
SDK Installation

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Software and Controls Group

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Contents

1	Development Platform	1
2	Server Configuration	2
2.1	Required Hardware	2
2.2	Operating System	2
2.2.1	Fedora 28 Server	2
2.3	Repository Configuration	6
2.4	Package List	7
2.5	Node Installation	7
2.6	MongoDB Configuration	7
2.7	Ethercat Configuration	8
2.8	Network Time Protocol Configuration	9
2.9	Precision Time Protocol Configuration (optional)	9
3	Software Development Kit (SDK)	10
4	Operations Workstation Configuration (optional, MacOS only)	12
4.1	Operating System	12
4.2	Packages	12
4.3	Python Installation	12
4.4	Node Installation	13
4.5	SDK Installation	13
5	Next Steps	14

DEVELOPMENT PLATFORM

The development platform is no longer distributed as a standalone ISO file. Instead, the following guide is provided to assist with hardware, operating system and third-party software configuration required for running the OCS SDK. Some key areas, such as disk partitioning, user authentication and NFS mounting of home directories, depend on individual factors at each partner institution and should therefore be considered examples only.

Benefits of this approach, versus distributing the complete ISO, include the ability to support different network, hardware and software platforms used for software development by different partner institutions, as well as allowing for separate upgrade schedules for the Development Platform and Software Development Kit without affecting ongoing subsystem software development.

Note: At GMTO, these instructions are formalized using Kickstart files and installed via the network using tools such as Cobbler. The GMTO DevOps team can provide assistance in setting up a similar system for development at partner institutions, if required.

The Observatory Control System (OCS) is designed to be a distributed system with device control components running on real-time computers, connected to common services and user interface components via the control network.

For device control systems, the following operating systems are supported:

- Fedora server

For user interfaces, the following operating systems are supported:

- MacOS

Future versions of the SDK will only support CentOS and MacOS (only for the UI framework). Fedora has a very short release and support cycle (6 months and 18 months respectively), which is not ideal for a platform that requires significant stability over long periods of time.

SERVER CONFIGURATION

Servers are used for developing, running and testing device control software and core services. When real-time communication with hardware is required, the real-time kernel should be installed and configured. The following guidelines for creating a server should be tailored according to its intended purpose.

2.1 Required Hardware

Minimum hardware requirements for development machines:

- Intel Pentium 4 or higher, 2 GHz CPU
- 1 GB Memory
- 20 GB Hard drive

Typical GMT OCS development machine specs:

- Intel Xeon E3 or higher, 3.2 GHz CPU
- 4 - 8 GB Memory
- 120 - 250 GB Hard drive

2.2 Operating System

Install the Operating System using these instructions:

2.2.1 Fedora 28 Server

The ISO file can be downloaded from the Fedora website: https://download.fedoraproject.org/pub/fedora/linux/releases/28/Server/x86_64/iso/

Alternatively, download the file directly from the terminal:

```
$ wget https://download.fedoraproject.org/pub/fedora/linux/releases/  
↪28/Server/x86_64/iso/Fedora-Server-dvd-x86_64-28-1.1.iso
```

Install the operating system on the development machine by either creating a bootable USB drive or via network installation using tools such as Cobbler and Kickstart. Other options include running Fedora 28 in a Virtual Machine or Docker Containers, however, the use of virtualization and its impact on connecting to actual hardware has not been fully tested.

Warning: The real-time Linux kernel requires the root partition to be an **ext4** file system. Please ensure that this is configured correctly in the disk partitioning settings.

2.2.1.1 Preparing USB for Installation

Full instructions for downloading Fedora 28 and preparing various types of boot media in different environments can be found here: https://docs.fedoraproject.org/en-US/fedora/f28/install-guide/install/Preparing_for_Installation/index.html

Alternatively, the following command-line instructions may be used on OSX or Linux:

Warning:

- The USB drive needs a minimum capacity of 3GB
- Ensure that you properly identify the device assigned to the USB drive
- The entire USB drive will be erased!

