

EECS498-008

Formal Verification

of Systems Software

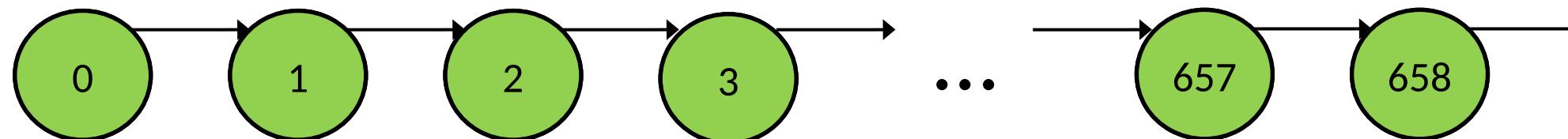
Material and slides created by
Jon Howell and Manos Kapritsos

Chapter 4: Proving properties

Expressing a system as a state machine allows us to **prove** that it has certain properties

- We will focus on safety properties
 - i.e. properties that hold throughout the execution

Basic tool: induction

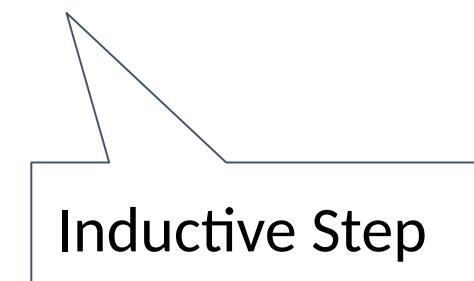


- Show that the property holds on state 0
- Show that if the property holds on state k , it must hold on state $k+1$

Let's prove a safety invariant!

```
predicate Safety(v:Variables) {  
    true // TBD  
}
```

```
lemma SafetyProof()  
    ensures forall v :: Init(v) ==> Safety(v)  
    ensures forall v, v' :: Safety(v) && Next(v, v') ==> Safety(v')  
{  
}
```



Let's prove a safety invariant!

Interactive proof development in editor

*Bisection debugging,
case analysis,
existential instantiation*



Jay Normal Form

As you begin writing more interesting specs, proofs will be nontrivial.

Pull all the nondeterminism into one place, and get a receipt.



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Jay Normal Form

```
datatype Step =
| Action1Step( <parameters> )
| Action2Step( <parameters> )
...

predicate NextStep(v: Variables, v': Variables, step:Step)
{
  match step
    case Action1Step(<parameters>) => Action1(v, v', <parameters>)
    case Action2Step(<parameters>) => Action2(v, v', <parameters>)
  ...
}

predicate Next(v: Variables, v': Variables)
{
  exists step :: NextStep(v, v', step)
}
```

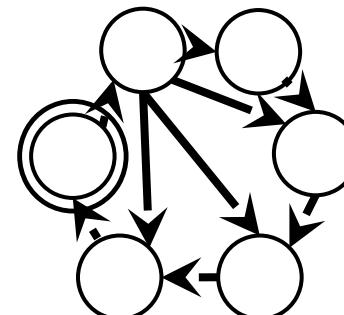
Administrivia

- Problem Set 2 will be released today
 - Chapters 3 and 4
 - Due Friday, October 7, 11:59pm
- Problem set 3 will be split into PS3 (Chapter 5, pre-project1) and PS4 (Chapter 6, post-project1).
 - Collectively still worth 8% of the total grade
 - Chapters 7 and 8 are now part of PS5
- Midterm coming up on October 12, 6-8pm

