EECS498-008 Formal Verification of Systems Software
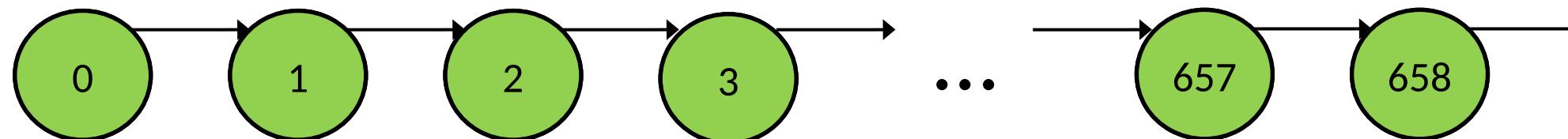
Material and slides created by

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Chapter 4: Proving properties

Expressing a system as a state machine allows us to prove that it has certain properties
- We will focus on safety properties
    - i.e. properties that hold throughout the execution

Basic tool: induction
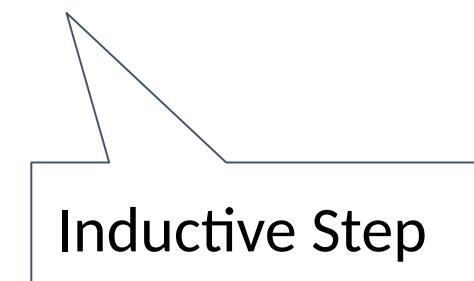
- Show that the property holds on state 0

- Show that if the property holds on state k, it must hold on state k+1

Let's prove a safety invariant!

```
predicate Safety(v:Variables) {
    true // TBD
}


lemma SafetyProof()
    ensures forall v :: Init(v) ==> Safety(v)
    ensures forall v, v' :: Safety(v) && Next(v, v') ==> Safety(v')
{
}
```

Base case

Inductive Step

Let's prove a safety invariant!

Interactive proof development in editor
Bisection debugging,
case analysis,
existential instantiation

Jay Normal Form

As you begin writing more interesting specs, proofs will be nontrivial.

Pull all the nondeterminism into one place, and get a receipt.

image: flickr/afagen CC-by-nc-sa

Jay Normal Form

```
datatype Step =
  | Action1Step( <parameters> )
  | Action2Step( <parameters> )
  ...

predicate NextStep(v: Variables, v': Variables, step:Step)
{
  match step
    case Action1Step(<parameters>) => Action1(v, v', <parameters>)
    case Action2Step(<parameters>) => Action2(v, v', <parameters>)
    ...
}
predicate Next(v: Variables, v': Variables)
{
    exists step :: NextStep(v, v', step)
}
```
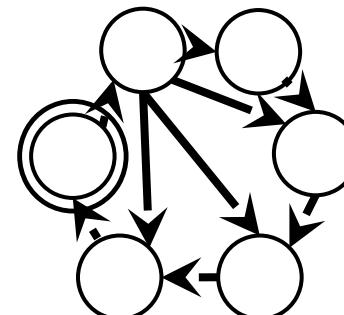
Administrivia

- Problem Set 2 will be released today
  - Chapters 3 and 4
    - Due Friday, October 7, 11:59pm

- Problem set 3 will be split into PS3 (Chapter 5, pre-project1) and PS4 (Chapter 6, post-project1).
  - Collectively still worth 8% of the total grade
  - Chapters 7 and 8 are now part of PS5

- Midterm coming up on October 12, 6-8pm
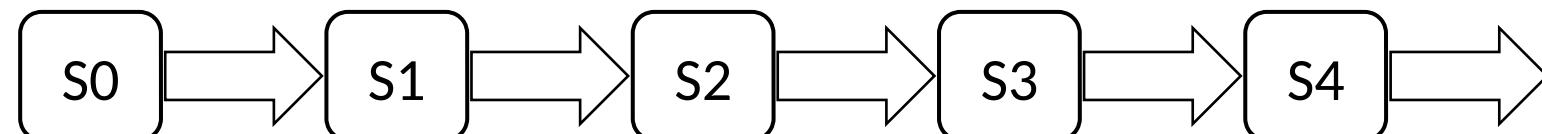
Safety property

