CS280 Fall 2023 Assignment 1 Part A

Basics & MLP

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1. Gradient descent for fitting GMM (10 points).

Consider the Gaussian mixture model

$$p(\mathbf{x}|\theta) = \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

where $\pi_j \geq 0, \sum_{j=1}^K \pi_j = 1$. (Assume $\mathbf{x}, \boldsymbol{\mu}_k \in \mathbb{R}^d, \boldsymbol{\Sigma}_k \in \mathbb{R}^{d \times d}$)

Define the log likelihood as

$$l(\theta) = \sum_{n=1}^{N} \log p(\mathbf{x}_n | \theta)$$

Denote the posterior responsibility that cluster k has for datapoint n as follows:

$$r_{nk} := p(z_n = k | \mathbf{x}_n, \theta) = \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{k'} \pi_{k'} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Sigma}_{k'})}$$

(a) Show that the gradient of the log-likelihood wrt μ_k is

$$\frac{d}{d\boldsymbol{\mu}_k}l(\theta) = \sum_{n} r_{nk} \boldsymbol{\Sigma}_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k)$$

Show:

the log-likelihood $l(\theta)$ in terms of the Gaussian mixture model:

$$l(\theta) = \sum_{n=1}^{N} \log \left(\sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right)$$

take the derivative with respect to μ_k :

$$\frac{d}{d\boldsymbol{\mu}_k}l(\theta) = \sum_{n=1}^{N} \frac{1}{\sum_{k'} \pi_{k'} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Sigma}_{k'})} \cdot \frac{d}{d\boldsymbol{\mu}_k} \left(\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right)$$

the derivative inside the summation:

$$\frac{d}{d\boldsymbol{\mu}_{k}}\left(\pi_{k}\mathcal{N}(\mathbf{x}_{n}|\boldsymbol{\mu}_{k},\boldsymbol{\Sigma}_{k})\right) = \pi_{k}\frac{d}{d\boldsymbol{\mu}_{k}}\mathcal{N}(\mathbf{x}_{n}|\boldsymbol{\mu}_{k},\boldsymbol{\Sigma}_{k})$$

the derivative of the multivariate Gaussian density function with respect to $oldsymbol{\mu}_k$ is:

$$\frac{d}{d\boldsymbol{\mu}_k} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) = -\boldsymbol{\Sigma}_k^{-1}(\mathbf{x}_n - \boldsymbol{\mu}_k) \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

substitute this back into up expression:

$$\frac{d}{d\boldsymbol{\mu}_k}l(\theta) = \sum_{n=1}^{N} \frac{\pi_k \cdot - \boldsymbol{\Sigma}_k^{-1}(\mathbf{x}_n - \boldsymbol{\mu}_k) \cdot \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{k'} \pi_{k'} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Sigma}_{k'})}$$

Finally, simplify the expression using the responsibility r_{nk} :

$$\frac{d}{d\boldsymbol{\mu}_k}l(\theta) = \sum_{n=1}^{N} r_{nk} \boldsymbol{\Sigma}_k^{-1} (\mathbf{x}_n - \boldsymbol{\mu}_k)$$

(b) Derive the gradient of the log-likelihood wrt π_k without considering any constraint on π_k . (bonus 2 points: with constraint $\sum_k \pi_k = 1$.)

Given the definition of $l(\theta)$ and r_{nk} from the previous context, we have:

$$l(\theta) = \sum_{n=1}^{N} \log p(\mathbf{x}_n | \theta)$$

To derive $\frac{d}{d\pi_k}l(\theta)$, take the derivative inside the summation:

$$\sum_{n=1}^{N} \frac{d}{d\pi_k} \log p(\mathbf{x}_n | \theta) = \sum_{n=1}^{N} \frac{d}{d\pi_k} \log \left(\sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right)$$

Simplifying, we have:

$$\sum_{n=1}^{N} \frac{1}{\sum_{k=1}^{K} \pi_k}$$

So, the derivative of the log-likelihood with respect to π_k is $\max \frac{1}{\pi_i}$, $i = 1 \to K$.