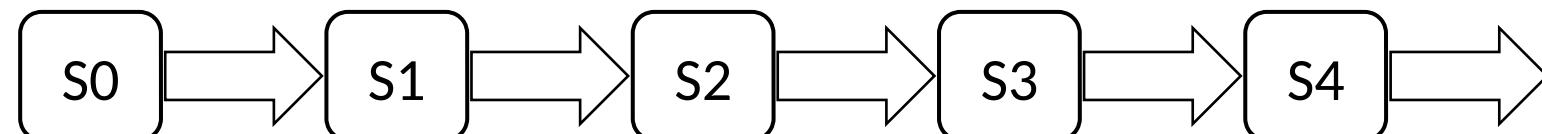
Safety property

Safety property (a.k.a. invariant): a property that **always** holds

State machine representation

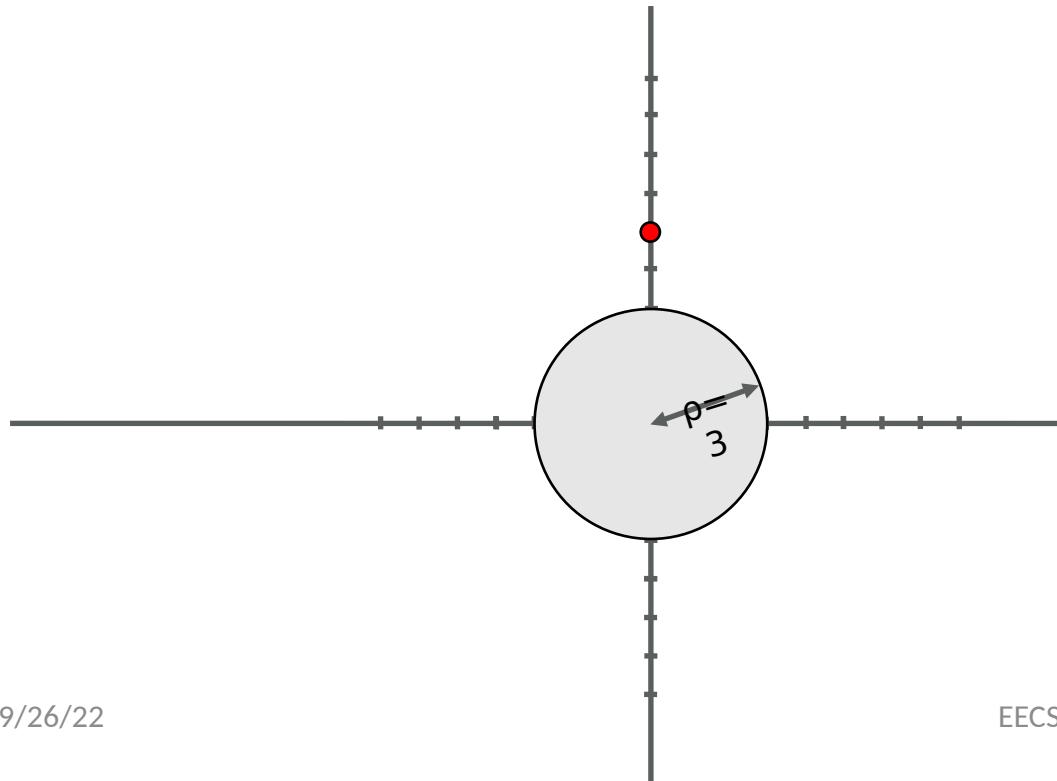


An execution



Example: Crawler

- Crawler starts at (0,5)
- It can move 1 step north or 1 step south-east
- Can it ever fall in the hole?

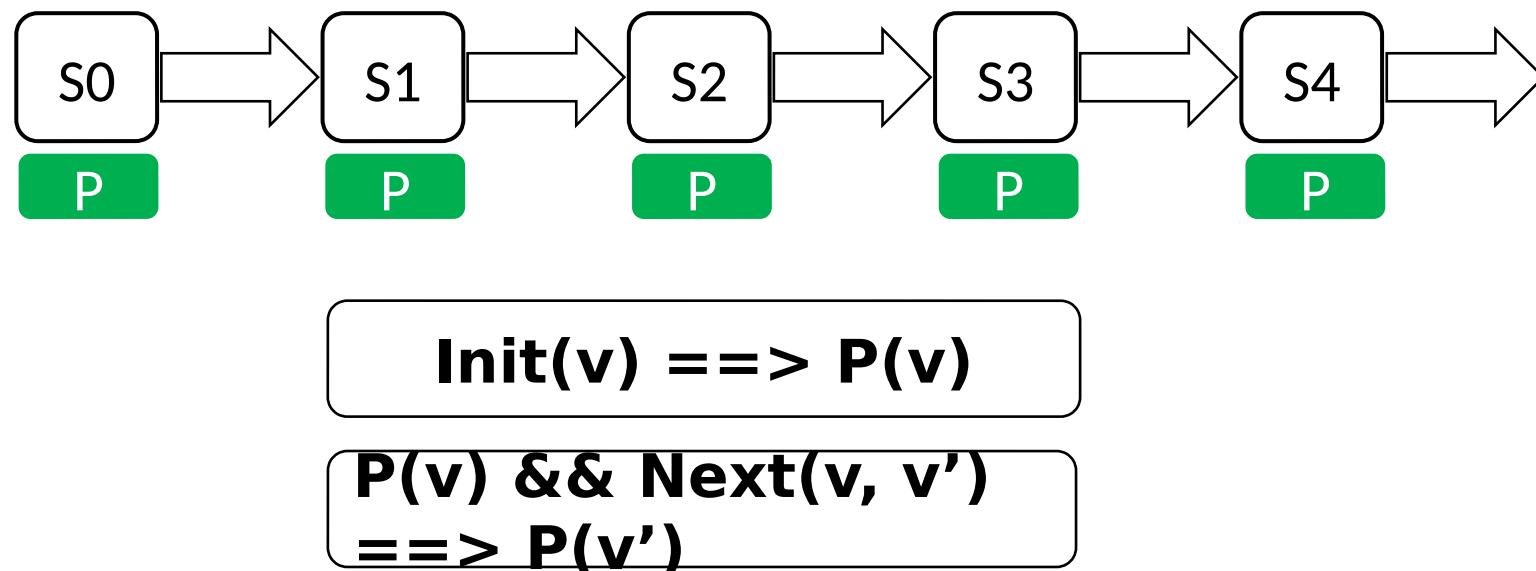


```
predicate Init(v:Variables) {  
  && v.x == 0  
  && v.y == 5  
}  
  
predicate MoveNorth(v:Variables,  
v':Variables) {  
  && v'.x == v.x  
  && v'.y == v.y + 1  
}  
  
predicate MoveSouthEast(v:Variables,  
v':Variables) {  
  && v'.x == v.x + 1  
  && v'.y == v.y - 1  
}
```

