

$$H(\omega) = \int_{-\infty}^{+\infty} f(\xi) \cdot e^{-j\omega\xi} \cdot G(\omega) \cdot d\xi = G(\omega) \cdot \int_{-\infty}^{+\infty} f(\xi) e^{-j\omega\xi} d\xi$$

$$= G(\omega) \cdot F(\omega)$$

第三章：随机过程的线性变换

线性系统： $y(t) = L[x(t)]$

线性系统的性质：^{叠加}叠加性，比例性，时不变性

$$\left\{ \begin{array}{l} \text{叠加性: } L\{x_1(t) + x_2(t)\} = L\{x_1(t)\} + L\{x_2(t)\} \\ \text{比例性: } L\{Kx(t)\} = K \cdot L\{x(t)\} \\ \text{时不变性: } L\{x(t)\} = y(t) \Rightarrow L\{x(t+\tau)\} = y(t+\tau) \end{array} \right.$$

① 使用冲激响应法获得传递函数：

$$y(t) = L\{x(t)\} = L\left\{ \int_{-\infty}^{+\infty} x(\xi) \delta(t-\xi) d\xi \right\} \quad \text{由于在L算子内有变量}$$

$$= \int_{-\infty}^{+\infty} x(\xi) L\{\delta(t-\xi)\} d\xi \quad \text{设 } L\{\delta(t-\xi)\} = h(t-\xi)$$

$$= \int_{-\infty}^{+\infty} x(\xi) \cdot h(t-\xi) d\xi = x(t) * h(t)$$

结论：若 $h(t) = L\{\delta(t)\}$ 为系统冲激响应

$$\Rightarrow L\{x(t)\} = x(t) * h(t)$$

② 使用频率响应法获得传递函数

$$y(t) = L\{x(t)\} = L\left\{ \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot e^{j\omega t} d\omega \right\} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(\omega) \cdot L\{e^{j\omega t}\} d\omega$$

↙ 只对t取感

由①知 $\forall x(t) \quad L\{x(t)\} = x(t) * h(t)$ 故 $L\{e^{j\omega t}\} = e^{j\omega t} * h(t)$

$$e^{j\omega t} * h(t) = \int_{-\infty}^{+\infty} e^{j\omega \xi} \cdot h(t-\xi) d\xi = \int_{-\infty}^{+\infty} e^{j\omega(t-\xi)} \cdot h(\xi) d\xi$$

$$= \int_{-\infty}^{+\infty} e^{j\omega t} \cdot \underbrace{e^{-j\omega \xi}}_{\text{冲激响应}} h(\xi) d\xi = e^{j\omega t} \cdot H(\omega)$$

故 $Y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \underbrace{X(\omega)}_{\text{输入函数}} \cdot \underbrace{H(\omega)}_{\text{频率响应函数}} \cdot e^{j\omega t} d\omega$ 同时

$$Y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \underbrace{Y(\omega)}_{\text{输出函数}} e^{j\omega t} d\omega \quad \text{故} \quad \boxed{\begin{matrix} Y(\omega) = X(\omega) \cdot H(\omega) \\ Y(t) = X(t) * h(t) \end{matrix}}$$

其中 $h(t) = \mathcal{L}\{\delta(t)\}$ ← 冲激响应函数

例1

已知 $Y(t) = X(t-T) - 2X(t) + X(t+T)$ 求频率响应函数

① 先求冲激响应 =

$$h(t) = \mathcal{L}\{\delta(t)\} = \delta(t-T) - 2\delta(t) + \delta(t+T)$$

② 再求频率响应函数：对冲激响应作傅里叶变换

$$H(j\omega) = \int_{-\infty}^{+\infty} e^{-j\omega t} h(t) dt = \int_{-\infty}^{+\infty} \underbrace{e^{-j\omega t} \delta(t-T)}_{\text{冲激响应}} - 2e^{-j\omega t} \delta(t) + e^{-j\omega t} \delta(t+T) dt$$

$$= e^{-j\omega T} - 2e^{-j\omega \cdot 0} + e^{-j\omega(-T)} = \cancel{e^{-j\omega T}} + e^{-j\omega T} - 2$$

$$= 2[\cos(\omega T) - 1]$$

均方收敛以及依概率收敛：

① 依概率收敛： $\lim_{n \rightarrow \infty} P\{|X_n - X| \geq \varepsilon\} = 0$ 记作 $\lim_{n \rightarrow \infty} X_n \stackrel{P}{=} X$