Safety property (a.k.a. invariant): a property that **always** holds

State machine representation

An execution

$$S0 \Rightarrow S1 \Rightarrow S2 \Rightarrow S3 \Rightarrow S4 \Rightarrow$$
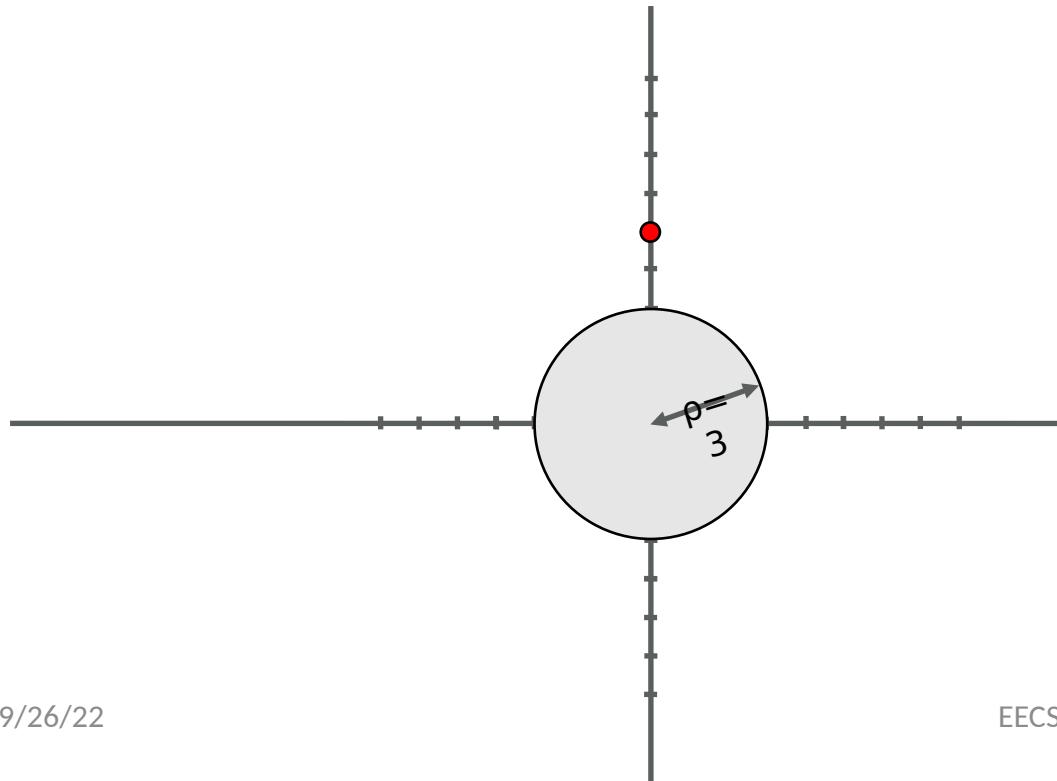
Example: Crawler

- Crawler starts at (0,5)
- It can move 1 step north or 1 step south-east
- Can it ever fall in the hole?
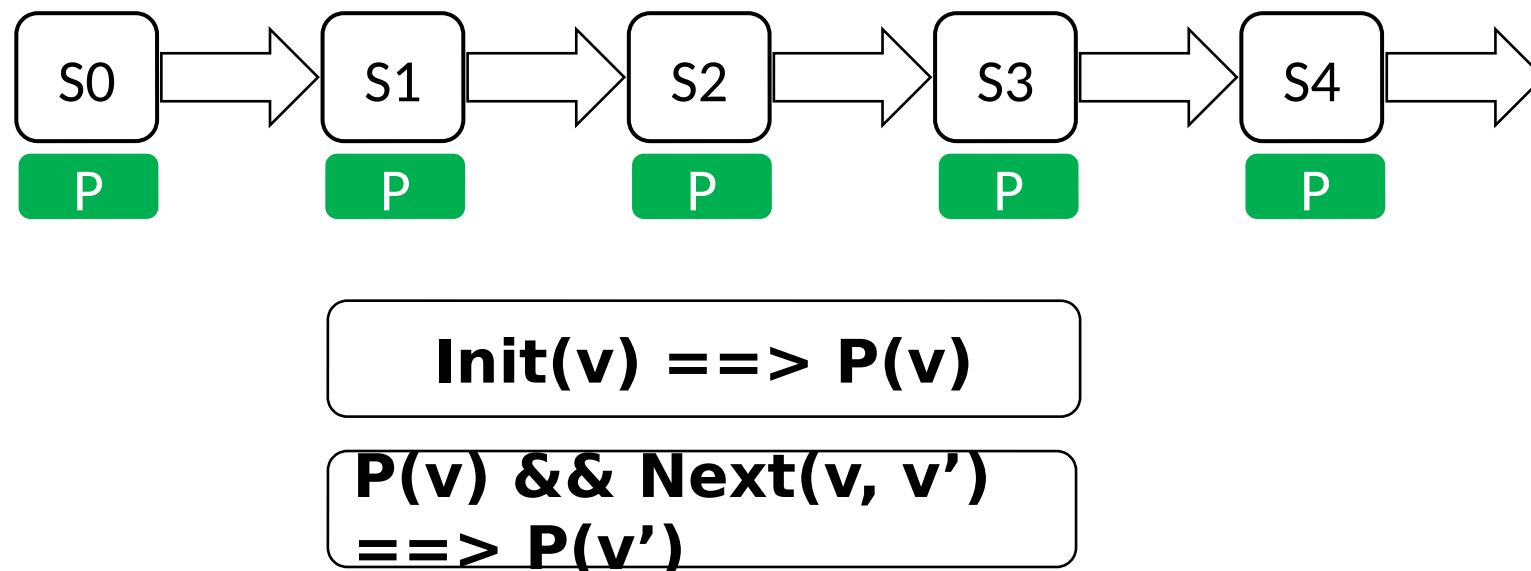

```
predicate Init(v:Variables) {
    && v.x == 0
    && v.y == 5
  }

  predicate MoveNorth(v:Variables,
v':Variables) {
    && v'.x == v.x
    && v'.y == v.y + 1
  }

  predicate MoveSouthEast(v:Variables,
v':Variables) {
    && v'.x == v.x + 1
    && v'.y == v.y - 1
}
```