Proving invariants

Proof by induction

- Prove it holds on the first state
- Prove it holds during a transition



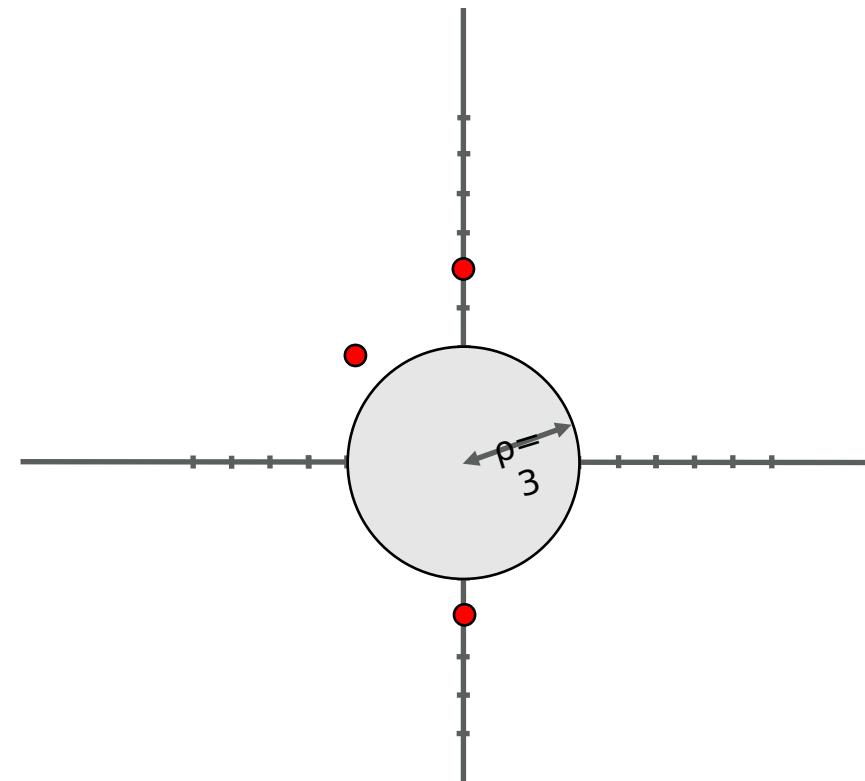
Proving the Crawler

```
predicate Init(v:Variables) {  
    && v.x == 0  
    && v.y == 5  
}  
  
predicate MoveNorth(v:Variables,  
v':Variables) {  
    && v'.x == v.x  
    && v'.y == v.y + 1  
}  
  
predicate MoveSouthEast(v:Variables,  
v':Variables) {  
    && v'.x == v.x + 1  
    && v'.y == v.y - 1  
}  
  
predicate InHole(v:Variables) {  
    v.x*v.x + v.y*v.y <= 3*3  
}
```

Safety property: $\neg \text{InHole}(v)$

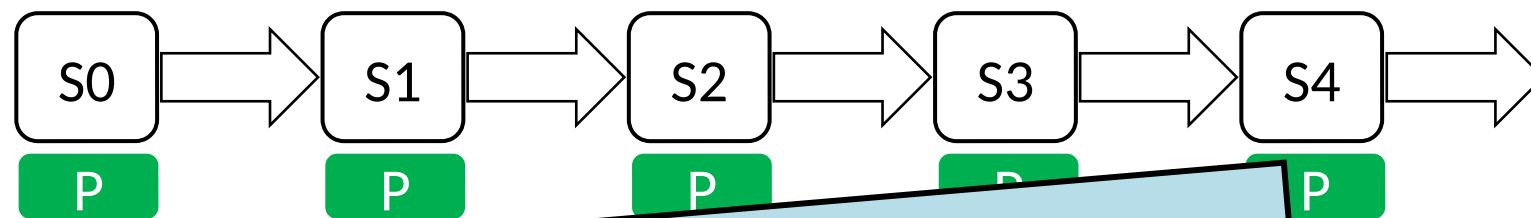
Init(v) ==> P(v) ✓

**P(v) && Next(v, v')
=> P(v')** ✗



Inductive invariants

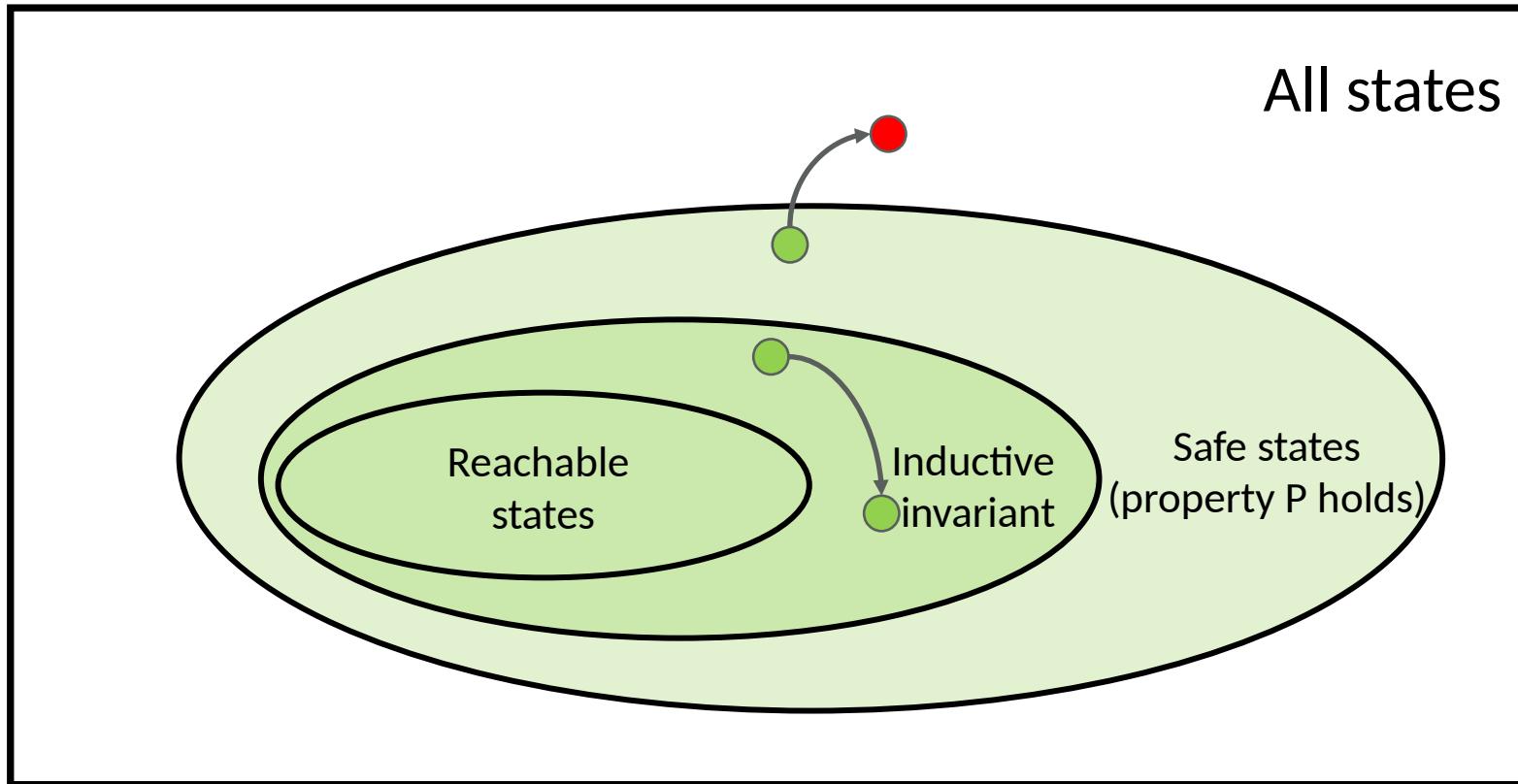
Safety property (a.k.a.
invariant):
a property that **always** holds