② 均方收敛： $\lim_{n \rightarrow \infty} E\{|X_n - X|^2\} = 0$ 记作 $\lim_{n \rightarrow \infty} X_n = X$

随机过程的均方连续:

$$\text{定义: } \lim_{\Delta t \rightarrow 0} E\{|X(t+\Delta t) - X(t)|^2\} = 0$$

条件: 若 $R_X(t, t)$ 在此连续, 则 $X(t)$ 均方连续 (充要)

$$\begin{aligned} \text{推导: } \lim_{\Delta t \rightarrow 0} E\{|X(t+\Delta t) - X(t)|^2\} &= \lim_{\Delta t \rightarrow 0} E\{X^2(t+\Delta t) + X^2(t) - 2X(t)X(t+\Delta t)\} \\ &= \lim_{\Delta t \rightarrow 0} \{R_X(t+\Delta t, t+\Delta t) + R_X(t, t) - 2R_X(t, t+\Delta t)\} \quad \text{若 } R_X \text{ 连续} = 0 \end{aligned}$$

$$\text{性质: } \lim_{\Delta t \rightarrow 0} E\{X(t+\Delta t)\} = E\{\lim_{\Delta t \rightarrow 0} X(t+\Delta t)\} = E[X(t)]$$

$$\text{验证: 若 } \lim_{\Delta t \rightarrow 0} X(t+\Delta t) = X \quad \text{则} \quad \lim_{\Delta t \rightarrow 0} E\{X(t+\Delta t)\} = E[X]$$

$$\hookrightarrow \lim_{\Delta t \rightarrow 0} E\{|X(t+\Delta t) - X|^2\} = 0$$

不知道

$$\text{已知 } f(t) \xrightarrow{F} F(\omega) \quad \text{若 } f(t) \xrightarrow{F} ? \quad \text{设 } t \rightarrow \infty \text{ 时 } f(t) = 0$$

$$\int_{-\infty}^{+\infty} f(t) e^{-j\omega t} dt = \int_{-\infty}^{+\infty} e^{-j\omega t} df(t) = \left[f(t) e^{-j\omega t} \right]_{-\infty}^{+\infty}$$

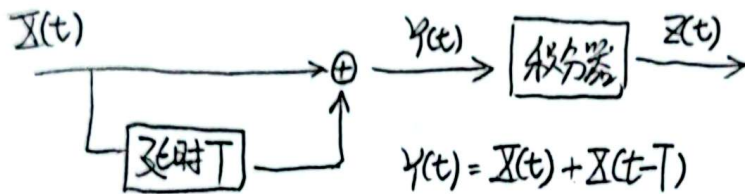
$$- \int_{-\infty}^{+\infty} f(t) d e^{j\omega t} = (j\omega) \int_{-\infty}^{+\infty} f(t) e^{-j\omega t} dt = (j\omega) F(\omega)$$

$$\left[f(t) e^{-j\omega t} \right]_{-\infty}^{+\infty} \text{ 在何条件下为零? 设 } f(t) \text{ 为偶函数}$$

$$\lim_{T \rightarrow \infty} f(T) \cdot \{e^{-j\omega T} - e^{j\omega T}\} = \lim_{T \rightarrow \infty} f(T) \cdot \{2j \sin \omega T\}$$

$$= f(\infty) \cdot 2\pi j \omega \delta(\omega)$$

例: 求 $H(j\omega)$



其中 $z(t) = \int_{-\infty}^t y(\xi) d\xi = \int_{-\infty}^t \{x(\xi) + x(\xi-T)\} d\xi$ 带入 $x(t) = f(t)$

$$h(t) = \int_{-\infty}^t \{ \delta(\zeta) + \delta(\zeta - T) \} d\zeta = u(t) + u(t - T)$$

$$\text{the } H(j\omega) = \int_{-\infty}^{+\infty} h(t) \cdot e^{-j\omega t} dt = \int_{-\infty}^{+\infty} \underbrace{u(t)}_{\text{rect}} \cdot e^{-j\omega t} dt + \int_{-\infty}^{+\infty} \underbrace{u(t-T)}_{\text{rect}} \cdot e^{-j\omega t} dt$$