OSX - with a drive on `/dev/disk2`

```
$ diskutil list
$ sudo diskutil unmountDisk /dev/disk2
$ sudo dd bs=4m if=Fedora-Server-dvd-x86_64-28-1.1.iso of=/dev/rdisk2
```

Linux - with a drive on `/dev/sdb`

```
$ sudo umount /dev/sdb*
$ sudo dd bs=4M if=Fedora-Server-dvd-x86_64-28-1.1.iso of=/dev/sdb
```

2.2.1.2 Booting from Prepared USB

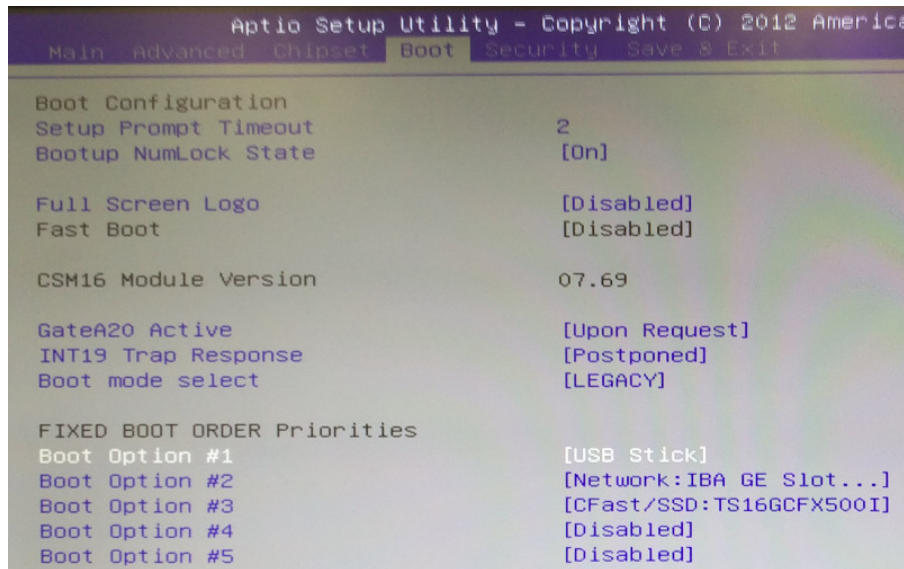
Full instructions for booting from prepared Fedora 28 installation media can be found here: https://docs.fedoraproject.org/en-US/fedora/f28/install-guide/install/Booting_the_Installation/

The following instructions are applicable to the HDK:

1. Configure your BIOS to boot from USB

This step is vendor specific. On the Beckhoff Industrial PC (IPC) provided with the Hardware Development Kit (HDK):

- 1.1 Insert the USB drive into the IPC and power up the system
- 1.2 Enter the BIOS settings by pressing the key.
- 1.3 In the Boot panel, set Option #1 to [USB Stick].



1.4 Select 'Save & Exit'; the system will reboot

2. OS Installation

Warning:

- Your system drive will be reformatted and erased! For HDK, **do not** use the Beckhoff CFast card with TwinCAT3!

2.1 Once the system is back up, select the 'Install Fedora 28' option

2.2.1.3 Installation (Using Anaconda)

The installation for the Server version of Fedora may be completed using the Anaconda Installer in either Graphical or Text Mode. Full instructions can be found here: https://docs.fedoraproject.org/en-US/fedora/f28/install-guide/install/Installing_Using_Anaconda/

Note: To boot the installer in text mode, add the boot option `inst.text` to the command line boot menu and select option 2 (Use text mode) from the subsequent menu. Text mode has some limitations, such as not being able to select a custom partitioning scheme.

Ensure that all items listed are configured appropriately, ready for installation.

```

1) Start UNC
2) Use text mode

Please make a selection from the above ['c' to continue, 'q' to quit, 'r' to
refresh]: 2
=====
Installation
=====
1) [x] Language settings                2) [!] Time settings
   (English (United States))           (Timezone is not set.)
3) [!] Installation source              4) [!] Software selection
   (Processing...)                     (Processing...)
5) [!] Installation Destination         6) [x] Network configuration
   (No disks selected)                 (Wired (enp0s3) connected)
7) [!] Root password                   8) [!] User creation
   (Password is not set.)              (No user will be created)

Please make a selection from the above ['b' to begin installation, 'h' to help,
'q' to quit, 'r' to refresh]: _
anaconda1:main* 2:shell 3:log 4:storage-log >Switch tab: Alt+Tab | Help: F1

```

1. **Language settings** - English (US)
2. **Time settings** - Select the appropriate Time Zone (for example America/Los_Angeles)
3. **Installation source** - Local media (CD/DVD)
4. **Software Selection** - Default packages are sufficient for now
5. **Installation Destination** - Select the appropriate drive for installation and whether to use the entire drive. Custom partitioning can be configured here as well. The default Partition Scheme to use is LVM. Ensure that the file system is set to `ext4` for the RT kernel to work.
6. **Network Configuration** - At least one interface with internet access should be configured
7. **Root Password** - Set a secure root password
8. **User Creation** - Create the default user. The default user for a typical GMT development environment is `gmt0`. This user should have Administrator access.

Warning: The real-time Linux kernel requires the root partition to be an **ext4** file system. Please ensure that this is configured correctly in the disk partitioning settings.

