

A BAYESIAN MODEL FOR DATA FLOW: BIKEMI

Andrea De Gobbis, Lorenzo Ghilotti, Giorgio Meretti

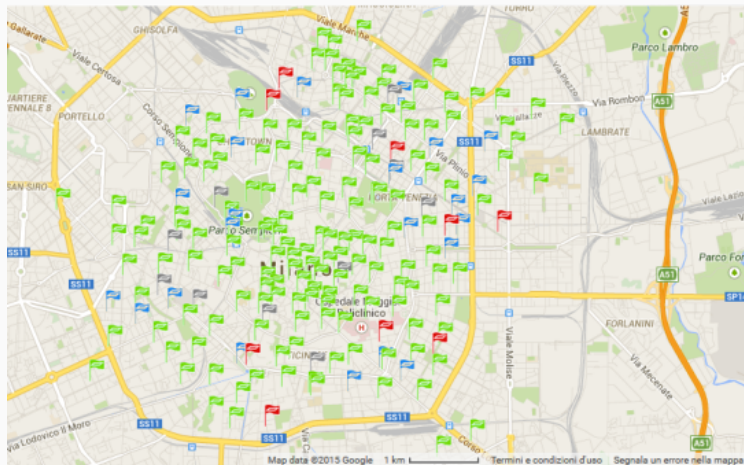
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Politecnico di Milano

What we are working on

The BikeMi stations net in Milan is rather large and travelled every day.

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The two perspective of the problem

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Our work is structured in two parts:

Global model

The total volume of travels in a specific day Y_t without considering the graph structure. This results in a single time series.

Network model

For each node, the analysis focuses on in and out bikes flow for specific time slots. The dimensionality is much higher.

MODEL

$$Y_t | \lambda_t \stackrel{iid}{\sim} \text{Po}(\lambda_t)$$

$$\log \lambda_t = \boldsymbol{\beta}^T \mathbf{z}_t$$

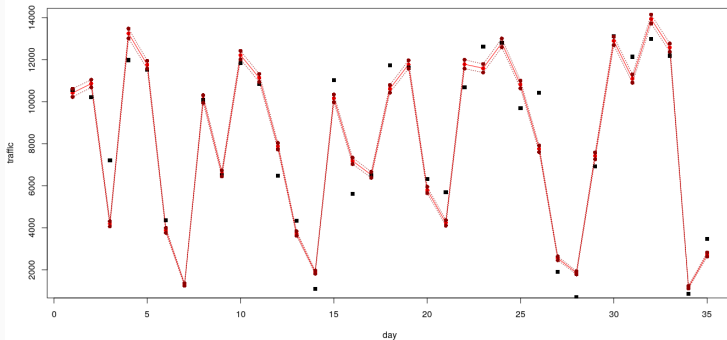
PRIOR

$$\beta_i \stackrel{iid}{\sim} \mathcal{N}(0, \sigma_\beta^2)$$

Loglinear GLM: Poisson likelihood

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comparison between actual and predicted Y



Negative Binomial distribution

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$X \sim \text{NegBin}(p, r)$ if :

$$f(k; p, r) = \frac{\Gamma(k+r)}{k! \Gamma(r)} p^k (1-p)^r, \quad k = 0, 1, 2, \dots$$

$$\mathbb{E}[X] = \mu = \frac{r(1-p)}{p} \quad \text{Var}(X) = \frac{r(1-p)}{p^2}$$

Moreover:

$$p = \frac{r}{r + \mu}$$

Loglinear GLM: NegBin likelihood (1)

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MODEL

$$Y_t | p_t, r \stackrel{ind}{\sim} \text{NegBin}(p_t, r)$$

$$p_t = \frac{r}{r + \mu_t}$$

$$\log \mu_t = \boldsymbol{\beta}^T \mathbf{z}_t$$

PRIORS

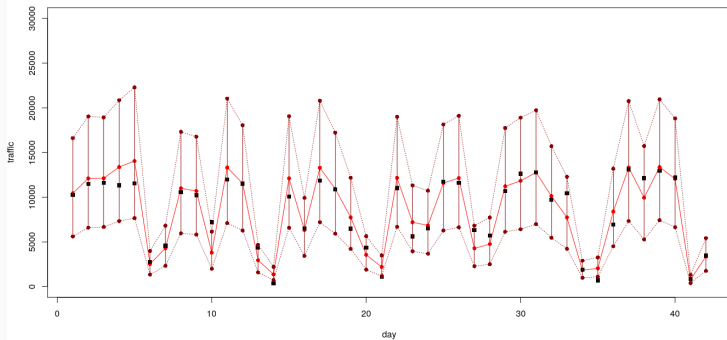
$$\boldsymbol{\beta} \sim \mathcal{N}_p(\mathbf{0}, \sigma_{\boldsymbol{\beta}}^2 \mathbf{I})$$

$$r \sim \mathcal{U}(0, 50)$$

Loglinear GLM: NegBin likelihood (1)

