

# perceptron

November 6, 2023

## 0.1 Perceptron Learning Algorithm

The perceptron is a simple supervised machine learning algorithm and one of the earliest neural network architectures. It was introduced by Rosenblatt in the late 1950s. A perceptron represents a binary linear classifier that maps a set of training examples (of  $d$  dimensional input vectors) onto binary output values using a  $d - 1$  dimensional hyperplane. But Today, we will implement **Multi-Classes Perceptron Learning Algorithm Given:** \* dataset  $\{(x^i, y^i)\}$ ,  $i \in (1, M)$  \*  $x^i$  is  $d$  dimension vector,  $x^i = (x_1^i, \dots, x_d^i)$  \*  $y^i$  is multi-class target variable  $y^i \in \{0, 1, 2\}$

A perceptron is trained using gradient descent. The training algorithm has different steps. In the beginning (step 0) the model parameters are initialized. The other steps (see below) are repeated for a specified number of training iterations or until the parameters have converged.

**Step0:** Initial the weight vector and bias with zeros

**Step1:** Compute the linear combination of the input features and weight.  $y_{pred}^i = \arg \max_k W_k * x^i + b$

**Step2:** Compute the gradients for parameters  $W_k$ ,  $b$ . **Derive the parameter update equation Here (5 points)**

TODO: Derive you answer hear #####

$$\frac{\partial L}{\partial W_k} = x_i$$

$$\frac{\partial L}{\partial b} = x_i$$

$$W_k^{new} = W_k^{old} - \eta \cdot \frac{\partial L}{\partial W_k}$$

$$b^{new} = b^{old} - \eta \cdot \frac{\partial L}{\partial b}$$

$\eta = learningrate$

```
[4]: from sklearn import datasets
import numpy as np
from sklearn.model_selection import train_test_split
import matplotlib.pyplot as plt
import random

np.random.seed(0)
random.seed(0)
```

/home/myu/.conda/envs/carla/lib/python3.7/importlib/\_bootstrap.py:219:  
RuntimeWarning: numpy.ufunc size changed, may indicate binary incompatibility.

```
Expected 192 from C header, got 216 from PyObject
return f(*args, **kwds)
```

```
[5]: iris = datasets.load_iris()
X = iris.data
print(type(X))
y = iris.target
y = np.array(y)
print('X_Shape:', X.shape)
print('y_Shape:', y.shape)
print('Label Space:', np.unique(y))
```

```
<class 'numpy.ndarray'>
X_Shape: (150, 4)
y_Shape: (150,)
Label Space: [0 1 2]
```

```
[6]: ## split the training set and test set
X_train,X_test,y_train,y_test=train_test_split(X,y,test_size=0.3,
↳random_state=0)
print('X_train_Shape:', X_train.shape)
print('X_test_Shape:', X_test.shape)
print('y_train_Shape:', y_train.shape)
print('y_test_Shape:', y_test.shape)

print(type(y_train))
```

```
X_train_Shape: (105, 4)
X_test_Shape: (45, 4)
y_train_Shape: (105,)
y_test_Shape: (45,)
<class 'numpy.ndarray'>
```

```
[7]: import numpy as np
import matplotlib.pyplot as plt

class MultiClsPLA(object):

    ## We recommend to absorb the bias into weight. W = [w, b]

    def __init__(self, X_train, y_train, X_test, y_test, lr, num_epoch,
↳weight_dimension, num_cls):
        super(MultiClsPLA, self).__init__()
        self.X_train = X_train
        self.y_train = y_train
        self.X_test = X_test
        self.y_test = y_test
        self.weight = self.initial_weight(weight_dimension, num_cls)
```

```

self.sample_mean = np.mean(self.X_train, 0)
self.sample_std = np.std(self.X_train, 0)
self.num_epoch = num_epoch
self.lr = lr
self.total_acc_train = []
self.total_acc_tst = []

def initial_weight(self, weight_dimension, num_cls):
    #####
    ##  TODO: Initialize the weight with  ##
    ##  small std and zero mean gaussian  ##
    #####
    weight = np.random.normal(0, 0.01, size=(weight_dimension+1, num_cls))
    return weight

def data_preprocessing(self, data):
    #####
    ##  TODO: Normlize the data          ##
    #####
    norm_data = (data - self.sample_mean) / self.sample_std
    return norm_data

def train_step(self, X_train, y_train, shuffle_idx):
    np.random.shuffle(shuffle_idx)
    X_train = X_train[shuffle_idx]
    y_train = y_train[shuffle_idx]

    train_acc = 0.0
    for i in range(X_train.shape[0]):
        x = np.concatenate((X_train[i], [1])) # Add 1 for bias term
        y = np.argmax(np.dot(x, self.weight), axis=0)

        if y != y_train[i]:
            self.weight[:, y_train[i]] += self.lr * x
            self.weight[:, y] -= self.lr * x

        train_acc += 1 if y == y_train[i] else 0

    train_acc /= X_train.shape[0]
    return train_acc

def test_step(self, X_test, y_test):
    X_test = self.data_preprocessing(data=X_test)
    num_sample = X_test.shape[0]
    test_acc = 0.0

    for i in range(num_sample):