$$\left\{ = \frac{1}{j\omega + e^{-j\omega T}} \cdot \frac{1}{j\omega + e^{-j\omega T}} \int_T^{+\infty} e^{-j\omega t} dt \right\} e^{-j\omega T} \int_{-\infty}^{+\infty} u(t-T) e^{-j\omega(t-T)} dt$$

$$= \frac{1}{j\omega} (1 + e^{-j\omega T}) \sqrt{\frac{1}{j\omega} e^{-j\omega T}} \Big|_{-\infty}^{+\infty} \quad 1 \quad \boxed{de^{j\omega t} = j\omega e^{j\omega t} dt}$$

$$= \left(0 + \frac{1}{100}\right) + (0 -$$

$$u(t) \xrightarrow{\text{求导}} f(t)$$

$$\frac{1}{j\omega} \leftarrow D(\omega) = \int_{-\infty}^{+\infty} \delta(t) \cdot e^{-j\omega t} dt = 1 \quad = \frac{1}{2\pi} \left[\frac{e^{-j\omega t}}{-j\omega} \right]_{-\infty}^{+\infty} + \int_{-\infty}^{+\infty} \delta(t) \cdot \frac{1}{j\omega} dt$$

$$\int_{-\infty}^{+\infty} u(t) e^{-j\omega t} dt = \int_0^{+\infty} \delta(t) * e^{j\omega t} dt = \left[-\frac{1}{j\omega} e^{-j\omega t} \right]_0^{+\infty} \quad \leftarrow R$$

$$= -\frac{1}{j\omega} e^{-j\omega R} - \left(-\frac{1}{j\omega}\right) = \underbrace{-\frac{1}{j\omega} e^{-j\omega R}}_{\text{desired}} + \frac{1}{j\omega}$$

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$$\int_{-\infty}^{+\infty} \sin(t) \cdot e^{-j\omega t} dt = \int_{-\infty}^0 -e^{-j\omega t} dt + \int_0^{+\infty} e^{-j\omega t} dt$$

$$= \left[\frac{1}{j\omega} e^{-j\omega t} \right]_{-\infty}^0 + \left[-\frac{1}{j\omega} e^{-j\omega t} \right]_0^{+\infty}$$

$$\text{设 } f(t) = \frac{1}{j\omega} e^{-j\omega t} \quad \downarrow \quad = [f(t)]_{-\infty}^0 + [-f(t)]_0^{+\infty}$$

$$= \lim_{R \rightarrow +\infty} \left\{ [f(t)]_{-R}^0 + [-f(t)]_0^{+R} \right\}$$

$$= \lim_{R \rightarrow +\infty} \left\{ f(0) - f(-R) + (-f(R)) - (-f(0)) \right\}$$

$$= \lim_{R \rightarrow +\infty} \left\{ 2f(0) - f(-R) - f(R) \right\} \rightarrow C(\omega)$$

$$= \frac{2}{j\omega} \left(- \lim_{R \rightarrow +\infty} \{ f(R) + f(-R) \} \right)$$

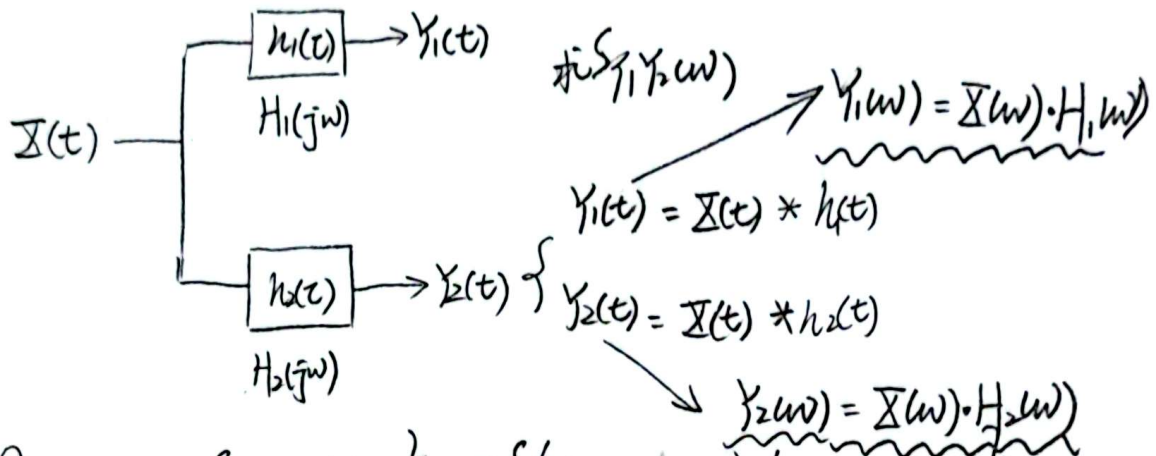
$$f(R) + f(-R) = \frac{1}{j\omega} \left\{ e^{-j\omega R} + e^{j\omega R} \right\} = \frac{1}{j\omega} \cdot 2 \cos(\omega R) = \frac{1}{j\omega} \cdot 2\pi \omega \delta(\omega) = \frac{2\pi}{j} \delta(\omega)$$