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comparison between actual and predicted Y



MODEL

$$Y_{tj} | p_{tj}, r_j \stackrel{\text{ind}}{\sim} \text{NegBin}(p_{tj}, r_j) \quad j = 1 : wday, j = 2 : wend$$

$$p_{tj} = \frac{r_j}{r_j + \mu_{tj}}$$

$$\log \mu_{tj} = \beta_1 + \beta_2 R_t + \beta_3 T_t + \theta_j$$

PRIORS

$$\beta_i | \tau_i \stackrel{\text{ind}}{\sim} \mathcal{N}(0, \tau_i) \quad i = 1, 2, 3$$

$$\tau_i \stackrel{\text{ind}}{\sim} \text{Gamma}(2, 10)$$

$$\theta_j | \tilde{\tau}_j \stackrel{\text{ind}}{\sim} \mathcal{N}(0, \tilde{\tau}_j) \quad j = 1, 2$$

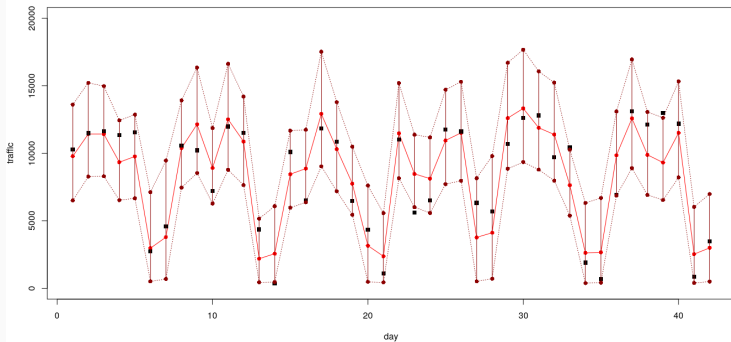
$$\tilde{\tau}_j \stackrel{\text{ind}}{\sim} \text{Gamma}(2, 10)$$

$$r_j \stackrel{\text{ind}}{\sim} \text{Unif}(0, 50) \quad j = 1, 2$$

Loglinear GLM: NegBin likelihood (2)

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comparison between actual and predicted Y



Main ingredients of **BSTS** model:

- locally linear trend μ_t ,
- periodicity γ_t ,
- autoregressive component ρ_t ,
- regression $\beta^T \mathbf{z}$.

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Standard BSTS

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MODEL

$$Y_t = \mu_t + \gamma_t + \rho_t + \beta^T \mathbf{z}_t + \tau_\epsilon^{-\frac{1}{2}} \tilde{\epsilon}_t$$

$$\mu_t = \mu_{t-1} + \delta_{t-1} + \tau_\eta^{-\frac{1}{2}} \tilde{\eta}_t$$

$$\delta_t = \delta_{t-1} + \tau_v^{-\frac{1}{2}} \tilde{v}_t$$

$$\gamma_t = \sum_{i=1}^{S-1} \gamma_{t+i-S} + \tau_w^{-\frac{1}{2}} \tilde{w}_t$$

$$\rho_t = \alpha \rho_{t-1} + \tau_u^{-\frac{1}{2}} \tilde{u}_t$$

$$\tilde{\epsilon}_t, \tilde{\eta}_t, \tilde{v}_t, \tilde{w}_t, \tilde{u}_t \stackrel{iid}{\sim} \mathcal{N}(0, 1)$$