Proving invariants

Proof by induction
- Prove it holds on the first state
- Prove it holds during a transition

$$Init(v) ==> P(v)$$

$$P(v) \&\& Next(v, v') ==> P(v')$$
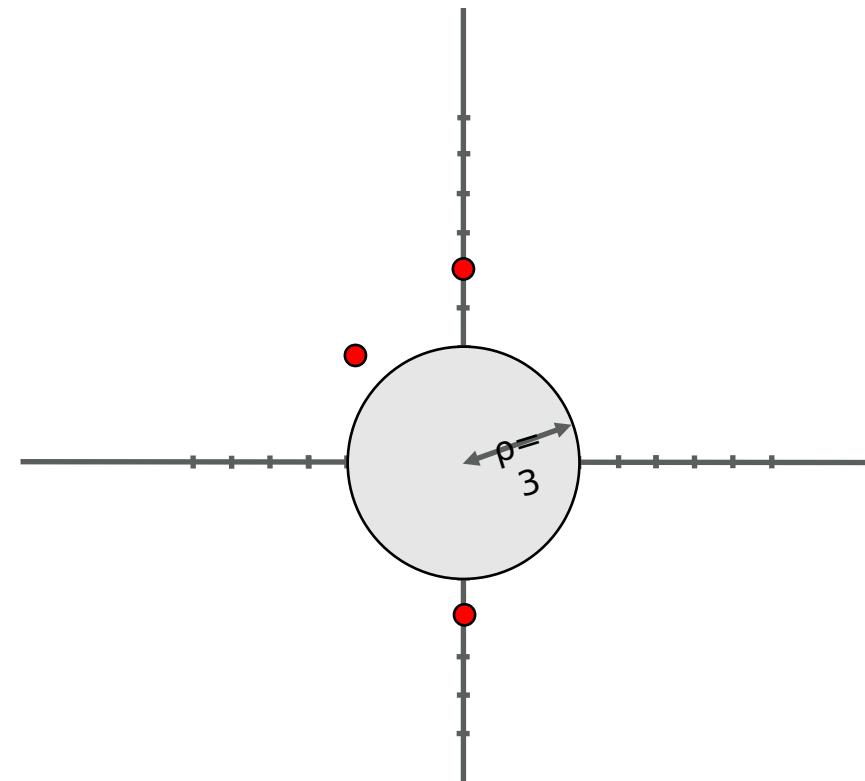
Proving the Crawler

```
predicate Init(v:Variables) {
   && v.x == 0
   && v.y == 5
 }

 predicate MoveNorth(v:Variables,
v':Variables) {
   && v'.x == v.x
   && v'.y == v.y + 1
 }

 predicate MoveSouthEast(v:Variables,
v':Variables) {
   && v'.x == v.x + 1
   && v'.y == v.y - 1
 }
predicate InHole(v:Variables) {
   v.x*v.x + v.y*v.y <= 3*3
}
```

Safety property: !InHole(v)
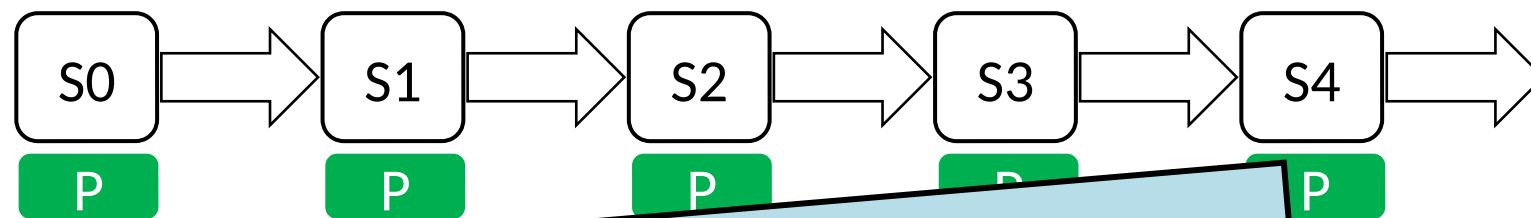
$$Init(v) ==> P(v) \checkmark$$

