

# ECS32B

Introduction to Data Structures

Graphs

Lecture 26



# Announcements

- SLAC on Monday will cover HW6 and the Makeup assignment.
- A sample final will be posted on Monday.
- Last lecture will mostly be final exam preparation.



# Graph anatomy review

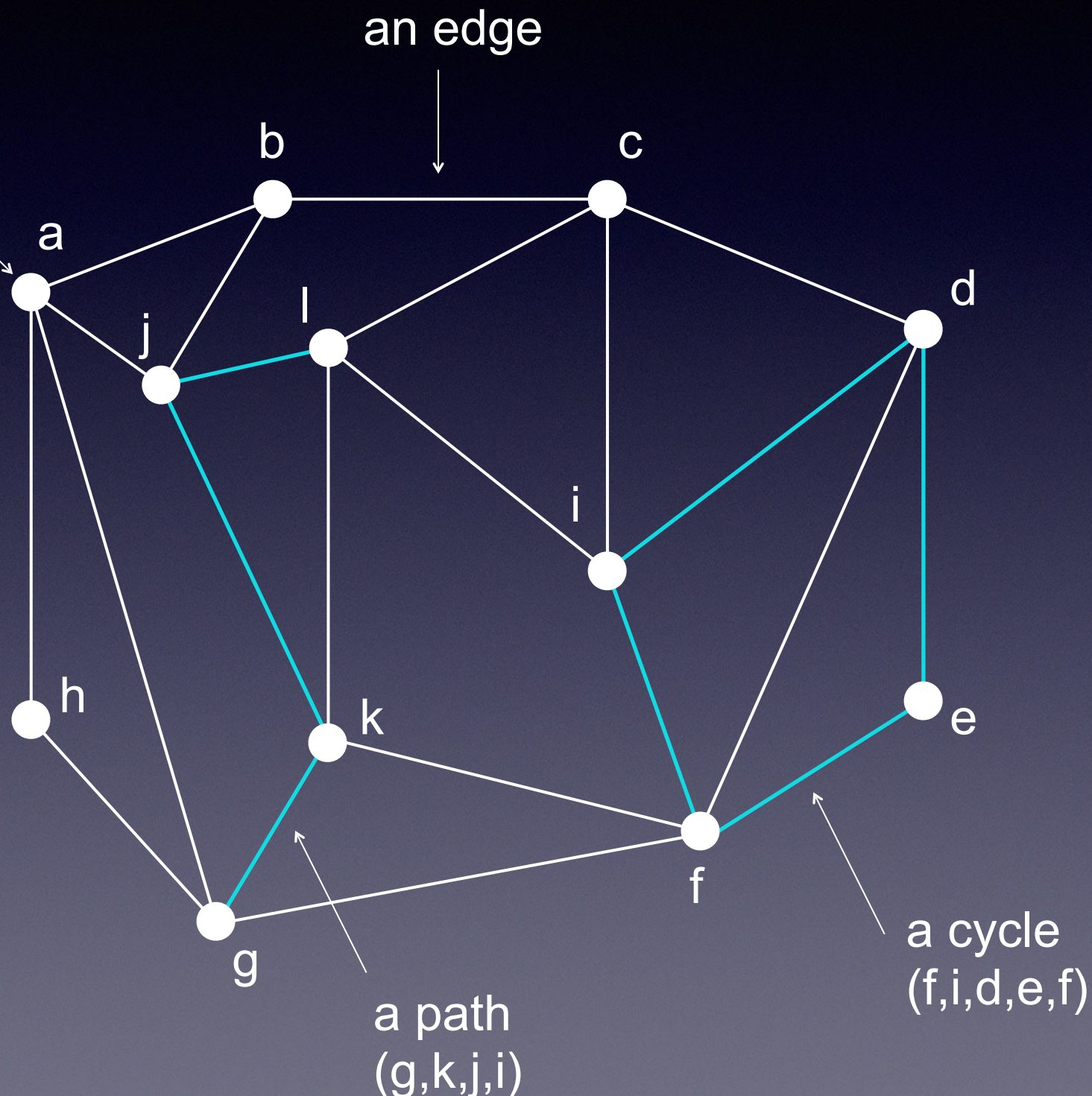
a vertex  
a.k.a node

an edge

There are  $|V|$  vertices. Often  $n$  is used to indicate the number of vertices.

There are  $|E|$  edges. Often  $m$  is used to indicate the number of edges. The number of edges is  $O(n^2)$

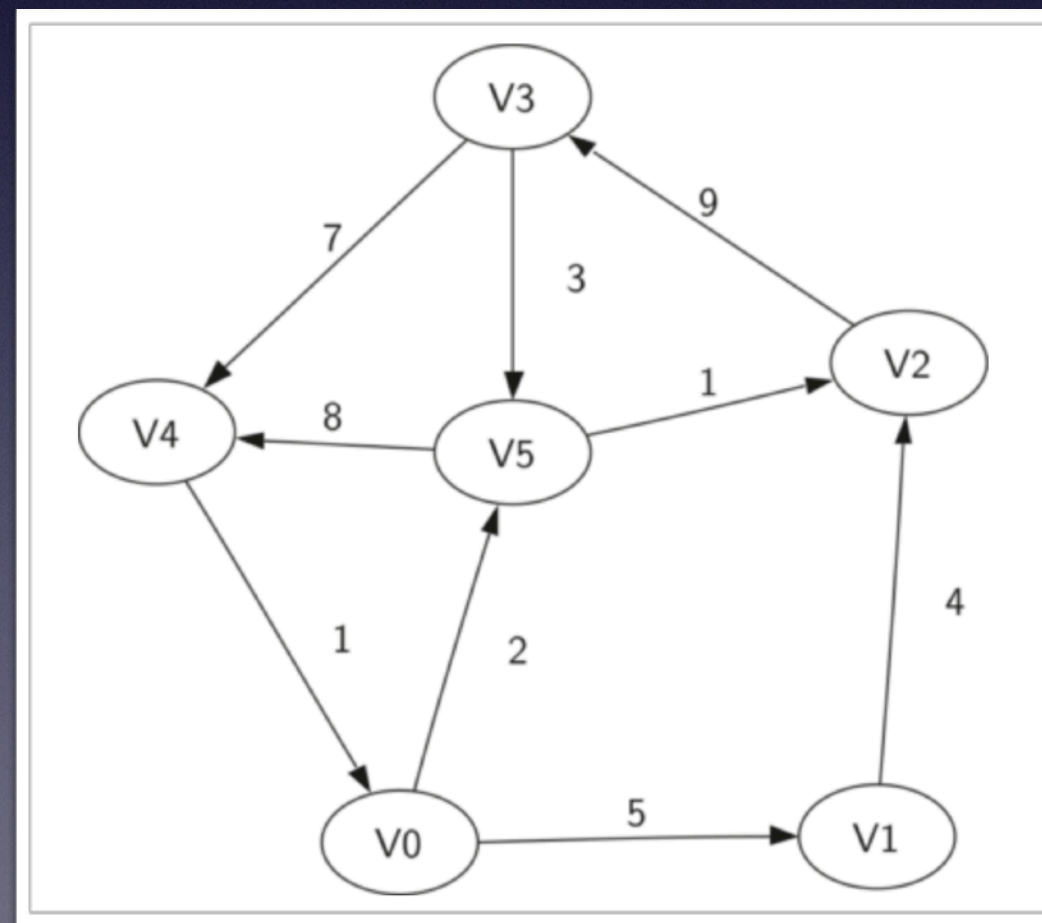
edges can be weighted or unweighted  
edges can be directed or undirected





# Concrete representation of a graph

How might you represent a graph in Python using nodes and pointers/references in a linked data structure?





# Concrete representations of graphs

Two methods of representing a graph are popular:

- **Adjacency Matrix** (edge based)

A  $n \times n$  matrix with 1 (or the weight) (or true) for an edge and 0 (or infinity) (or false) for not-an-edge.

- **Adjacency List** (vertex based)

A vector (array) of lists, one for each vertex. Each list has the adjacent vertices.



# Adjacency Matrix

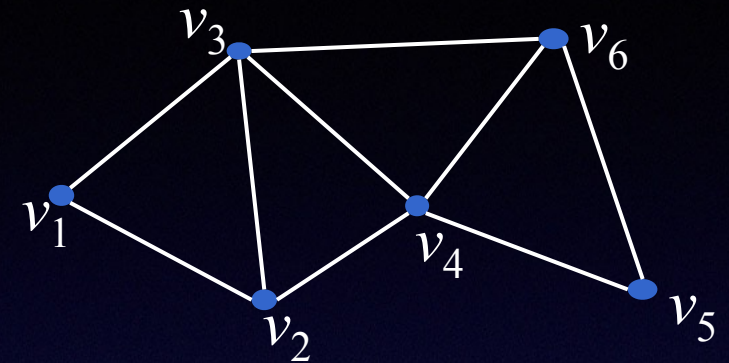
E.g. A graph with  $n$  vertices  
 $v_1, v_2, \dots, v_n$ .

The entry in row  $i$  and column  $j$  of **A** tells us something about the edge  $(v_i, v_j)$  in the graph.

The **adjacency matrix** contains 0's and 1's indicating if an edge is present or not. You could also use True or False, or you could use weights in the case of a weighted graph.

The adjacency matrix of an undirected graph is symmetric.

For graphs with few edges, the adjacency matrix is sparse (i.e., contains mostly zeros).

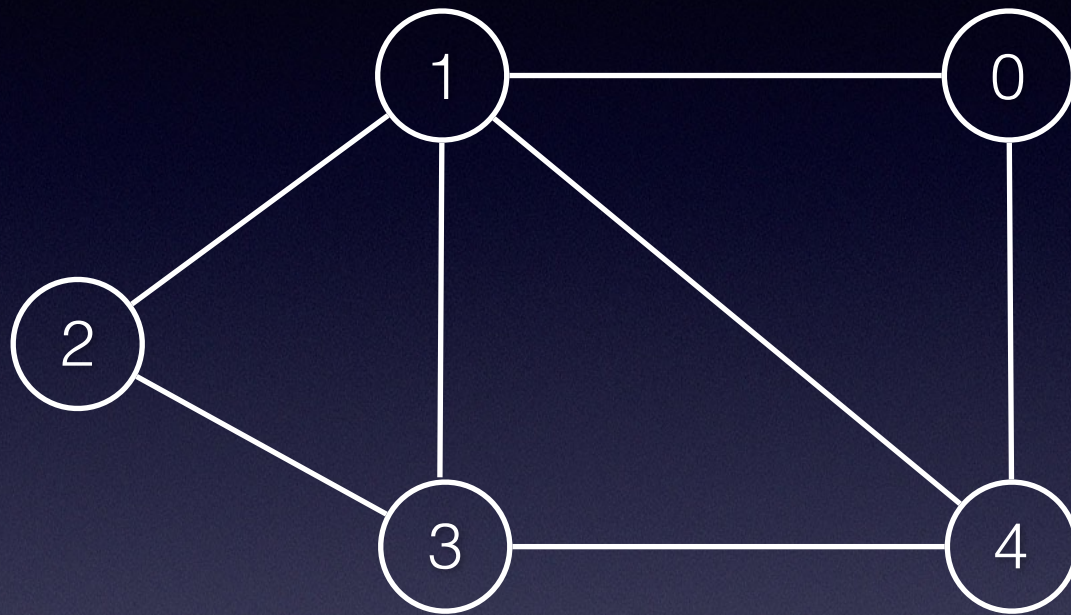


|       | $v_1$ | $v_2$ | $v_3$ | $v_4$ | $v_5$ | $v_6$ |
|-------|-------|-------|-------|-------|-------|-------|
| $v_1$ | 0     | 1     | 1     | 0     | 0     | 0     |
| $v_2$ | 1     | 0     | 1     | 1     | 0     | 0     |
| $v_3$ | 1     | 1     | 0     | 1     | 0     | 1     |
| $v_4$ | 0     | 1     | 1     | 0     | 1     | 1     |
| $v_5$ | 0     | 0     | 0     | 1     | 0     | 1     |
| $v_6$ | 0     | 0     | 1     | 1     | 1     | 0     |

Adjacency Matrix A



# Another Adjacency Matrix



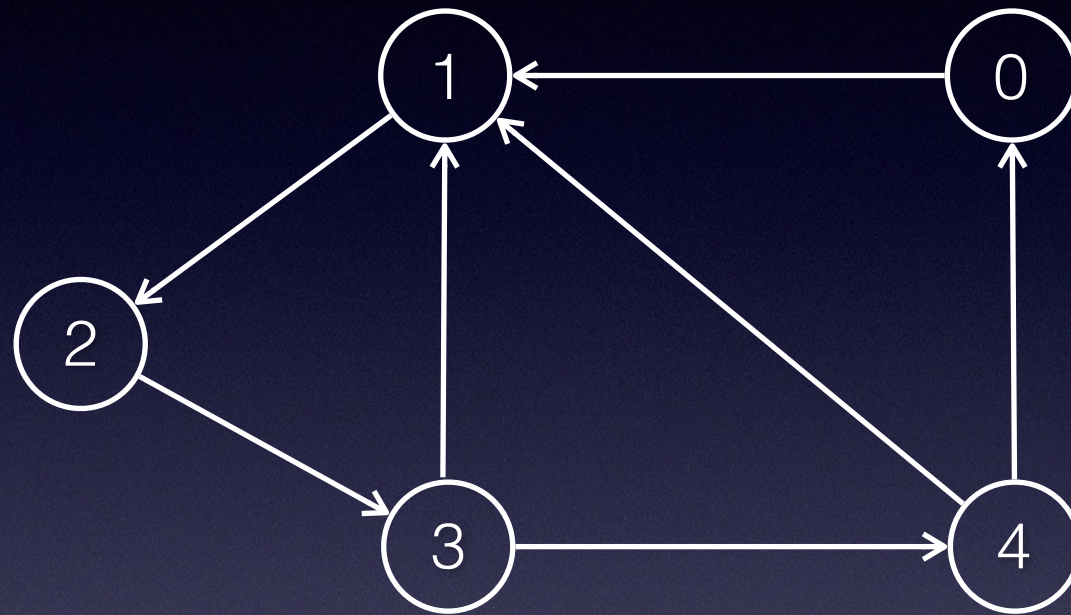
|   | 0 | 1 | 2 | 3 | 4 |
|---|---|---|---|---|---|
| 0 | 0 | 1 | 0 | 0 | 1 |
| 1 | 1 | 0 | 1 | 1 | 1 |
| 2 | 0 | 1 | 0 | 1 | 0 |
| 3 | 0 | 1 | 1 | 0 | 1 |
| 4 | 1 | 1 | 0 | 1 | 0 |

Notice the symmetry.

Adjacency Matrix



# Another Adjacency Matrix (Digraph)



|   | 0 | 1 | 2 | 3 | 4 |
|---|---|---|---|---|---|
| 0 | 0 | 1 | 0 | 0 | 0 |
| 1 | 0 | 0 | 1 | 1 | 0 |
| 2 | 0 | 0 | 0 | 1 | 0 |
| 3 | 0 | 0 | 0 | 0 | 1 |
| 4 | 1 | 1 | 0 | 0 | 0 |

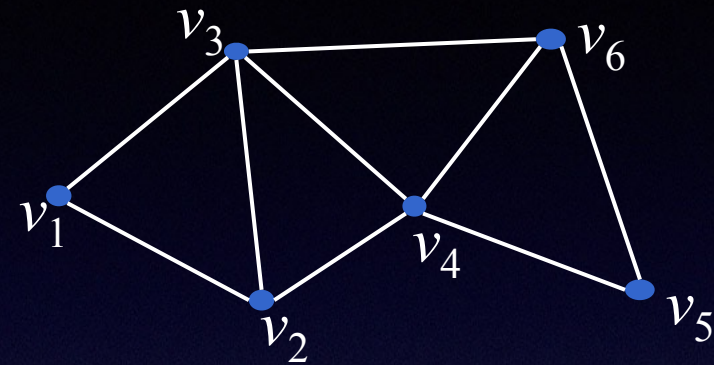
No longer symmetric

Adjacency Matrix



# Adjacency list

E.g. A graph with  $n$  vertices  
 $v_1, v_2, \dots, v_n$ .



The adjacency list is never sparse  
(even for a graph with few edges).  
The space is well-used

Notice that an undirected edge  
is listed at both of the vertices it  
connects

|       |                      |
|-------|----------------------|
| $v_1$ | $v_2, v_3$           |
| $v_2$ | $v_1, v_3, v_4$      |
| $v_3$ | $v_1, v_2, v_4, v_6$ |
| $v_4$ | $v_2, v_3, v_5, v_6$ |
| $v_5$ | $v_4, v_6$           |
| $v_6$ | $v_3, v_4, v_5$      |

Adjacency List



# Concrete representation of a graph

We've been looking at abstract representations; now we'll see how we might implement them as an ADT

Operations on a graph (things we might want to do):

- Create a graph of  $n$  vertices.
- Insert a vertex
- Insert an edge
- Query the existence of an edge
- Iterate over the vertices adjacent to a given vertex.



# Operations defined for the graph ADT

**Graph()**

returns an empty graph

**addVertex**(vert)

adds a vertex to a graph

**addEdge**(fromVert, toVert, weight=0)

adds an optionally weighted directed edge to a graph and any necessary vertices.

**getVertex**(vertKey)

returns vertex objected by name

**getVertices**()

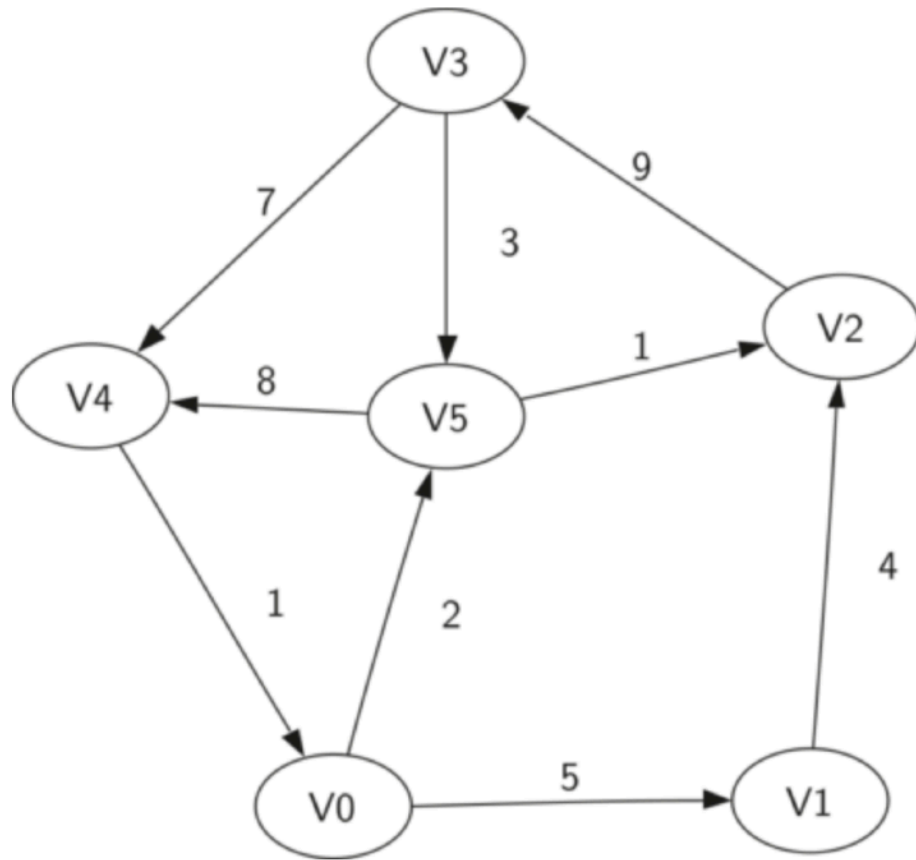
returns list of all vertices

**in** (is vertex in graph?)

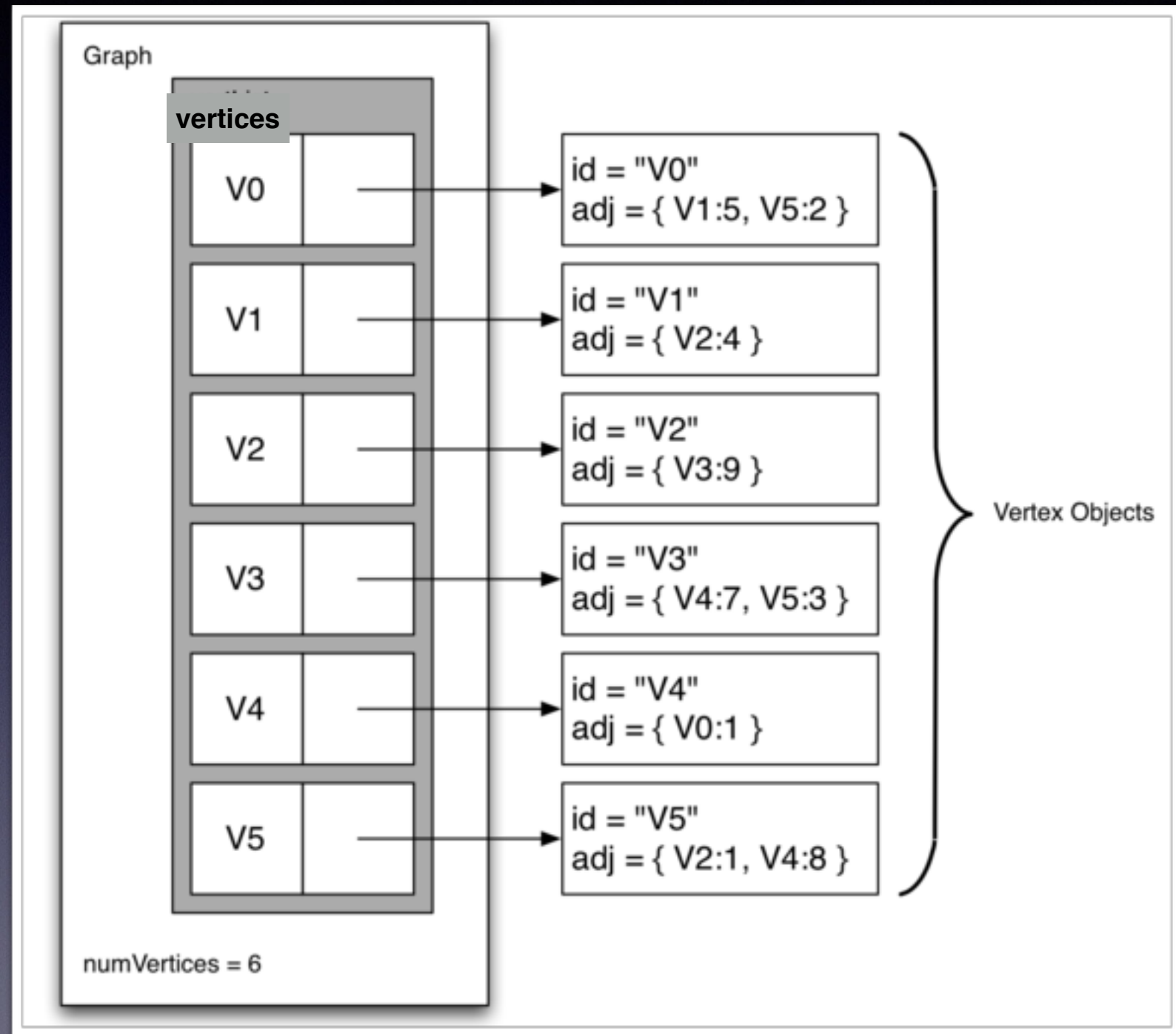
The only two methods you really need to create a graph are **Graph()** and **addEdge()**



# Graph object adjacency list representation

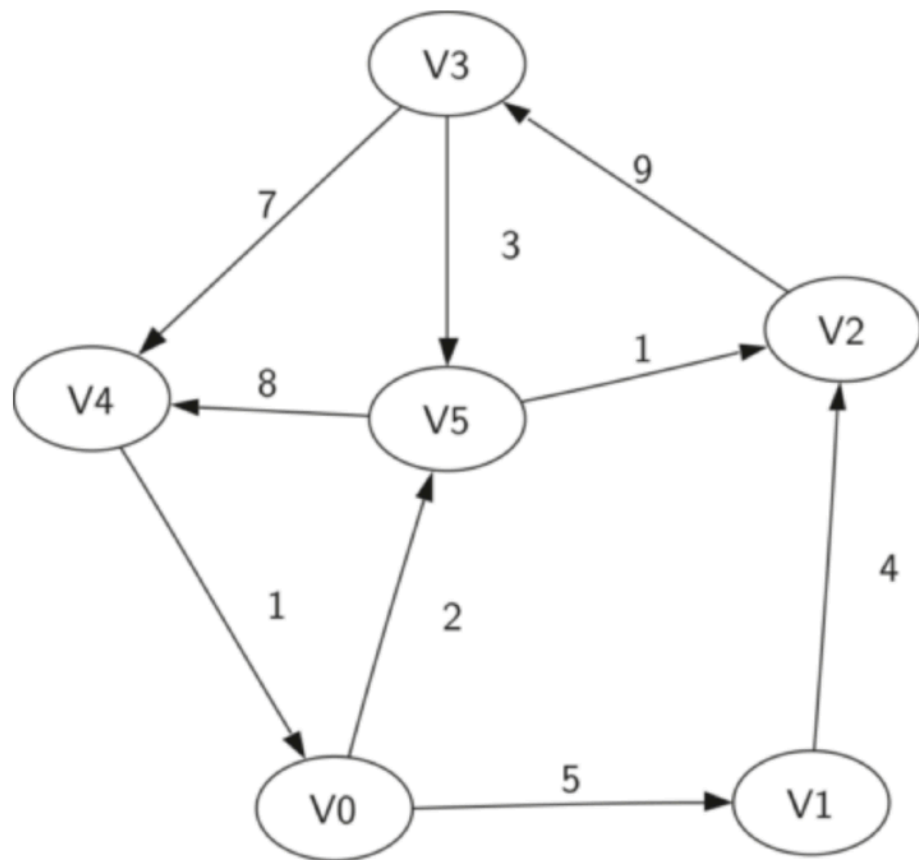


Our textbook uses an adjacency list in each Vertex object to represent the edges





# Creating a graph



**g = Graph()** creates a new graph **g**.  
**g.addEdge()** also creates the vertices

**g.getVertices()** returns a list of ids while **g.vertices** is actually a dictionary mapping ids to Vertex objects

```
>>> g = Graph()
>>> g.addEdge(0,1,5)
>>> g.addEdge(0,5,2)
>>> g.addEdge(1,2,4)
>>> g.addEdge(2,3,9)
>>> g.addEdge(3,4,7)
>>> g.addEdge(3,5,3)
>>> g.addEdge(4,0,1)
>>> g.addEdge(5,4,8)
>>> g.addEdge(5,2,1)
>>> g.getVertices()
[0, 1, 5, 2, 3, 4]
>>> g.vertices
{0: <__main__.Vertex object at 0x10935c780>,
1: <__main__.Vertex object at 0x1082384e0>, 5: <__main__.Vertex object at 0x10adf2a58>, 2: <__main__.Vertex object at 0x10ade86a0>, 3: <__main__.Vertex object at 0x1082385c0>, 4: <__main__.Vertex object at 0x1082385f8>}
```



# Graph traversal

- Many graph algorithms involve visiting each vertex in a systematic order.
- The two most common traversal algorithms are **breadth-first** and **depth-first**.
- Although these are traversals, the traversals are usually employed to find something in the graph (e.g., a vertex/node, or more likely a path to that vertex/node), so they're more commonly called **breadth-first search** and **depth-first search**.