INITIAL CONDITIONS

$$\mu_0 \sim \mathcal{N}(m, \tau_\eta) \quad m \text{ hpm}$$

$$\delta_0 \sim \mathcal{N}(d, \tau_v) \quad d \text{ hpm}$$

$$\gamma_{0:(2-S)} \sim \mathcal{N}_{S-1}(\mathbf{g}, \tau_w \mathbf{I}) \quad \mathbf{g} \text{ hpm}$$

$$\rho_0 \sim \mathcal{N}(r, \tau_u) \quad r \text{ hpm}$$

PRIORS

$$\beta \sim \mathcal{N}_p(\mathbf{0}, \tau_b \mathbf{I}) \quad \tau_b \text{ hpm}$$

$$\alpha \sim \mathcal{N}(a, \tau_a) \quad a, \tau_a \text{ hpm}$$

$$\tau_\epsilon \sim \text{Unif}(a_\epsilon, b_\epsilon) \quad a_\epsilon, b_\epsilon \text{ hpm}$$

$$\tau_\eta \sim \text{Unif}(a_\eta, b_\eta) \quad a_\eta, b_\eta \text{ hpm}$$

$$\tau_v \sim \text{Unif}(a_v, b_v) \quad a_v, b_v \text{ hpm}$$

$$\tau_w \sim \text{Unif}(a_w, b_w) \quad a_w, b_w \text{ hpm}$$

$$\tau_u \sim \text{Unif}(a_u, b_u) \quad a_u, b_u \text{ hpm}$$

INDEPENDENCE

$$\{\tilde{\epsilon}_t, \tilde{\eta}_t, \tilde{u}_t, \tilde{w}_t, \tilde{v}_t, \mu_0, \delta_0, \gamma_{0:(-S+2)}, \rho_0,$$

$$\beta, \alpha, \tau_\epsilon, \tau_\eta, \tau_v, \tau_w, \tau_u\}$$

$$\text{family of } \perp \text{ real random variables}$$

Hyperparameters for BSTS

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We fix the **hyperparameters** as follows:

	τ_{ϵ}	τ_{η}	τ_v	τ_w	τ_u
a	1e-7	1e-5	1e-5	1e-5	1e-5
b	1e-4	1e-4	1e-4	1e-4	1e-3

m and g according to **frequentist stationarization**

	τ_{α}	τ_{β}	r	d
value	1e-5	1e-5	0	0

4 rules for a proper evaluation

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1. performance is subject to correctness of modelling assumptions and **proper diagnostics**,
2. use codified Bayesian tools to evaluate the worth of a model from a **predictive** viewpoint,
3. in absence of strong evidence for a format let **interpretability** be the deciding factor,
4. in case of a draw in the previous points, select the **simplest** paradigm.

Some diagnostics

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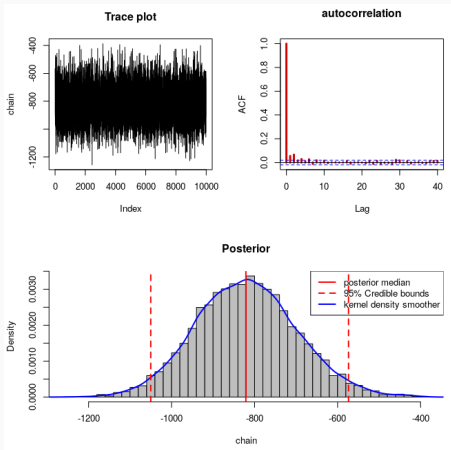


Figure 1: Diagnostics for β_1 samples

Prediction

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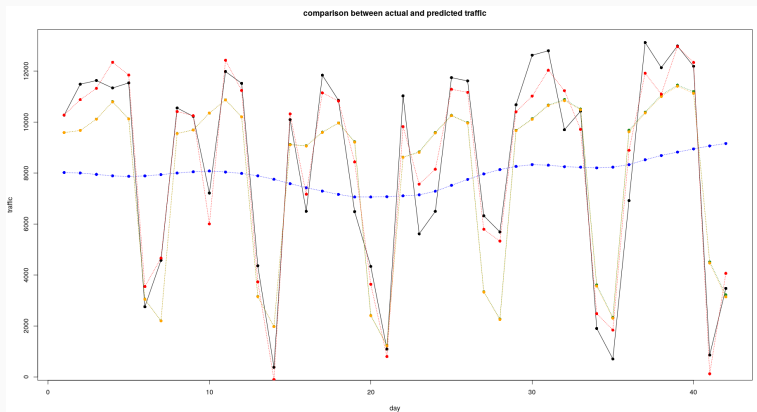