$$P(v) \&\& Next(v, v') ==> P(v') \times$$

Inductive invariants

Safety property (a.k.a. invariant):
a property that **always** holds

S0 → S1 → S2 → S3 → S4 →

P   P   P   P   P
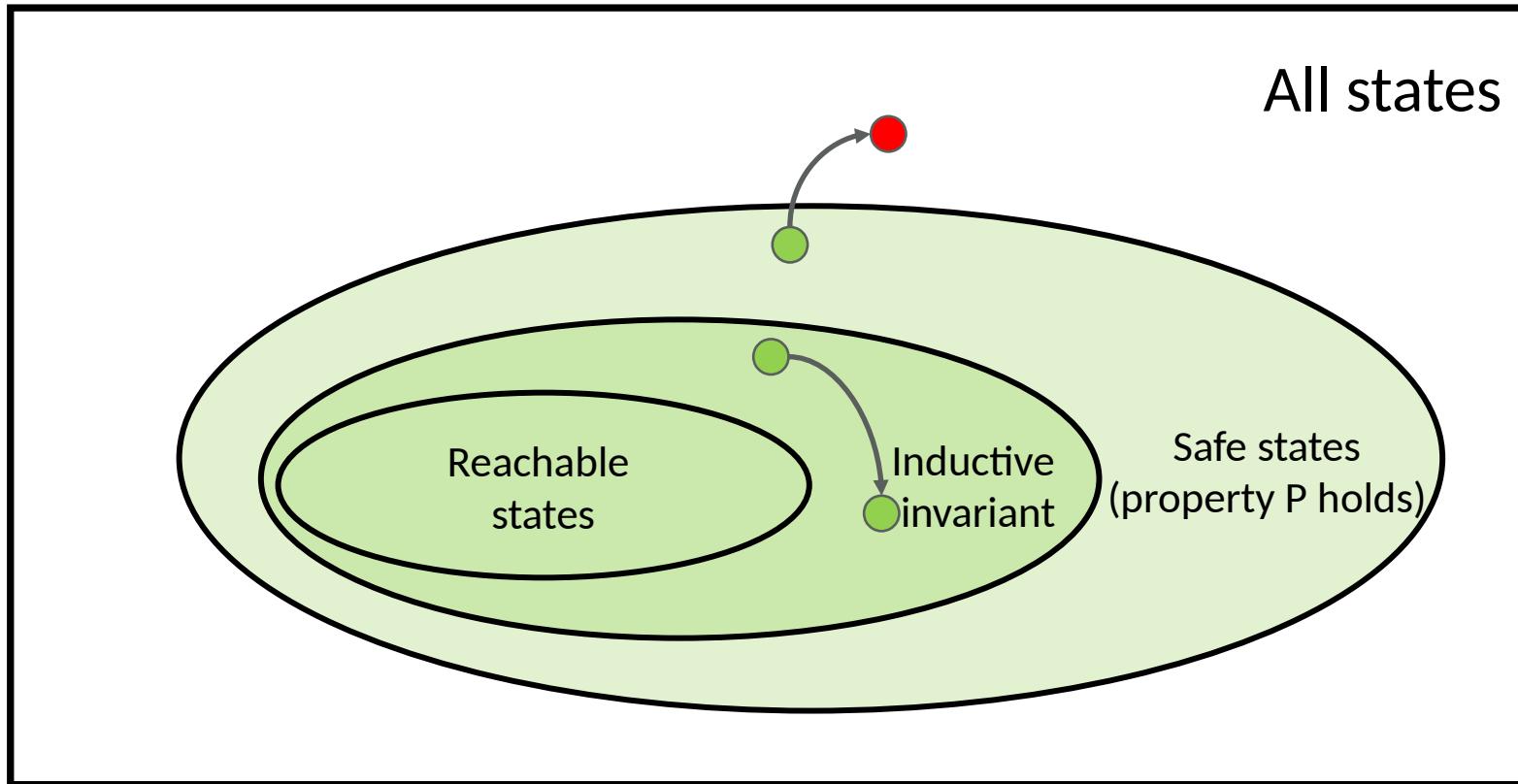
The problem:
Property P may **not** be inductive!

... (v)
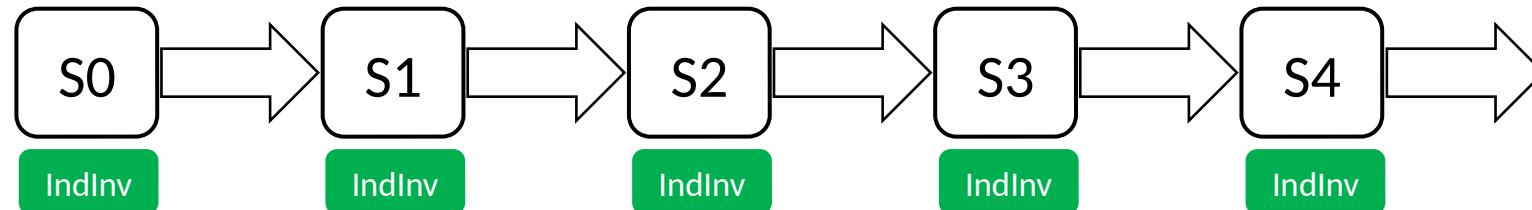
**P(v) && Next(v, v')
==> P(v')**