$$\cos(\omega R) \pm j \sin(\omega R)$$

$$\cos\left(\omega\left(R + \frac{\pi}{2\omega}\right)\right)$$

$$= \underbrace{\cos \omega R \cos\left(\frac{\pi}{2}\right)}_0 + \sin \omega R \cdot \underbrace{\sin\left(\frac{\pi}{2}\right)}_1 = \sin \omega R$$

2024-12-21 复习



$$R_{Y_1 Y_2}(\tau) = E \{ Y_1(t) Y_2(t+\tau) \} = E \{ (X(t) * h_1(t)) \cdot (X(t+\tau) * h_2(t+\tau)) \}$$

$$\therefore S_{Y_1 Y_2}(\omega) = E \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} X(\xi_1) \cdot h_1(\tau - \xi_1) \cdot X(\xi_2) \cdot h_2(\tau - \xi_2) d\xi_1 d\xi_2 \right\}$$

$$= E \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} X(\xi_1) X(\xi_2) h_1(\tau - \xi_1) h_2(\tau - \xi_2) d\xi_1 d\xi_2 \right\}$$

$$= E \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} R_X(\xi_1 - \xi_2) h_1(\tau - \xi_1) h_2(\tau - \xi_2) d\xi_1 d\xi_2 \right\}$$

$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (R_X * h_1)(\tau - \xi_2) h_2(\tau - \xi_2) d\xi_2$$

$$= R_X(\tau) * h_1(\tau) * h_2(\tau)$$

$$U = \frac{\partial(u, v)}{\partial(\xi_1, \xi_2)} = \begin{vmatrix} 1 & 1 \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = \frac{1}{2}$$

$$= \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} R_X(v) h_1(\tau - \frac{1}{2}(u+v)) h_2(\tau - \frac{1}{2}(u-v)) \frac{1}{2} du dv$$

$$= R_X(\tau) * h_1(\tau) * h_2(\tau)$$

$$\text{故 } S_{Y_1 Y_2}(\omega) = \frac{1}{2} S_X(\omega) \cdot H_1(j\omega) \cdot H_2^*(j\omega)$$

2024-12-21 复习

求导 18

求线性系统输出的协方差函数: 已知 $\begin{cases} h(t) \\ H(j\omega) \end{cases}$ 求 $Y(t) = X(t) * h(t)$ 的

$C_X(t)$

$$C_Y(t) = E \{ (Y(t) - m_Y)(Y(t) - m_Y) \} = E \{ Y(t)Y(t) \} - m_Y^2 = R_Y(t) - m_Y^2$$

$$R_Y(t) = E \{ (X(t) * h(t)) \cdot (X(t) * h(t)) \}$$

$$= E \left\{ \int_{-\infty}^{+\infty} X(\xi_1) h(t - \xi_1) d\xi_1 \cdot \int_{-\infty}^{+\infty} X(\xi_2) h(t - \xi_2) d\xi_2 \right\}$$

$$= E \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(t - \xi_1) h(t - \xi_2) R_X(\xi_1 - \xi_2) d\xi_1 d\xi_2 \right\}$$

设 $\begin{cases} u = \xi_1 - \xi_2 \\ v = \xi_2 \end{cases} \rightarrow \begin{cases} \xi_1 = u + v \\ \xi_2 = v \end{cases}$

