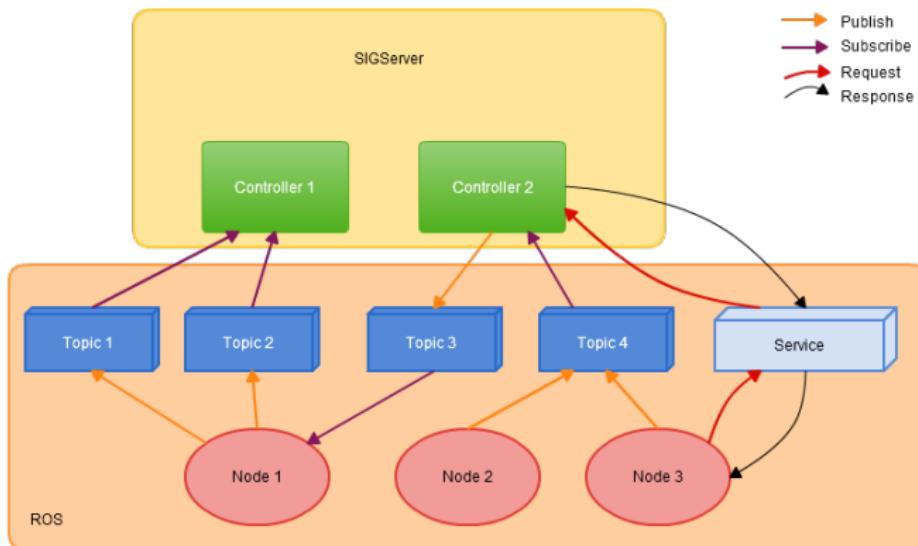
Goal



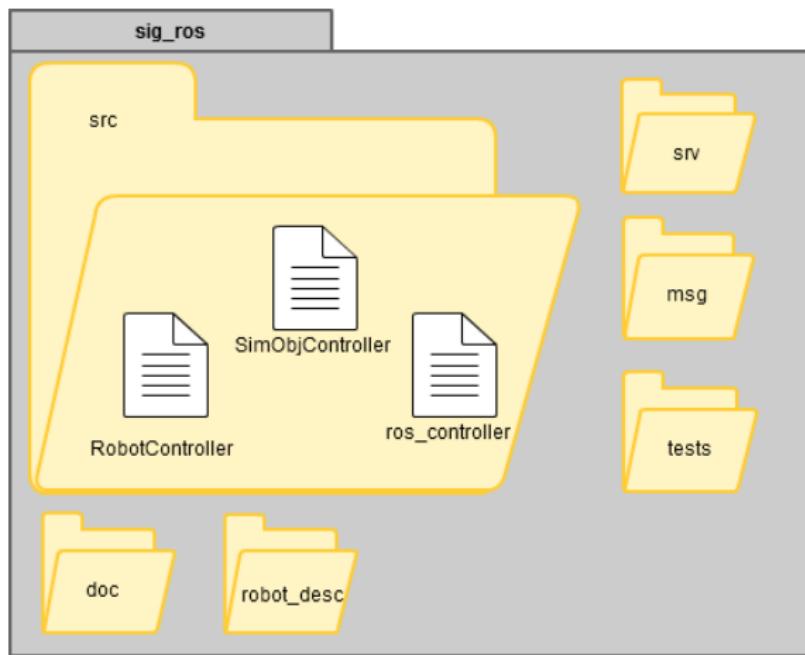
Robot Operating System



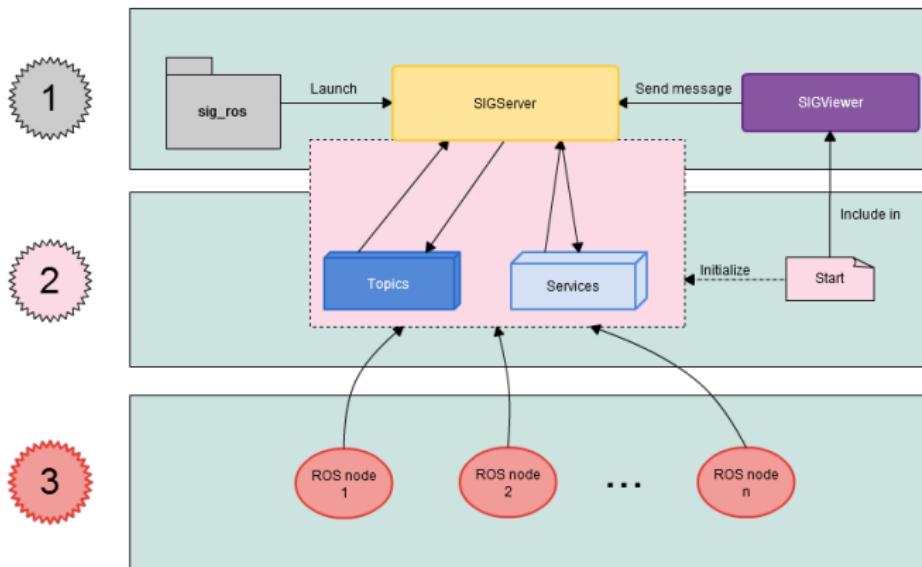
Generalities



Package



Use



Inverse kinematics

Introduction
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More functionnalities
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Conclusion
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Result

To go further

Introduction
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More functionnalities
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Conclusion
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Skills