Invariants vs Inductive invariants

All states

Reachable states

Inductive invariant

Safe states (property P holds)

Proving safety with Inductive invariants

$$IndInv(v) ==> P(v)$$

S0 → S1 → S2 → S3 → S4 →

IndInv   IndInv   IndInv   IndInv   IndInv
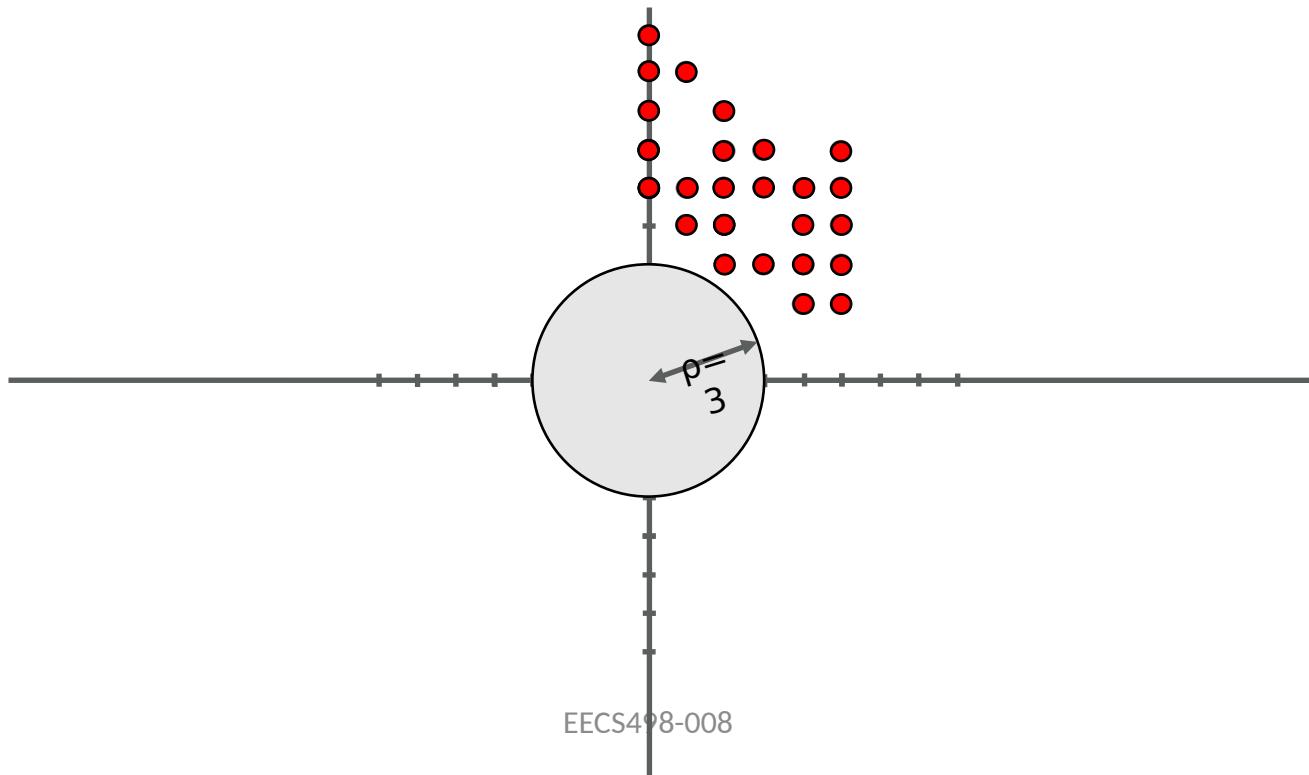
$$Init(v) ==> IndInv(v)$$