Figure 2: Sum of trend (blue), periodicity (green), autoregression (yellow) and regression (red)

Prediction

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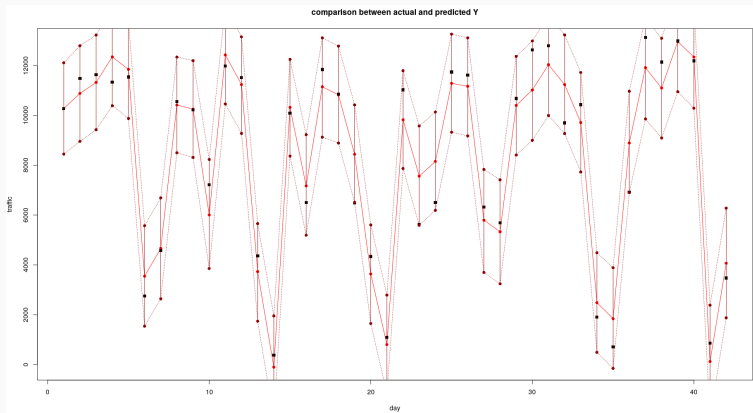


Figure 3: 90% **credibility intervals** in dark red, in black the true responses y

Without temperature

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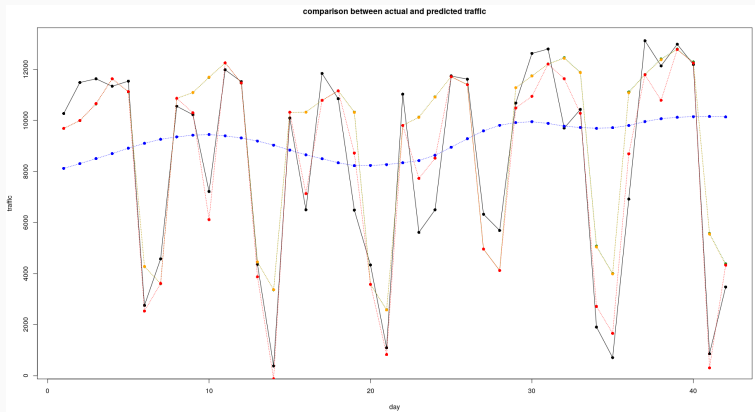


Figure 4: Sum of trend (blue), periodicity (green), autoregression (yellow) and regression (red)

Robust version

We apply the **lag operator**

$\mathcal{L}_t(\cdot) = \frac{1}{2}(\cdot)_{t-1} + \frac{1}{3}(\cdot)_{t-S} + \frac{1}{6}(\cdot)_{t-2S}$ to the trend.

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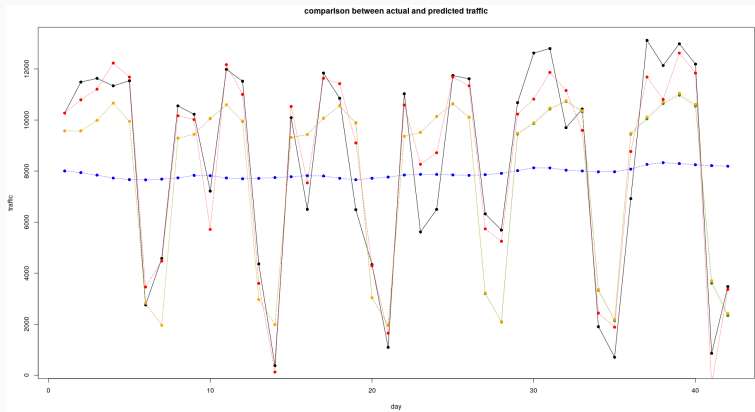


Figure 5: Cumulative action of trend (blue), periodicity (green), autoregression (yellow) and regression (red) in robust model

According to the criteria we have the following **results**:

	standard	no temperature	robust
Mean standardized residuals	0.5809041	0.6066627	0.6031869
Mean tail probabilities	0.2979543	0.298591	0.2908414
$elpd_{loo}$	-362.6	-365.4	-364.1