$J = \frac{\partial(\xi_1, \xi_2)}{\partial(u, v)} = \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} = 1$

$$= E \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(t - u - v) h(v) R_X(u) du dv \right\}$$

$$= R_X(t) * h(t) * h(-t) = R_X(t)$$

$$= \int_{-\infty}^{+\infty} \left\{ \int_{-\infty}^{+\infty} h(t - u - v) h(v) dv \right\} \cdot R_X(u) du$$

$(h * h)(t - u) \cdot R_X(u)$

$$= (h * h + R_X)(t)$$

2024-12-23 复习: 白噪声通过RC积分器

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$$S_X(\omega) = \frac{1}{2} N_0. \quad h(t) = a e^{-at} \quad (t > 0) \leftrightarrow \frac{2a^2}{a^2 + \omega^2} \quad \text{设 } a = \frac{1}{RC}$$

$$\textcircled{1} R_X(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \frac{1}{2} N_0 \cdot e^{j\omega\tau} d\omega = \frac{N_0}{2} \delta(\tau)$$

$$\textcircled{2} R_Y(\tau) = R_X(\tau) * h(\tau) * h(-\tau) = \frac{N_0}{2} R_h(\tau) = \frac{N_0 a}{4} e^{-a|\tau|}$$

$$\begin{array}{c} \updownarrow \\ S_Y(\omega) = S_X(\omega) \cdot H(\omega) \cdot H^*(\omega) = \frac{N_0}{2} \cdot \frac{a}{2} \cdot \frac{2a}{a^2 + \omega^2} \end{array}$$

$$\begin{aligned} R_h(\tau) &= \int_{-\infty}^{+\infty} a e^{-a\xi} \cdot a e^{-a(\tau+\xi)} d\xi \\ &= a e^{-a\tau} \int_{-\infty}^{+\infty} a e^{-2a\xi} d\xi = \frac{1}{2} a e^{-a\tau} \int_{-\infty}^{+\infty} (-2a) e^{-2a\xi} d\xi \\ &= -\frac{1}{2} a e^{-a\tau} \cdot \left[e^{-2a\xi} \right]_{-\infty}^{+\infty} = \frac{a}{2} e^{-a|\tau|} \end{aligned}$$

* RC 积分器: $t < 0$ 时 $h(t) = 0$

噪声等效带宽 $S_Y(\omega_0) \Delta \omega_e = \int_0^{\infty} S_Y(\omega) d\omega$

↑ 最大功率谱密度值

↓ 功率谱密度在频率轴积分

白噪声通过理想低通网络: $|H(j\omega)| = \begin{cases} K_0, & -\Delta\omega < \omega < \Delta\omega \\ 0, & \text{else} \end{cases}$

白噪声: $S_X(\omega) = \frac{N_0}{2}$

① 求 $R_X(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \frac{N_0}{2} \cdot e^{+j\omega\tau} d\omega = \frac{N_0}{2} \cdot \delta(\tau)$

② 求 $R_h(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} H^2(j\omega) e^{+j\omega\tau} d\omega = \frac{1}{2\pi} \int_{-\Delta\omega}^{+\Delta\omega} K_0^2 \cdot e^{+j\omega\tau} d\omega$

$$\left\{ \begin{aligned} & \int_{-\Delta\omega}^{+\Delta\omega} \frac{1}{j\tau} e^{+j\omega\tau} d\omega = \frac{1}{j\tau} \cdot 2\sin\omega\tau = \frac{2\sin\omega\tau}{j\tau} \cdot K_0^2 \\ & \text{修正: } \frac{1}{j\tau} \cdot 2\sin\omega\tau = \frac{2\sin\omega\tau}{j\tau} \cdot K_0^2 \end{aligned} \right.$$

当 $\Delta\omega \rightarrow \infty$ 时 $R_h(\tau) \rightarrow 2\pi K_0^2 \delta(\tau)$

③ 求 $R_Y(\tau) = R_X(\tau) * R_h(\tau) = \int_{-\infty}^{+\infty} R_X(\xi) \cdot R_h(\tau-\xi) d\xi = \frac{N_0}{2} \cdot R_h(\tau) = \frac{N_0}{2} \cdot \frac{K_0^2 \Delta\omega}{\pi}$

$\delta(\tau) * h(\tau) = h(\tau)$

这种做法与 PPT 结果不同。

$S_Y(\omega) = S_X(\omega) \cdot |H(j\omega)|^2 = \begin{cases} \frac{N_0 K_0^2}{2}, & -\Delta\omega < \omega < \Delta\omega \\ 0, & \text{else} \end{cases}$