The following extract from the GMTO kickstart file shows settings used for automated PXE installs:

```

# -- Installation Parameters -----
↪-----
install                               # Install, instead of ↪
↪Upgrade                             #
reboot                               # Reboot after ↪
↪installation                         #
text                                 # Use text mode install
keyboard us                          # System keyboard
lang en_US                           # System language
timezone America/Los_Angeles         # System timezone
bootloader --location=mbr             # Bootloader ↪
↪configuration                       #
clearpart --all --initlabel           # Partition clearing ↪
↪information                         #
skipx                                # Skip X11 ↪
↪configuration                       #

```

```

# -- Security Settings -----
↪-----
auth --useshadow --enablemd5           # Use shadow passwords
firewall --enabled                     # Firewall_
↪configuration
selinux --disabled                    # SELinux configuration
rootpw --iscrypted $default_password_crypted # Root password

# -- User configuration -----
↪-----
user --name=gmt0 --password=gmt0 --plaintext

# -- Disk Partitioning -----
↪-----
clearpart --drives=sda                 # Remove existing_
↪partitions
zerombr                               # Clear the Master_
↪Boot Record
part /boot --label=/boot --asprimary --size=500 --fstype=ext4 --
↪ondisk=sda
part swap --recommended --ondisk=sda
part / --label=/ --fstype=ext4 --grow --ondisk=sda

```

After installation, the system will reboot. Remove the boot drive (USB drive or network mount) and select the default kernel.

[\[back to top\]](#)

Warning: If you plan to develop real-time components, the Linux kernel requires the root partition to be an **ext4** file system. Please ensure that this is configured correctly in the disk partitioning settings.

2.3 Repository Configuration

Some required RPMs are built by GMT0 and need to be downloaded from the GMT0 Yum Repository, currently hosted on Amazon Web Services.

To add the GMT repositories:

1. Add the file `/etc/yum.repos.d/gmt.repo` with the following content:

```

[gmt]
name=GMT $releasever - $basearch
baseurl=http://52.52.46.32/srv/gmt/yum/stable/$releasever/
gpgcheck=0
enabled=1

```

2. Add the file `/etc/yum.repos.d/gmt-updates.repo` with the following content:

```

[gmt-updates]
name=GMT $releasever - $basearch - Updates
baseurl=http://52.52.46.32/srv/gmt/yum/updates/$releasever/
gpgcheck=0
enabled=1

```


2.4 Package List

The following RPM packages should be installed by an Administrative user for use in the development environment:

1. Install Common OS Utilities

```
$ sudo dnf install -y xorg-x11-xauth urw-fonts wget net-tools pciutils
$ sudo dnf install -y strace rpl bash-completion sed
```

2. Install Development Tools

```
$ sudo dnf install -y autoconf automake cmake elfutils gcc gdb libtool make
$ sudo dnf install -y cpp cscope ctags gc gcc-c++ gcc-gdb-plugin glibc-devel
$ sudo dnf install -y glibc-headers kernel-headers libstdc++-devel
$ sudo dnf install -y flex git libcurl-devel
$ sudo dnf install -y python3-sphinx python3-sphinx_rtd_theme
```

3. Install OCS Dependencies

```
$ sudo dnf install -y rdma librdmacm-devel boost-devel
```

2.5 Node Installation

1. Download and install **Node version 10**:

```
$ curl -sL https://rpm.nodesource.com/setup_10.x | sudo bash -
$ sudo dnf install -y nodejs
```

2. Install necessary node packages:

```
$ sudo npm install -g coffeescript webpack webpack-cli raw-loader
```

2.6 MongoDB Configuration

1. Install the necessary packages:

```
$ sudo dnf install -y mongodb mongodb-server
```

2. Configure the firewall

```
$ sudo firewall-offline-cmd --direct --add-rule ipv4 filter INPUT 0 -p tcp --
->dport 27017 -j ACCEPT
```

2. Enable the MongoDB service

```
$ sudo systemctl enable mongod
$ sudo systemctl start mongod
```

3. Check that the MongoDB service is up

```
$ sudo systemctl status -l mongod
```

2.7 Ethercat Configuration

EtherCAT is a high-speed fieldbus communication system used for real-time control. The following configuration steps should be used as a guide when configuring EtherCAT communications.

1. Install the real-time kernel and relevant packages

```
$ sudo dnf install -y --nogpgcheck kernel-3.14.73-rt78.x86_64 ethercat-devel
```

Warning: This Linux kernel requires the root partition to be an **ext4** file system. Otherwise, your machine will not boot.