Future prediction

We try to predict **one week ahead**

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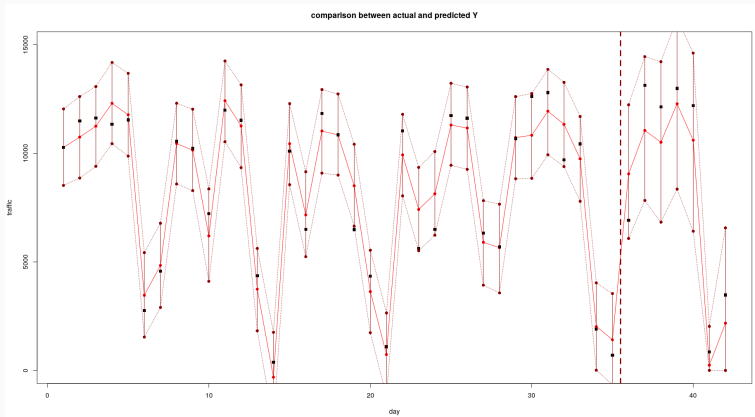


Figure 6: Predicted traffic with the model

Standard BSTS with time zones

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MODEL

$$Y_{F(t-1)+h} = \mu_t + \gamma_t + \chi_{F(t-1)+h} +$$

$$+ \beta^T \mathbf{z}_{th} + \tau_\epsilon^{-\frac{1}{2}} \tilde{\epsilon}_{F(t-1)+h}$$

$$\mu_t = \mu_{t-1} + \delta_{t-1} + \tau_\eta^{-\frac{1}{2}} \tilde{\eta}_t$$

$$\delta_t = \delta_{t-1} + \tau_v^{-\frac{1}{2}} \tilde{v}_t$$

$$\gamma_t = \sum_{i=1}^{S-1} \gamma_{t+i-S} + \tau_w^{-\frac{1}{2}} \tilde{w}_t$$

$$\chi_{F(t-1)+h} = \sum_{j=1}^{F-1} \chi_{F(t-1)+h+j-F} +$$

$$+ \tau_u^{-\frac{1}{2}} \tilde{u}_{F(t-1)+h}$$

$$\tilde{\epsilon}_{F(t-1)+h}, \tilde{\eta}_t, \tilde{v}_t, \tilde{w}_t, \tilde{u}_{F(t-1)+h} \stackrel{iid}{\sim} \mathcal{N}(0, 1)$$

INITIAL CONDITIONS

$$\mu_0 \sim \mathcal{N}(m, \tau_\eta) \quad m \text{ hpm}$$

$$\delta_0 \sim \mathcal{N}(d, \tau_v) \quad d \text{ hpm}$$

$$\gamma_{0:(2-S)} \sim \mathcal{N}_{S-1}(\mathbf{g}, \tau_w \mathbf{I}) \quad \mathbf{g} \text{ hpm}$$

$$\chi_{0:(2-F)} \sim \mathcal{N}_{F-1}(\mathbf{c}, \tau_u \mathbf{I}) \quad \mathbf{c} \text{ hpm}$$

PRIORS

$$\beta \sim \mathcal{N}_p(\mathbf{0}, \tau_b \mathbf{I}) \quad \tau_b \text{ hpm}$$

$$\tau_\epsilon \sim \text{Unif}(a_\epsilon, b_\epsilon) \quad a_\epsilon, b_\epsilon \text{ hpm}$$

$$\tau_\eta \sim \text{Unif}(a_\eta, b_\eta) \quad a_\eta, b_\eta \text{ hpm}$$

$$\tau_v \sim \text{Unif}(a_v, b_v) \quad a_v, b_v \text{ hpm}$$

$$\tau_w \sim \text{Unif}(a_w, b_w) \quad a_w, b_w \text{ hpm}$$

$$\tau_u \sim \text{Unif}(a_u, b_u) \quad a_u, b_u \text{ hpm}$$

INDEPENDENCE

$$\{\tilde{\epsilon}_t, \tilde{\eta}_t, \tilde{w}_t, \tilde{v}_t, \mu_0, \delta_0, \gamma_{0:(-S+2)},$$