$\therefore R_Y(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S_Y(\omega) e^{+j\omega\tau} d\omega = \frac{1}{2\pi} \int_{-\Delta\omega}^{+\Delta\omega} \frac{N_0 K_0^2}{2} \cdot e^{+j\omega\tau} d\omega$

$$\left\{ \begin{aligned} & = \frac{N_0 K_0^2}{4\pi} \cdot \left[\frac{1}{j\tau} e^{+j\omega\tau} \right]_{-\Delta\omega}^{+\Delta\omega} = \frac{N_0 K_0^2}{4\pi} \cdot \frac{2\sin\omega\tau}{j\tau} \\ & \text{修正: } \frac{N_0 K_0^2}{4\pi} \cdot \frac{2\sin\omega\tau}{j\tau} \end{aligned} \right.$$

这种做法也与 PPT 不同。

看下教材吧: 算出来一样的结果但与 PPT 不同。

符合教材。

基本方法: $\begin{cases} R_Y(\tau) = R_X(\tau) * R_h(\tau) \\ S_Y(\omega) = S_X(\omega) \cdot H(j\omega) \cdot H^*(j\omega) \end{cases}$

2024-12-28 复习：设 $x(t)$ 为确定信号。

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$x(t) = A \cos(\omega_0 t + \theta)$ 求 FT:

$$X(\omega) = \int_{-\infty}^{+\infty} x(t) e^{-j\omega t} dt = \int_{-\infty}^{+\infty} A \cos(\omega_0 t + \theta) e^{-j\omega t} dt$$

$$= A \int_{-\infty}^{+\infty} \left[\cos(\omega_0 t) \cos \theta - \sin(\omega_0 t) \sin \theta \right] e^{-j\omega t} dt$$

$$= A \cos \theta \int_{-\infty}^{+\infty} \cos \omega_0 t e^{-j\omega t} dt - A \sin \theta \int_{-\infty}^{+\infty} \sin \omega_0 t e^{-j\omega t} dt$$

$$\frac{1}{2}(e^{j\omega_0 t} + e^{-j\omega_0 t}) \quad \frac{1}{2j}(e^{j\omega_0 t} - e^{-j\omega_0 t})$$

$$= \frac{A\pi}{2} \cos \theta \cdot (\delta(\omega - \omega_0) + \delta(\omega + \omega_0)) - \frac{A\pi}{2} \sin \theta \cdot (\delta(\omega - \omega_0) - \delta(\omega + \omega_0))$$

这说明任意一个确定信号，在频域上总是只有两个点处的贡献。

- ① $\omega - \omega_0$ 处贡献: $\frac{A\pi}{2} \cos \theta - \frac{A\pi}{2} \sin \theta$
- ② $\omega + \omega_0$ 处贡献: $\frac{A\pi}{2} \cos \theta + \frac{A\pi}{2} \sin \theta$

因此，任意给定一个频谱图，我们可以将其分解成 $\sum_i P_i \delta_i$ 的形式

其中 $\delta_i = \delta(\omega - \omega_i)$ ，成对出现可以分解成无数个 $\cos(\omega_0 t + \theta)$ 叠加的形式

设 $x(t) = A \cos(\omega_0 t + \theta)$ 是随机信号， A 为常量， $\theta \in [0, 2\pi]$ 均匀

$$R_x(\tau) = E \{ A \cos(\omega_0 \tau + \theta) \cdot A \cos \theta \} = A^2 \cdot E \left\{ \frac{1}{2} [\cos(\omega_0 \tau + 2\theta) + \cos \omega_0 \tau] \right\}$$

$$= \frac{1}{2} A^2 \cos \omega_0 \tau$$

$$\text{故 } S_x(\omega) = \int_{-\infty}^{+\infty} R_x(\tau) e^{-j\omega \tau} d\tau = \frac{1}{2} A^2 \int_{-\infty}^{+\infty} \cos \omega_0 \tau e^{-j\omega \tau} d\tau = \frac{2\pi}{4} A^2 \cdot (\delta(\omega + \omega_0) + \delta(\omega - \omega_0))$$

$$= \frac{A^2 \pi}{2} \cdot (\delta(\omega - \omega_0) + \delta(\omega + \omega_0))$$