$$IndInv(v) \;\&\&\; Next(v, v') ==> IndInv(v')$$
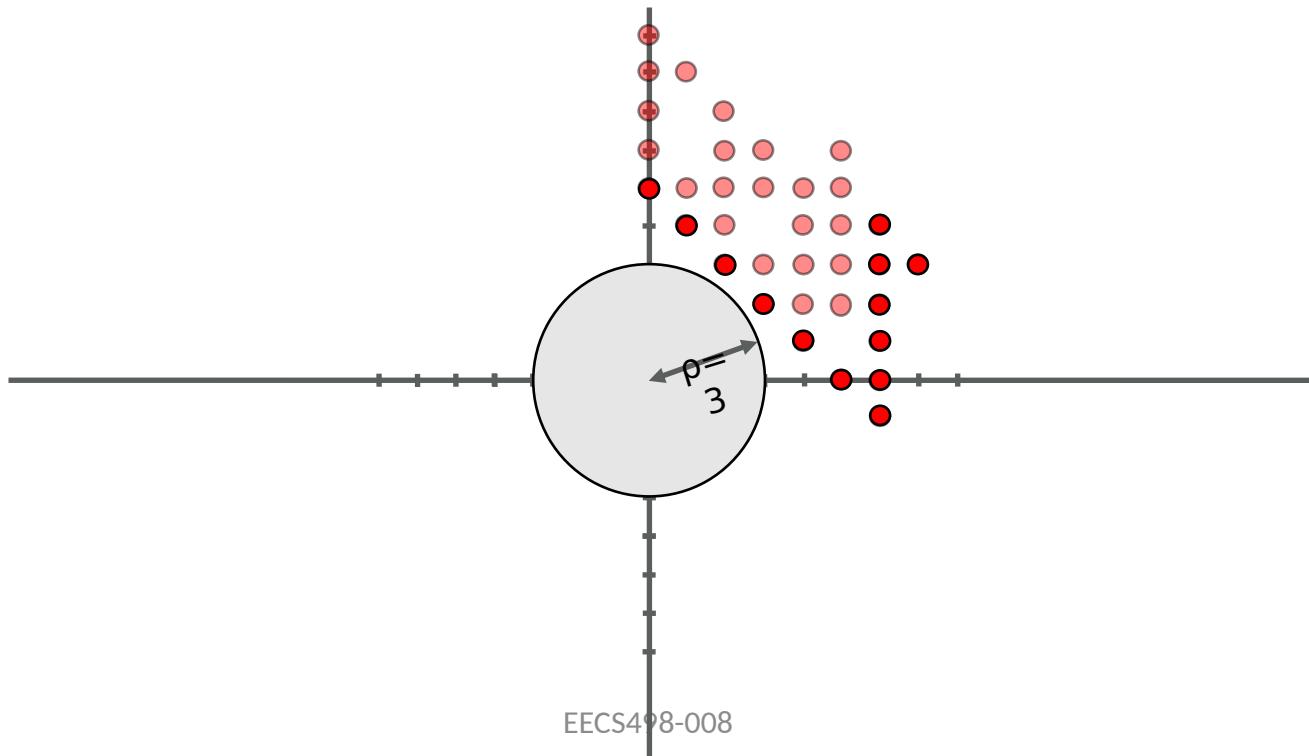
Proving the Crawler
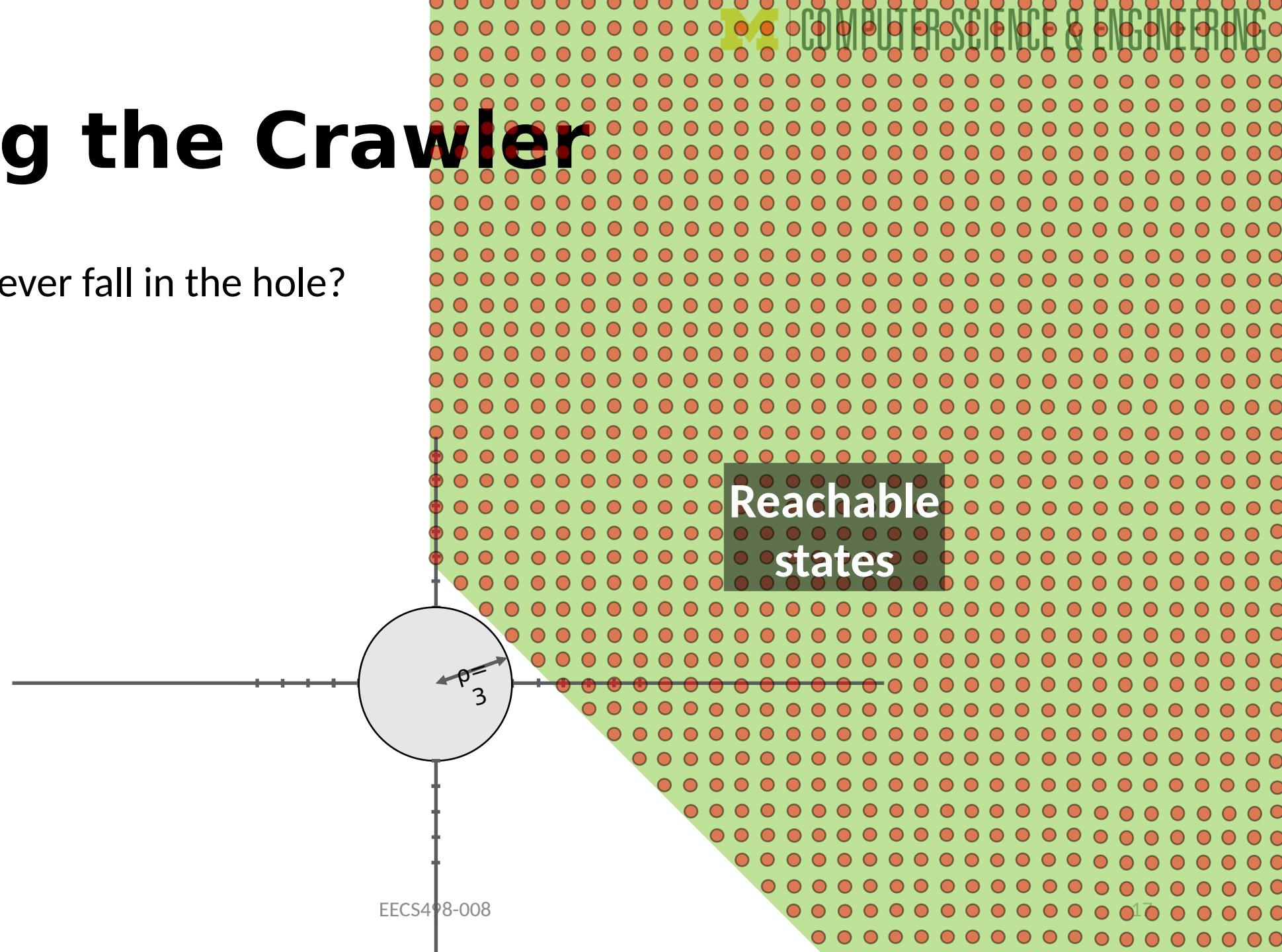
Can the crawler ever fall in the hole?