2. Select the Ethernet interface to be used for EtherCAT communication (e.g. `enp4s0`) and edit the corresponding configuration file (e.g. `/etc/sysconfig/network-scripts/ifcfg-enp4s0`) to set the following options:

```
BOOTPROTO=none
ONBOOT=no
```

3. Check the Hardware Address of the selected EtherCAT network interface

```
$ ifconfig
```

4. Edit `/etc/ethercat.conf` and set the following configuration options:

```
MASTER0_DEVICE="<mac_address_1>"
MASTER0_BACKUP="<mac_address_2>" # optional line
```

where `<mac_address_1>` and `<mac_address_2>` are the two hardware addresses associated with the Ethercat network interface communicating with the Ethercat ring (redundant topology). If you prefer using a linear topology (non redundant), comment or remove the second line (`MASTER0_BACKUP="<mac_address_2>"`).

5. Edit `/usr/lib/systemd/system/ethercat.service` and uncomment the following line:

```
Before=network.service
```

6. Reboot into the RT Kernel, if you're not in it already.

7. Enable the Ethercat service

```
$ sudo systemctl enable ethercat
$ sudo systemctl start ethercat
```

8. Edit `/etc/security/limits.d/99-realtime.conf` and add the following options:

```
@realtime - rtprio 99
@realtime - memlock unlimited
```

9. Add a new group and add the "gmto" user to it.

```
$ sudo groupadd -f -g 2001 realtime
$ sudo usermod --groups realtime gmto
```

8. Test the Ethercat configuration

```
$ ethercat master
$ ethercat slaves
```

If the “ethercat master” command does not produce the correct output, ensure that you’re currently running the real-time kernel. If the “ethercat slaves” command produces no output, check that the ethernet cable is connected to the correct port as configured above.

2.8 Network Time Protocol Configuration

For general network timekeeping, use NTP, unless Precision Time Protocol is required.

1. Install the necessary packages:

```
$ sudo dnf install -y chrony
```

2. Enable the NTP Service

```
$ sudo systemctl enable chronyd
```

2.9 Precision Time Protocol Configuration (optional)

1. Install the necessary packages:

```
$ sudo dnf install -y linuxptp
```

2. Edit `/etc/ptp4l.conf` and add the following options:

```
[global]
slaveOnly      1
verbose        1
time_stamping  software
summary_interval 6
[enp3s0]
```

where `[enp3s0]` should be set to the interface to use for PTP.

3. Edit `/etc/sysconfig/phc2sys` and add the following options:

```
OPTIONS="-a -r -u 60"
```

4. Edit `/etc/sysconfig/ptp4l` and add the following options:

```
OPTIONS="-f /etc/ptp4l.conf -i enp3s0"
```

5. Configure access through the firewall

```
$ sudo firewall-offline-cmd --direct --add-rule ipv4 filter INPUT 0 -p udp --
→dport 319:320 -j ACCEPT
```

6. Enable the ptp service

```
$ sudo systemctl enable ptp4l
```

SOFTWARE DEVELOPMENT KIT (SDK)

The Software Development Kit is distributed as a TAR file and can be downloaded from the GMTO release server.

The SDK should be installed in a **Global GMT Software Location**, defined by the GMT_GLOBAL environment variable (default value: /opt/gmt). A **Local Working Directory**, defined by the GMT_LOCAL variable, is used as a unique workspace for individual developers. The local working directory typically resides underneath the /home/<username> directory.

1. Download the latest SDK distribution:

```
$ wget http://52.52.46.32/srv/gmt/releases/sdk/linux/gmt-sdk.tar.gz
```

2. Extract the TAR file in the /opt directory, into a new folder for the latest release:

```
$ sudo mkdir /opt/gmt_release_1.6.1
$ sudo tar -xzvf gmt-sdk.tar.gz -C /opt/gmt_release_1.6.1
```

3. Create a symbolic link from the **Global GMT Software Location** to the latest release:

```
$ sudo ln -sf /opt/gmt_release_1.6.1 /opt/gmt
```

4. Create a **Local Working Directory**

```
$ mkdir <local_working_dir>
```

where <local_working_dir> is in the current users' home directory, for example ~/work. The GMT software modules developed by the user are created in this folder.

5. Add the following lines to your .bash_profile (or .kshrc or .bashrc depending on your preferred shell)

```
$ export GMT_GLOBAL=/opt/gmt
$ export GMT_LOCAL=<local_working_dir>
$ source $GMT_GLOBAL/bin/gmt_env.sh
```

This will ensure that the environment variables are correctly configured when opening a new terminal. Please log out and back in for the changes to take effect. To configure the environment for the current shell, run the commands manually.