The problem:
Property P may **not** be inductive!

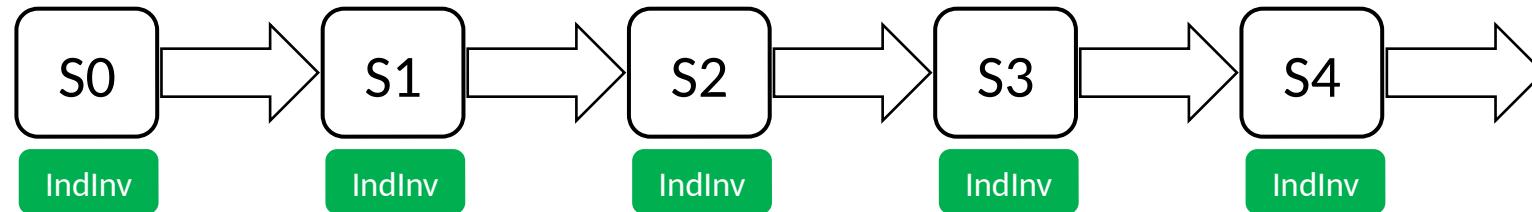
$$\begin{aligned} P(v) \text{ \&\& } \text{Next}(v, v') \\ ==> P(v') \end{aligned}$$

Invariants vs Inductive invariants



Proving safety with Inductive invariants

IndInv(v) ==> P(v)

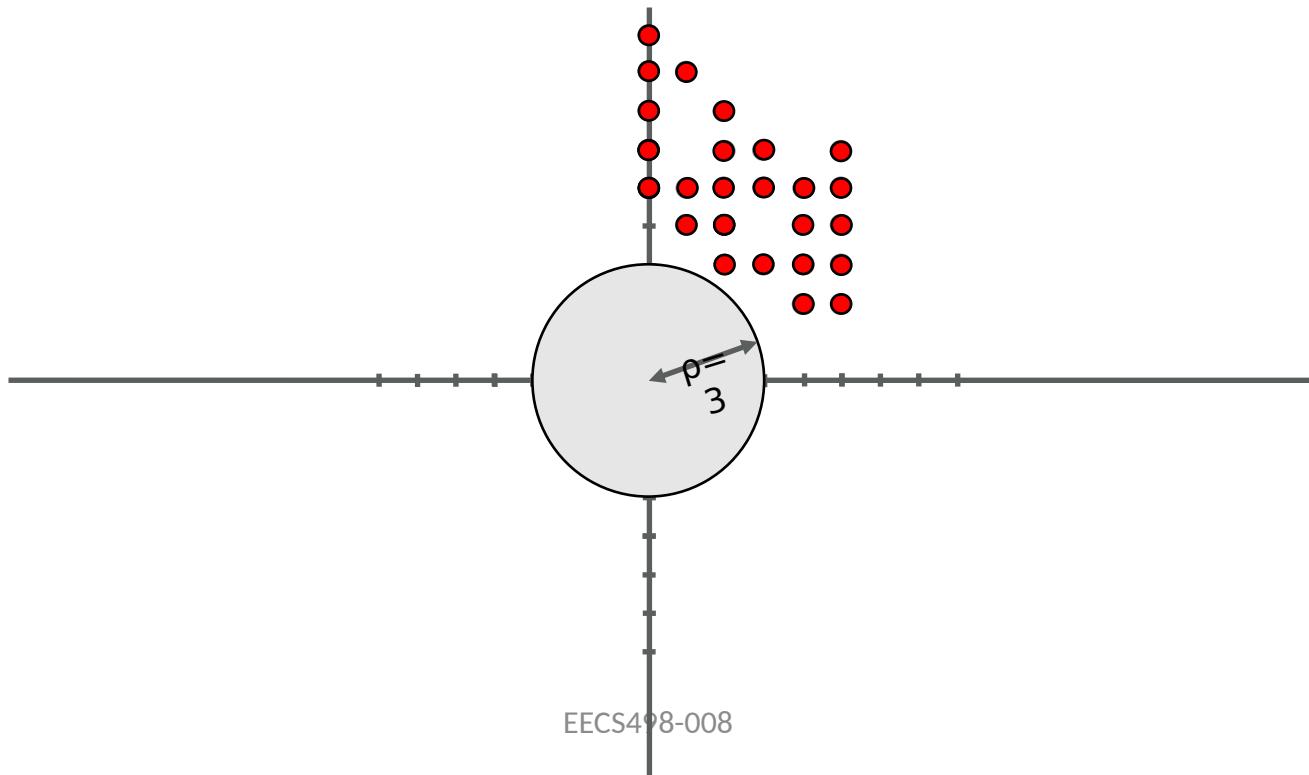


Init(v) ==> IndInv(v)

