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Horribly  
Optimistic  
Statisticians



CV SEMINAR

YOLO

11.06.2024 Computer Vision Seminar 23/24



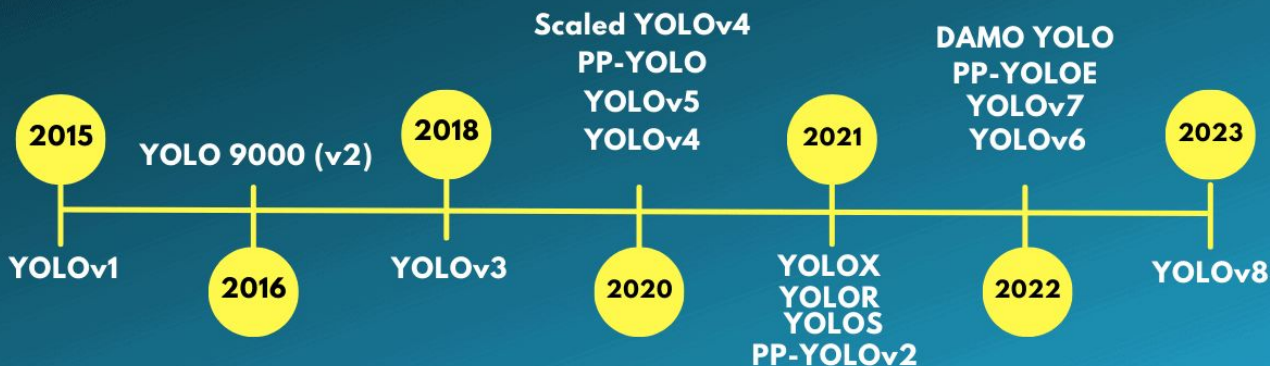
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<https://medium.datadriveninvestor.com/yolov8-the-evolution-of-real-time-object-detection-7c158948e0de>



## YOLO Object Detection Models Timeline





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<https://www.baeldung.com/cs/yolo-algorithm>