Proving the Crawler

Can the crawler ever fall in the hole?

$\rho = 3$

Proving the Crawler

Can the crawler ever fall in the hole?

Reachable states

$\rho = 3$
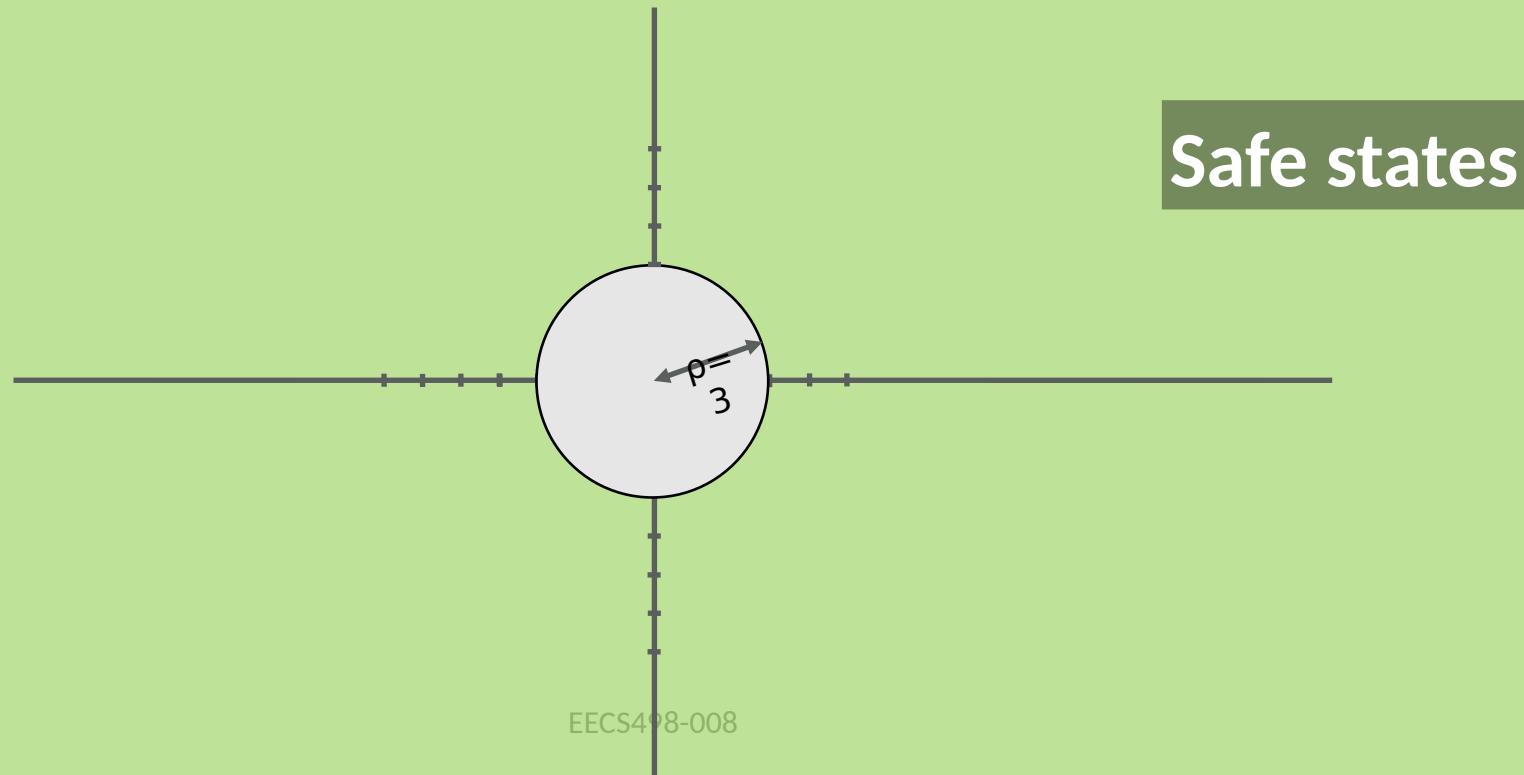
Naïve safety proof
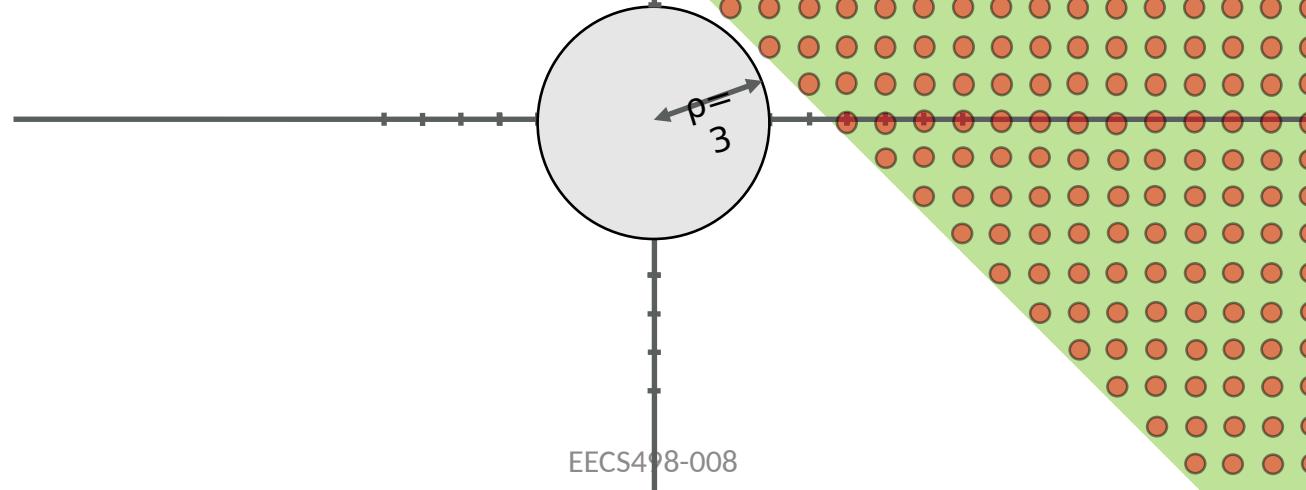
**Safe(v) && Next(v, v')
==> Safe(v')**