# Breadth-first concept

- Starting at a source vertex **s**
- Systematically explore the edges to discover every vertex reachable from **s**.
- Produces a “breadth-first tree”
  - Root of s
  - Contains all vertices reachable from s
  - **Path from s to v has the shortest number of edges**



# Breadth-first algorithm

Take a start (or source) vertex, mark it identified (color it **grey**), and place it into a queue.

**While the queue is not empty:**

Take a vertex,  $u$ , out of the queue (Begin processing  $u$ )

For all vertices  $v$ , adjacent to  $u$ ,

If  $v$  is still **white**

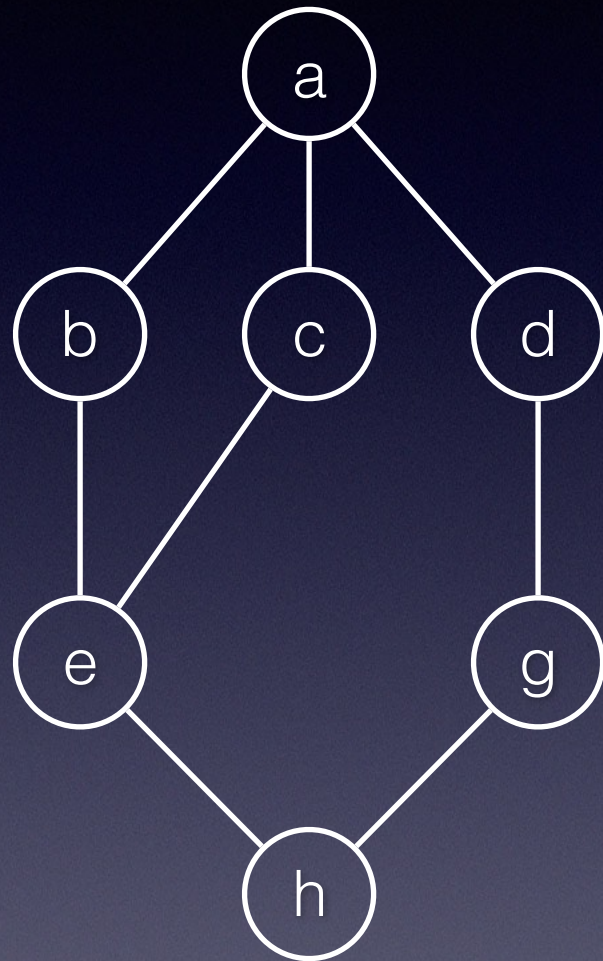
Mark it identified (color it **grey**)

Place it into the queue

We are now done processing  $u$  (color it **black**)



# Breadth-first concept



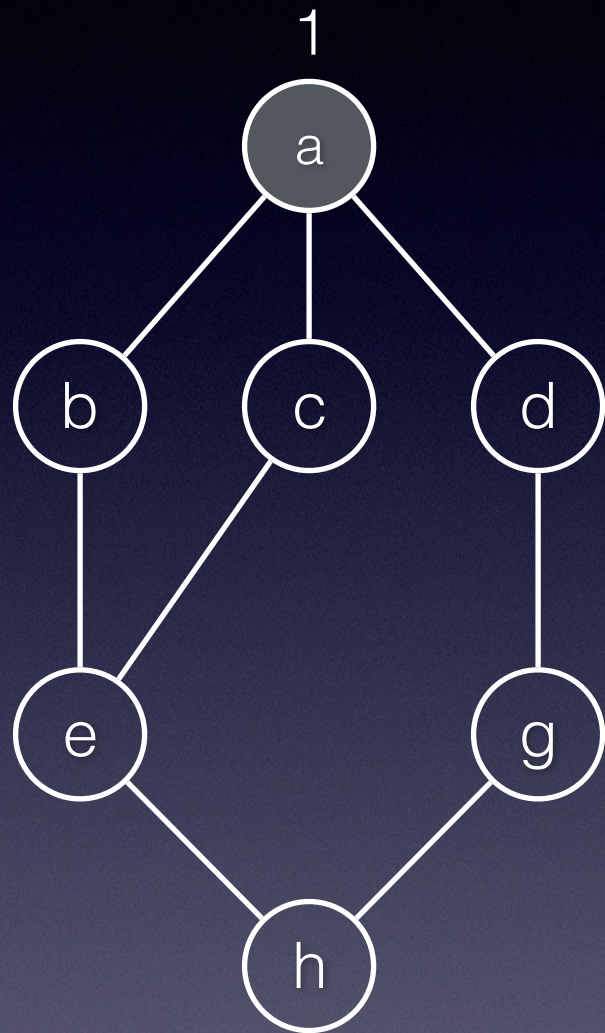
Queue: [ ]

(right is front of queue)

Processing:



# Breadth-first concept



Queue: [a]

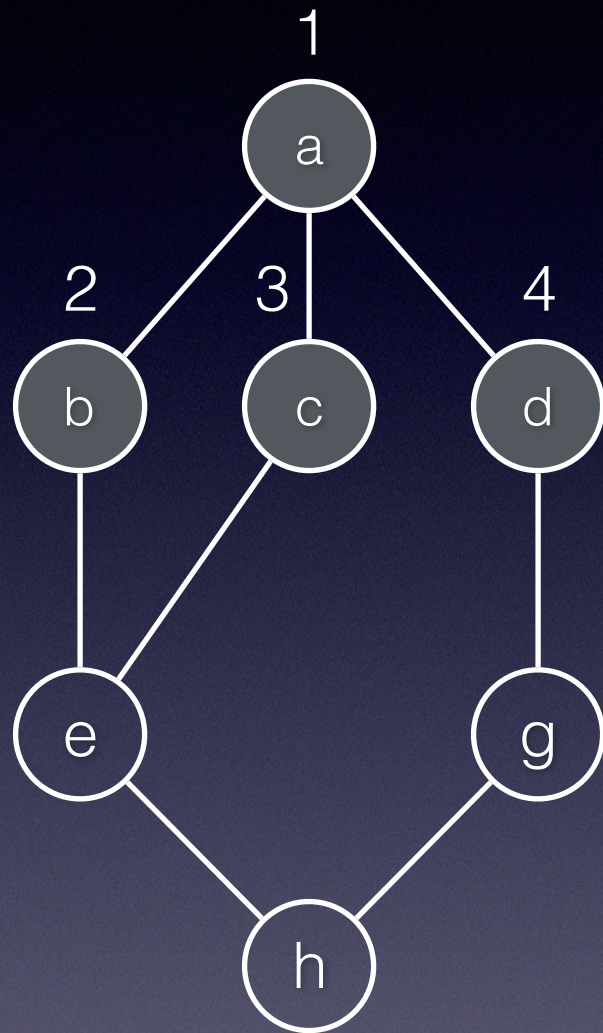
(right is front of queue)

Processing:

We will number the vertices in the order they are identified/processed/visited. This is not essential to implementing the algorithm



# Breadth-first concept

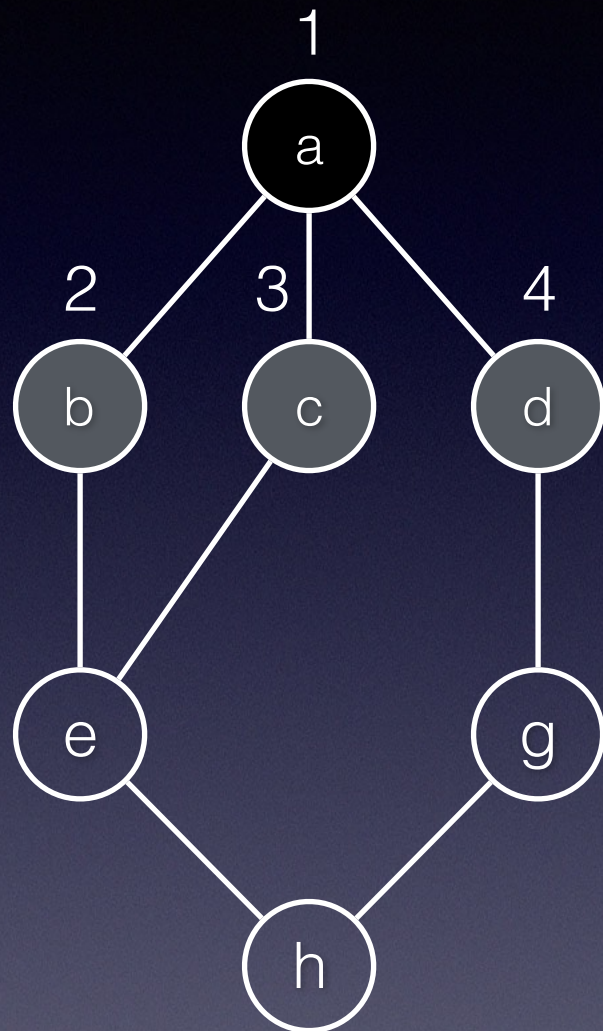


Queue: [d,c,b]

Processing: a



# Breadth-first concept



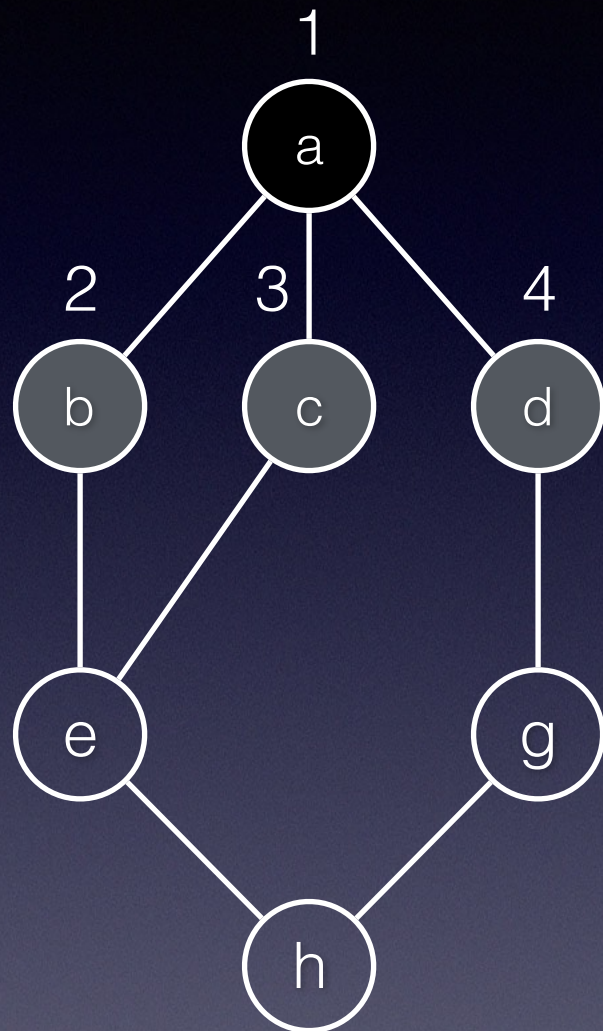
Queue: [d,c,b]

Processing:





# Breadth-first concept



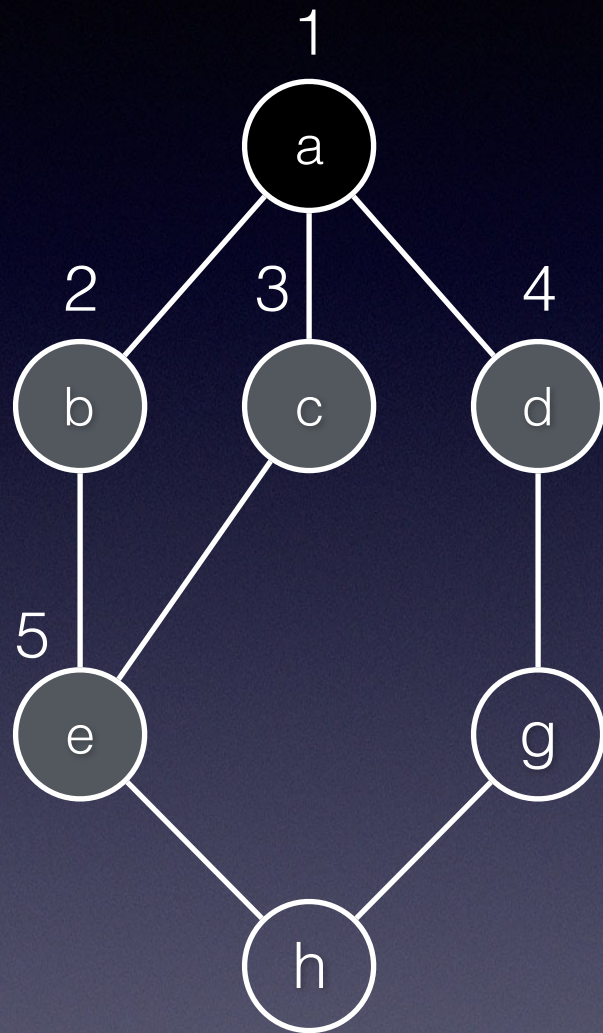
Queue: [d,c]

Processing: b





# Breadth-first concept



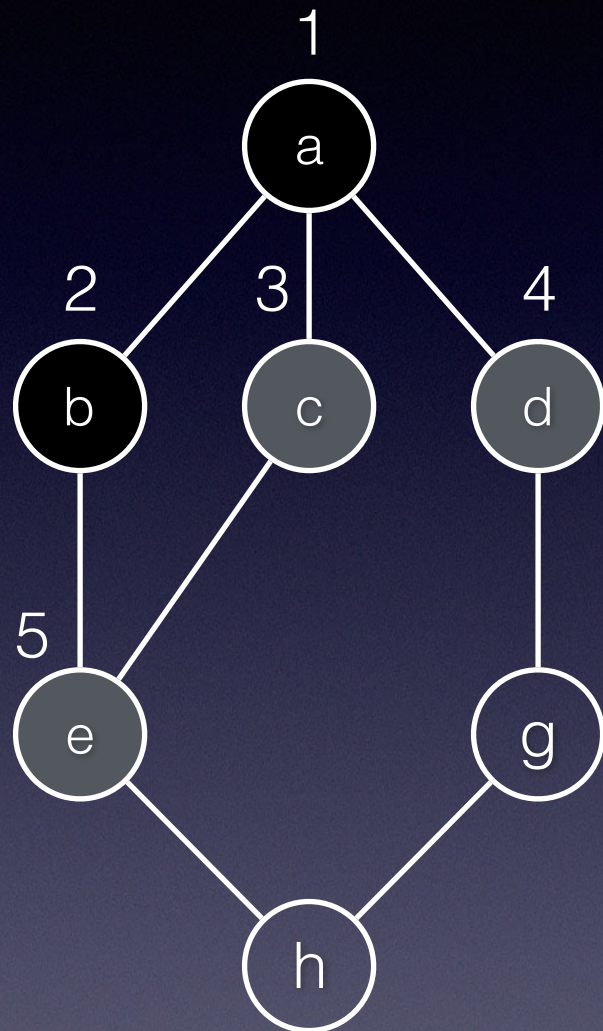
Queue: [e,d,c]

Processing: b



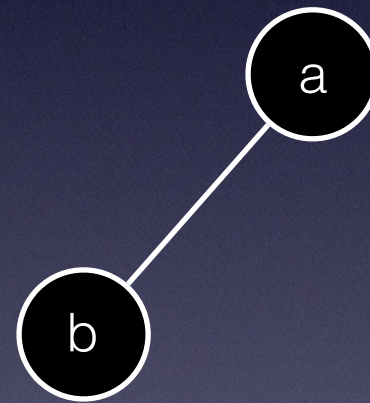


# Breadth-first concept



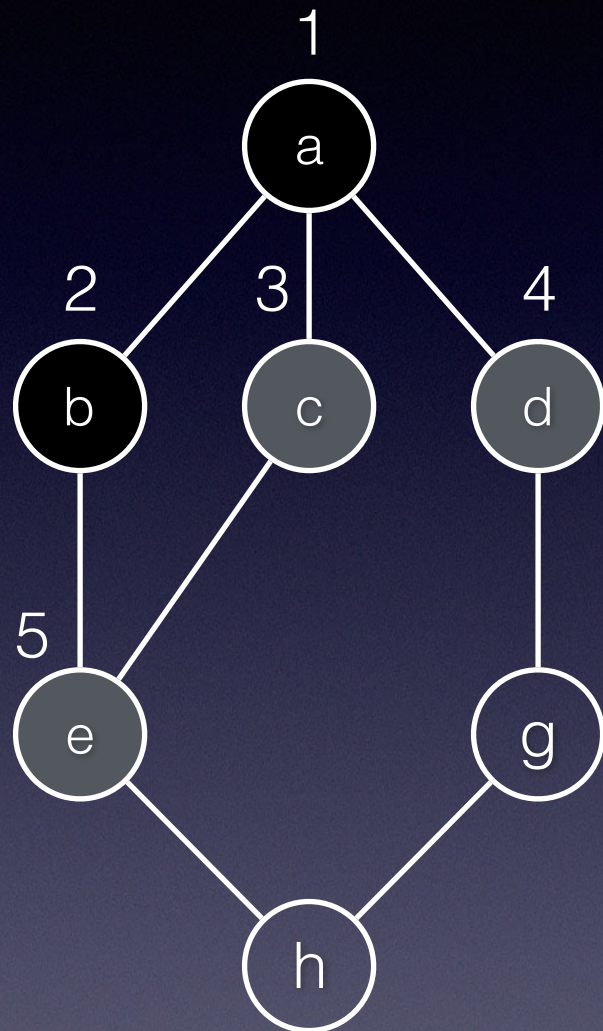
Queue: [e,d,c]

Processing:



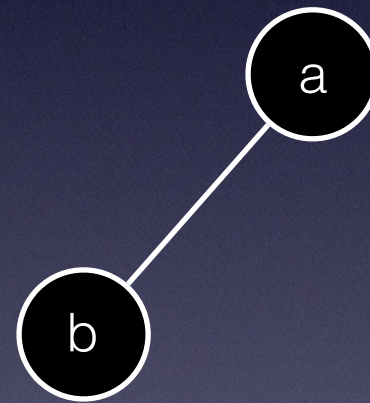


# Breadth-first concept



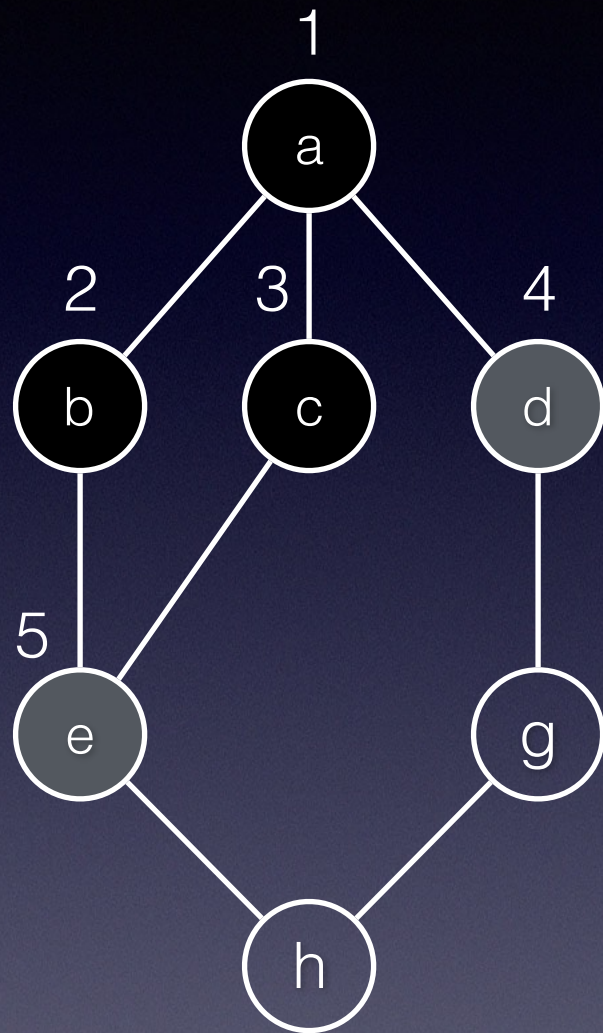
Queue: [e,d]

Processing: c



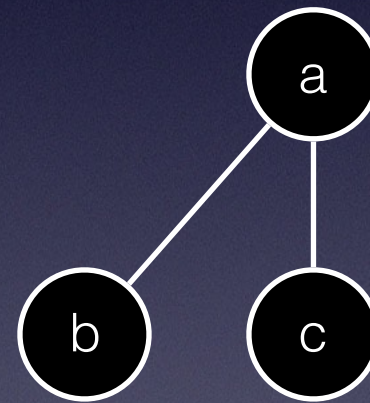


# Breadth-first concept



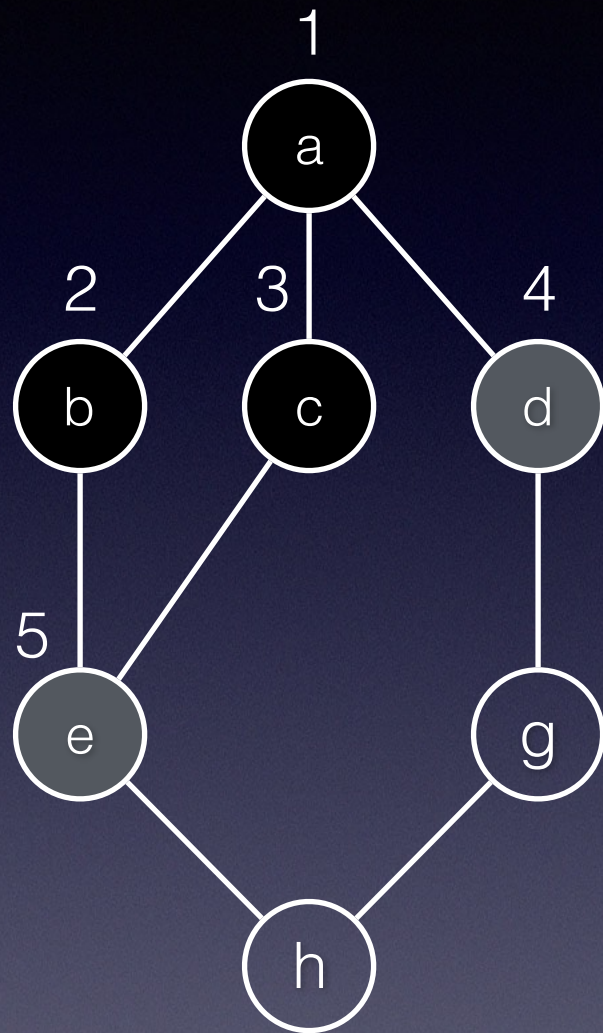
Queue: [e,d]

Processing:



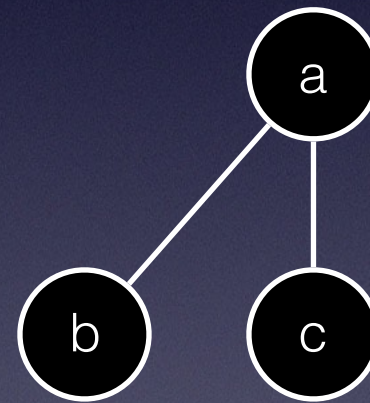


# Breadth-first concept



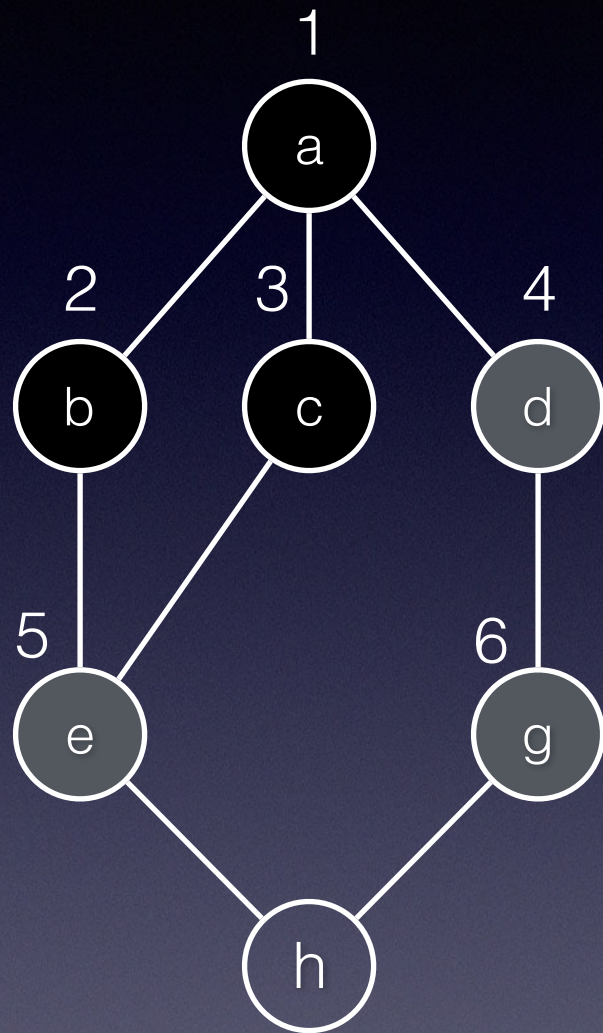
Queue: [e]