**IndInv(v) && Next(v, v')
==> IndInv(v')**

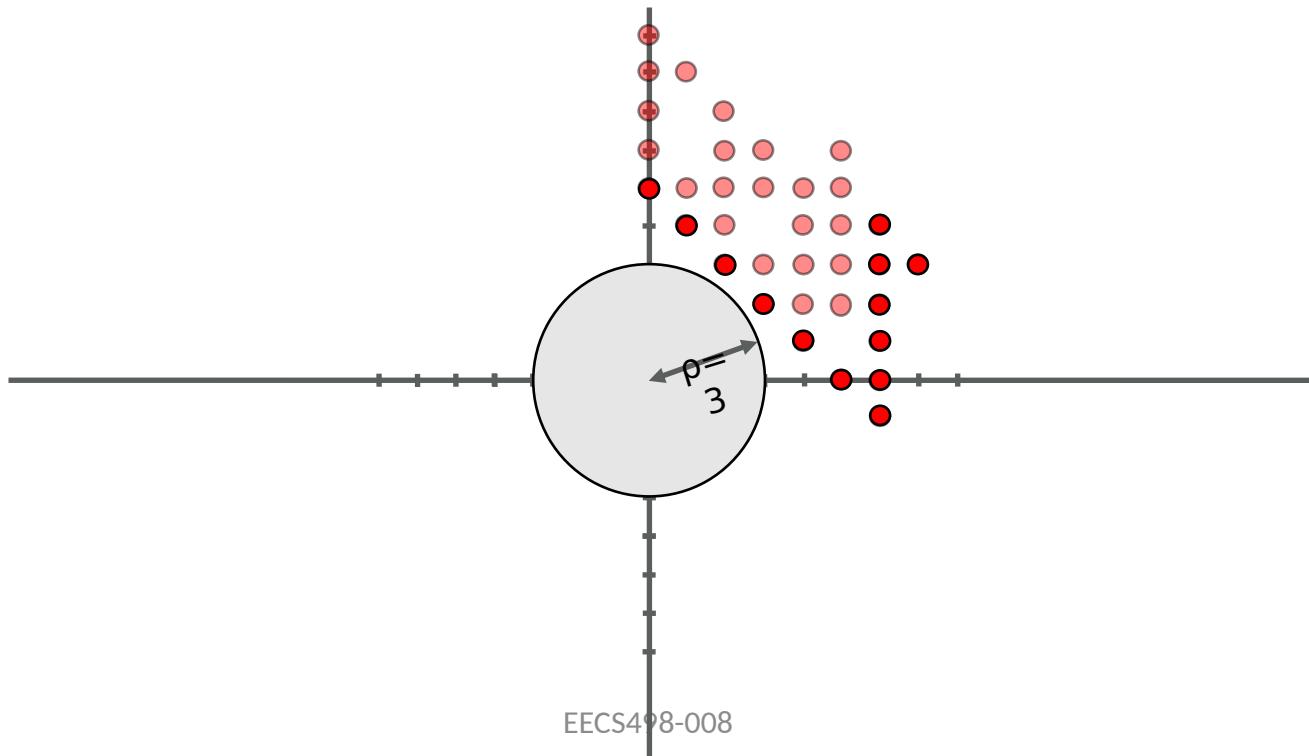
Proving the Crawler

Can the crawler ever fall in the hole?