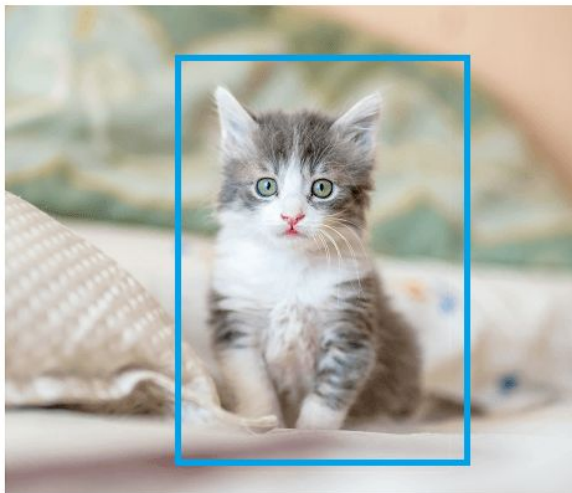
# Detekcja obiektów

**classification**

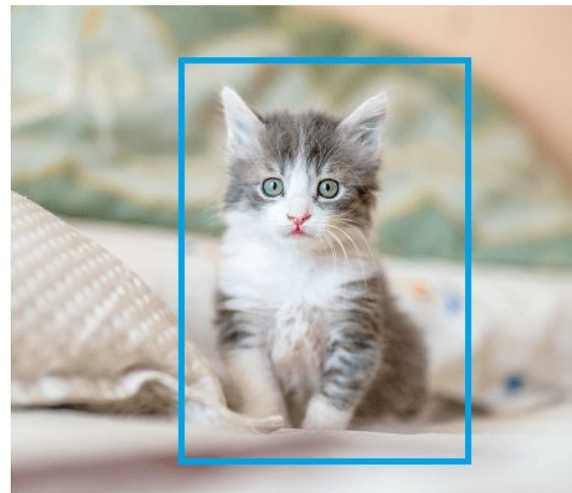


**cat**

**localization**



**detection**



**cat**



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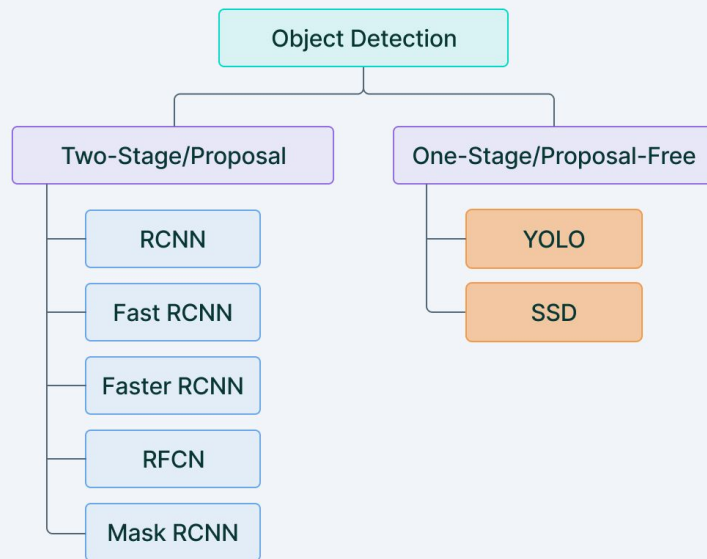
<https://www.v7labs.com/blog/object-detection-guide>



## Podział:

- Jednoetapowe
- Dwuetapowe

### One and two stage detectors



V7 Labs



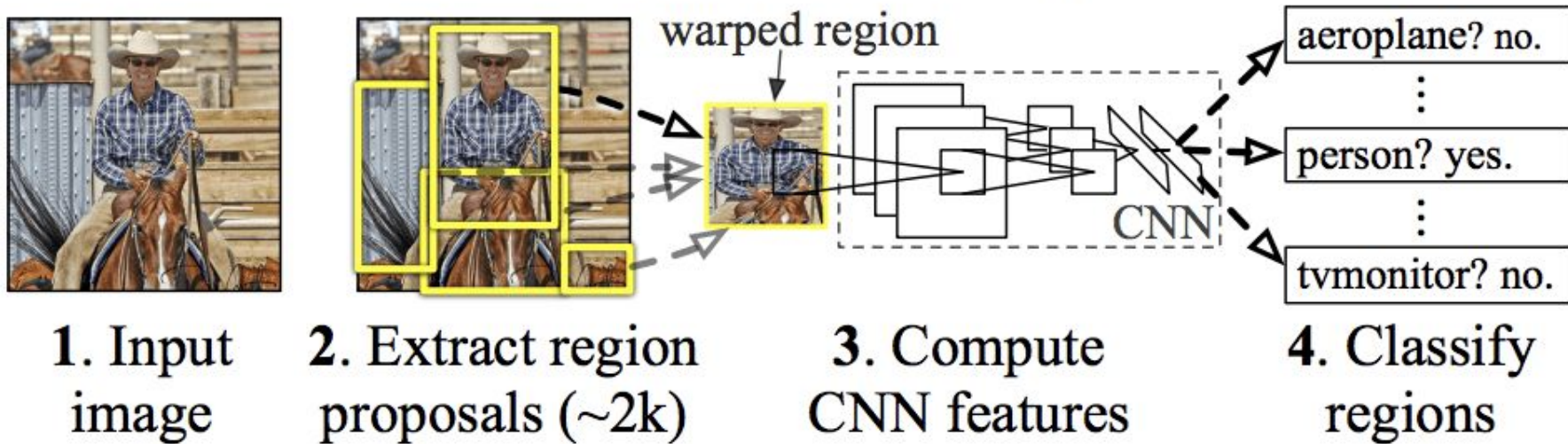
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<https://arxiv.org/abs/1311.2524>



