Last in class lecture - Fall 2020 Quadratic program (QP)

Useful Fact about QPs

We consider the QP

$$x^* = \underset{x \in \mathbb{R}^m}{\arg \min} \quad \frac{1}{2} x^{\top} Q x + q x$$

$$A_{in} x \leq b_{in}$$

$$A_{eq} x = b_{eq}$$

$$lb \leq x \leq ub$$

$$(11.55)$$

and assume that Q is symmetric $(Q^{\top} = Q)$ and **positive definite**^a $(x \neq 0 \implies x^{\top}Qx > 0)$, and that the subset of \mathbb{R}^m defined by the constraints is non empty, that is

$$C := \{ x \in \mathbb{R}^m \mid A_{in}x \leq b_{in}, \ A_{eq}x = b_{eq}, \ lb \leq x \leq ub \} \neq \emptyset.$$

$$(11.56)$$

Then x^* exists and is unique.

$$\frac{\min_{x \in \mathbb{R}^{n}} \frac{1}{2} x^{T} Q x + q x + c}{A_{in} x \leq b_{in}}$$

$$A_{eq} x = b_{eq}$$

$$C_{b} \leq 2 \leq U_{b}$$

$$Q^{T} = Q \quad \text{Symmetric}, \quad x^{T} Q x > 0$$

$$x \neq 0$$

 $[^]a\mathrm{Positive}$ definite matrices are treated in Chapter A.3.

Example 1:

$$J(x_1, x_2) = (x_1 - 2) + (x_2 - 1)$$
 $z^{opt} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$
 $J(x) = x_1^2 + 4 - 4x_1 + x_2^2 + 1 - 2x_2$
 $= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 4 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} +$
 $\Rightarrow J(x) = 2^T Q x + 9 x + C$

Constant

 $Q = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, q = \begin{bmatrix} -4 & -2J \\ -2J \end{bmatrix}, C = 5$

Remark:

i) max $f(x) = max$ $f(x) + C$

ii) max $f(x) = max$ $f(x) + C$

iii) max $f(x) = max$ $f(x) = -C$
 $f(x) = -C$

$$\begin{array}{c}
x_{1} + 2x_{2} \leqslant 12 \\
3x_{1} + 3x_{2} \leqslant 25
\end{array}$$

$$\begin{array}{c}
x_{1} \leqslant 7 \\
x_{2} \leqslant 5 \\
x_{1} \geqslant 0
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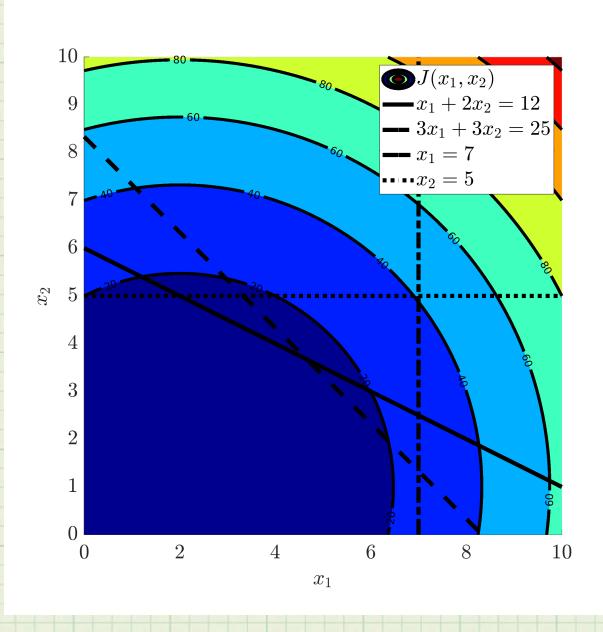
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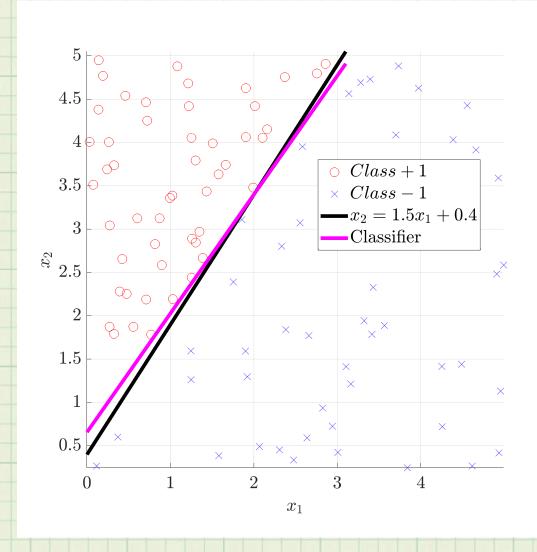
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Contour plot

Example 2: Man-margin Classifier



each
$$\angle or o$$
 is a data point xi
 $x_i \in \mathbb{R}^2$ (inpues), labels are ± 1 ,

 $y_i \in \{-1, +1\}$ (target or output).

Data set
$$D = \{(x_i, y_i)\}_{i=1}^n$$

$$a^Tx + b = 0 \rightarrow w^Tx = 0$$

$$V := \begin{bmatrix} a \\ b \end{bmatrix}, x = \begin{bmatrix} x \\ 1 \end{bmatrix}$$

$$win \frac{1}{2} \quad WW1^2$$

$$s.t. \quad w^Tx_i > 1 \quad \text{if } y_i = 1$$

$$w^Tx_i < -1 \quad \text{if } y_i = 1$$

$$w^Tx_i < -1 \quad \text{if } y_i = 1$$

$$y = 1$$

$$x = 1$$

$$y = 1$$