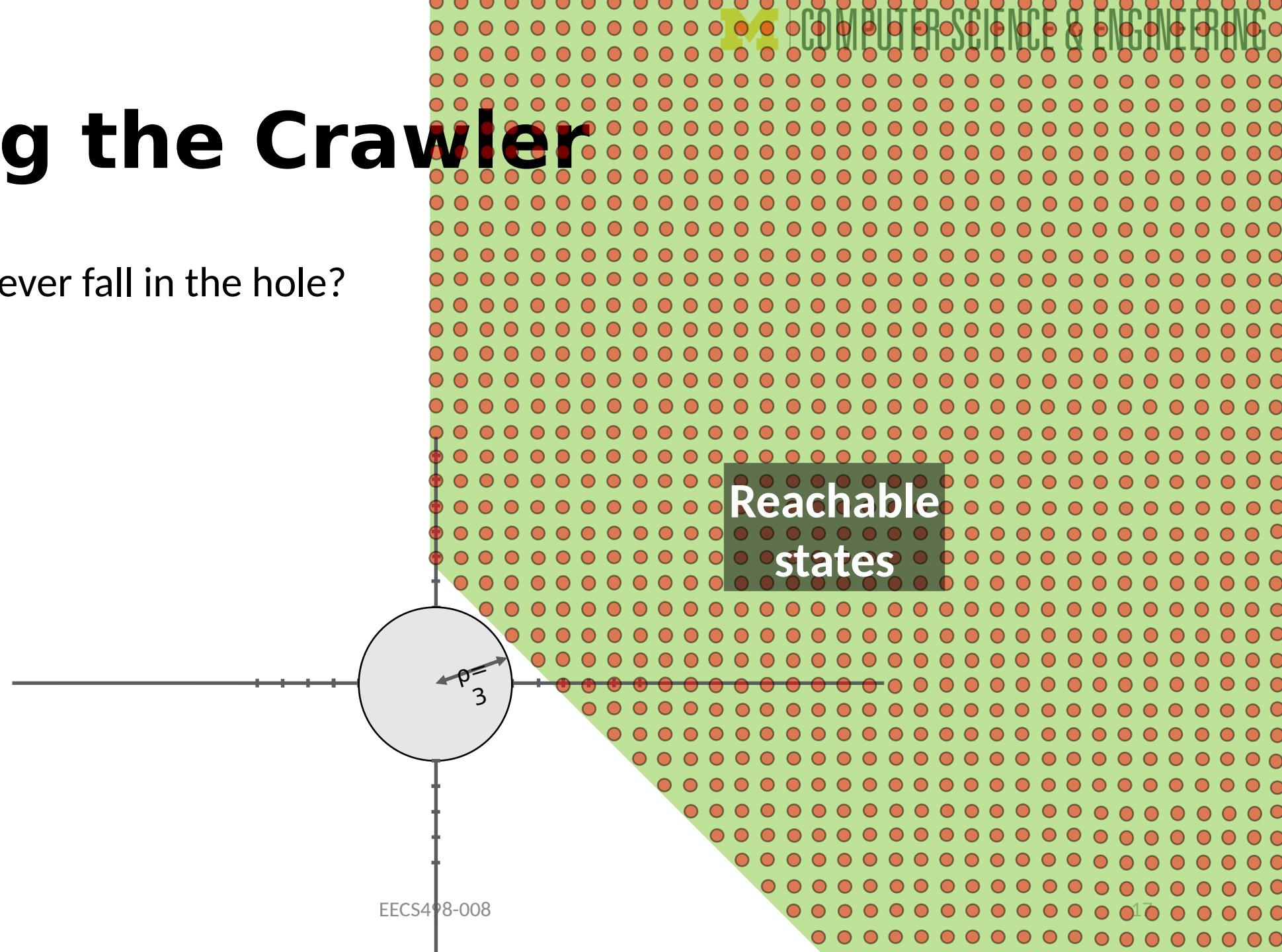
Proving the Crawler

Can the crawler ever fall in the hole?



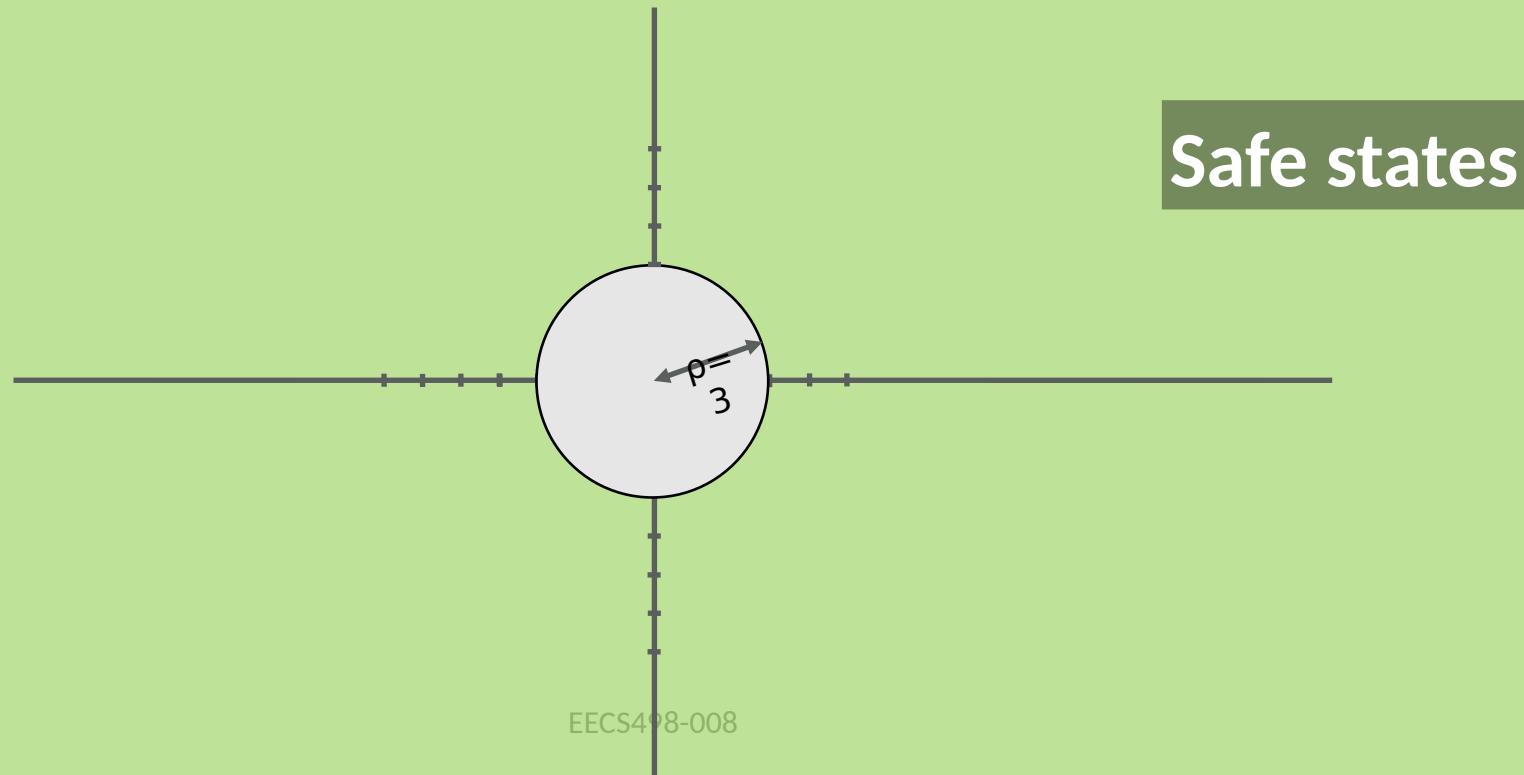
Proving the Crawler

Can the crawler ever fall in the hole?