Safe states

$\rho = 3$
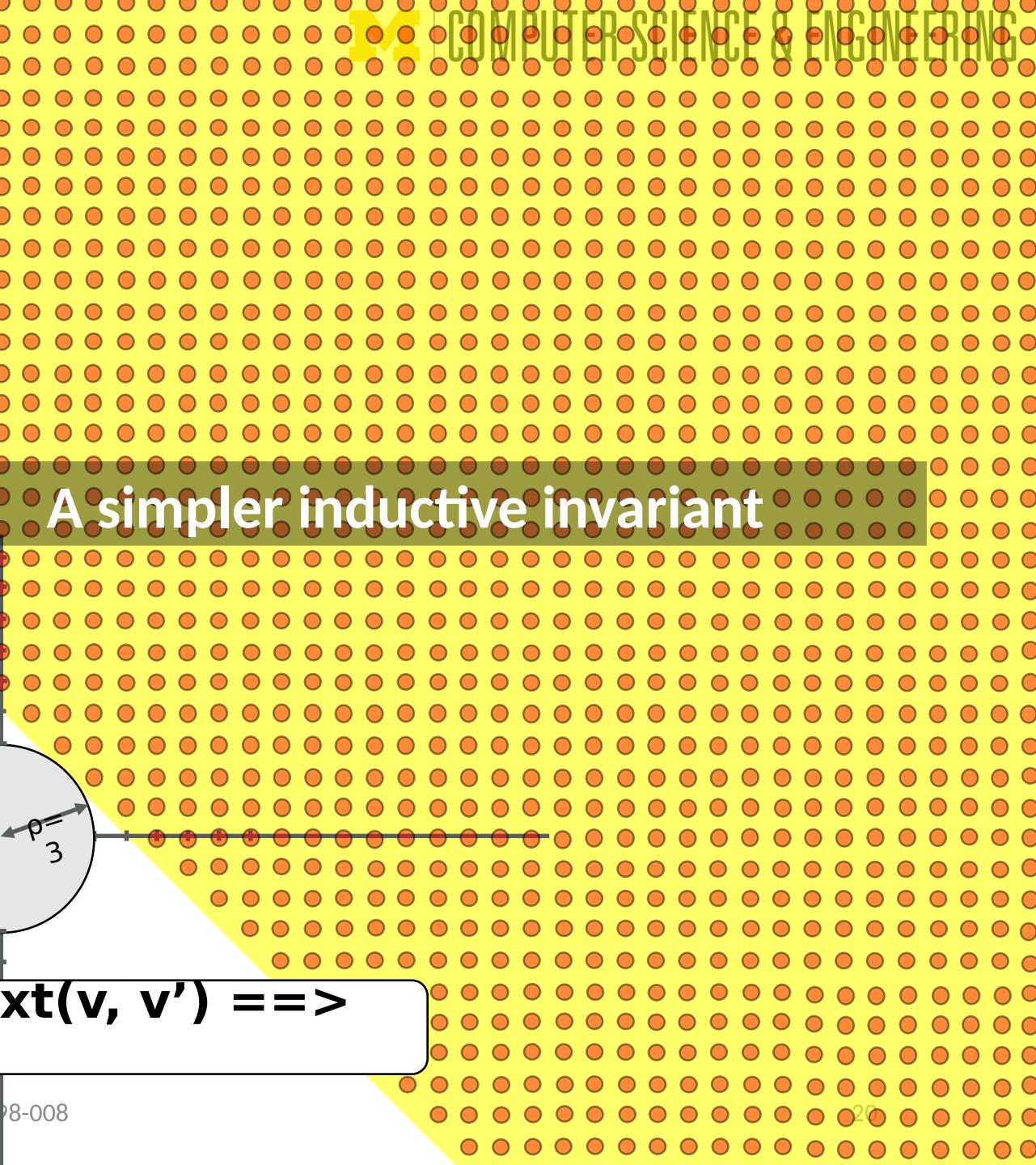
Safety proof using a stronger invariant

InGreenRegion(v) && Next(v, v') ==> InGreenRegion(v')

The set of reachable states is always an inductive invariant

$\rho = 3$

A simpler inductive invariant
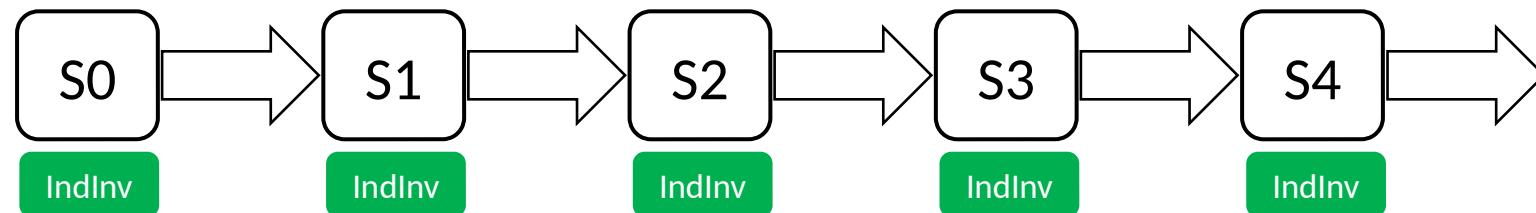
**InYellowRegion(v) && Next(v, v') ==>
InYellowRegion(v')**

Proving safety with Inductive invariants
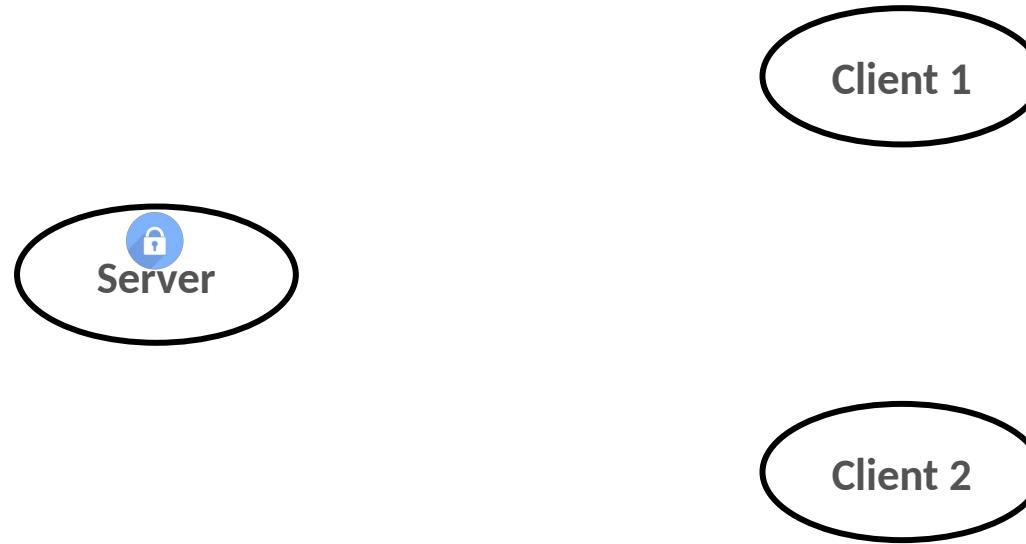
IndInv(v) ==> Safety(v)

Init(v) ==> IndInv(v)

IndInv(v) && Next(v, v')
==> IndInv(v')

Example: lock server

Client 1

Server

Client 2

Safety property: $\neg(C1 \wedge C2)$

Both clients cannot hold the lock at the same time

Example: lock server