6. Check the values of the environment variables:

```
$ gmt_env
```

7. Install Node Modules

```
$ cd $GMT_GLOBAL
$ npm install

$ cd $GMT_LOCAL
$ cp $GMT_GLOBAL/package.json ./
$ npm install
```

Install global node modules for *Webpack* and *Coffeescript*.

```
$ sudo npm install -g coffeescript webpack webpack-cli coffee-loader
```

8. Initialize the Development Environment:

```
$ cd $GMT_LOCAL
$ gds init
```

The correct folders will be created in the \$GMT_LOCAL directory for use when compiling and running modules.

9. Create a **modules** directory in \$GMT_LOCAL

```
$ cd $GMT_LOCAL
$ mkdir modules
```

10. Create the **bundles.coffee** and **ocs_local_bundle.coffee** files, defining the local modules under development

These files may be copied from \$GMT_GLOBAL and then edited to reflect the developer's configuration.

```
$ mkdir $GMT_LOCAL/etc/bundles
$ cp $GMT_GLOBAL/etc/bundles/bundles.coffee $GMT_LOCAL/etc/bundles/
$ cp $GMT_GLOBAL/etc/bundles/ocs_local_bundle.coffee $GMT_LOCAL/etc/bundles/
```

Edit **bundles.coffee** to point to the **ocs_local_bundle.coffee** file

```
module.exports =
  ocs_local_bundle: {scope: "local", desc: "GMT iSample and HDK bundle"}
```

Edit **ocs_local_bundle.coffee** to include the **isample** and **HDK** modules, or other modules that you are working on

```
module.exports =
name:      "local"
desc:      "List of local development modules"
elements:
  isample_dcs: { active: true, test: false, developer: 'gmto', domain:
    ↪ 'idcs' }
  hdk_dcs:     { active: true, test: false, developer: 'gmto', domain:
    ↪ 'idcs' }
```

11. Build all model files from modules in your **ocs_local_bundles** definition using **webpack**. For example:

```
$ cd $GMT_LOCAL/modules/ocs_hdk_dcs/model
$ webpack
$ cd $GMT_LOCAL/modules/ocs_isample_dcs/model
$ webpack
```

OPERATIONS WORKSTATION CONFIGURATION (OPTIONAL, MACOS ONLY)

The OCS User Interface needs to be run on a system with sufficient graphical rendering capability. At the moment, the Real-time kernel used for device control systems running EtherCAT does not contain the graphics modules necessary to support the user interface. It is recommended to run the user interface in a Mac, connected to the DCS via the network. Future releases will include support for Linux workstations.

4.1 Operating System

Apple Mac systems have the operating system already installed. The User Interface has been tested on the following versions of MacOS:

- MacOS High Sierra
- MacOS Mojave

4.2 Packages

There are very few external packages that are not already installed in MacOS. The application Homebrew can be used to install these:

1. Install Homebrew

```
$ /usr/bin/ruby -e "$(curl -fsSL https://raw.githubusercontent.com/Homebrew/  
→install/master/install)"
```

More information can be found on the Homebrew website: <<https://brew.sh/>>

2. Install common utilities

```
$ brew install wget
```

4.3 Python Installation

1. Check whether Python3 is installed

```
$ python3 --version
```

2. Install Python3, if not already installed

```
$ brew install python3
```

4.4 Node Installation

1. Install Node

Follow the instructions here <https://nodesource.com/blog/installing-nodejs-tutorial-mac-os-x/>

4.5 SDK Installation

1. Follow steps on section *Software Development Kit (SDK)* for installing the SDK.
2. Create a **local javascript library folder** in order to create built bundles for your model files. This folder is also used to install upgraded version of the library.

```
$ mkdir -p $GMT_LOCAL/lib/js
```

3. Copy UI JavaScript lib files to \$GMT_LOCAL/lib/js/

```
$ cp ocs_ui_fwkw_elements.js ocs_ui_fwkw_widgets.js ocs_ui_fwkw.js $GMT_LOCAL/  
→lib/js/
```

4. Systems that run the User Interface require compiled model files to be used by the Navigator application.

Build all model files from modules in your ocs_local_bundles definition using webpack. For example:

```
$ cd $GMT_LOCAL/modules/ocs_hdk_dcs/model  
$ webpack  
$ cd $GMT_LOCAL/modules/ocs_isample_dcs/model  
$ webpack
```

NEXT STEPS

To start using the SDK with the Hardware Development Kit (HDK), instructions can be found here: [hdk_example](#).

To run the Navigator application and start using the UI framework, see the UI Framework guide: [ui_fw](#).

[\[back to top\]](#)