Processing: d



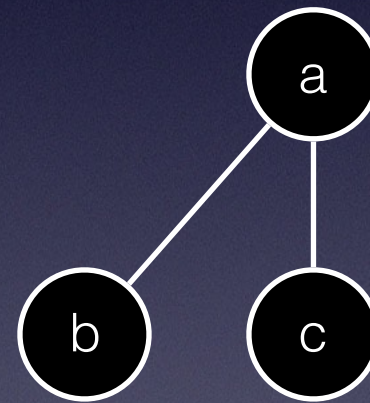


# Breadth-first concept



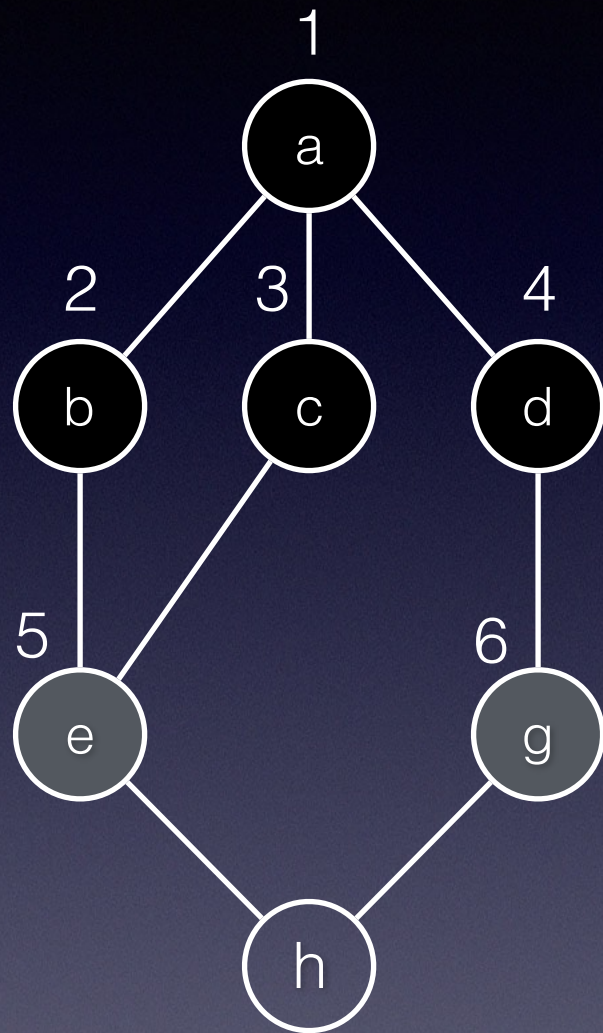
Queue: [g,e]

Processing: d



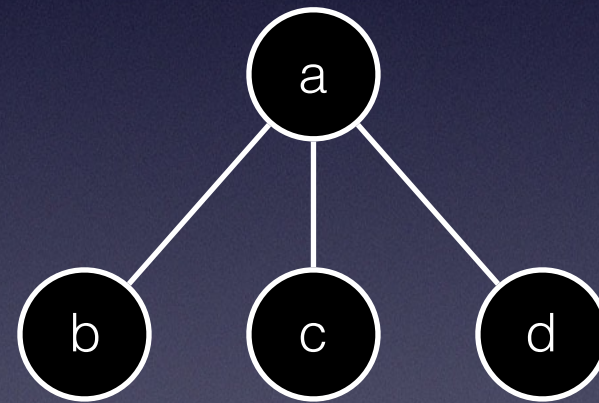


# Breadth-first concept



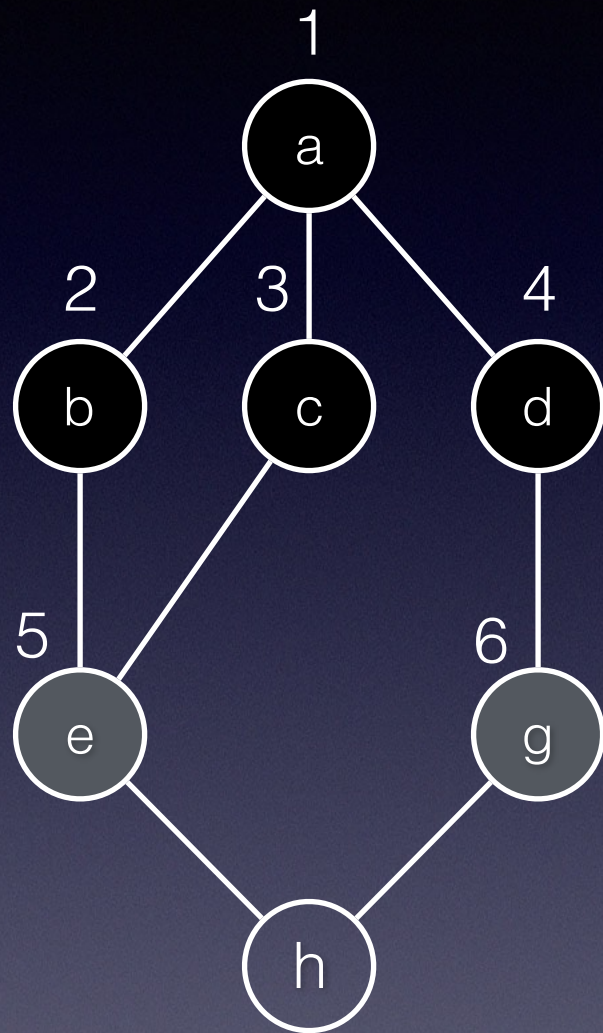
Queue: [g,e]

Processing:



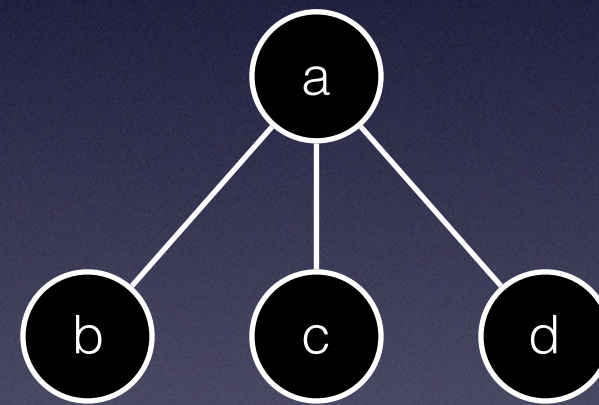


# Breadth-first concept



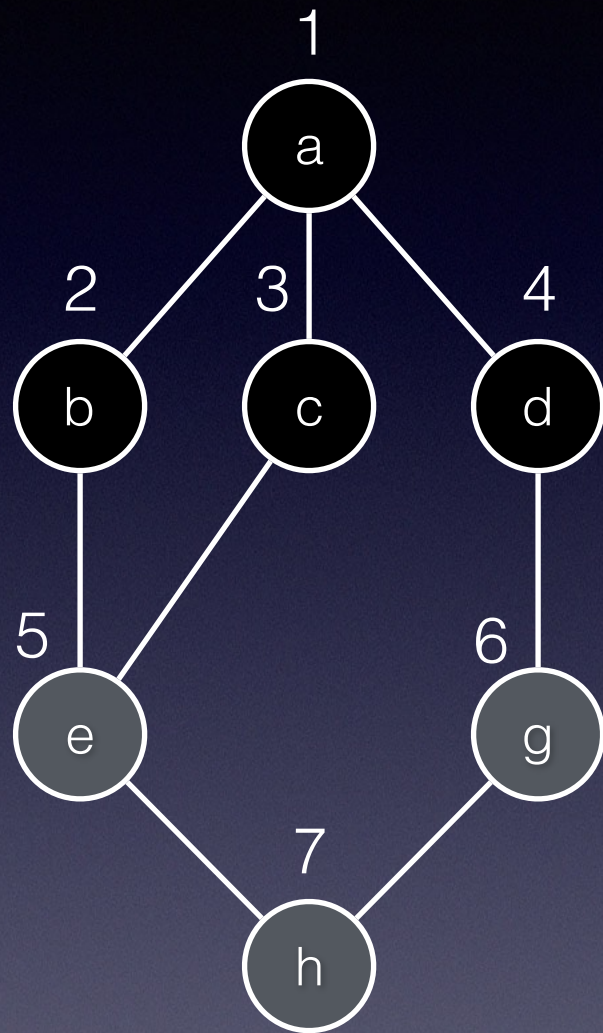
Queue: [g]

Processing: e



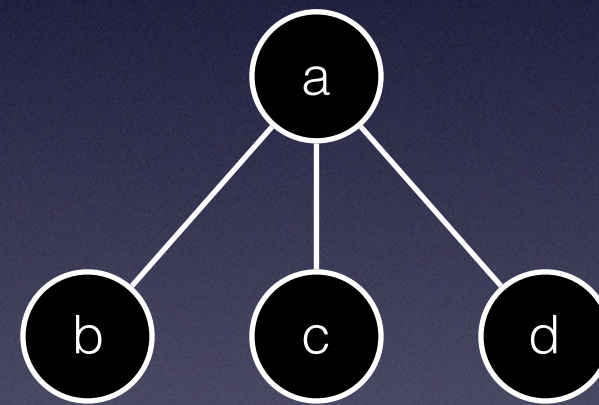


# Breadth-first concept



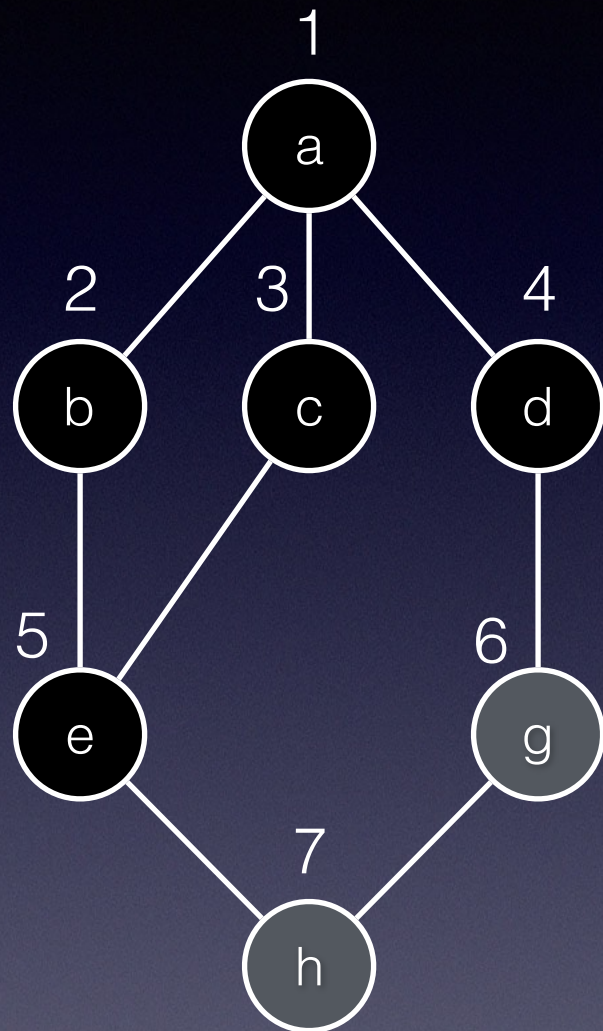
Queue: [h,g]

Processing: e



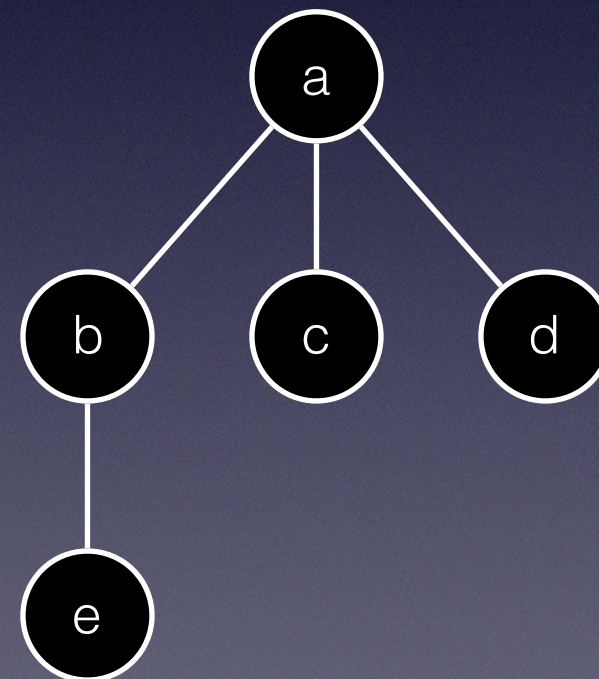


# Breadth-first concept



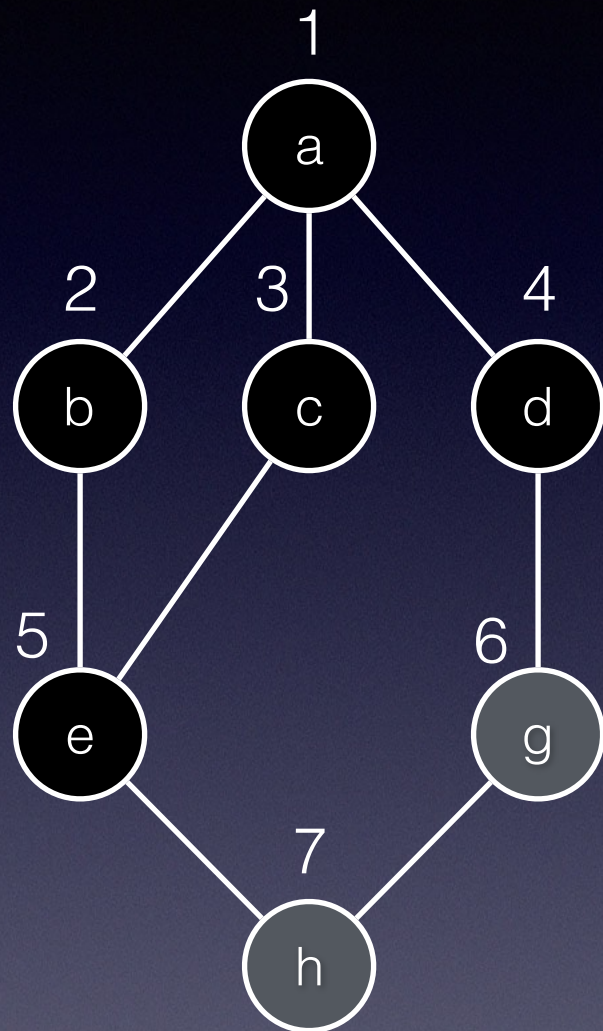
Queue: [h,g]

Processing:



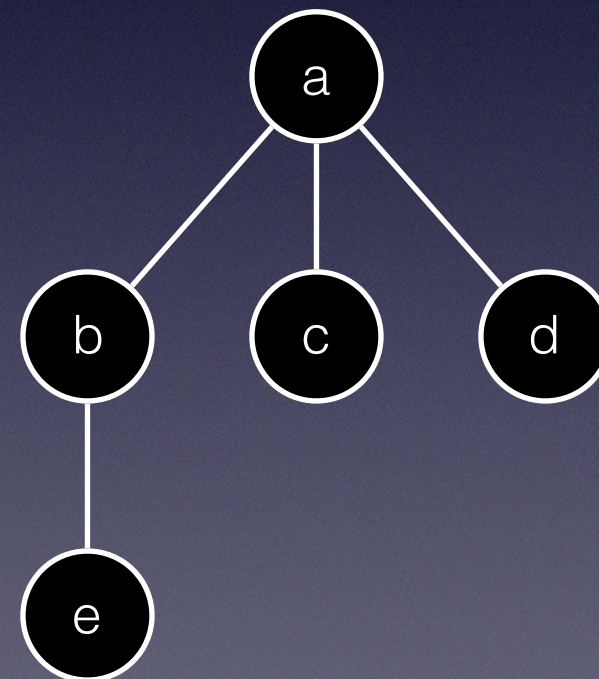


# Breadth-first concept



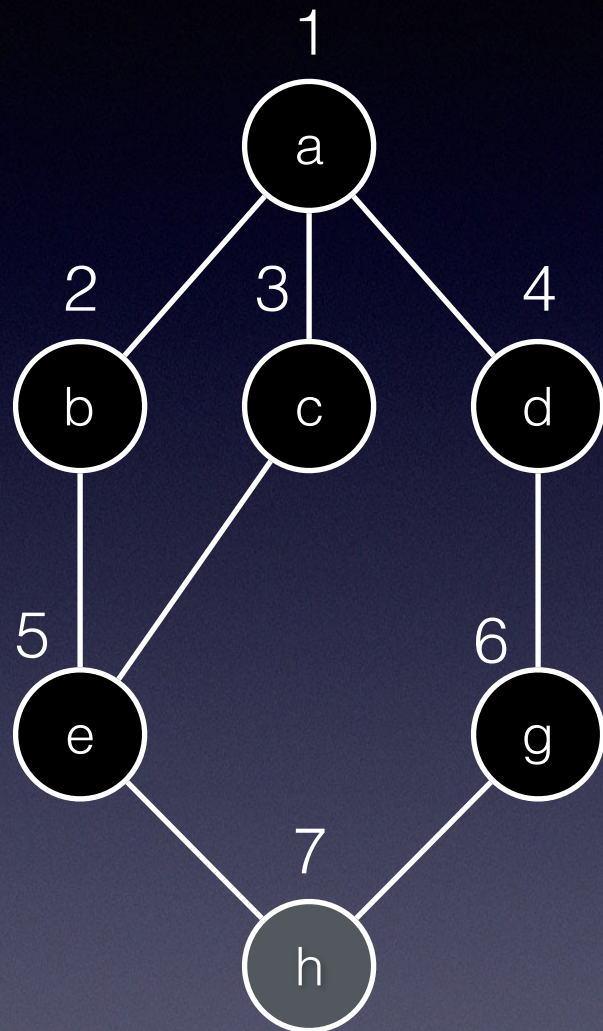
Queue: [h]

Processing: g



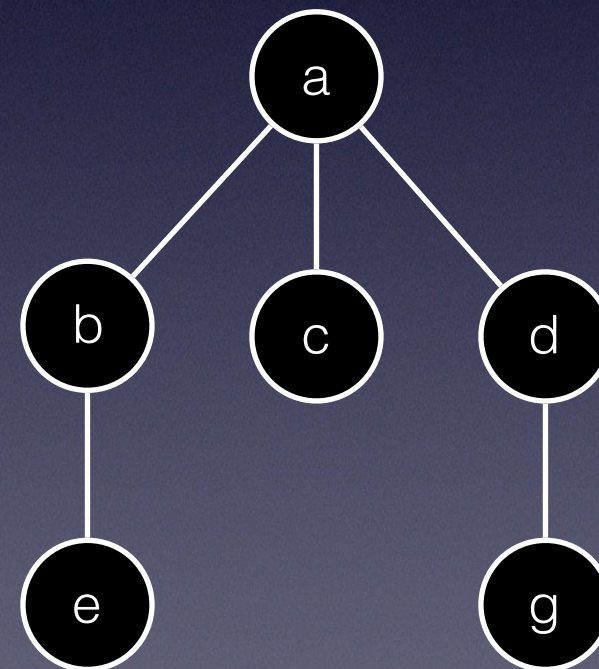


# Breadth-first concept



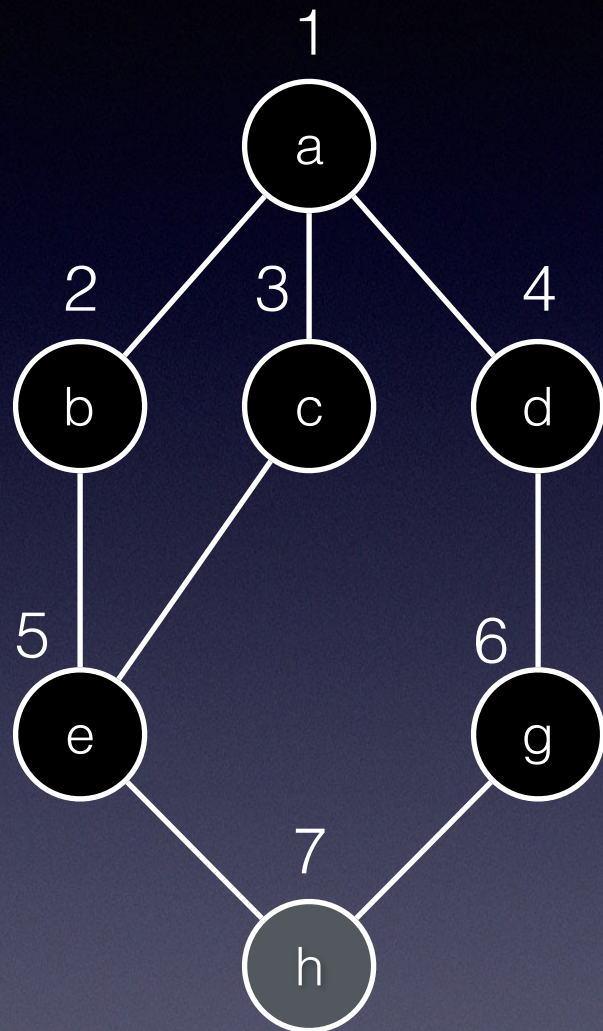
Queue: [h]

Processing:



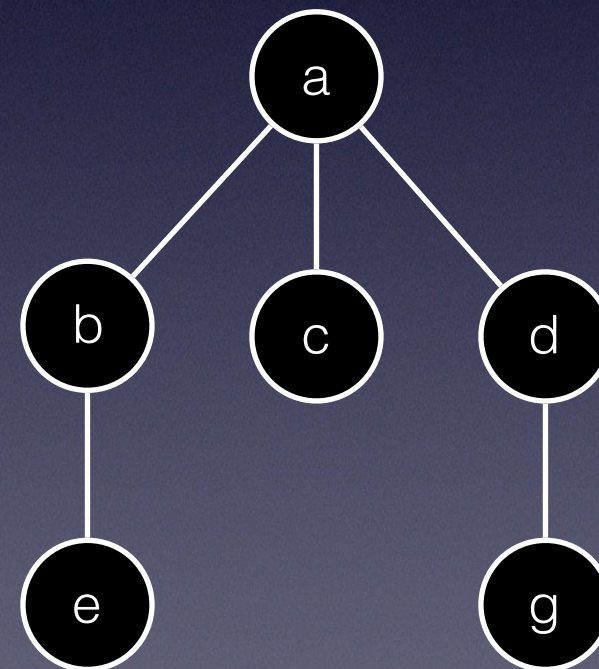


# Breadth-first concept



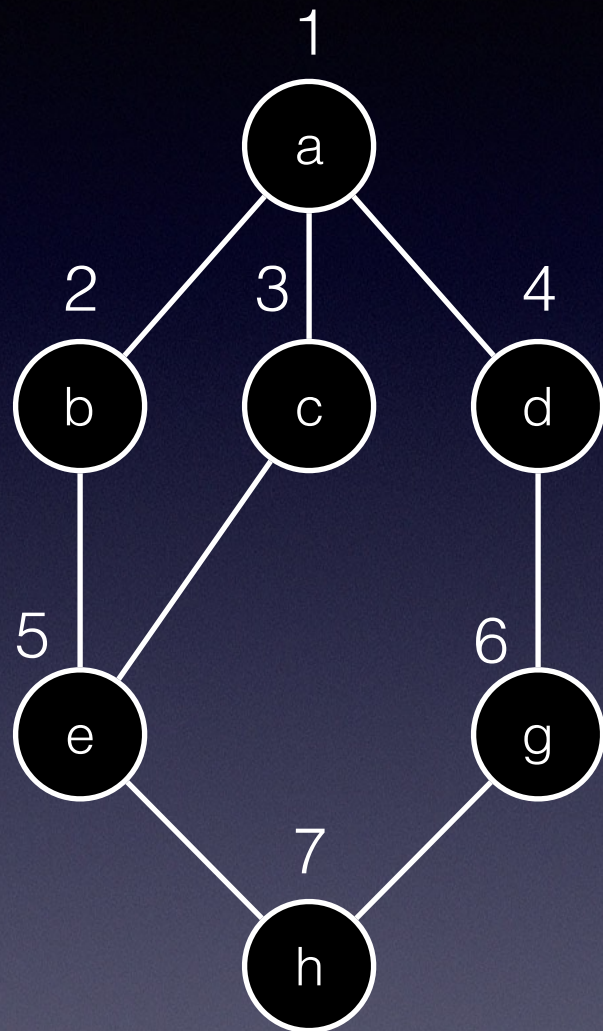
Queue: []

Processing: h



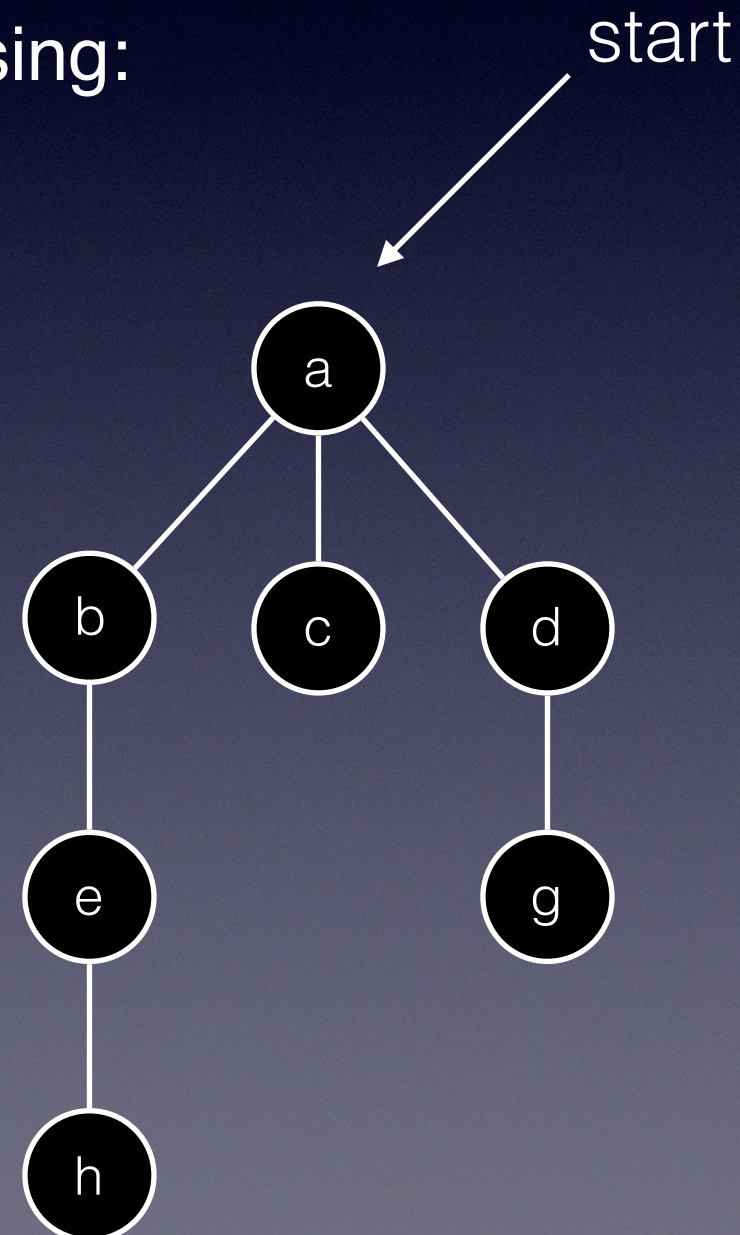


# Breadth-first concept



Queue: []

Processing:



Assuming all edges have equal cost (e.g., distance), breadth-first will always find shortest path from start to goal.