$$\chi_{0:(2-F)}, \beta, \tau_\epsilon, \tau_\eta, \tau_v, \tau_w, \tau_u\}$$

family of \perp real random variables

Division in time zones

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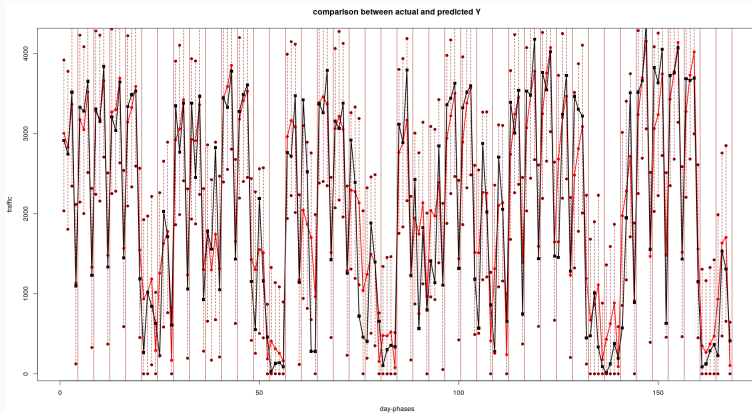


Figure 7: Global time series per slot

In the network models we deal with the **flows** of bicycles inward and outward a cluster of station, given a time interval.

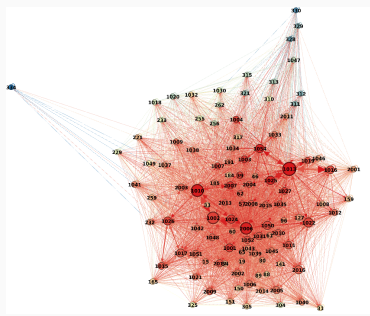
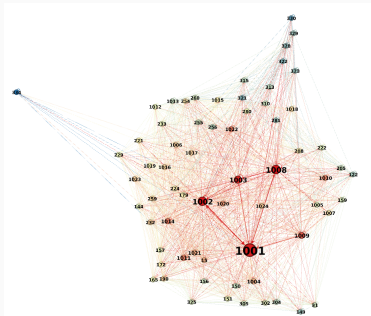
The problem is the with the very high dimensionality of the data, and the computational weight due to the high number of parameters.

To shrink the model we first introduced a prior clusterization with a modified **DBSCAN** and later using simplifying hypothesis.

The euclidian distance isn't versatile enough

- We fed the classic DBSCAN a different **semidistance**,
$$smd(x, y) = \frac{p(y)+p(x)}{2} ||x - y||.$$
- $p(x) = g(||x - x_0||)$ where x_0 are the coordinates of the Duomo, and $g(u) = \max\{\beta, e^{(\frac{u}{\alpha})^2 \log(1-\gamma)} + \gamma\}$
- We fitted the parameters in a way to minimize the autorings, and to break down the biggest clusters

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Preprocessing

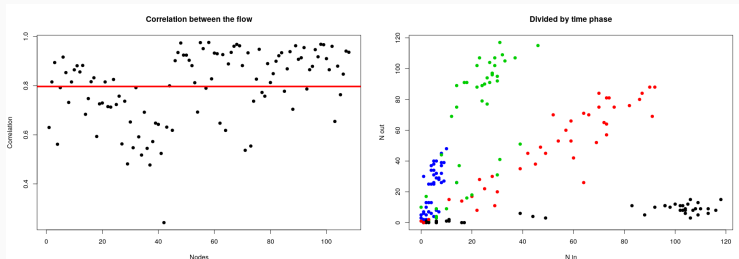
```
> ins[1:8,1:8]
```

	15	19	30	31	33	39	46	54
1	1	17	11	1	2	27	14	5
2	10	11	18	7	2	32	12	8
3	23	13	14	12	1	71	9	17
4	7	4	7	5	0	13	8	4
5	8	26	22	2	5	31	17	8
6	18	9	17	8	8	53	13	5
7	21	14	24	11	1	77	10	11
8	4	8	6	10	1	13	8	11

The two flows are structured as 168 x 109 matrices where the columns are the nodes and the rows are the evolving time

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Correlations between the flows in the same node



The likelihood is a **Bivariate Poisson**, a distribution over $\mathbb{N} \times \mathbb{N}$.

$$\begin{cases} Y_j = X_0 + X_j & j = 1, 2 \\ X_j \sim \text{Po}(\lambda_j) & j = 0, 1, 2 \end{cases} \quad (1)$$

In this way $\text{Cov}(Y_1, Y_2) = \text{Var}(X_0) = \lambda_0$. And marginally $Y_j \sim \text{Po}(\lambda_0 + \lambda_j)$.