## R-CNN: *Regions with CNN features*

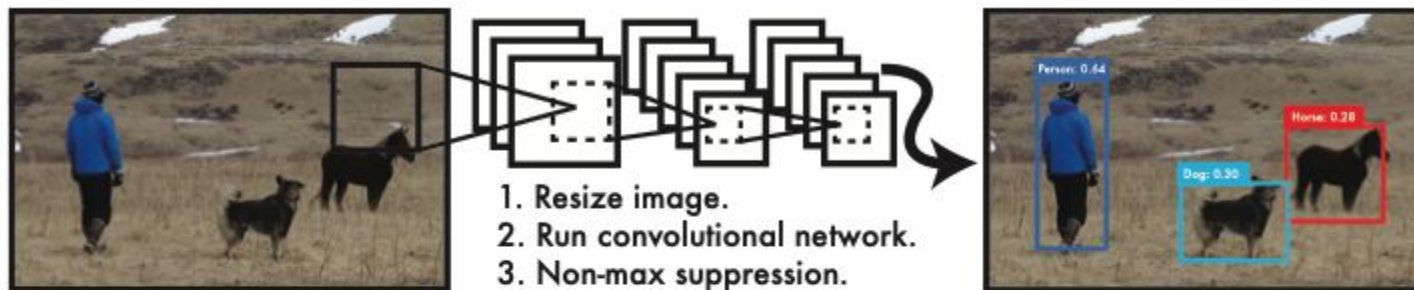




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<https://arxiv.org/pdf/1506.02640v5>



**Figure 1: The YOLO Detection System.** Processing images with YOLO is simple and straightforward. Our system (1) resizes the input image to  $448 \times 448$ , (2) runs a single convolutional network on the image, and (3) thresholds the resulting detections by the model's confidence.





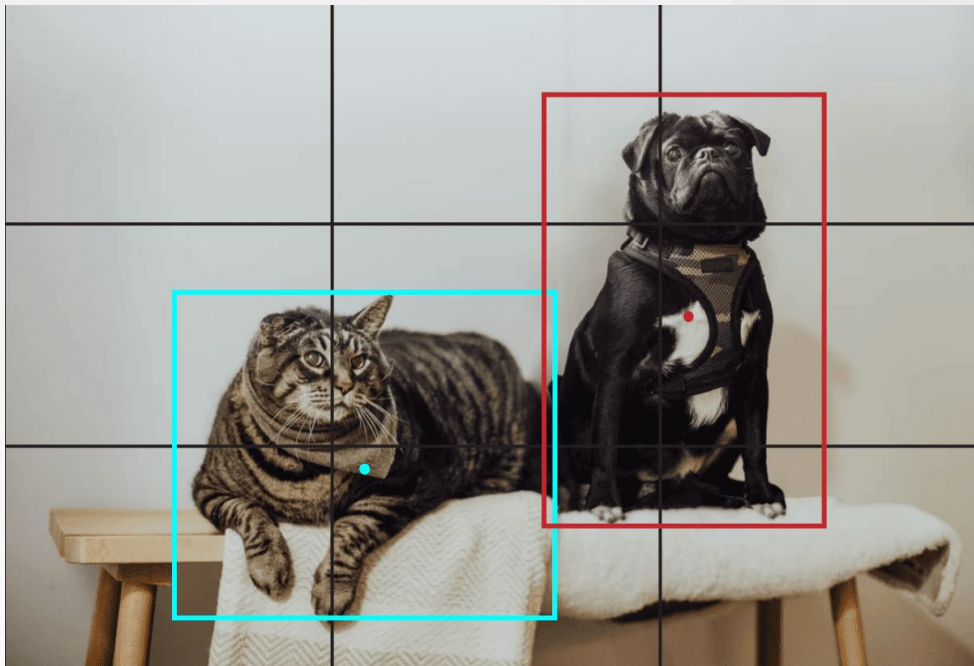
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<https://www.baeldung.com/cs/yolo-algorithm>