# Lewis Carroll's Word Ladders

F00L

P00L

P0LL

P0LE

PALE

SALE

SAGE

A game invented on Christmas day 1877. Player is asked to transform a start word into an end word, using single letter substitutions to create existing words at each step.



# Lewis Carroll's Word Ladders

|       |       |      |      |      |
|-------|-------|------|------|------|
| BLACK | WHEAT | FIND | LOVE | WARM |
| CLACK | CHEAT | FINE | LIVE | WORM |
| CRACK | CHEAP | LINE | GIVE | WORD |
| TRACK | CHEEP | LIVE | GAVE | CORD |
| TRICK | CREEP | LOVE | LATE | COLD |
| TRICE | CREED | LOSE | HATE |      |
| TRITE | BREED |      |      |      |
| WRITE | BREAD |      |      |      |
| WHITE |       |      |      |      |

He used clever start and end word pairs



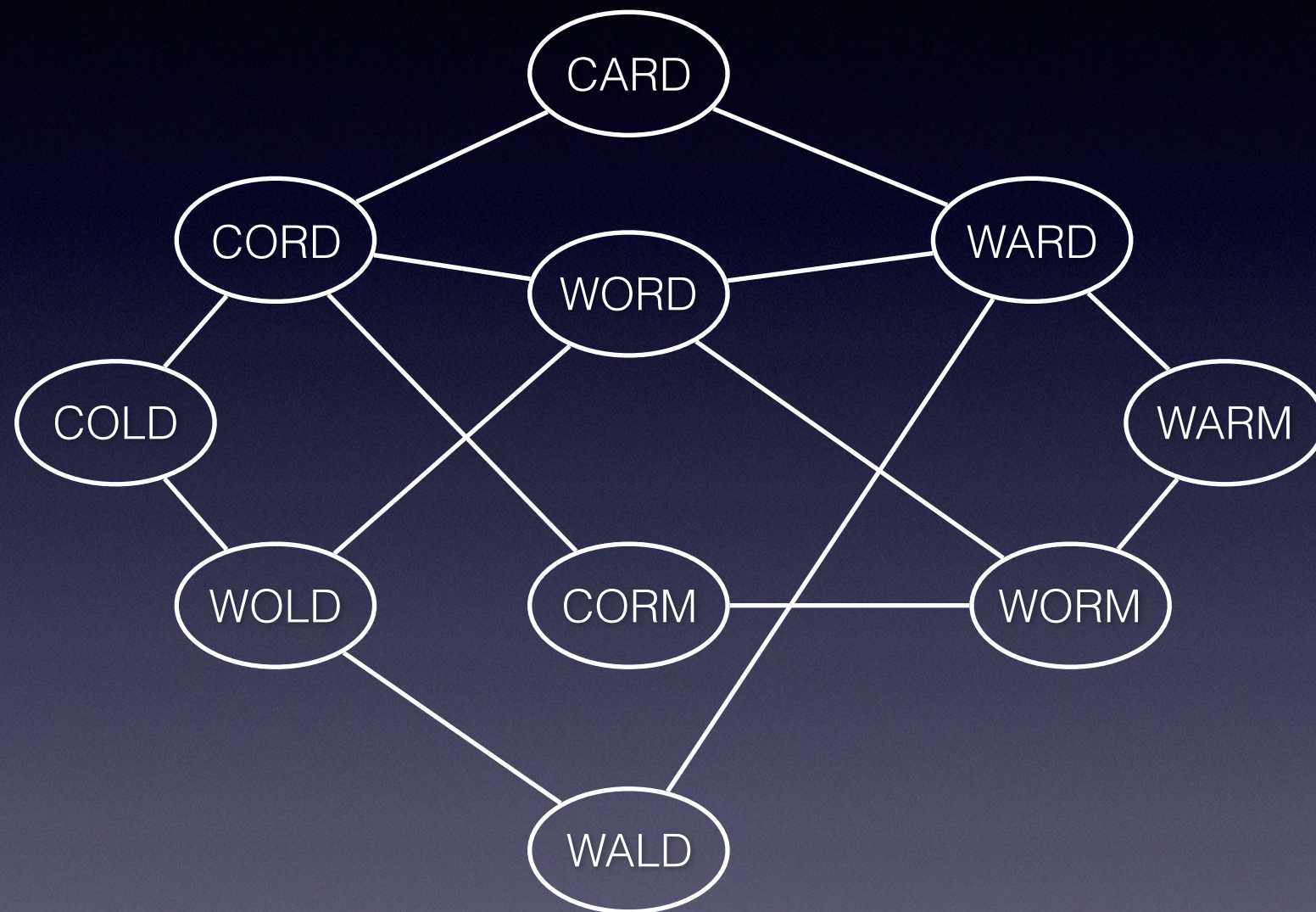
# Word Ladders

COLD → CORD → CARD → WARD → WARM  
COLD → CORD → CORM → WORM → WARM  
COLD → CORD → WORD → WARD → WARM  
COLD → CORD → WORD → WORM → WARM  
COLD → WOLD → WALD → WARD → WARM  
COLD → WOLD → WORD → WARD → WARM  
COLD → WOLD → WORD → WORM → WARM

As wikipedia knows, there are many ways to transform  
COLD to WARM



# Word Ladders



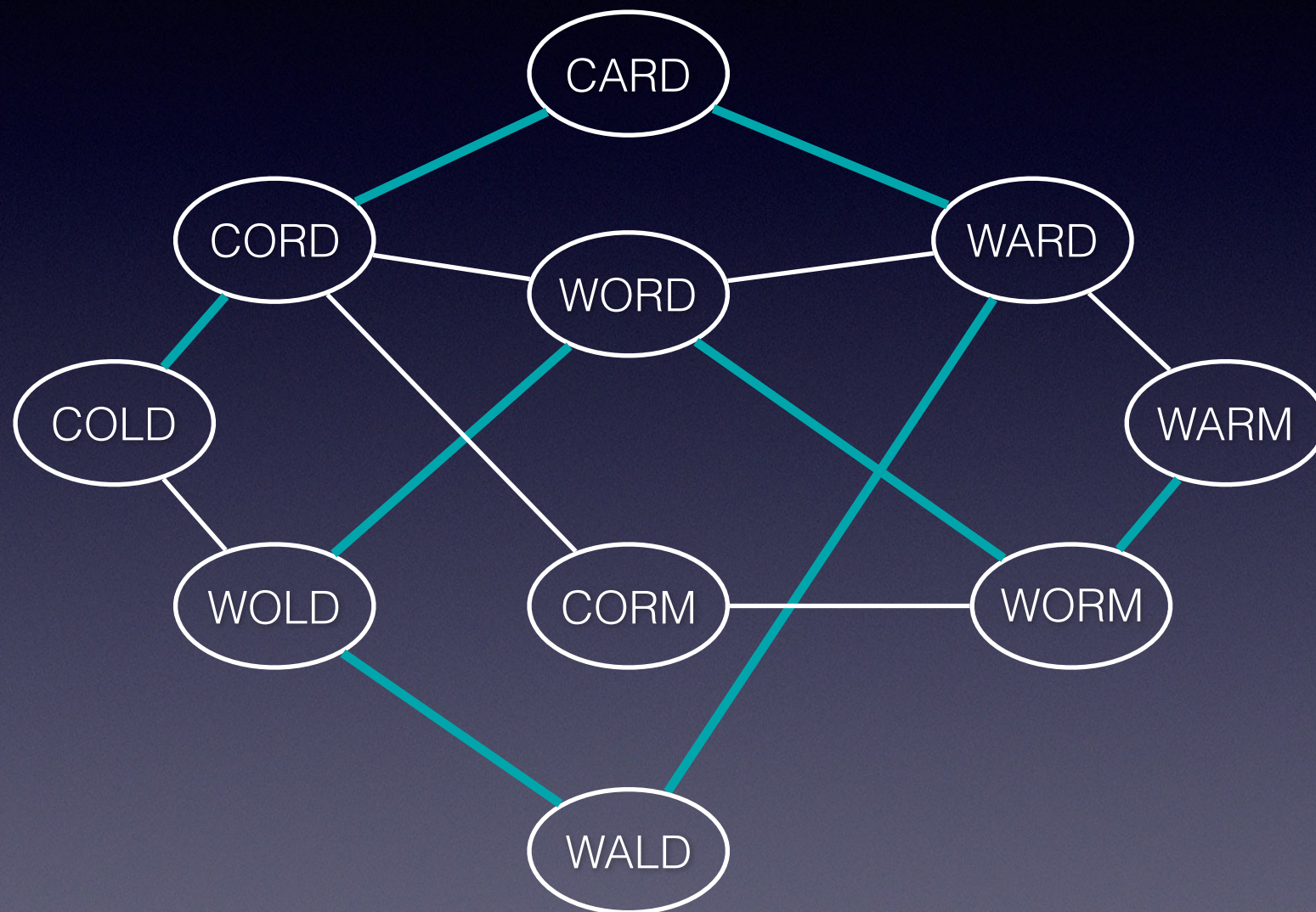
The vertices represent words

What defines an edge?

What is a path?



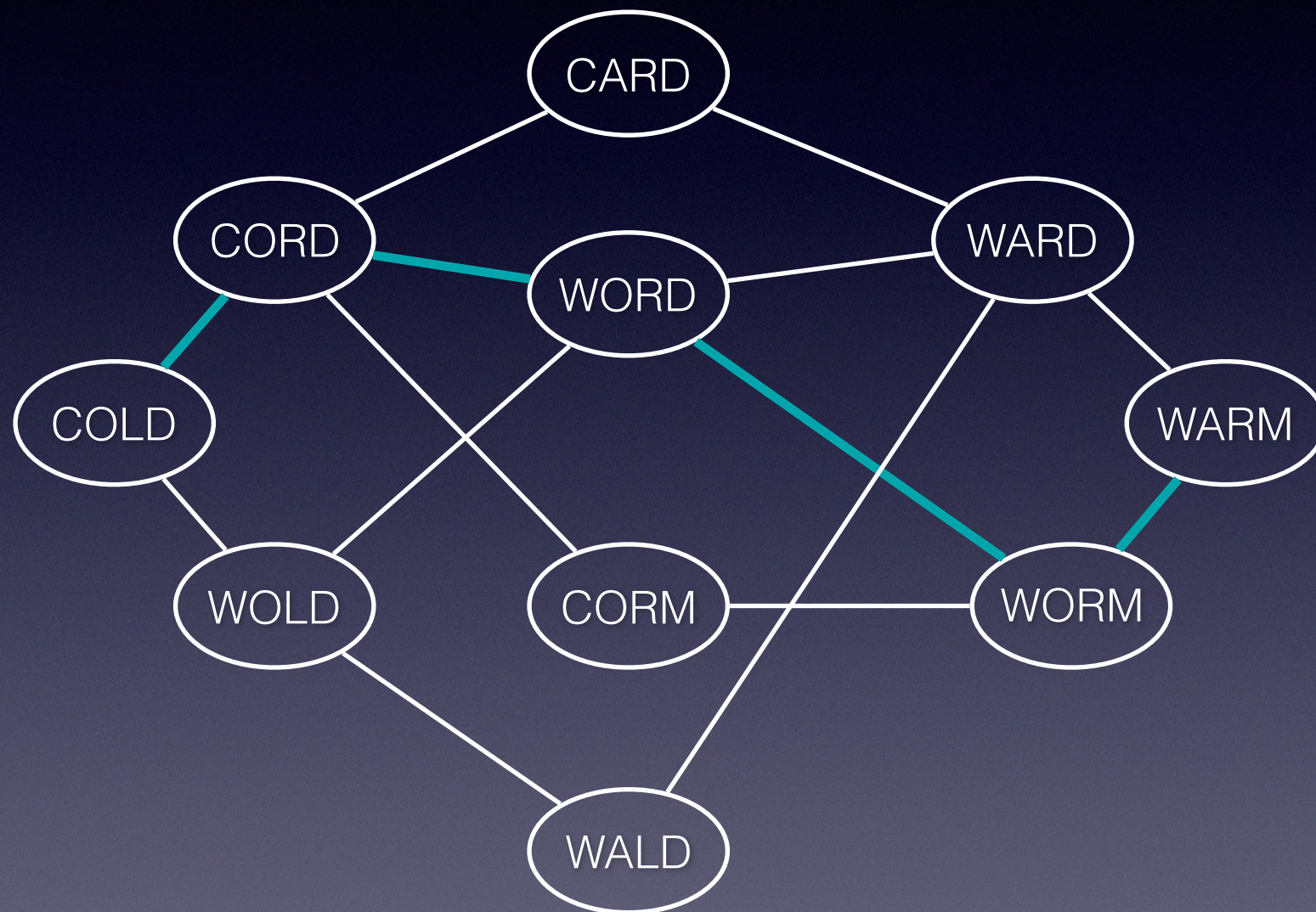
# Word Ladders



COLD  
CORD  
CARD  
WARD  
WALD  
WOLD  
WORD  
WORM  
WARM



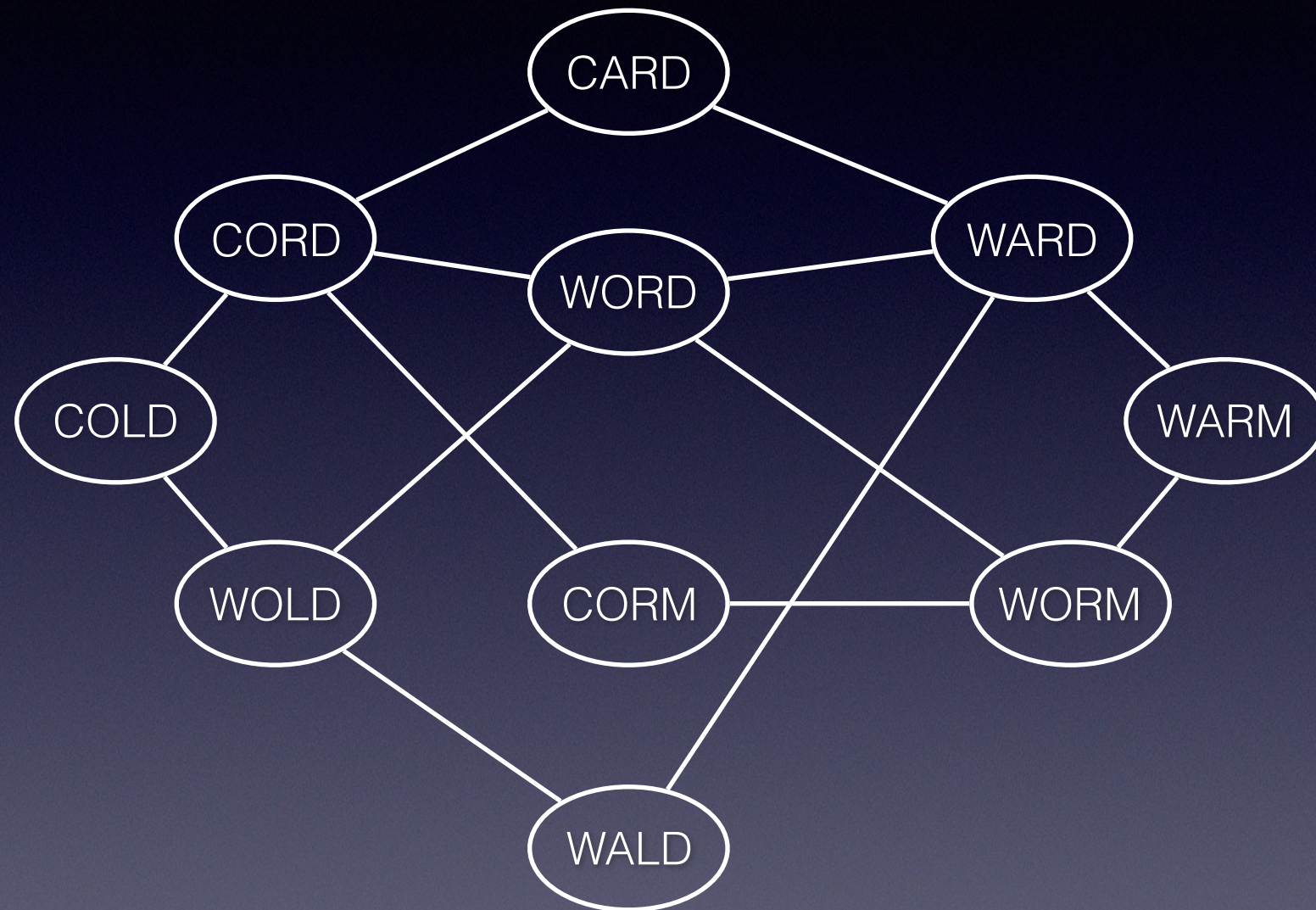
# Word Ladders



COLD  
CORD  
WORD  
WORM  
WARM



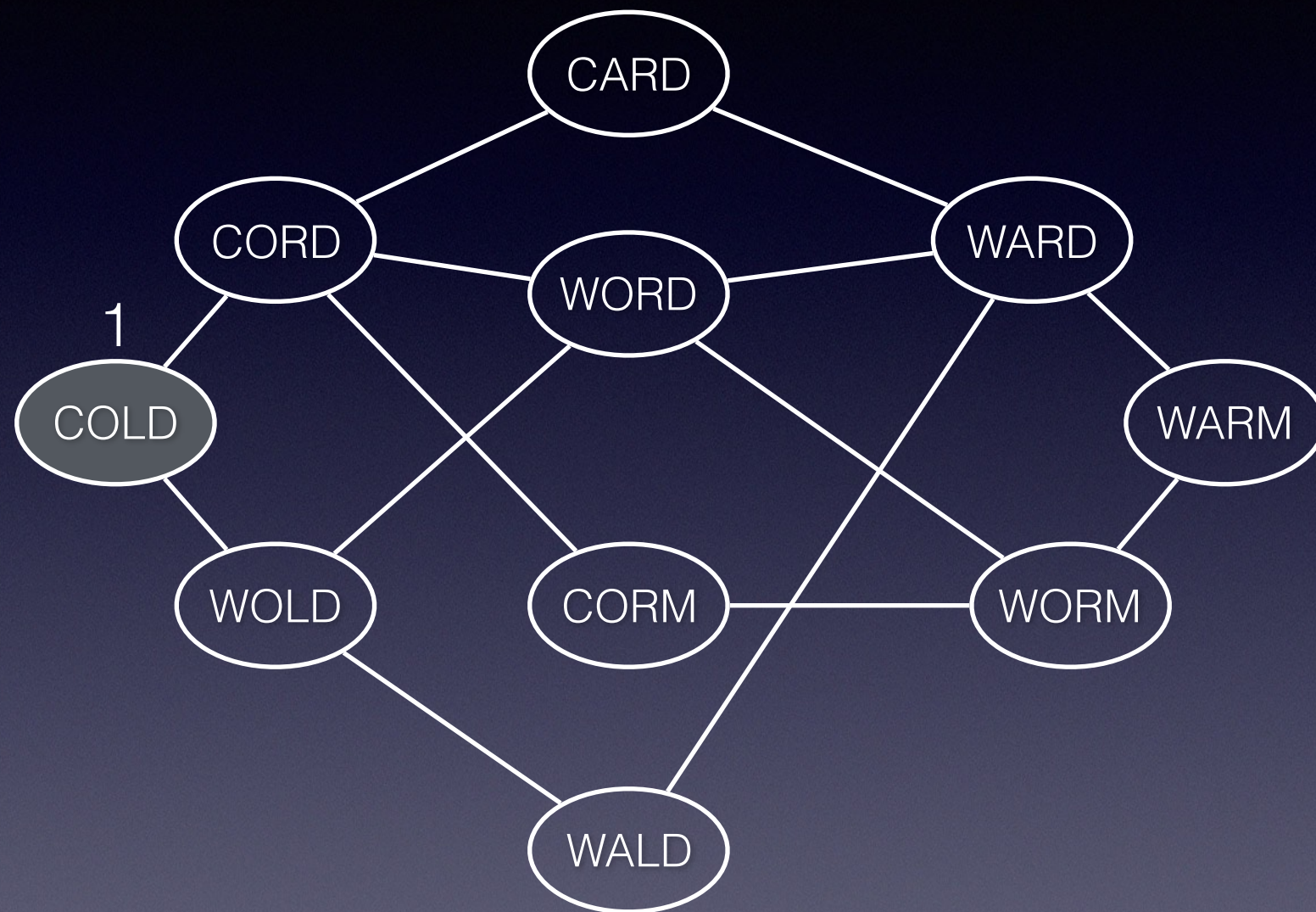
# Use breadth first search to find a shortest path



Queue: []  
Processing:



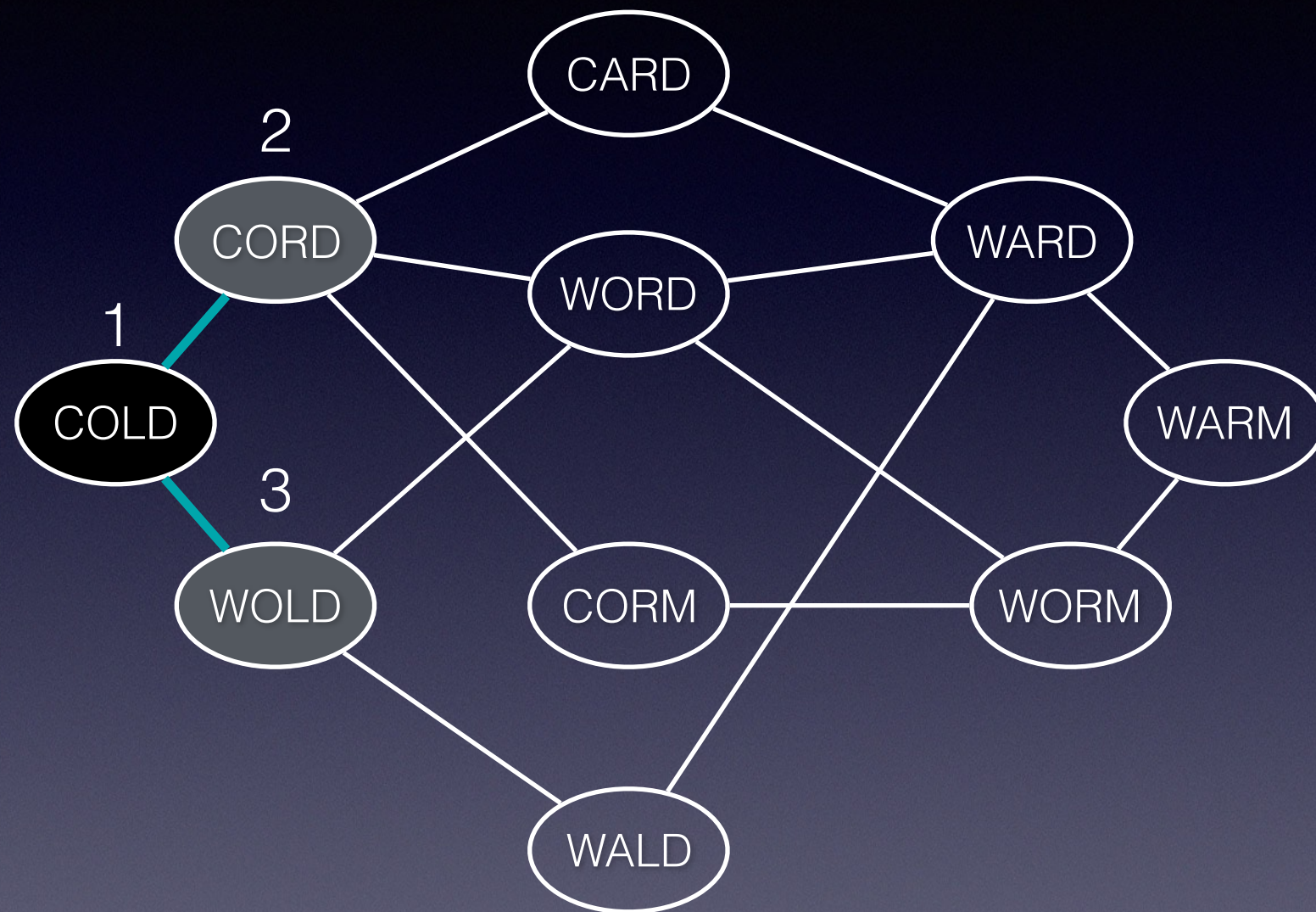
# Word Ladders



Queue: [COLD]  
Processing:



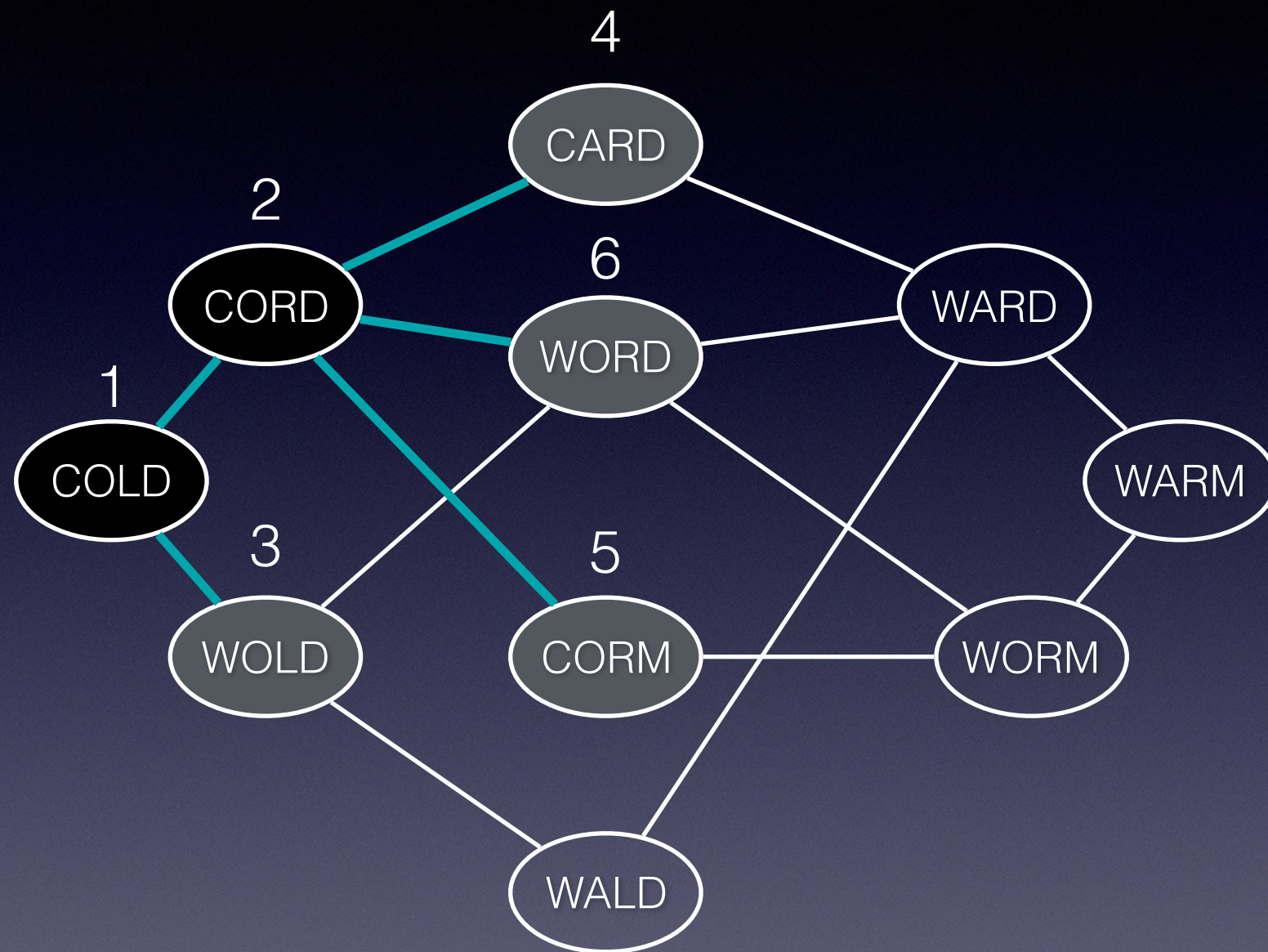
# Word Ladders



Queue: [WOLD, CORD]  
Processing: COLD



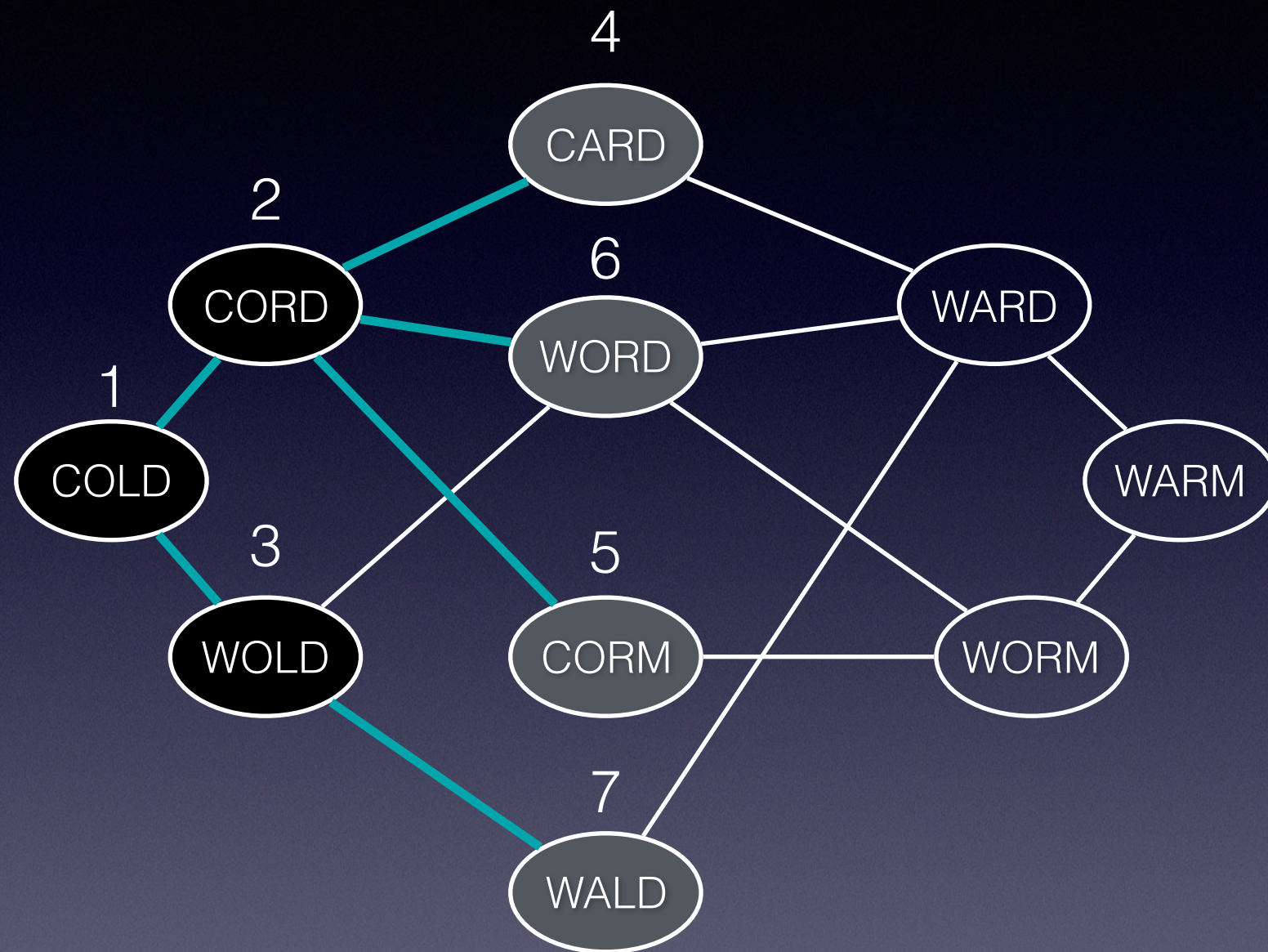
# Word Ladders



Queue: [WORD, CORM, CARD, WOLD]  
Processing: CORD



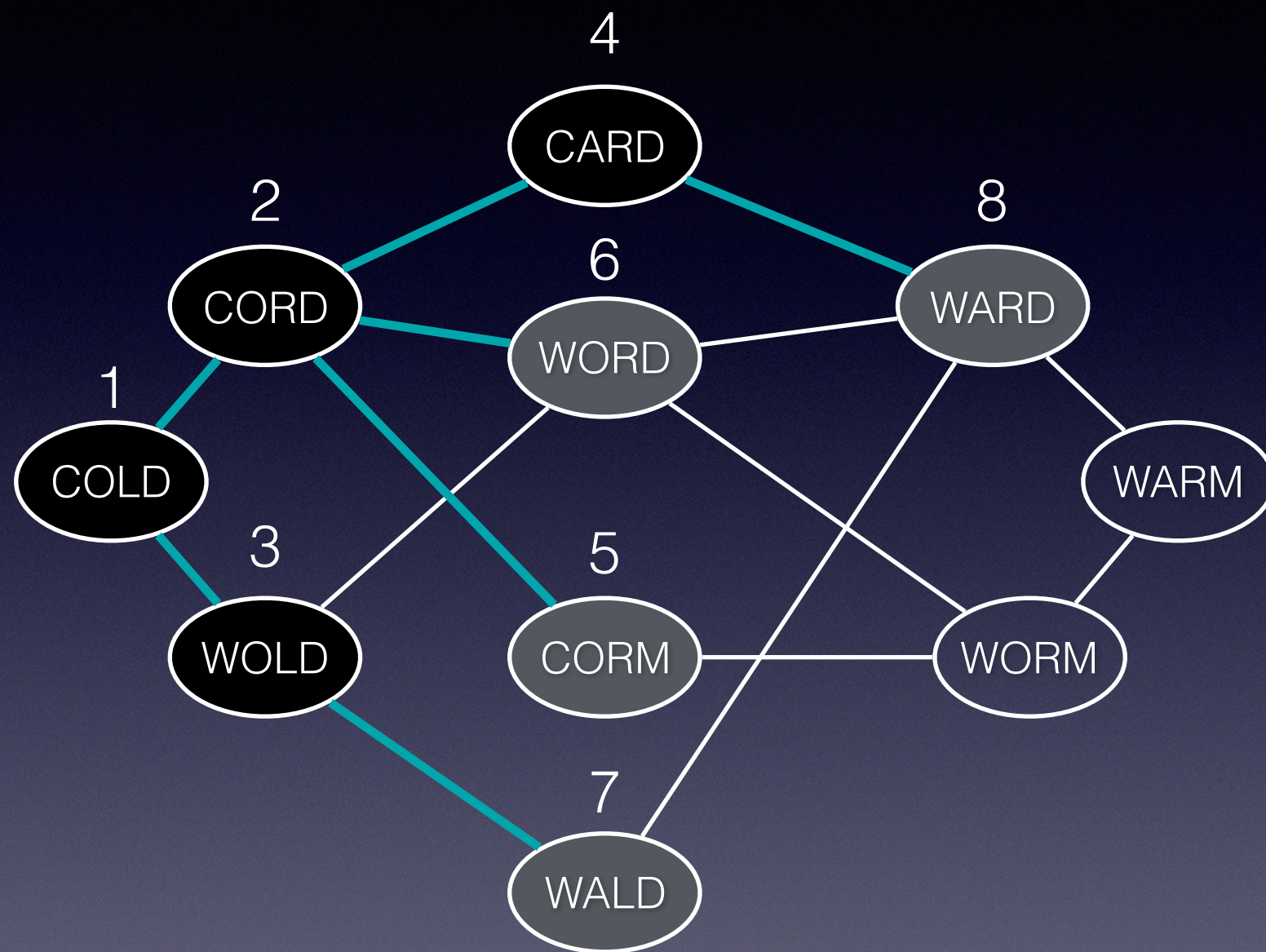
# Word Ladders



Queue: [WALD, WORD, CORM, CARD]  
Processing: WOLD



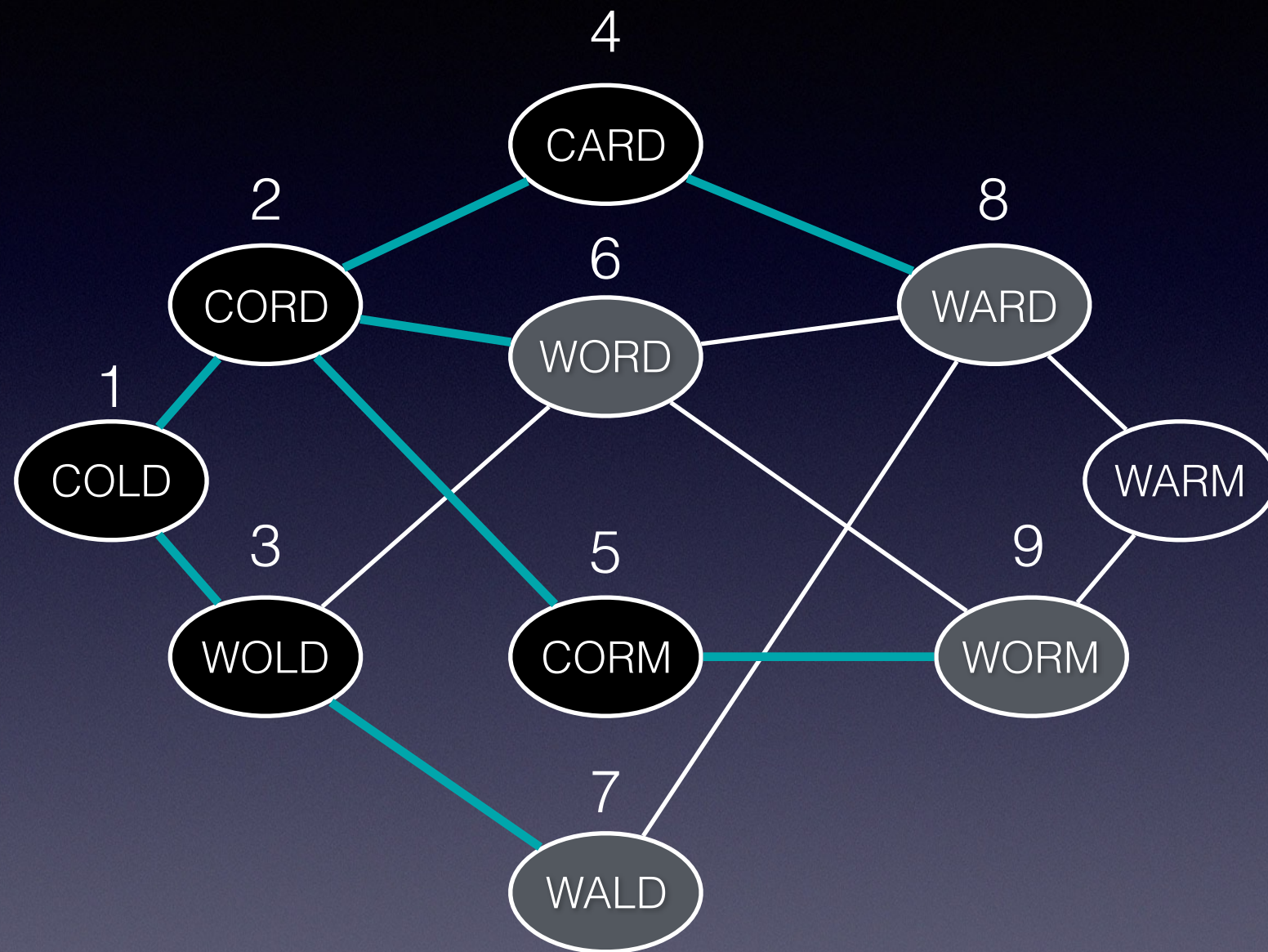
# Word Ladders



Queue: [WARD,WALD,WORD,CORM]  
Processing: CARD



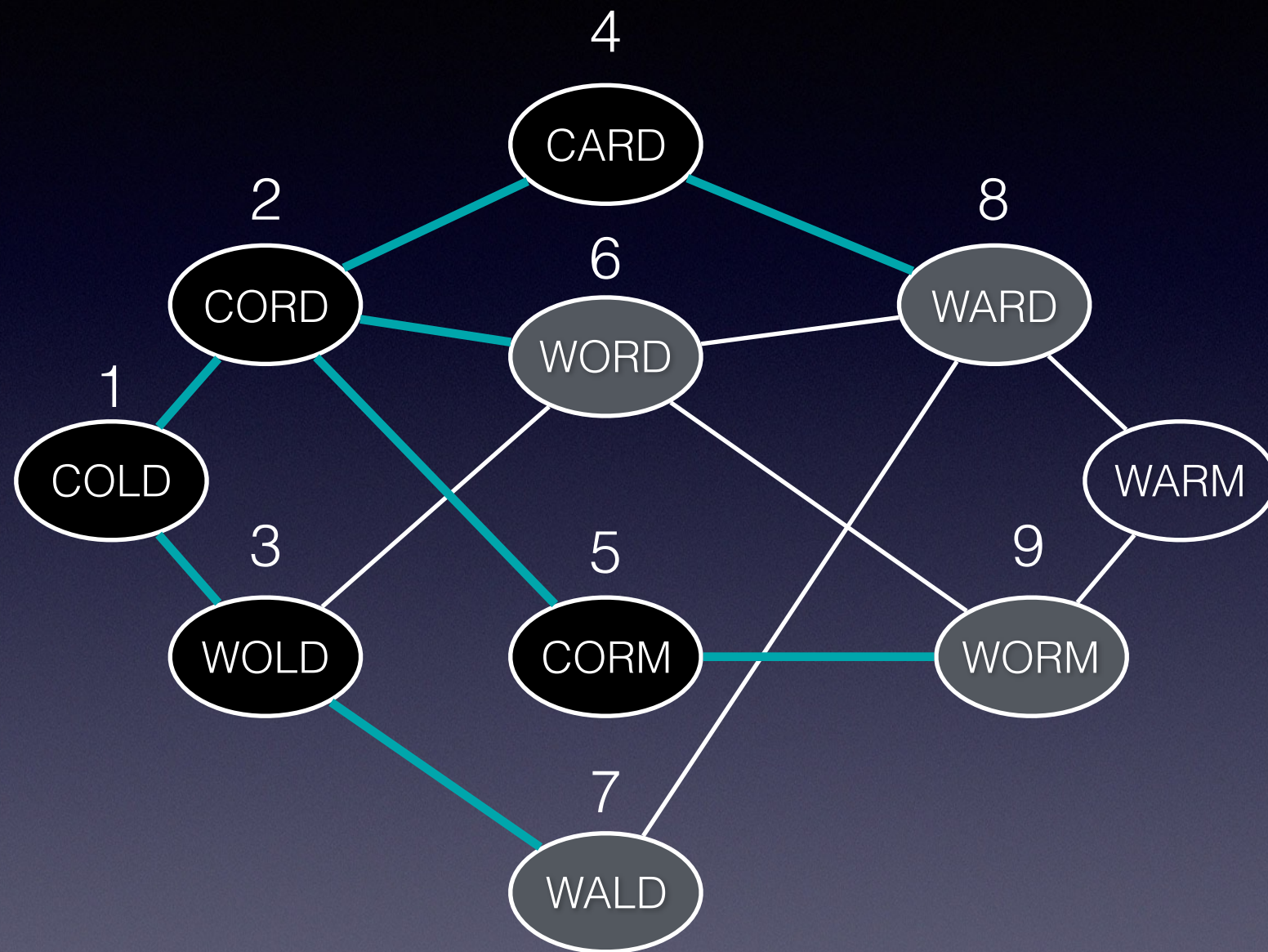
# Word Ladders



Queue: [WORM, WARD, WALD, WORD]  
Processing: CORM



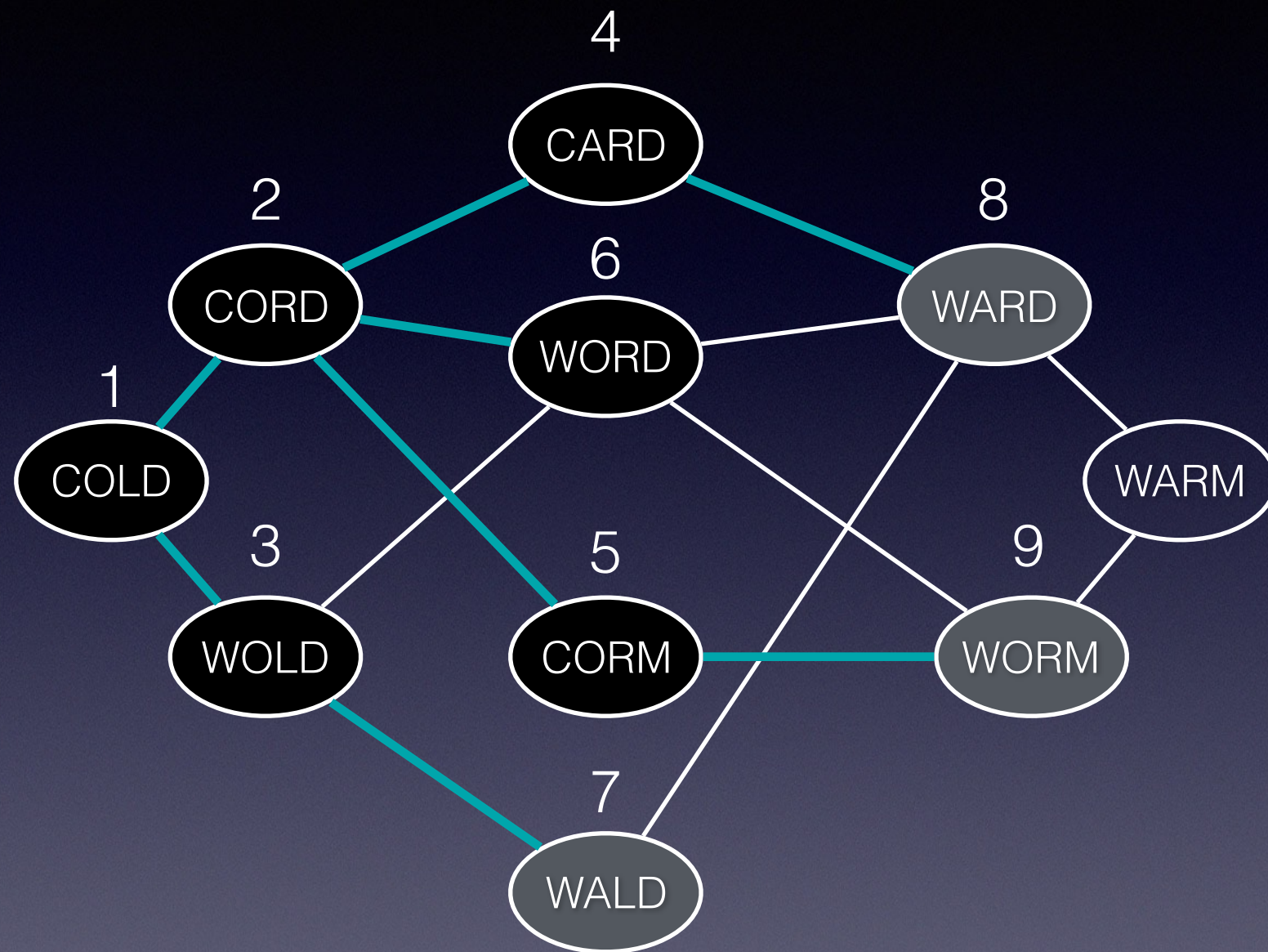
# Word Ladders



At this point we know the order in which the nodes will be processed. We get the last node for free. But let's continue