Some simplifying hypothesis

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TWO WAY MIXED EFFECT

$$\beta_{ith} \cdot \mathbf{x} \Rightarrow (\alpha_t + \gamma_h) \cdot \mathbf{x}$$

OFFSETS

$$\log\left(\frac{\lambda_{ith}}{O_i}\right) = (\alpha_t + \gamma_h) \cdot \mathbf{x}$$

$$\Rightarrow \log(\lambda_{ith}) = \log(O_i) + (\alpha_t + \gamma_h) \cdot \mathbf{x}$$

The offsets model

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$$\left\{ \begin{array}{l} \log(\lambda_{ith}^{(j)}) = (\theta^{(j)} + \alpha_t^{(j)} + \gamma_h^{(j)}) \cdot \mathbf{x} + \log(O_i) \\ \theta^{(j)} | a, B \stackrel{iid}{\sim} \mathcal{N}(a, B) \\ \alpha_t^{(j)} | \Sigma \stackrel{iid}{\sim} \mathcal{N}(0, \Sigma) \\ \gamma_h^{(j)} | \Omega \stackrel{iid}{\sim} \mathcal{N}(0, \Omega) \\ a \sim \mathcal{N}(a_0, A_0) \\ B \sim \text{invWishart}(B_0, p + 1) \\ \Sigma, \Omega \stackrel{iid}{\sim} \text{invWishart}(C_0, p + 1) \end{array} \right. \quad (2)$$

Where $\alpha_t^{(j)}, \beta_h^{(j)}, \theta^{(j)}, a \in \mathbb{R}^3, \Sigma, \Omega, B \in \mathbb{R}^{3 \times 3}$ are the parameters, $A_0, B_0, C_0 \in \mathbb{R}^{3 \times 3}, a_0 \in \mathbb{R}^3$ are the hyperparameters, and \mathbf{x} are the covariates.

The offsets are the the average of the traffic of the first 12 days.

The parametric offsets (PO) model

The offsets are now grouped with the other parameters.

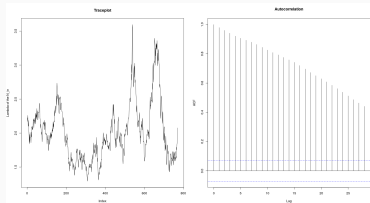
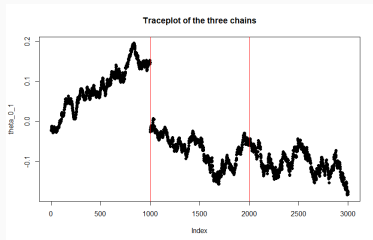
$$\left\{ \begin{array}{l} \log(\lambda_{ith}^{(j)}) = (\theta^{(j)} + \alpha_t^{(j)} + \beta_h^{(j)}) \cdot \mathbf{x} + \Phi_i \\ \theta^{(j)} | a, B \stackrel{iid}{\sim} \mathcal{N}(a, B) \\ \alpha_t^{(j)} | \Sigma \stackrel{iid}{\sim} \mathcal{N}(0, \Sigma) \\ \beta_h^{(j)} | \Omega \stackrel{iid}{\sim} \mathcal{N}(0, \Omega) \\ \Phi_i \stackrel{iid}{\sim} \mathcal{N}(\Phi_0, F_0) \\ a \sim \mathcal{N}(a_0, A_0) \\ B \sim invWishart(B_0, p + 1) \\ \Sigma, \Omega \stackrel{iid}{\sim} invWishart(C_0, p + 1) \end{array} \right. \quad (3)$$

Where $\alpha_t^{(j)}, \beta_h^{(j)}, \theta^{(j)}, a \in \mathbb{R}^3$, $\Sigma, \Omega, B \in \mathbb{R}^{3 \times 3}$, $\Phi_i \in \mathbb{R}$ are the parameters, $A_0, B_0, C_0, F_0 \in \mathbb{R}^{3 \times 3}$, $a_0 \in \mathbb{R}^3$, $\Phi_0 \in \mathbb{R}$ are the hyperparameters, and \mathbf{x} are the covariates.

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Posterior with JAGS

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	N^{IN}	N^{OUT}
Offsets	41.0%	62.2%
PO	39.7%	38.6%

The results are unsatisfactory, the iterations are not enough to stabilize the MCMC and the autocorrelation is too high. The **predictive power** is low.

Prediction Intervals for arriving bikes at Cadorna cluster