# Jak działa YOLO?

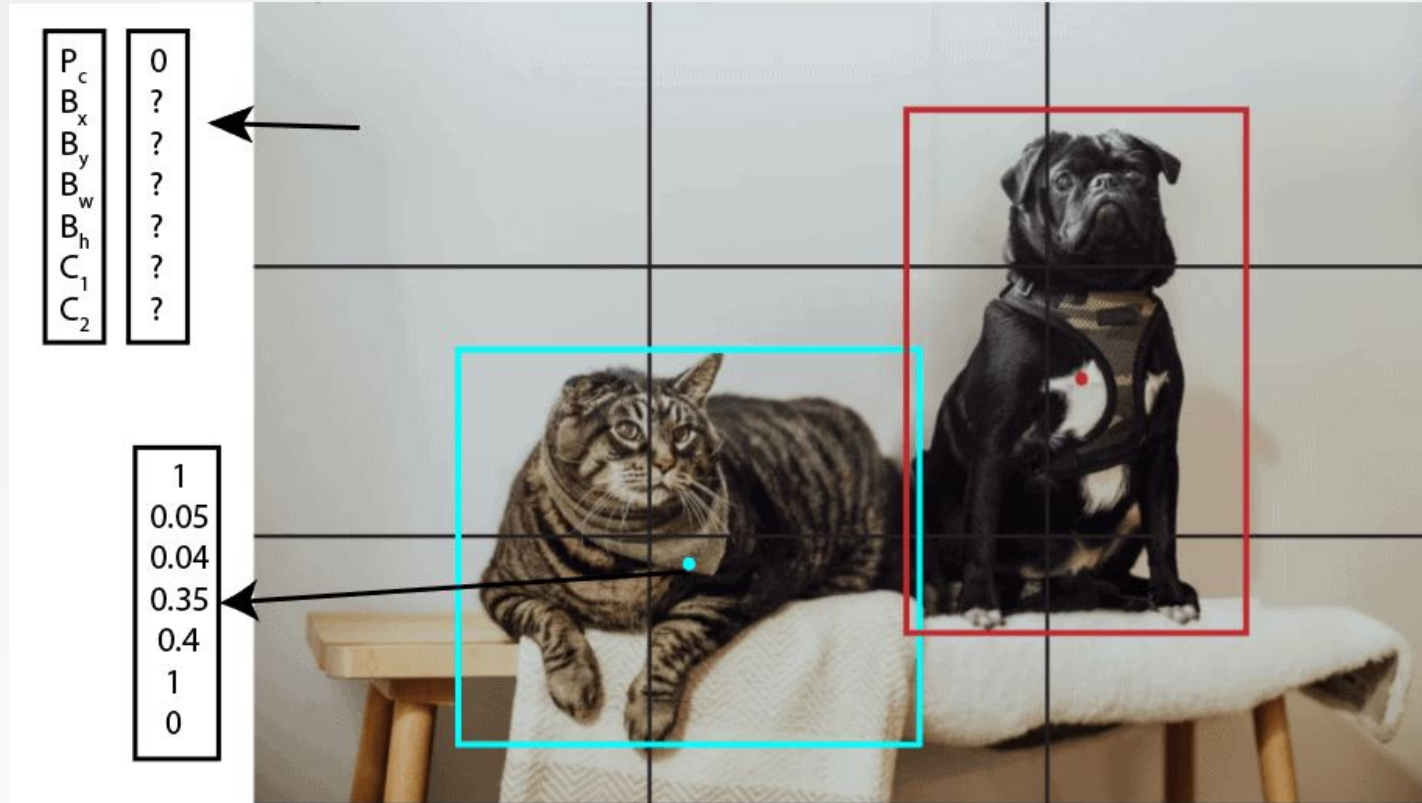




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<https://www.baeldung.com/cs/yolo-algorithm>