Naïve safety proof

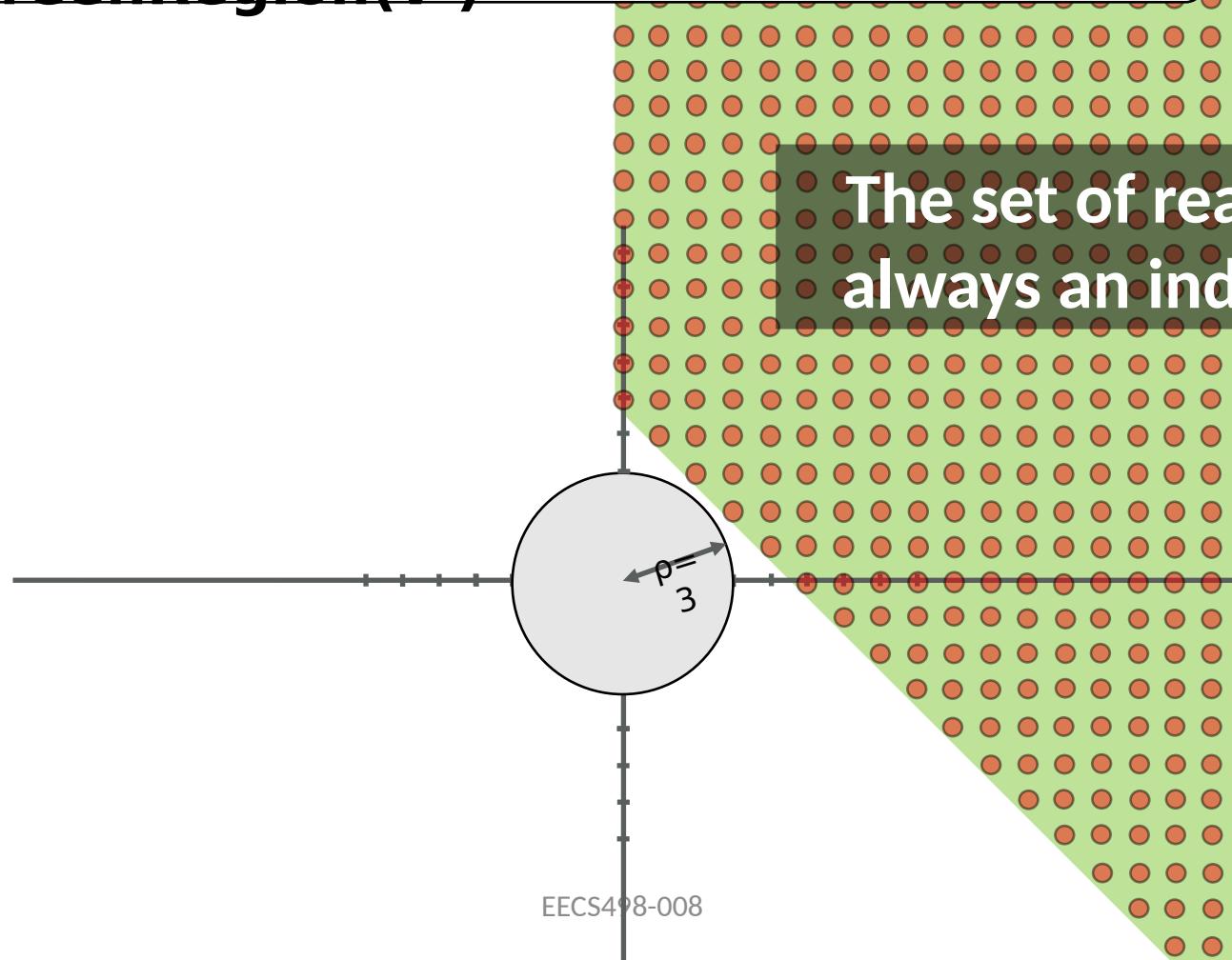
**Safe(v) && Next(v, v')
==> Safe(v')**

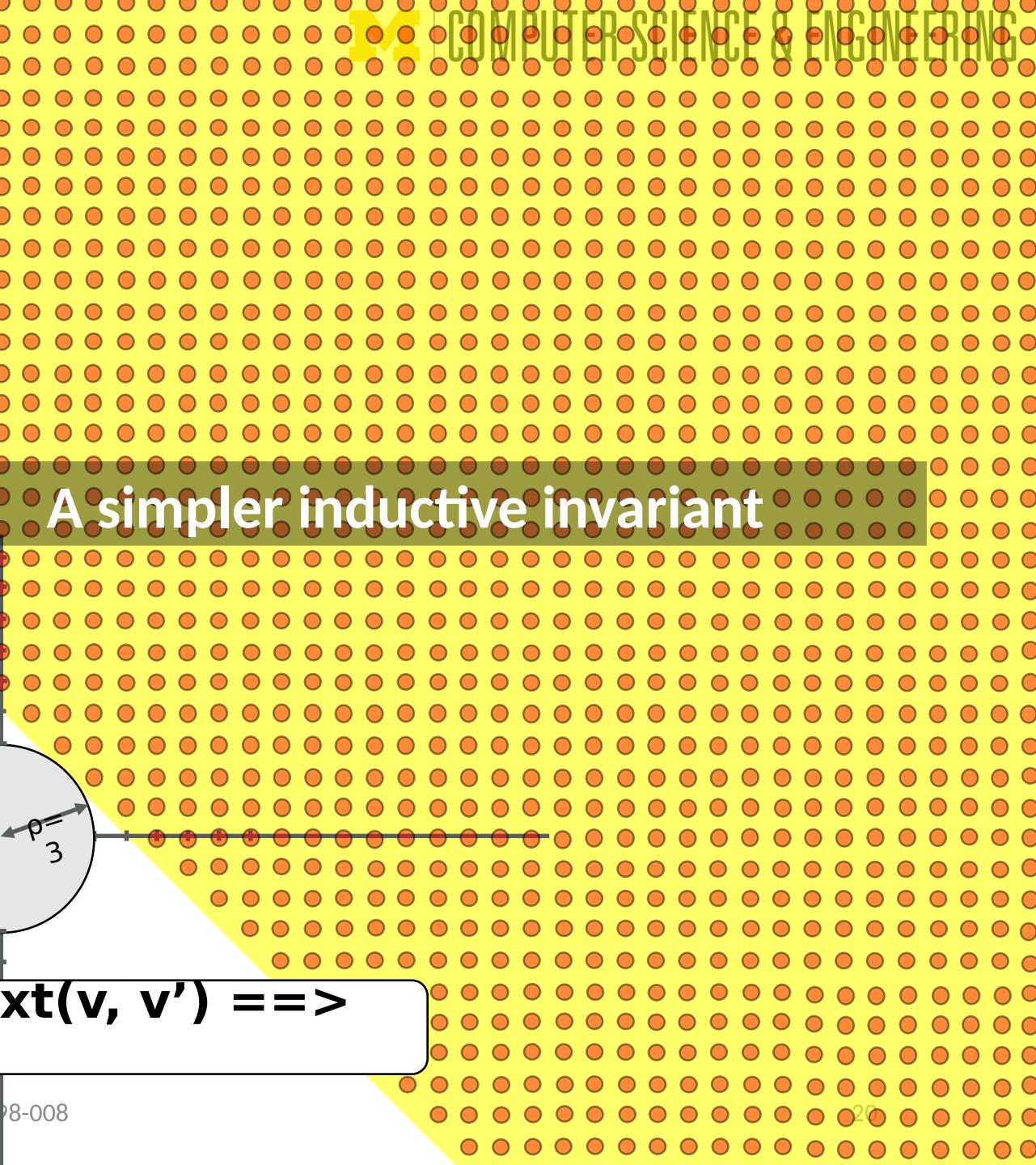


Safety proof using a stronger invariant

**InGreenRegion(v) && Next(v, v') ==>
InGreenRegion(v')**

The set of reachable states is
always an inductive invariant





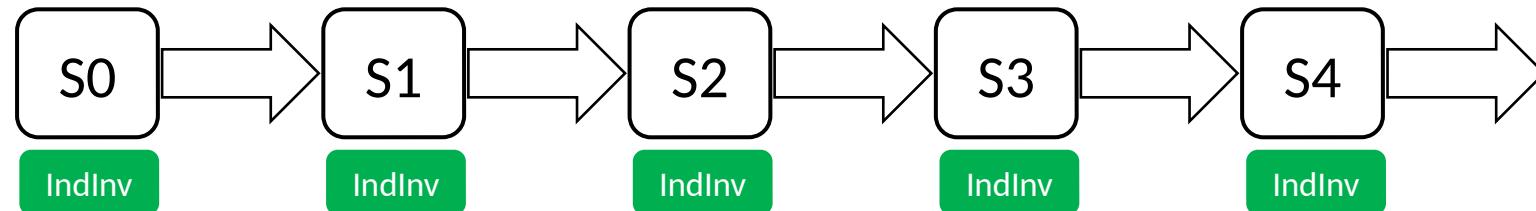