```

```

        x = np.concatenate((X_test[i], [1]))
        y = np.argmax(np.dot(x, self.weight), axis=0)
        test_acc += 1 if y == y_test[i] else 0

    test_acc /= num_sample
    return test_acc

def train(self):
    self.X_train = self.data_preprocessing(data=self.X_train)
    num_sample = self.X_train.shape[0]
    shuffle_index = np.array(range(0, num_sample))

    for epoch in range(self.num_epoch):
        training_acc = self.train_step(X_train=self.X_train, y_train=self.
→y_train, shuffle_idx=shuffle_index)
        tst_acc = self.test_step(X_test=self.X_test, y_test=self.y_test)
        self.total_acc_train.append(training_acc)
        self.total_acc_tst.append(tst_acc)
        print('epoch:', epoch, 'traing_acc:%.3f'%training_acc, 'tst_acc:%.
→3f'%tst_acc)

def vis_acc_curve(self):
    train_acc = np.array(self.total_acc_train)
    tst_acc = np.array(self.total_acc_tst)
    plt.plot(train_acc)
    plt.plot(tst_acc)
    plt.legend(['train_acc', 'tst_acc'])
    plt.show()

```

[8]: `np.random.seed(0)`

```

#####
### TODO:
### 1. You need to import the model and pass some parameters.
### 2. Then training the model with some epoches.
### 3. Visualize the training acc and test acc verus epoches
lr = 0.01 #
num_epoch = 50 #
weight_dimension = X_train.shape[1] #
num_cls = len(set(y_train))
model = MultiClsPLA(X_train, y_train, X_test, y_test, lr, num_epoch,
→weight_dimension, num_cls)

#
model.train()

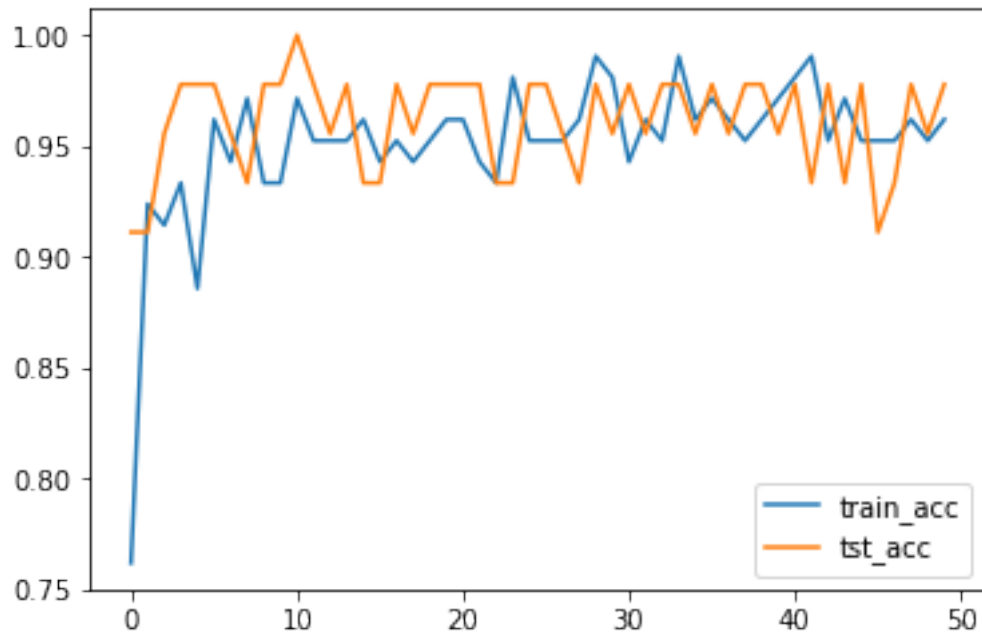
#