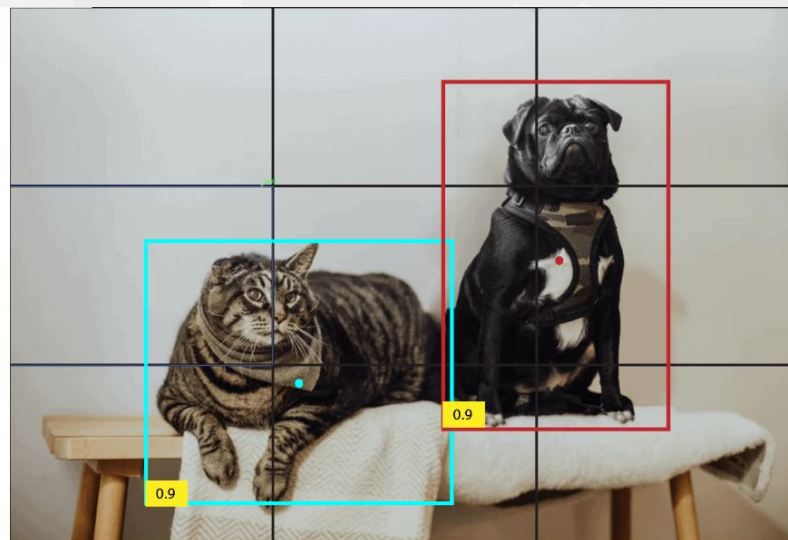
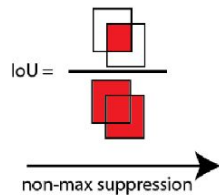
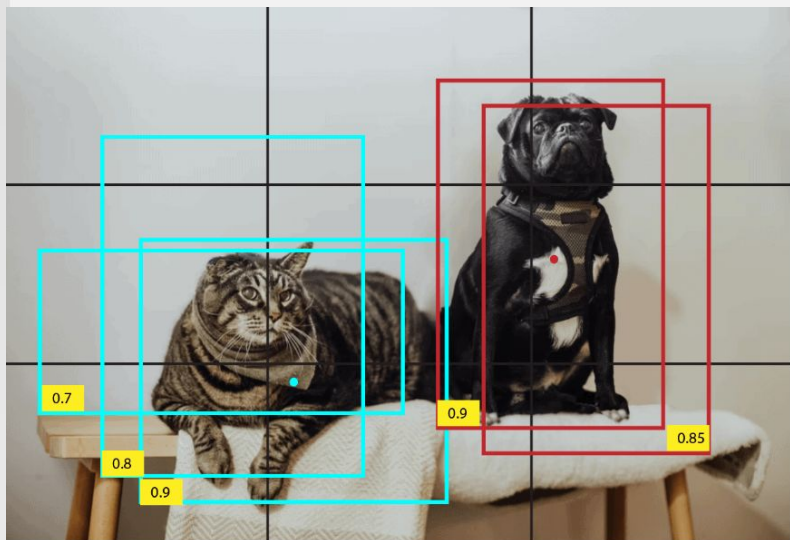
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<https://www.baeldung.com/cs/yolo-algorithm>

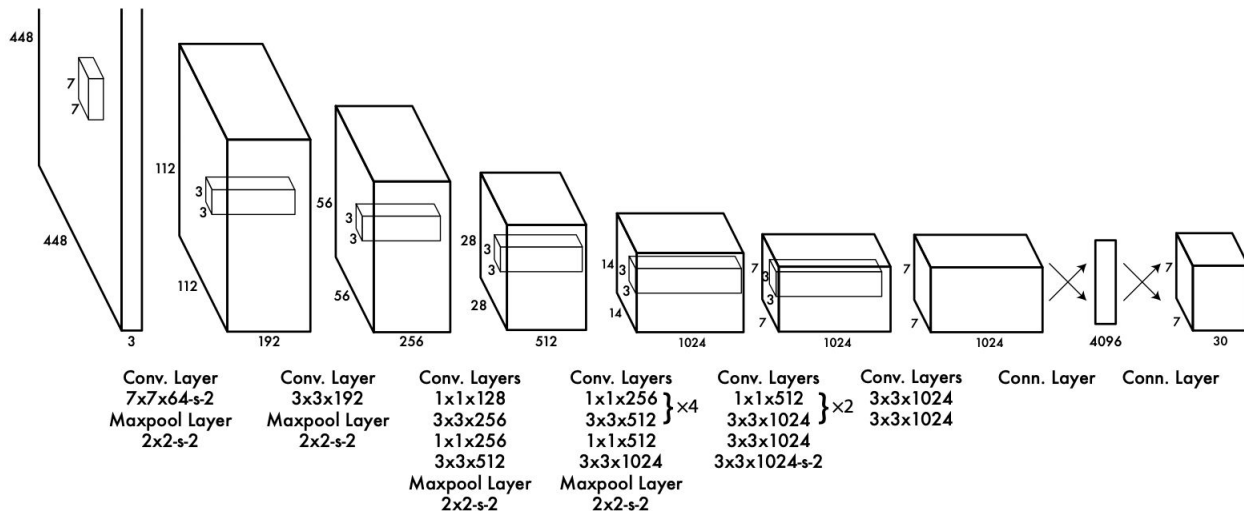


$$IoU = \frac{\text{area of the intersection between } B_1 \text{ and } B_2}{\text{area of the union between } B_1 \text{ and } B_2},$$





