# COMP90054 Workshop 3

# Recap: Manhattan Problem

- Consider an  $m \times m$  Manhattan Grid, and a set of coordinates G to visit in any order.
- **Hint**: Consider a set of coordinates *V'* remaining to be visited, or a set of coordinates *V* already visited. What's the difference between them
- Formulate a state-based search problem to find a tour of all the desired points (i.e. define a state space, applicable actions, transition and cost functions).

## m x m Grid

	Assume We are here	

 $P = {S, s0, SG, A, T, C}$ 

- a set of coordinates *G* to visit in any order
- Using a set of coordinates V' remaining to be visited,

# Recap: Manhattan Problem

- a set of coordinates G to visit in any order
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$$ullet S = \{\langle x,y,V'
angle \mid x,y \in \{0,\ldots,m-1\} \, \wedge \, V' \subseteq G\}$$

• 
$$s_0 = \langle (0,0), G \setminus \{(0,0)\} \rangle$$

$$ullet \ S_G = \{\langle (x,y), \{\}
angle \mid x,y \in \{0,\ldots,m-1\}\}$$

$$ullet \ A(\langle x,y,V'
angle)=\{(dx,dy)\mid$$

$$dx, dy \in \{-1, 0, 1\}$$

$$\bullet \wedge |dx| + |dy| = 1$$

$$ullet \wedge x + dx, y + dy \in \{0, \ldots, m-1\}$$

• 
$$(x+dx,y+dy) \notin W$$

$$\bullet \ T(\langle x,y,V'\rangle,(dx,dy))=\langle x+dx,y+dy,V'\setminus\{(x+dx,y+dy)\}\rangle$$

• 
$$c(a, s) = 1$$

Reformulate the state-space model from *Review and Recap* as a STRIPS problem  $P = \langle F, O, I, G \rangle$ 

## STRIPS Model

- **A problem** in STRIPS is a tuple  $P = \langle F, O, I, G \rangle$ :
  - F stands for set of all atoms (boolean vars)
  - O stands for set of all operators (actions)
  - $I \subseteq F$  stands for initial situation
  - $\blacksquare$   $G \subseteq F$  stands for goal situation

## STRIPS Model

- lacktriangle Operators  $o \in O$  represented by
  - the Add list  $Add(o) \subseteq F$
  - the Delete list  $Del(o) \subseteq F$
  - the Precondition list  $Pre(o) \subseteq F$

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- ullet  $F=\{at(x,y), visited(x,y) \mid x,y \in \{0,\ldots,m-1\}\}$
- $O = \{move(x, y, x', y'):$ 
  - Prec:
  - Add:
  - Del:

- $I = \{at(0,0), visited(0,0)\}$
- ullet  $G=\{visited(x,y)\mid (x,y)\in G'\}$

•  $I = \{at(0,0), visited(0,0)\}$ 

•  $G = \{visited(x,y) \mid (x,y) \in G'\}$ 

```
• F = \{at(x, y), visited(x, y) \mid x, y \in \{0, \dots, m-1\}\}
• O = \{move(x, y, x', y'):
    • Prec: at(x,y)
    • Add: at(x', y'), visited(x', y')
    • Del: at(x,y)
                                                      x,y,x', xy' & 6... u-17
  for each adjacent (x,y),(x',y'), and (x',y')\not\in W }
```

#### notWall(x,y)

- $F = \{at(x,y), visited(x,y) \mid x,y \in \{0,\ldots,m-1\}\}$
- $O = \{move(x, y, x', y'):$ 
  - Prec: at(x, y) notWall(x,y), notWall(x', y')
  - Add: at(x', y'), visited(x', y')
  - Del: at(x,y)

for each adjacent  $(x,y), (x^\prime,y^\prime)$ 

- $I = \{at(0,0), visited(0,0)\}$
- $ullet \ G = \{visited(x,y) \mid (x,y) \in G'\}$

G1					G2
	Wall	Wall	Starting point		

- Goal-counting
- Manhattan distance to the closest goal(position) heuristic
- Manhattan distance to the furthest goal(position) heuristic
- Your own heuristic...

# **Recap: Dominant Relation**

- If heuristic h1 dominates heuristic h2:
- Then we will have h1(s) >= h2(s), for all s belongs to state space S
- And both h1 and h2 need to be admissible