```

```
model.vis_acc_curve()
```

```
epoch: 0 traing_acc:0.762 tst_acc:0.911
epoch: 1 traing_acc:0.924 tst_acc:0.911
epoch: 2 traing_acc:0.914 tst_acc:0.956
epoch: 3 traing_acc:0.933 tst_acc:0.978
epoch: 4 traing_acc:0.886 tst_acc:0.978
epoch: 5 traing_acc:0.962 tst_acc:0.978
epoch: 6 traing_acc:0.943 tst_acc:0.956
epoch: 7 traing_acc:0.971 tst_acc:0.933
epoch: 8 traing_acc:0.933 tst_acc:0.978
epoch: 9 traing_acc:0.933 tst_acc:0.978
epoch: 10 traing_acc:0.971 tst_acc:1.000
epoch: 11 traing_acc:0.952 tst_acc:0.978
epoch: 12 traing_acc:0.952 tst_acc:0.956
epoch: 13 traing_acc:0.952 tst_acc:0.978
epoch: 14 traing_acc:0.962 tst_acc:0.933
epoch: 15 traing_acc:0.943 tst_acc:0.933
epoch: 16 traing_acc:0.952 tst_acc:0.978
epoch: 17 traing_acc:0.943 tst_acc:0.956
epoch: 18 traing_acc:0.952 tst_acc:0.978
epoch: 19 traing_acc:0.962 tst_acc:0.978
epoch: 20 traing_acc:0.962 tst_acc:0.978
epoch: 21 traing_acc:0.943 tst_acc:0.978
epoch: 22 traing_acc:0.933 tst_acc:0.933
epoch: 23 traing_acc:0.981 tst_acc:0.933
epoch: 24 traing_acc:0.952 tst_acc:0.978
epoch: 25 traing_acc:0.952 tst_acc:0.978
epoch: 26 traing_acc:0.952 tst_acc:0.956
epoch: 27 traing_acc:0.962 tst_acc:0.933
epoch: 28 traing_acc:0.990 tst_acc:0.978
epoch: 29 traing_acc:0.981 tst_acc:0.956
epoch: 30 traing_acc:0.943 tst_acc:0.978
epoch: 31 traing_acc:0.962 tst_acc:0.956
epoch: 32 traing_acc:0.952 tst_acc:0.978
epoch: 33 traing_acc:0.990 tst_acc:0.978
epoch: 34 traing_acc:0.962 tst_acc:0.956
epoch: 35 traing_acc:0.971 tst_acc:0.978
epoch: 36 traing_acc:0.962 tst_acc:0.956
epoch: 37 traing_acc:0.952 tst_acc:0.978
epoch: 38 traing_acc:0.962 tst_acc:0.978
epoch: 39 traing_acc:0.971 tst_acc:0.956
epoch: 40 traing_acc:0.981 tst_acc:0.978
epoch: 41 traing_acc:0.990 tst_acc:0.933
epoch: 42 traing_acc:0.952 tst_acc:0.978
epoch: 43 traing_acc:0.971 tst_acc:0.933
epoch: 44 traing_acc:0.952 tst_acc:0.978
epoch: 45 traing_acc:0.952 tst_acc:0.911
```

```
epoch: 46 traing_acc:0.952 tst_acc:0.933
epoch: 47 traing_acc:0.962 tst_acc:0.978
epoch: 48 traing_acc:0.952 tst_acc:0.956
epoch: 49 traing_acc:0.962 tst_acc:0.978
```



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