## Architektura YOLOv1



**Figure 3: The Architecture.** Our detection network has 24 convolutional layers followed by 2 fully connected layers. Alternating  $1 \times 1$  convolutional layers reduce the features space from preceding layers. We pretrain the convolutional layers on the ImageNet classification task at half the resolution ( $224 \times 224$  input image) and then double the resolution for detection.



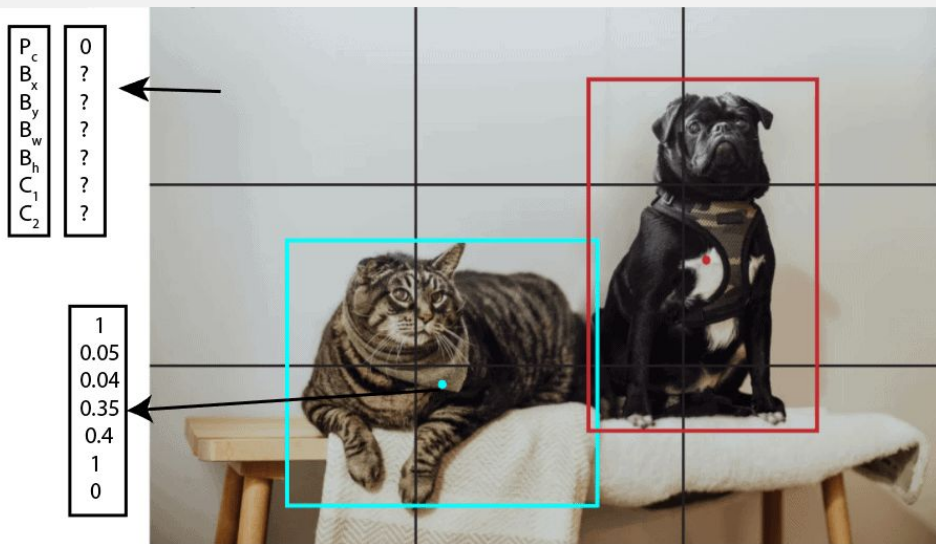
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<https://arxiv.org/pdf/1506.02640v5>



# Funkcja straty



$$\begin{aligned}
 & \lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left[ (x_i - \hat{x}_i)^2 + (y_i - \hat{y}_i)^2 \right] \\
 & + \lambda_{\text{coord}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left[ \left( \sqrt{w_i} - \sqrt{\hat{w}_i} \right)^2 + \left( \sqrt{h_i} - \sqrt{\hat{h}_i} \right)^2 \right] \\
 & + \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{obj}} \left( C_i - \hat{C}_i \right)^2 \\
 & + \lambda_{\text{noobj}} \sum_{i=0}^{S^2} \sum_{j=0}^B \mathbb{1}_{ij}^{\text{noobj}} \left( C_i - \hat{C}_i \right)^2 \\
 & + \sum_{i=0}^{S^2} \mathbb{1}_i^{\text{obj}} \sum_{c \in \text{classes}} (p_i(c) - \hat{p}_i(c))^2
 \end{aligned}$$