**InYellowRegion(v) && Next(v, v') ==>
InYellowRegion(v')**

Proving safety with Inductive invariants

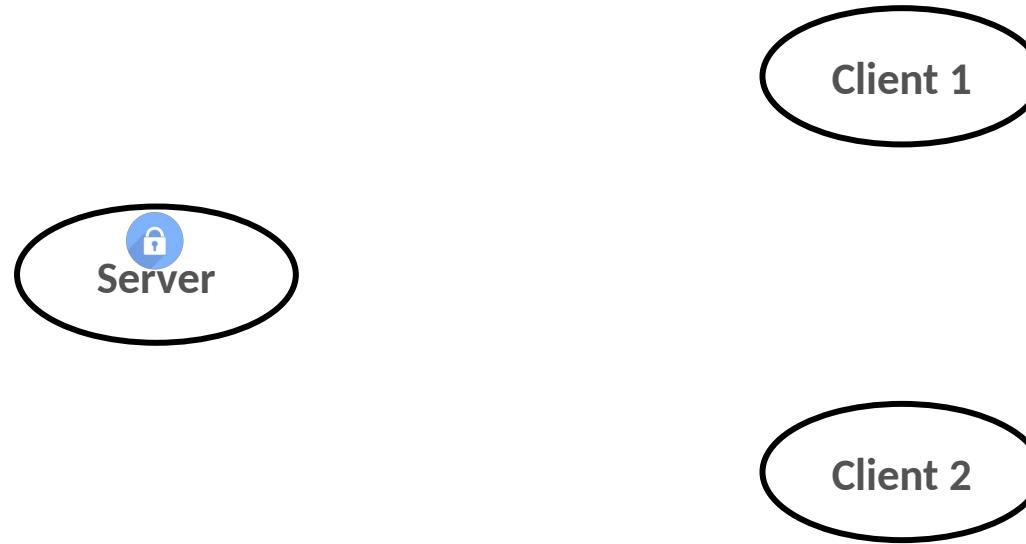
IndInv(v) ==> Safety(v)

Init(v) ==> IndInv(v)

**IndInv(v) && Next(v, v')
==> IndInv(v')**



Example: lock server



Safety property: $\neg(C1 \wedge C2)$

Both clients cannot hold the lock at the same time

Example: lock server