Considering, with constraint $\sum_{k} \pi_{k} = 1$,

We define the Lagrangian function:

$$L(\theta, \lambda) = l(\theta) + \lambda \left(1 - \sum_{k} \pi_{k}\right)$$

we take partial derivatives with respect to π_k and λ , and set them equal to zero to find the optimal solution:

Taking the partial derivative with respect to π_k :

$$\frac{\partial L}{\partial \pi_k} = \frac{1}{\pi_k} - \lambda = 0$$

Solving for π_k :

$$\pi_k = \frac{1}{\lambda}$$

Taking the partial derivative with respect to λ :

$$\frac{\partial L}{\partial \lambda} = 1 - \sum_{k} \pi_k = 1 - K \cdot \frac{1}{\lambda} = 0$$

Solving for λ :

$$\lambda = K$$

Substituting $\lambda = K$ back into $\pi_k = \frac{1}{\lambda}$, we get:

$$\pi_k = \frac{1}{K}$$

This means that under the constraint $\sum_k \pi_k = 1$, the derivative of the log-likelihood $l(\theta)$ with respect to π_k remains $\frac{1}{\pi_k}$, but now π_k follows a uniform distribution, where each π_k is equal to $\frac{1}{K}$.

2. Sotfmax & Computation Graph (10 points).

Recall that the softmax function takes in a vector (z_1, \ldots, z_D) and returns a vector (y_1, \ldots, y_D) . We can express it in the following form:

$$r = \sum_{j} e^{z_j} \qquad y = \frac{e^{z_j}}{r}$$

(a) Consider D = 2, i.e. just two inputs and outputs to the softmax. Draw the computation graph relating z_1, z_2, r, y_1 , and y_2 .

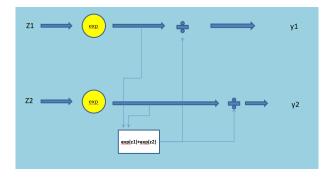


Figure 1: An image of a computation

(b) Determine the backprop updates for computing the \bar{z}_j when given the \bar{y}_i . You need to justify your answer. (You may give your answer either for D=2 or for the more general case.)

For the Loss of Softmax:

$$L_i = -\log y_i$$

For the calculation of Softmax:

$$y_j = \frac{e^{z_j}}{r}$$

where $r = \sum_{j} e^{z_j}$.

We want to compute $\bar{z_j}$, which is the gradient of the input z_j with respect to the loss, given $\bar{y_j}$. According to the chain rule:

$$\bar{z_j} = \frac{\partial L}{\partial z_j} = \frac{\partial L}{\partial y_j} \cdot \frac{\partial y_j}{\partial z_j} = \bar{y_j} \cdot \frac{\partial y_j}{\partial z_j}$$

We know:

$$\frac{\partial y_j}{\partial z_j} = y_j \cdot (1 - y_j)$$

So:

$$\bar{z_j} = \bar{y_j} \cdot y_j \cdot (1 - y_j)$$

- (c) Write a function to implement the vector-Jacobian product (VJP) for the softmax function based on your answer from part (b). For efficiency, it should operate on a minibatch. The inputs are:
 - a matrix Z of size $N \times D$ giving a batch of input vectors. N is the batch size and D is the number of dimensions. Each row gives one input vector $z = (z_1, \ldots, z_D)$.
 - A matrix $\mathbf{Y}_{\mathbf{bar}}$ giving the output error signals. It is also $N \times D$

The output should be the error signal $\mathbf{Z}_{\mathbf{bar}}$. Do not use a for loop. function:

```
import numpy as np

def softmax_vjp(Z, Y_bar):
    Y = np.exp(Z) / np.sum(np.exp(Z), axis=1, keepdims=True)
    return Y_bar * Y * (1 - Y)

# Example usage
Z = np.array([[1, 2], [3, 4]]) # Input Z
Y_bar = np.array([[0.1, 0.2], [0.3, 0.4]]) # Output error signals
Z_bar = softmax_vjp(Z, Y_bar) # Compute input error signals
print(Z_bar)
```