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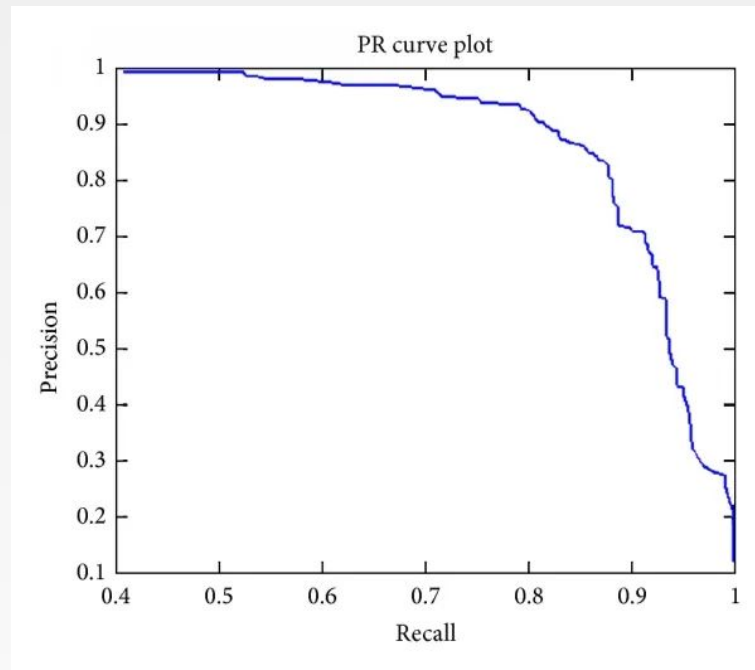
<https://towardsdatascience.com/on-object-detection-metrics-with-worked-example-216f173ed31e>



# Metryki

- Średnia precyzja (AP)
- mAP – mean Average Precision

		Actual	
		Positive	Negative
Predicted	Positive	<b>True Positive</b>	<b>False Positive</b>
	Negative	<b>False Negative</b>	<b>True Negative</b>





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<https://arxiv.org/pdf/2405.14458>

## YOLOv10







## Dual label assignment

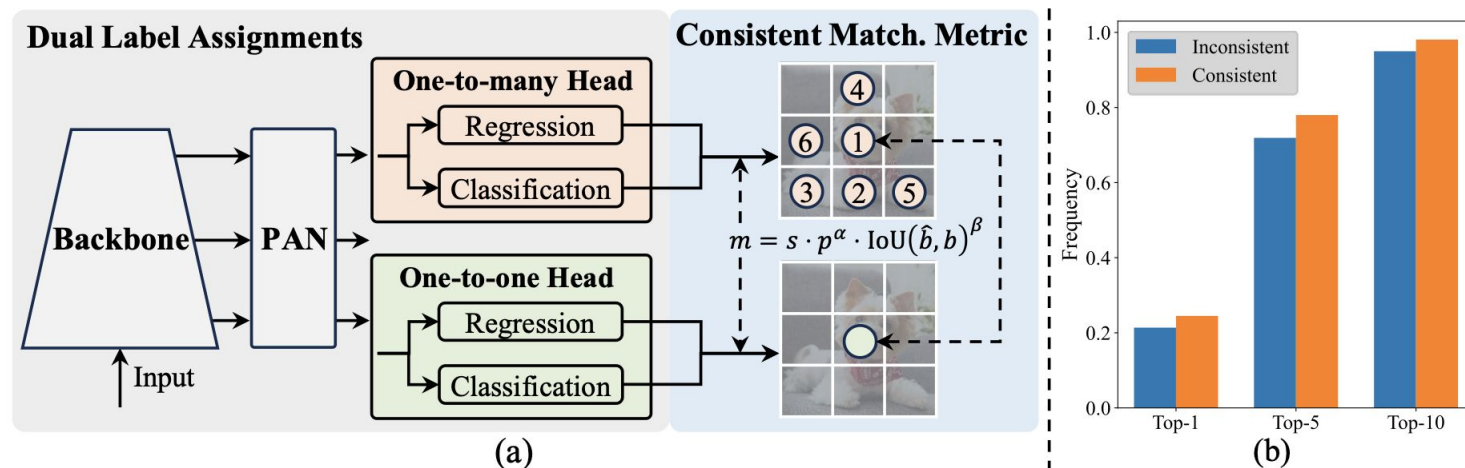


Figure 2: (a) Consistent dual assignments for NMS-free training. (b) Frequency of one-to-one assignments in Top-1/5/10 of one-to-many results for YOLOv8-S which employs  $\alpha_{o2m}=0.5$  and  $\beta_{o2m}=6$  by default [20]. For consistency,  $\alpha_{o2o}=0.5$ ;  $\beta_{o2o}=6$ . For inconsistency,  $\alpha_{o2o}=0.5$ ;  $\beta_{o2o}=2$ .





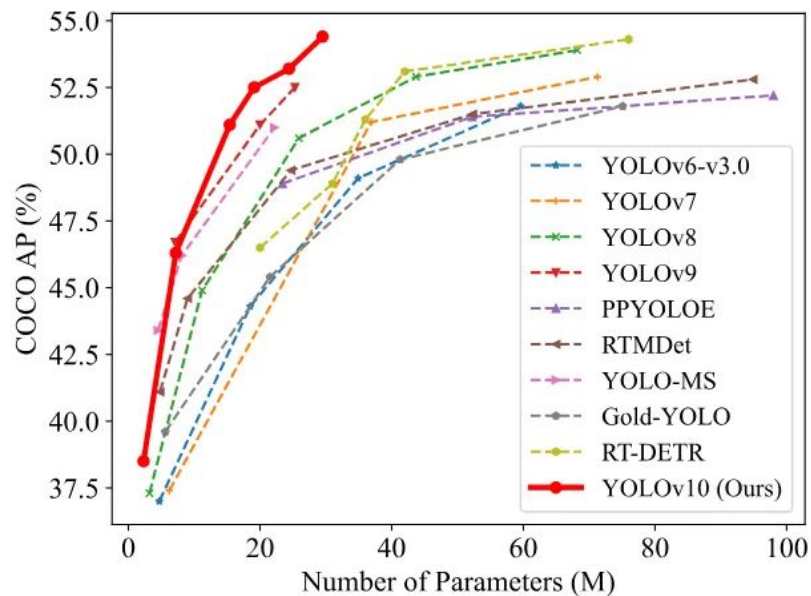
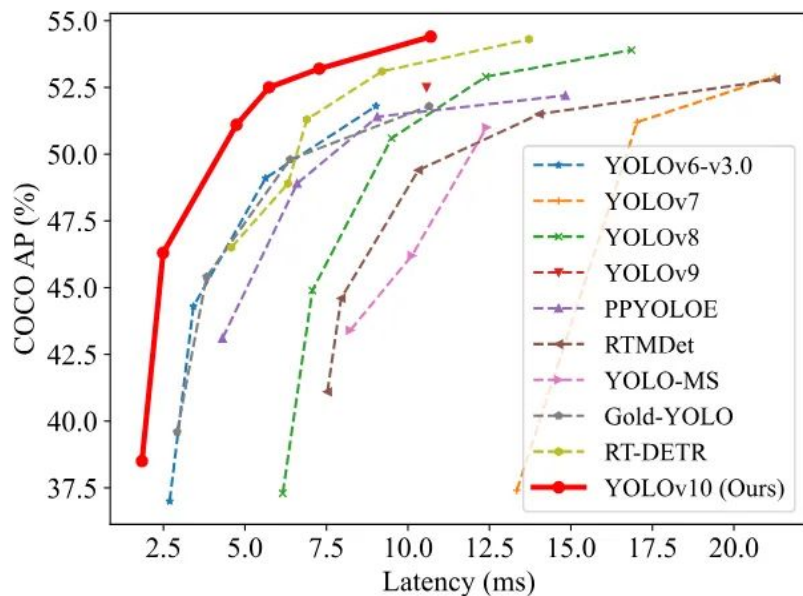
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<https://arxiv.org/pdf/2405.14458>



## YOLOv10





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# Materialy

- [YOLO Explained. What is YOLO? | by Ani Aggarwal | Analytics Vidhya | Medium](#)
- <https://colab.research.google.com/github/roboflow-ai/notebooks/blob/main/notebooks/train-yolov10-object-detection-on-custom-dataset.ipynb>
- [YOLOv10: Instant Real-Time Object Detection with YOLO \(You Only Look Once\) | by AI TutorMaster | May, 2024 | Level Up Coding](#)