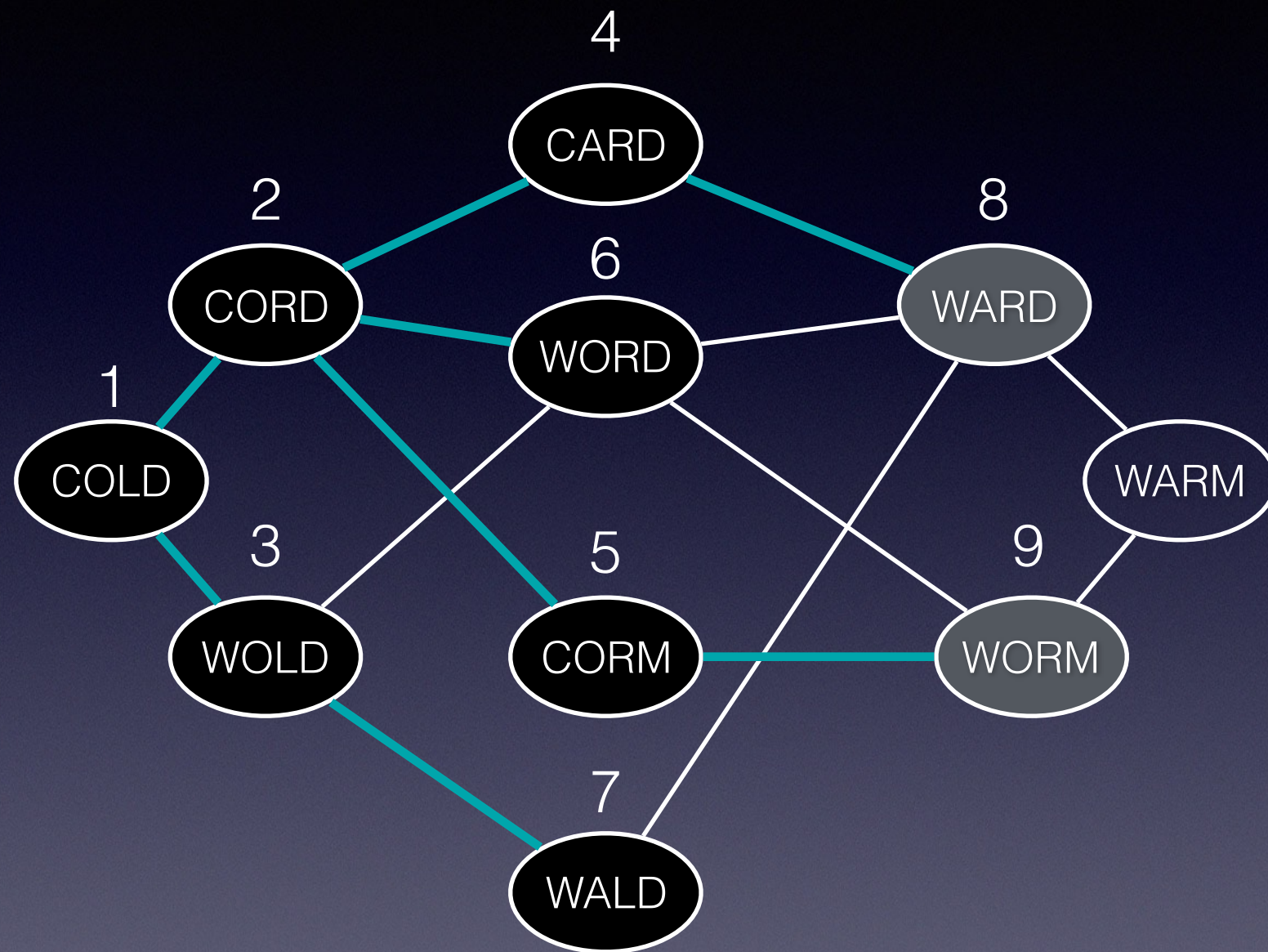
# Word Ladders



Queue: [WORM, WARD, WALD]  
Processing: WORD



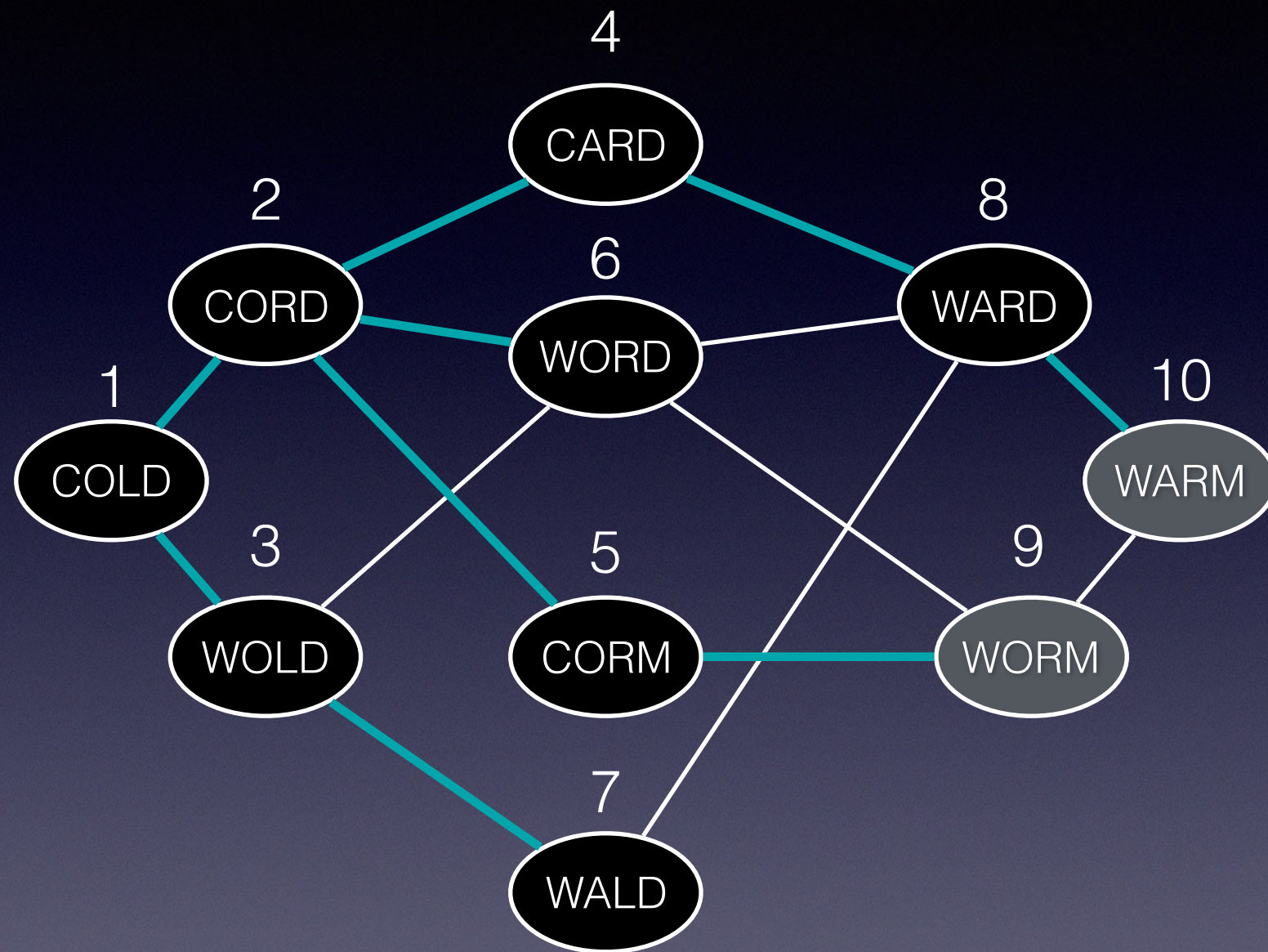
# Word Ladders



Queue: [WORM, WARD]  
Processing: WALD



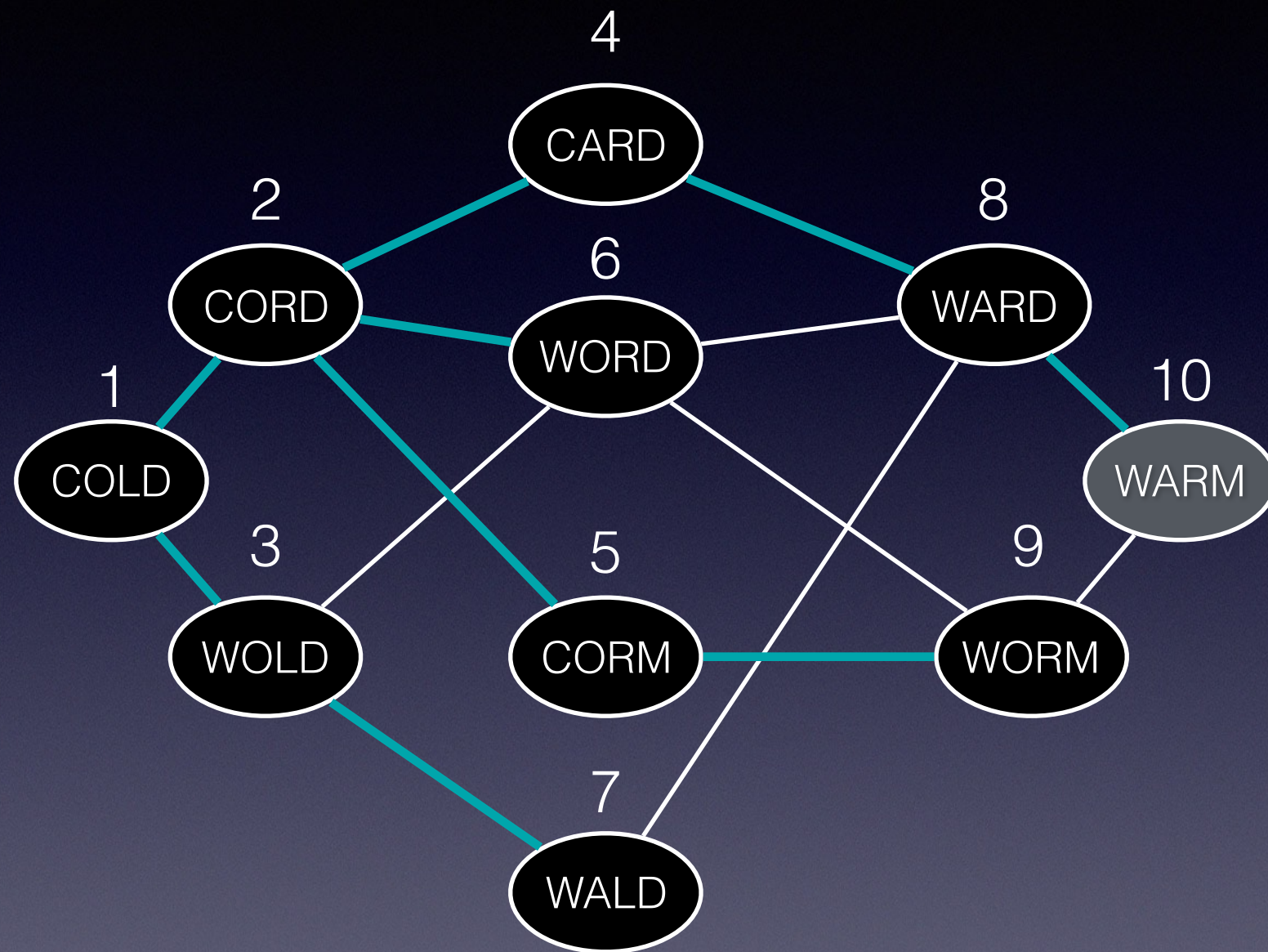
# Word Ladders



Queue: [WARM, WORM]  
Processing: WARD



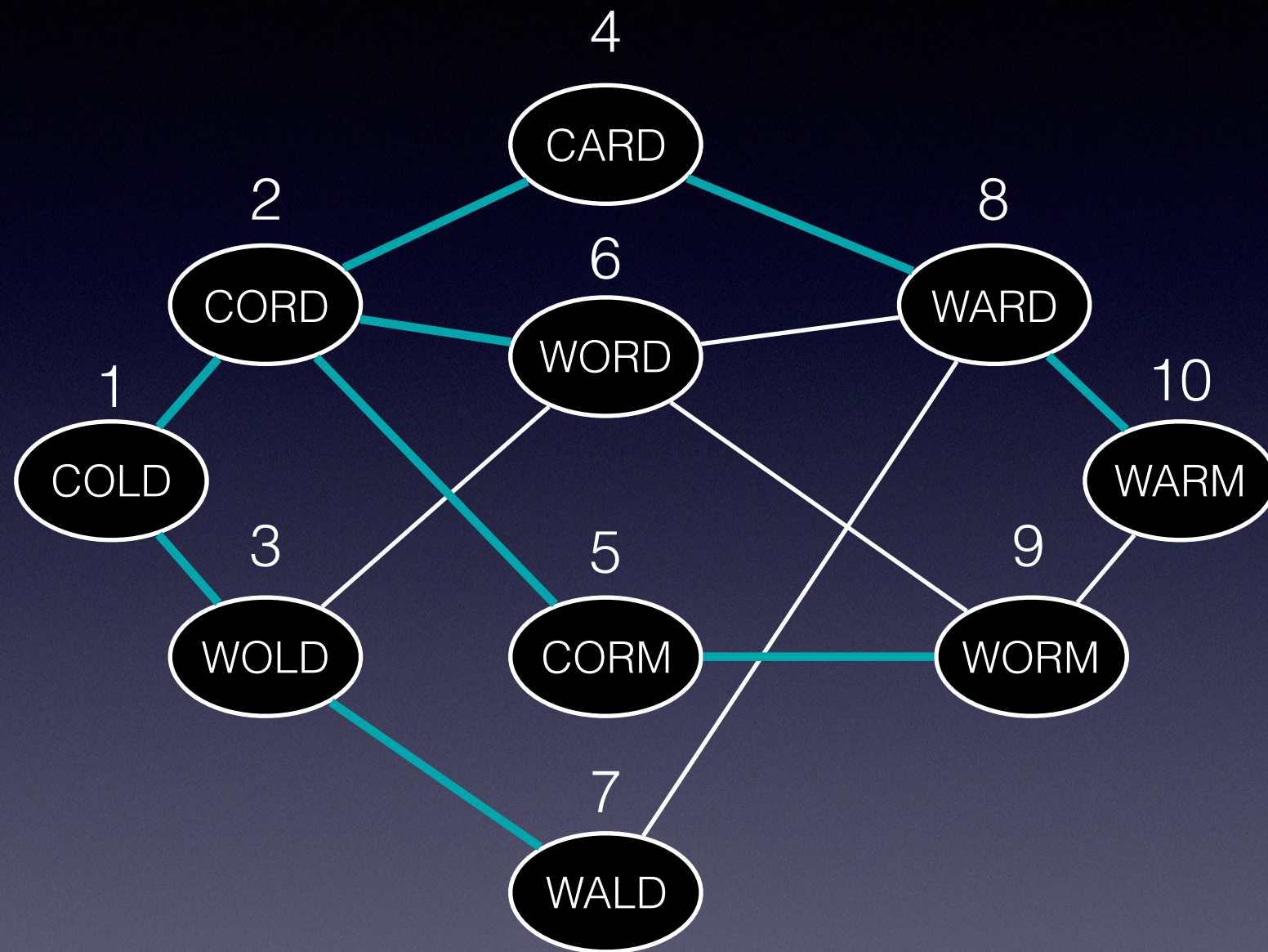
# Word Ladders



Queue: [WARM]  
Processing: WORM



# Word Ladders



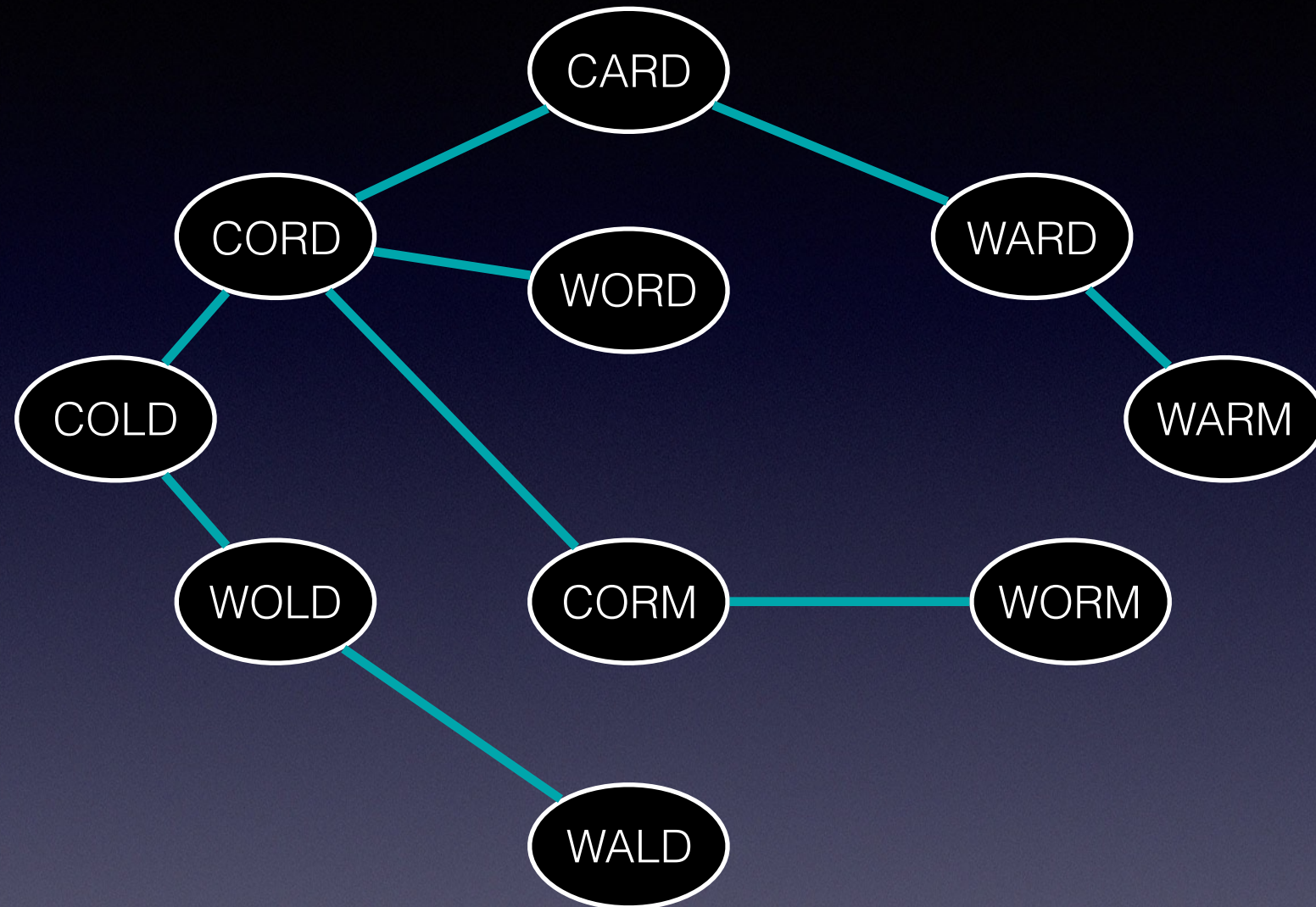
Queue: []

Processing: WARM

Done processing nodes



# Word Ladders



Notice that we have built a tree. Each path from the root to a leaf is a shortest word ladder from the root word to the leaf word. Though as we showed earlier, there may be others equally short





# THE ORACLE OF BACON



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How it Works

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Other stuff »

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Judi Dench has a Bacon number of 2.

Find a different link

Judi Dench

was in

Mrs Henderson Presents

with

Toby Jones

was in

Frost/Nixon

with

Kevin Bacon

Do you know about the six degrees of separation?  
How about the six degrees of Kevin Bacon?  
How would you use a graph here?

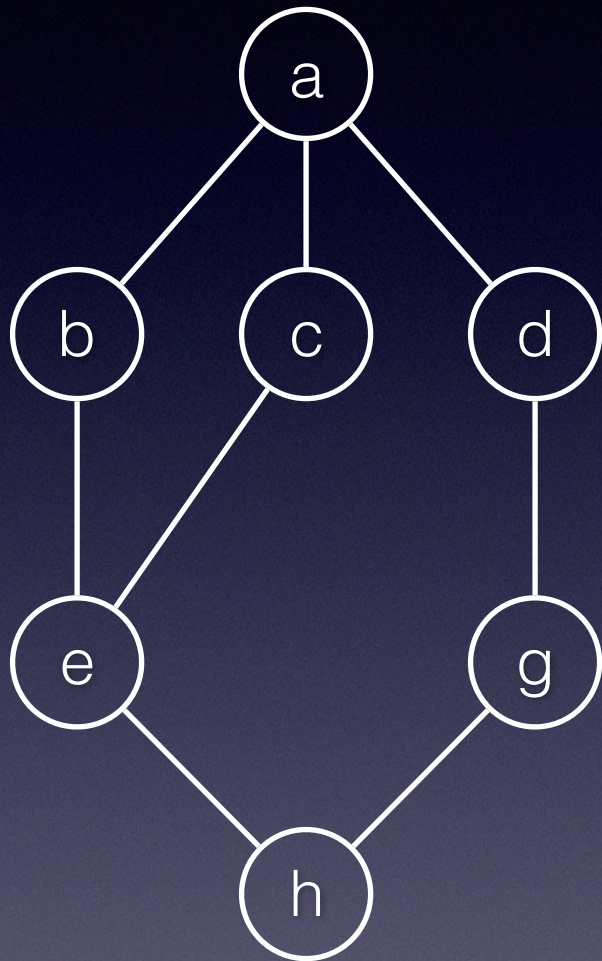


# Depth-first concept

- Starting at a source vertex  $s$
- Follow a simple path discovering new vertices until you cannot find a new vertex
- Back-up until you can start finding new vertices
- Creates a "depth first tree"



# Depth-first search



What's the order in which these vertices will be visited?

Assume that when we have a choice of which edge to follow, we always follow the edge connected to the alphabetically smallest vertex first.



# Iterative depth-first algorithm

Take a start vertex and push it on a stack.

While the stack is not empty

    Pop a vertex,  $u$ , from the stack (Begin visiting  $u$ )

    If not visited, mark it visited (color it **grey**)

    For all vertices  $v$ , adjacent to  $u$ : (ordered z-a)\*

        If  $v$  is still **white**

            Push it on the stack

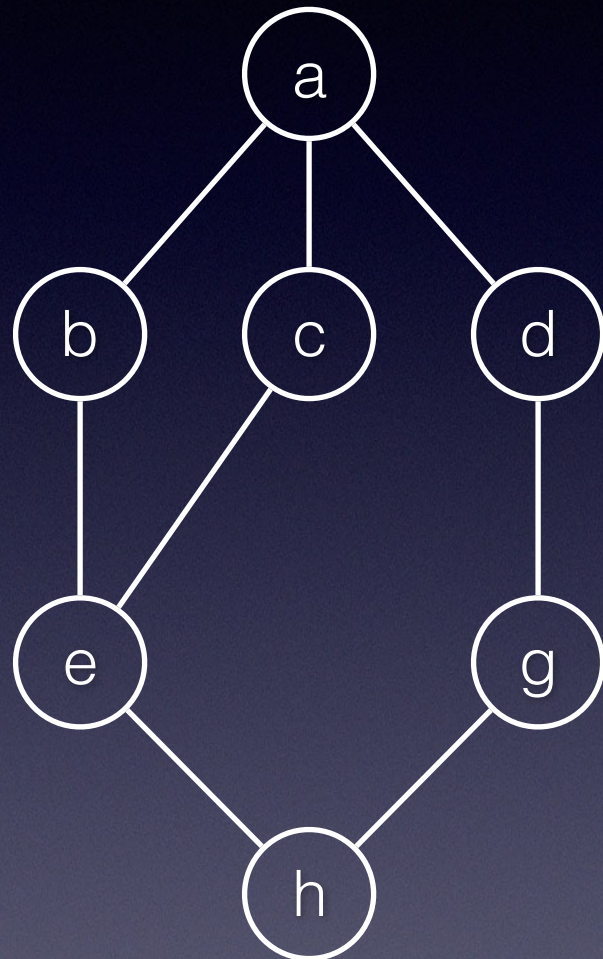
    We are now done visiting  $u$  (color it **black**)

This is the same as the breadth-first algorithm, except (1) it uses a **stack** instead of a **queue**, and (2) it marks a vertex as identified after it is popped from the stack, not before.

\* For a iterative algorithm, to visit nodes from a-z, we need to reverse their order before pushing them onto the stack.



# Depth-first search



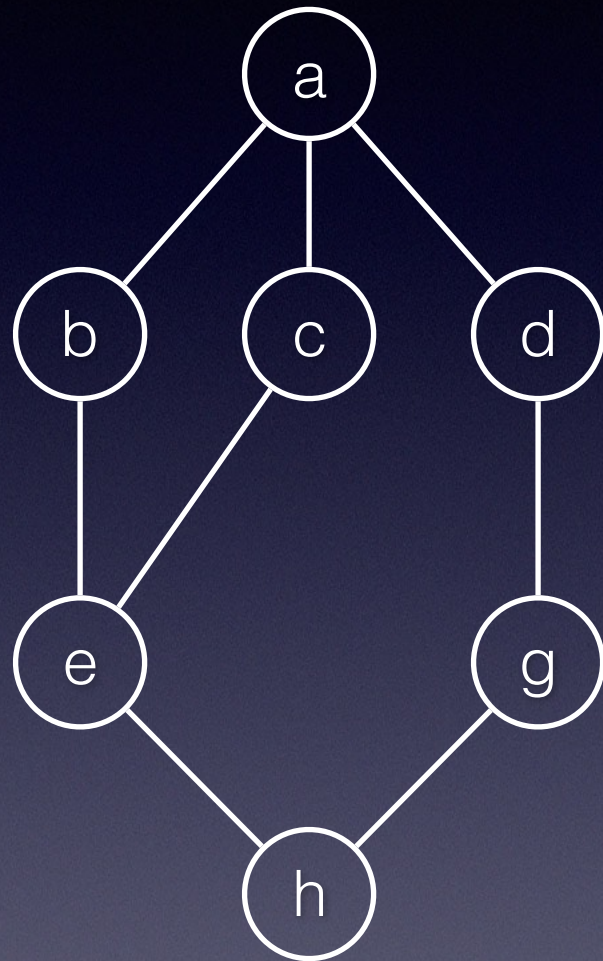
Stack: []

(right is top of stack)

Visiting:



# Depth-first search



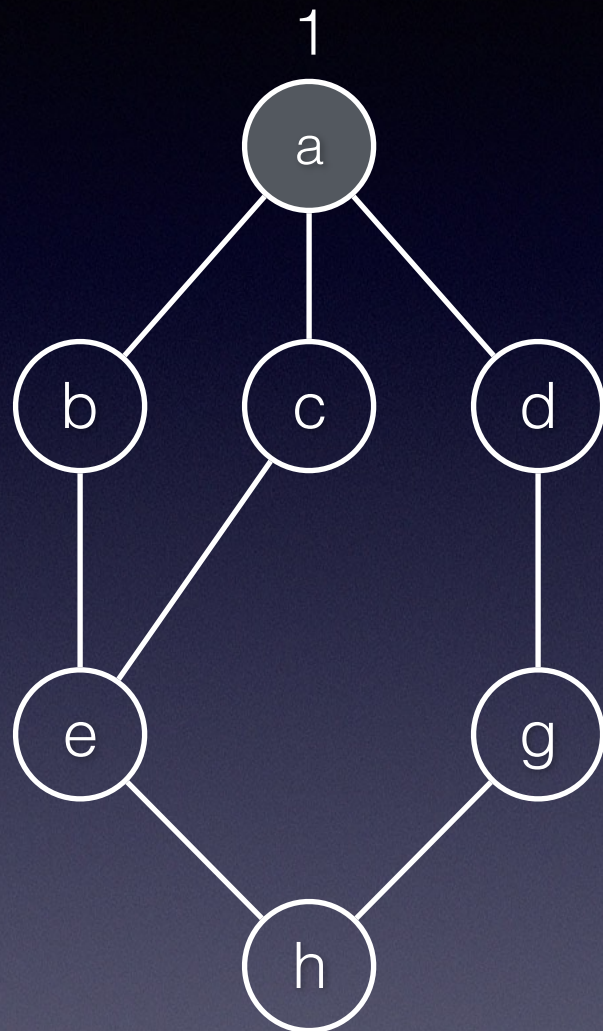
Stack: [a]

(right is top of stack)

Visiting:



# Depth-first search



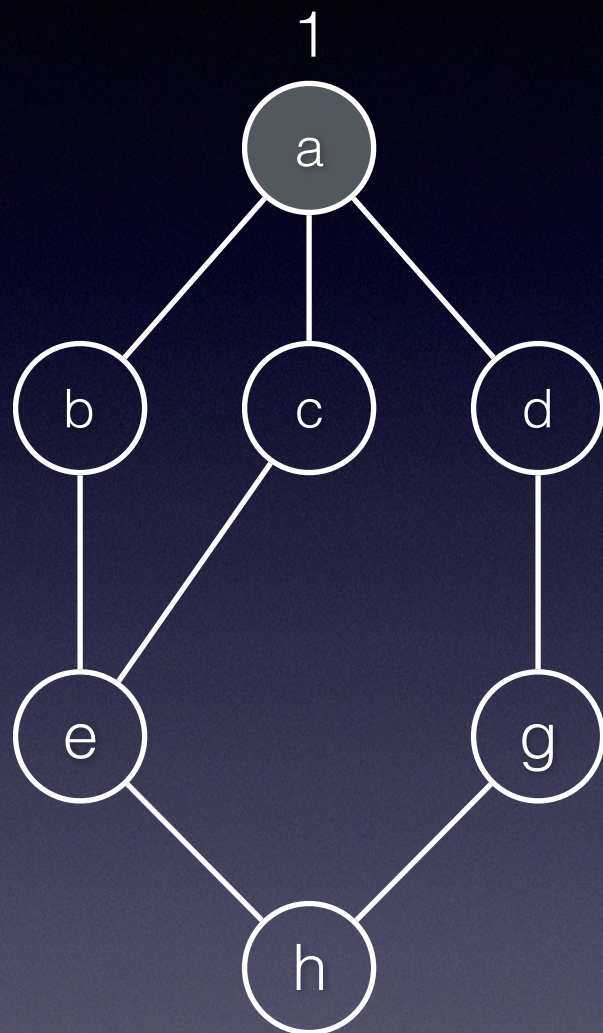
Stack: []

Visiting: a

We will number the vertices in the order they are first visited. This is not essential to implementing the algorithm



# Depth-first search

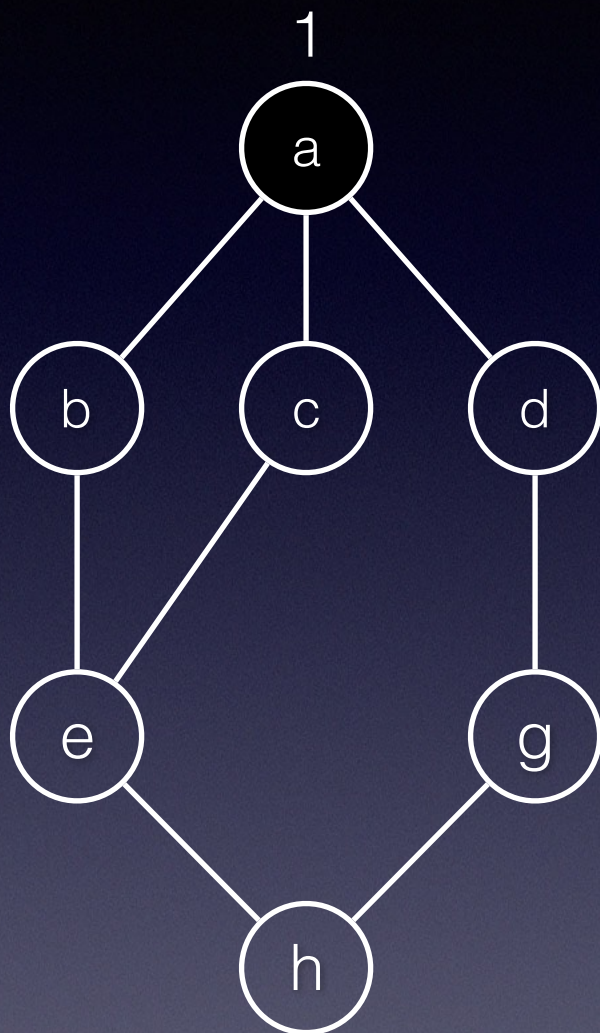


Stack: [d,c,b]

Visiting: a



# Depth-first search



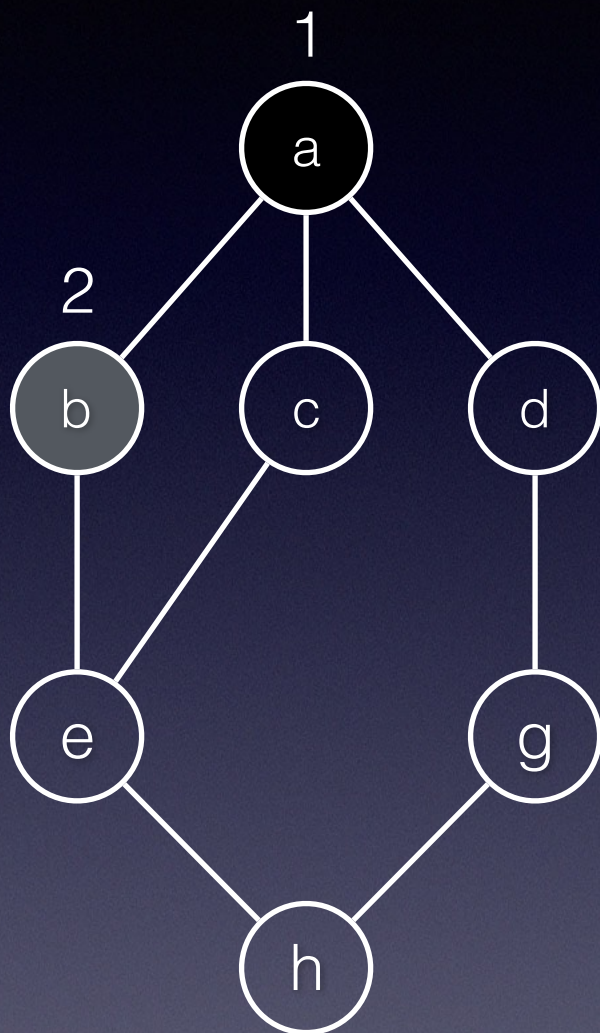
Stack: [d,c,b]

Visiting:





# Depth-first search



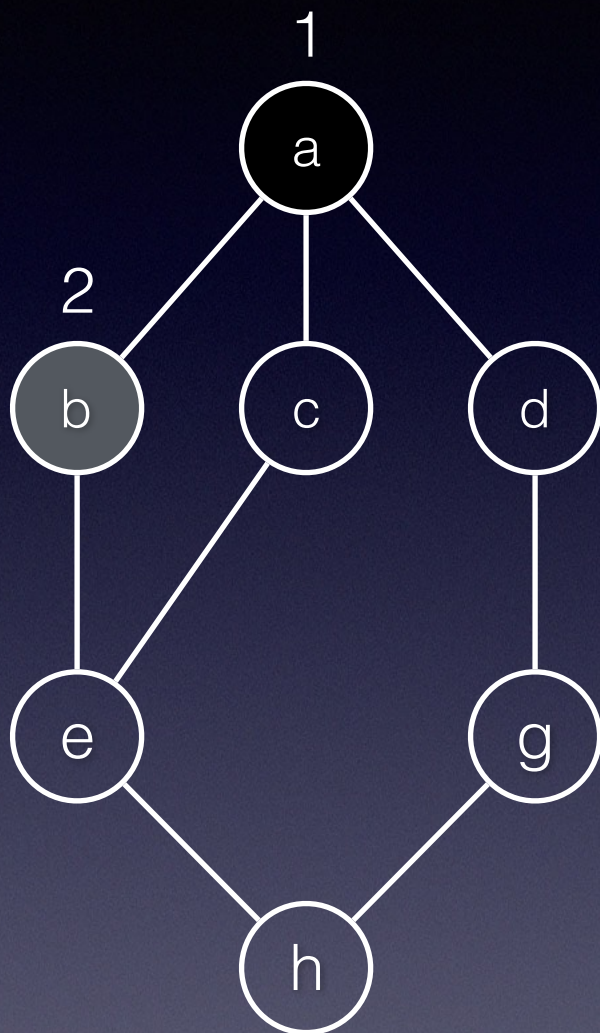
Stack: [d,c]

Visiting: b





# Depth-first search



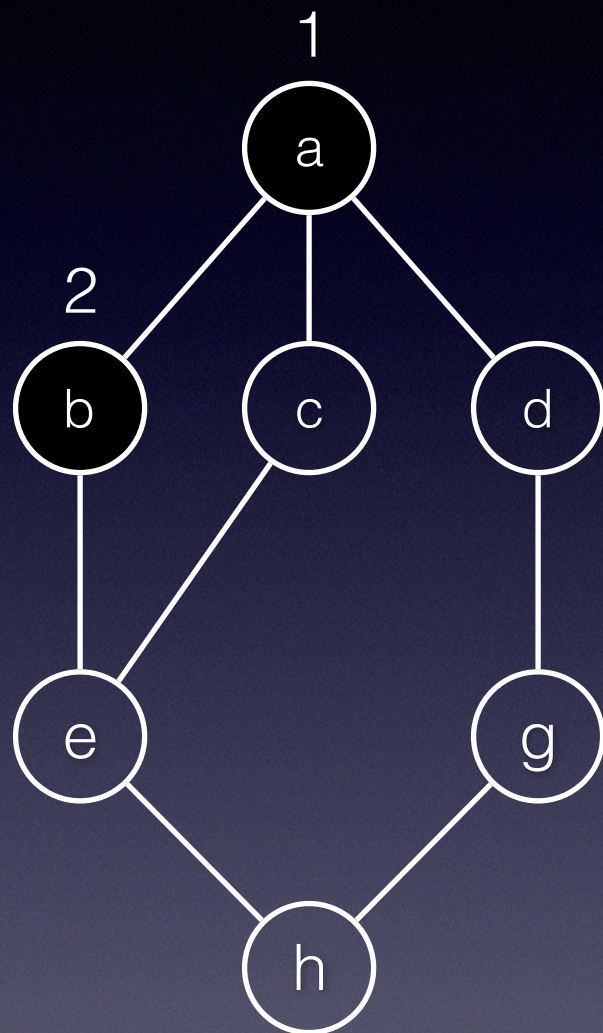
Stack: [d,c,e]

Visiting: b



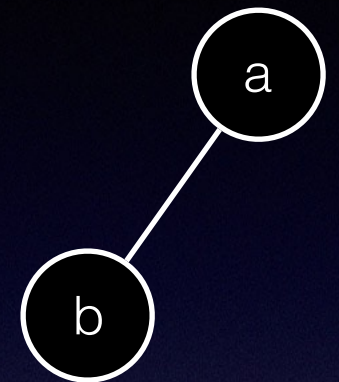


# Depth-first search



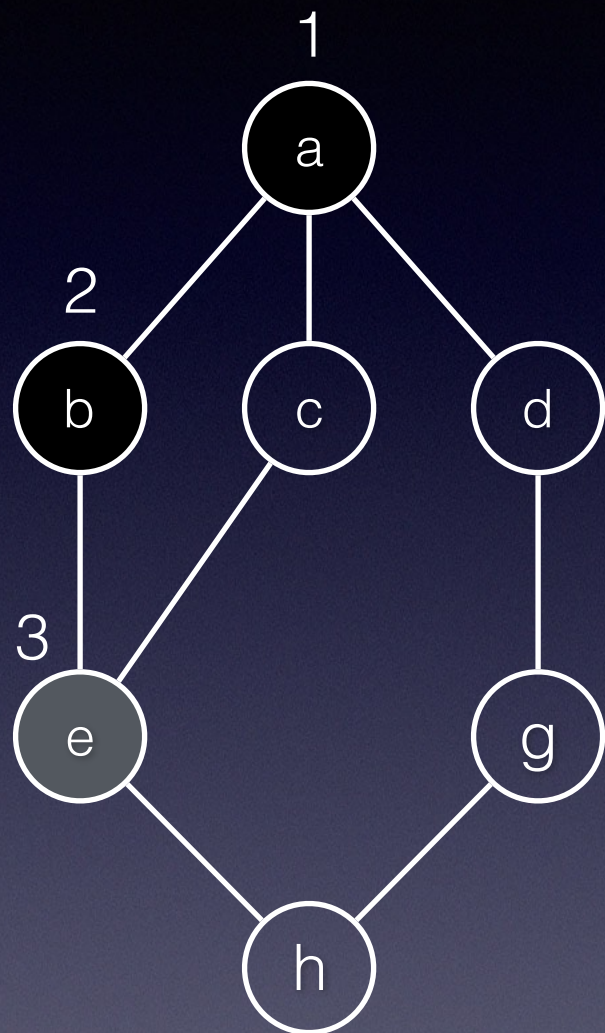
Stack: [d,c,e]

Visiting:



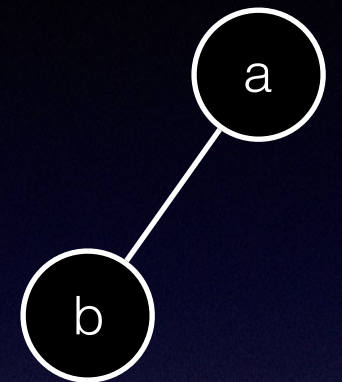


# Depth-first search



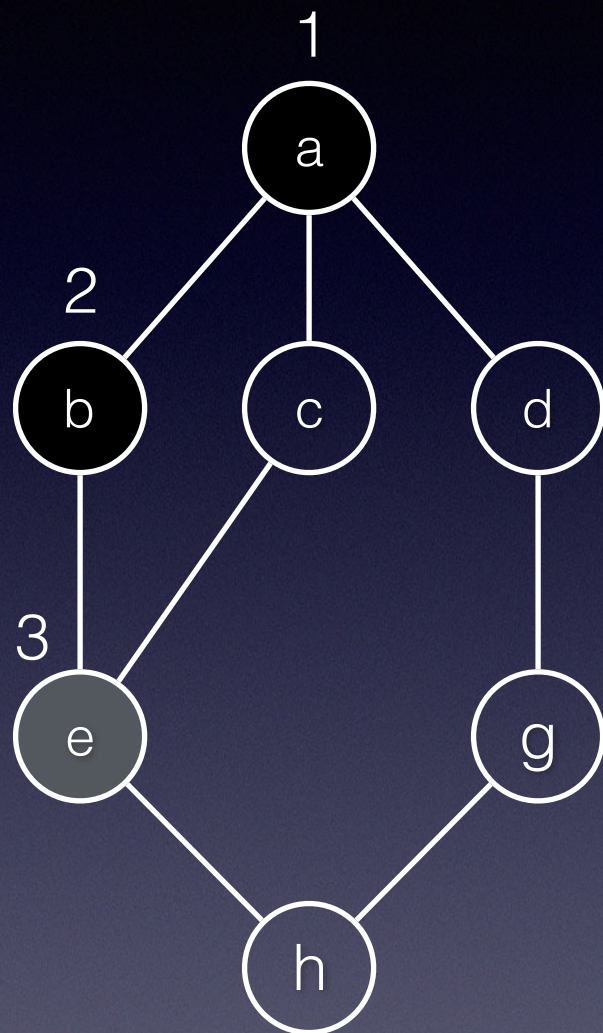
Stack: [d,c]

Visiting: e



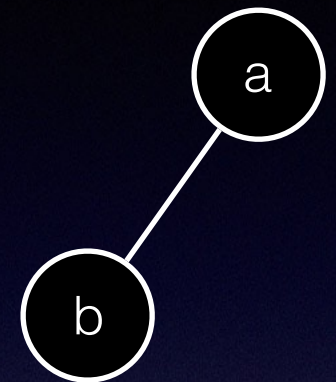


# Depth-first search



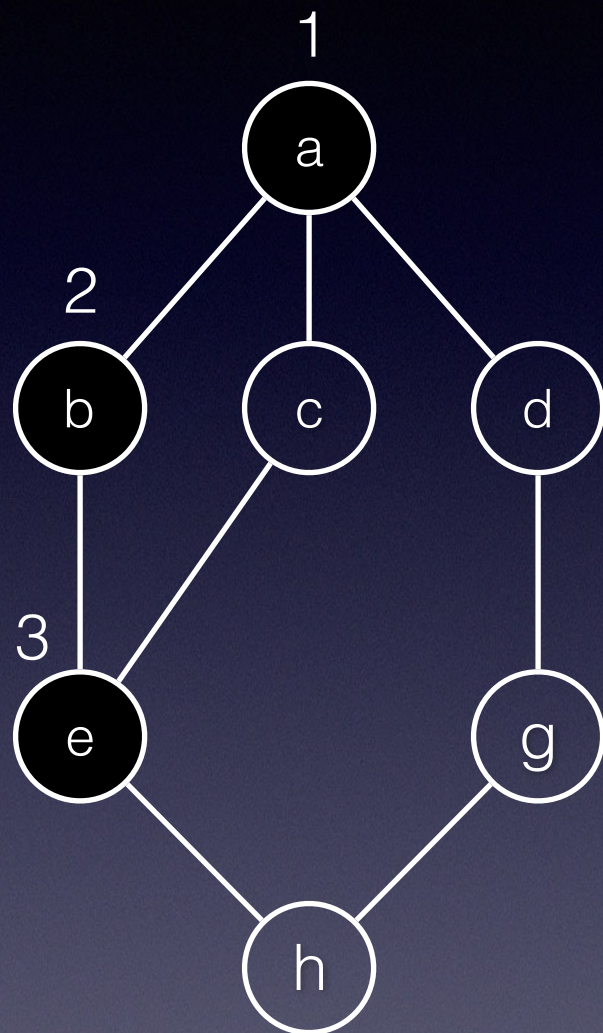
Stack: [d,c,h,c]

Visiting: e



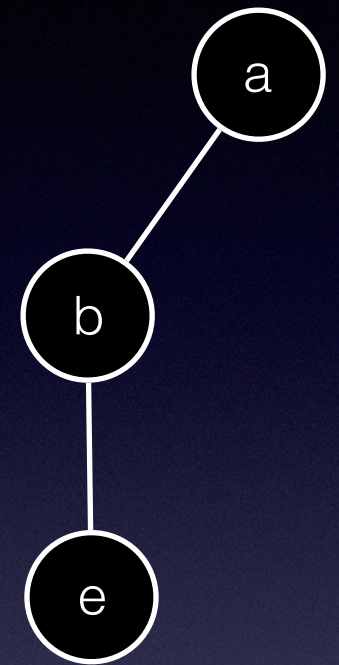


# Depth-first search



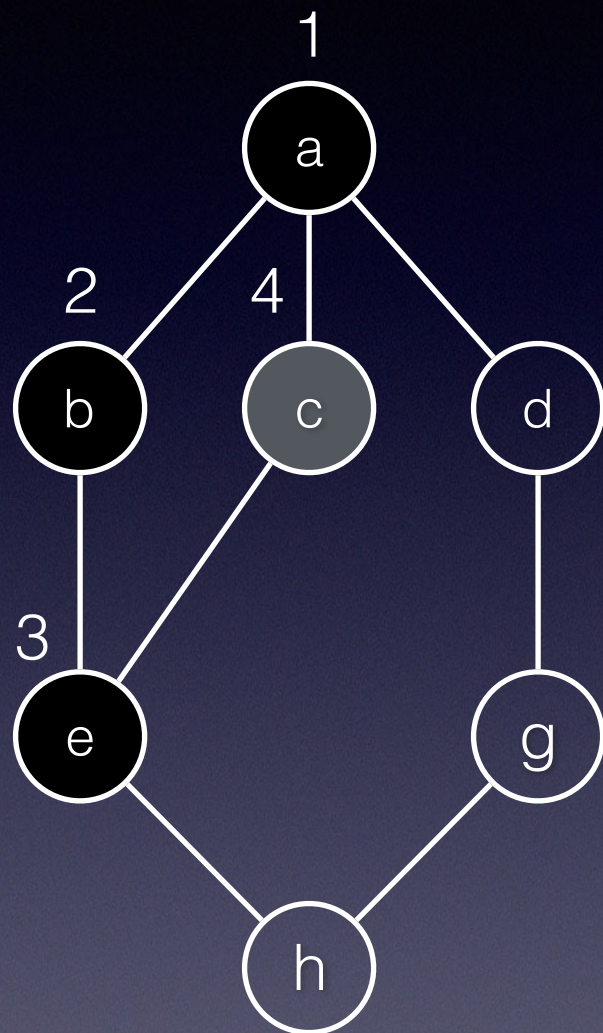
Stack: [d,c,h,c]

Visiting:



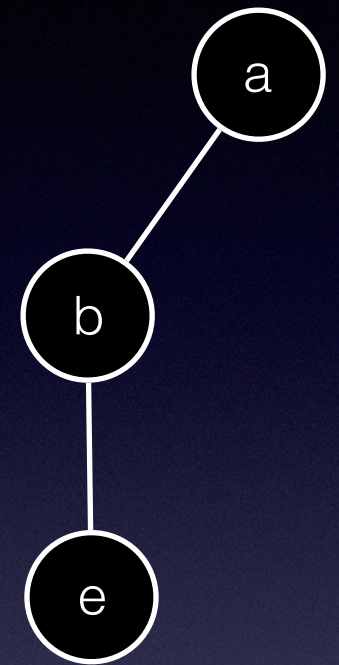


# Depth-first search



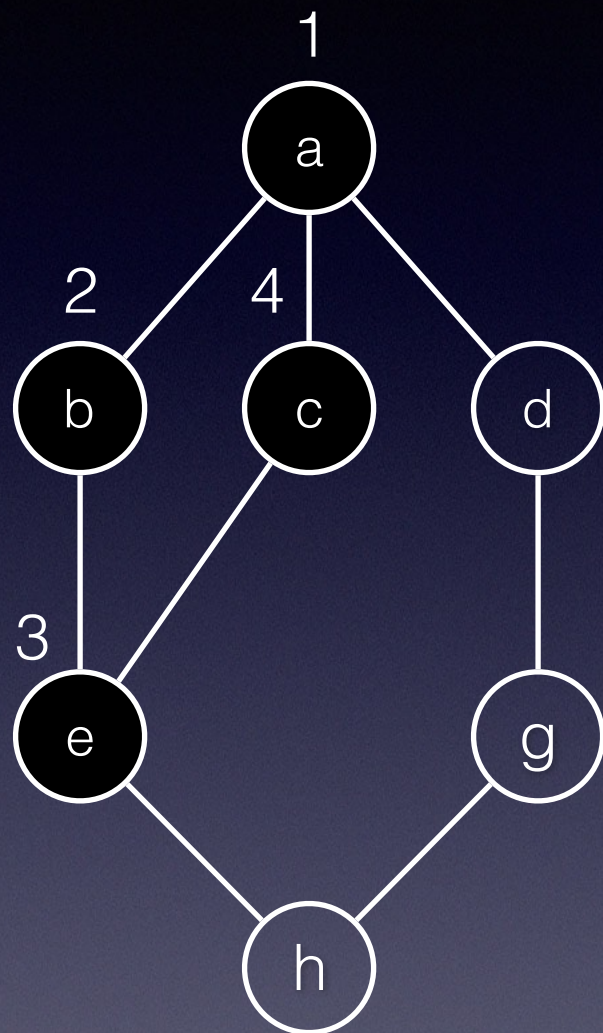
Stack: [d,c,h]

Visiting: c



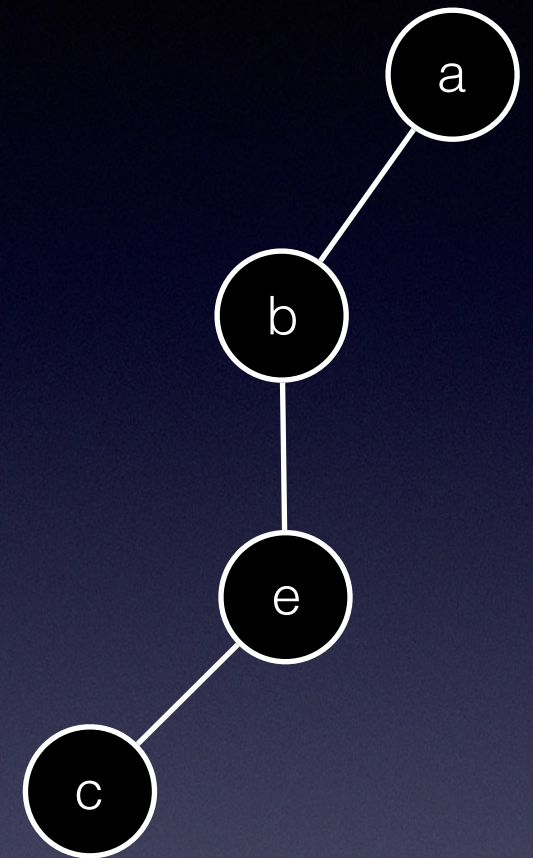


# Depth-first search



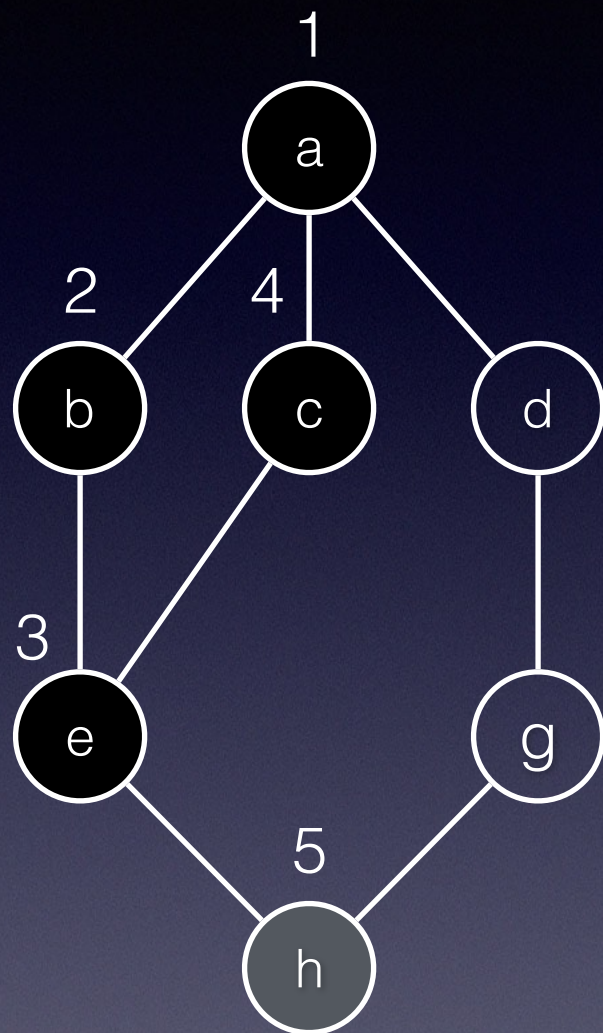
Stack: [d,c,h]

Visiting:



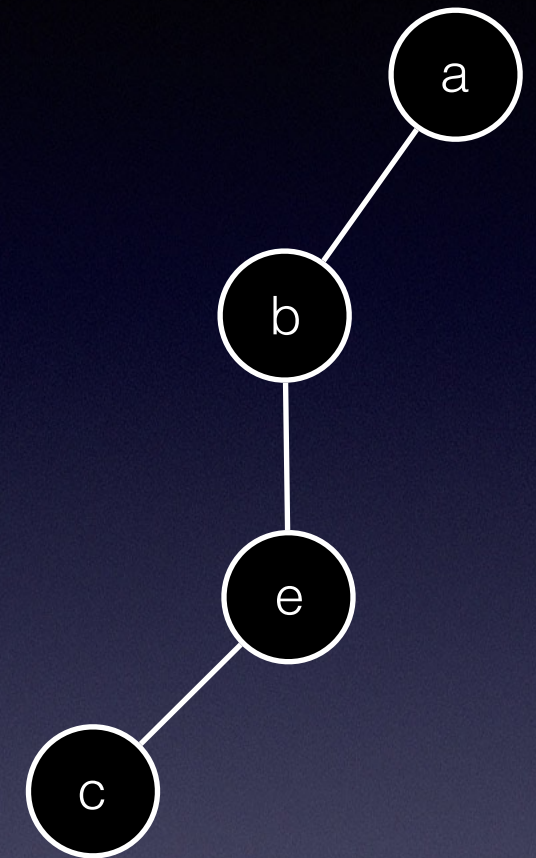


# Depth-first search



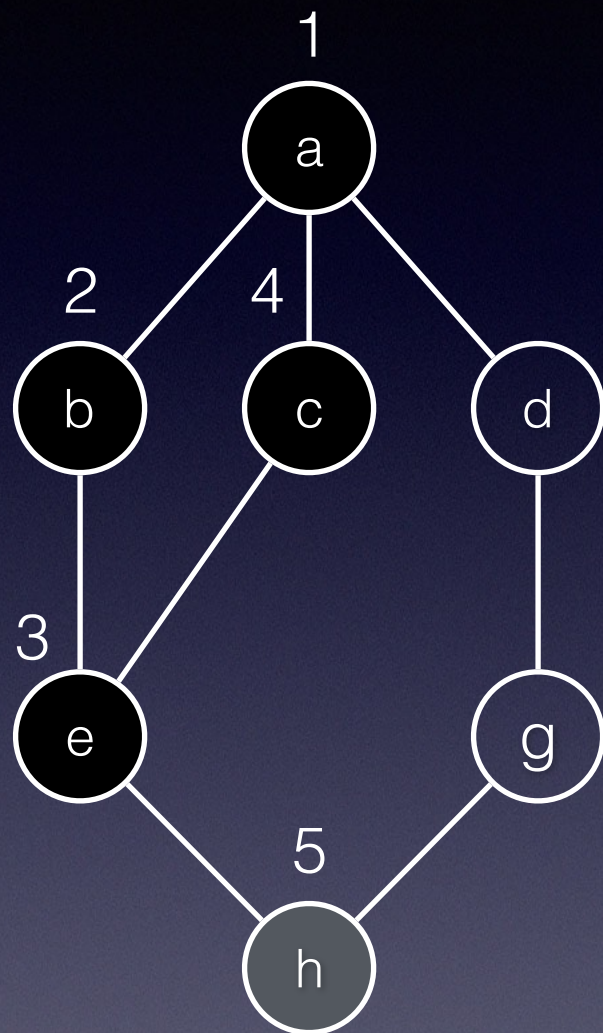
Stack: [d,c]

Visiting: h



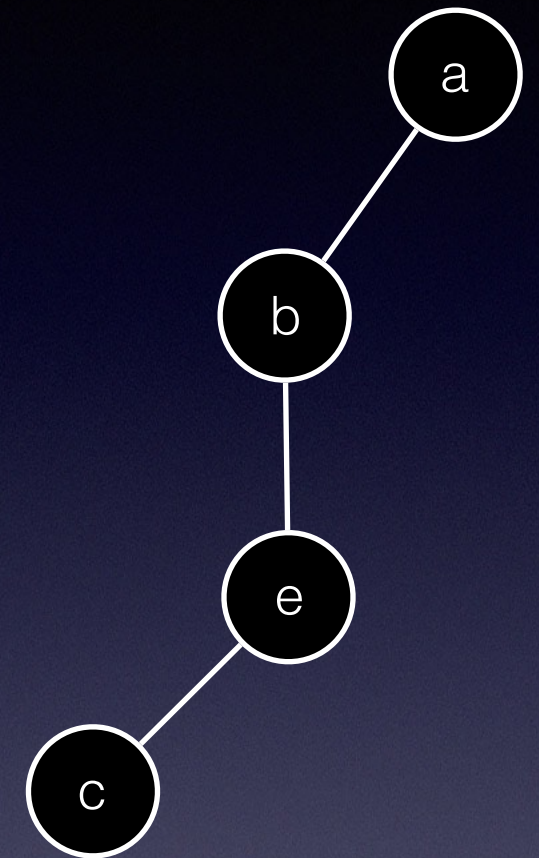


# Depth-first search



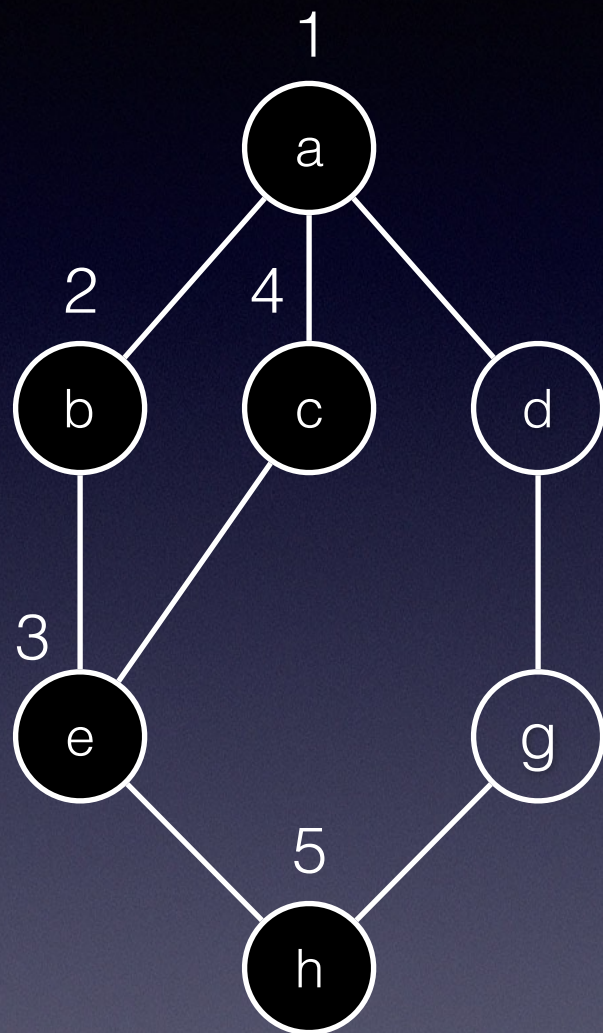
Stack: [d,c,g]

Visiting: h



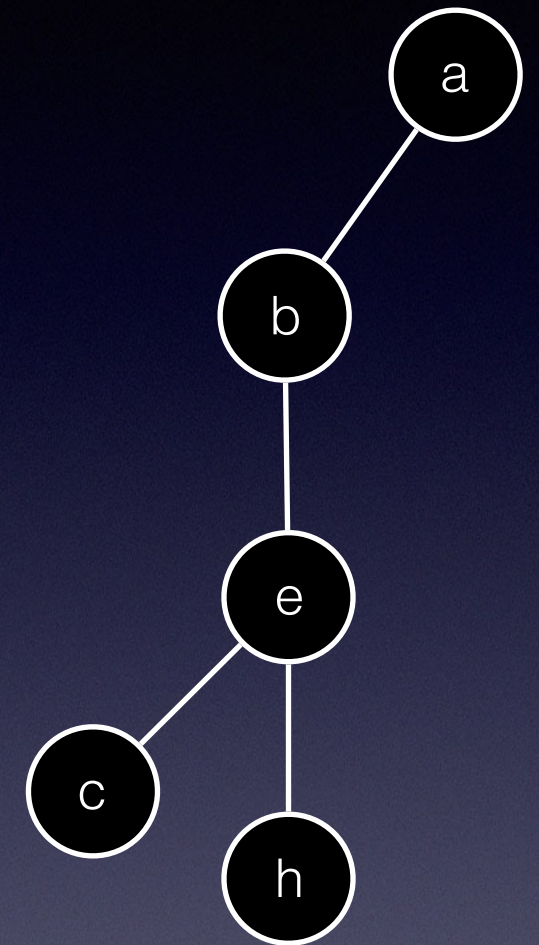


# Depth-first search



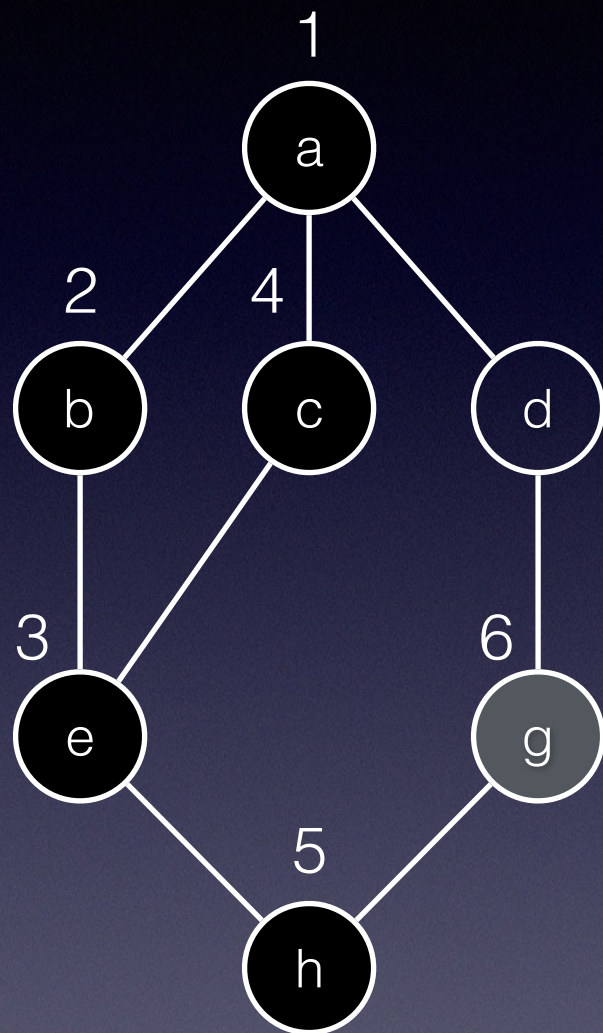
Stack: [d,c,g]

Visiting:



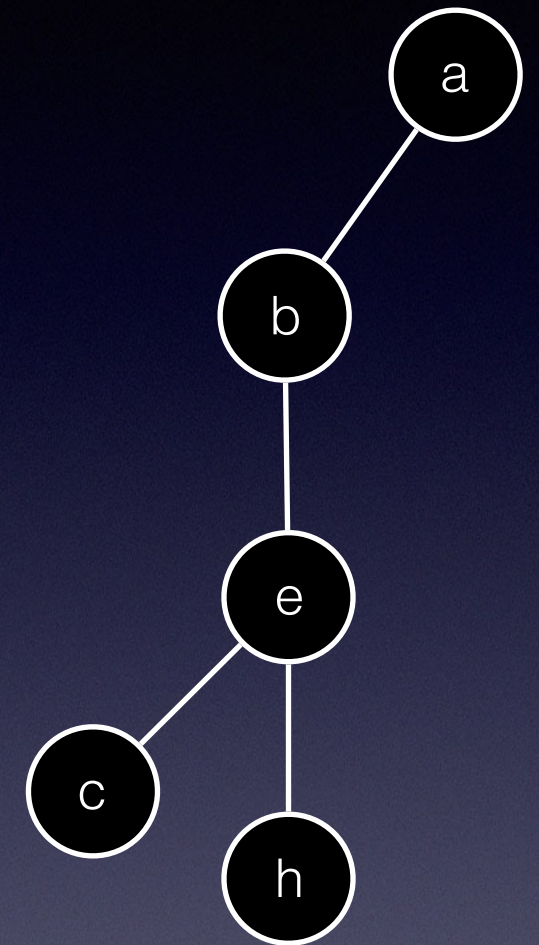


# Depth-first search



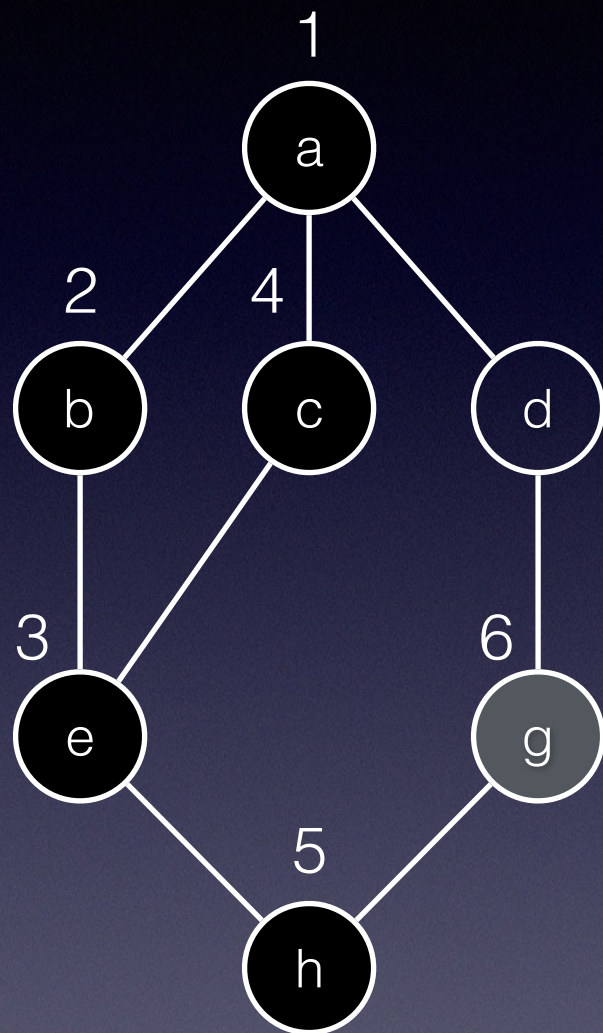
Stack: [d,c]

Visiting: g



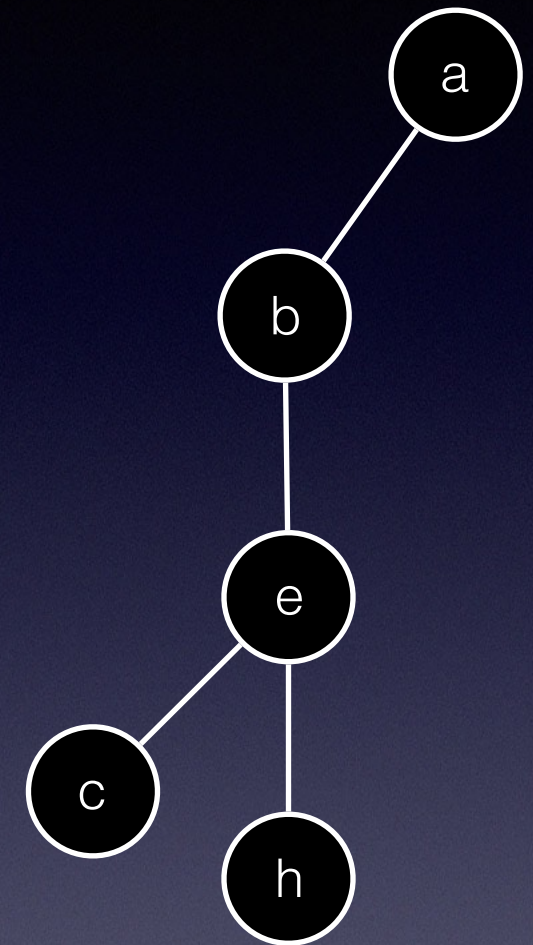


# Depth-first search



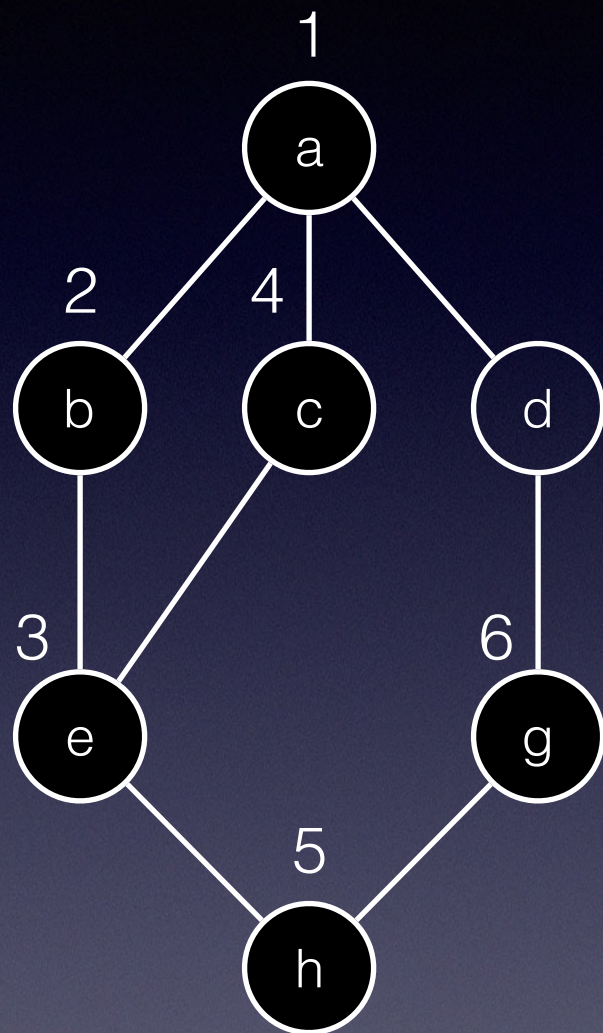
Stack: [d,c,d]

Visiting: g



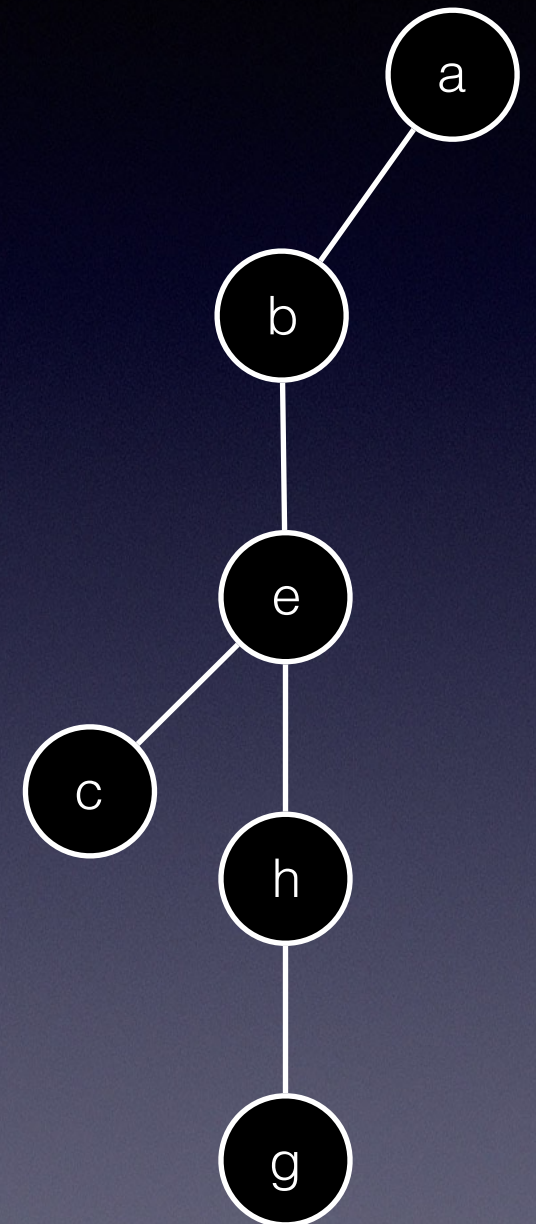


# Depth-first search



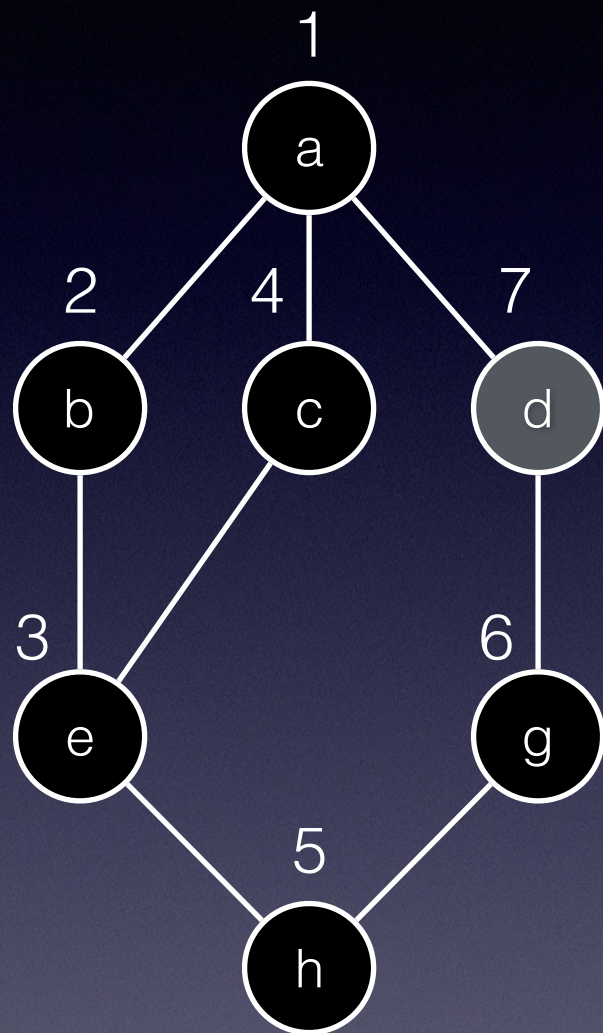
Stack: [d,c,d]

Visiting:



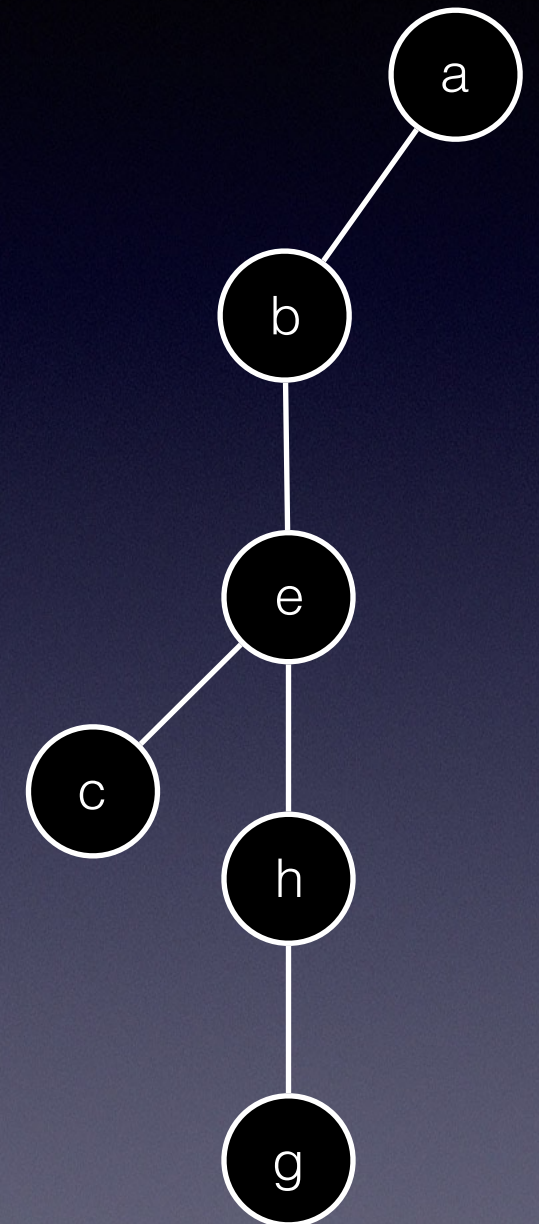


# Depth-first search



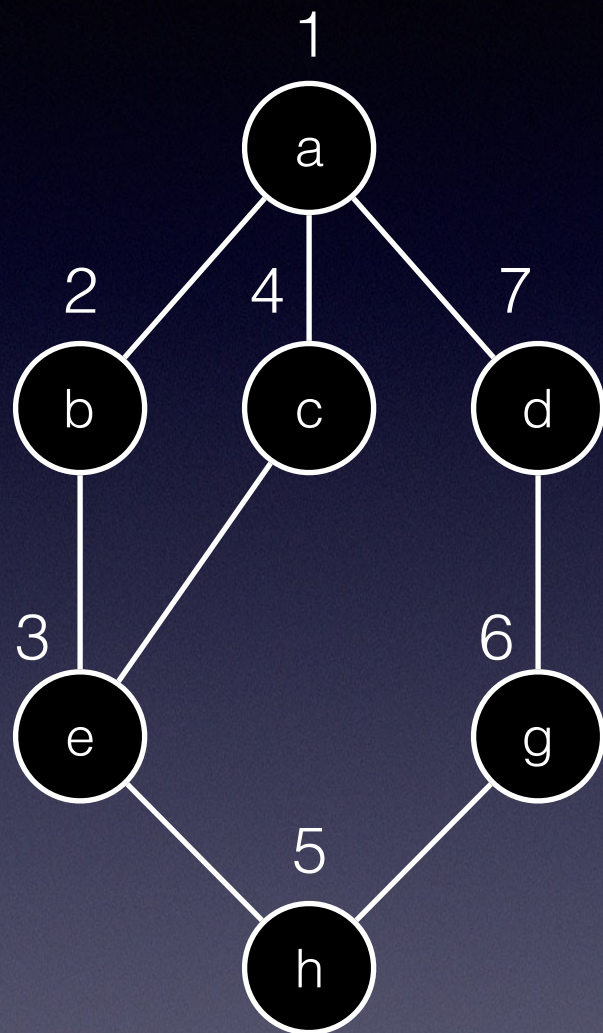
Stack: [d,c]

Visiting: d



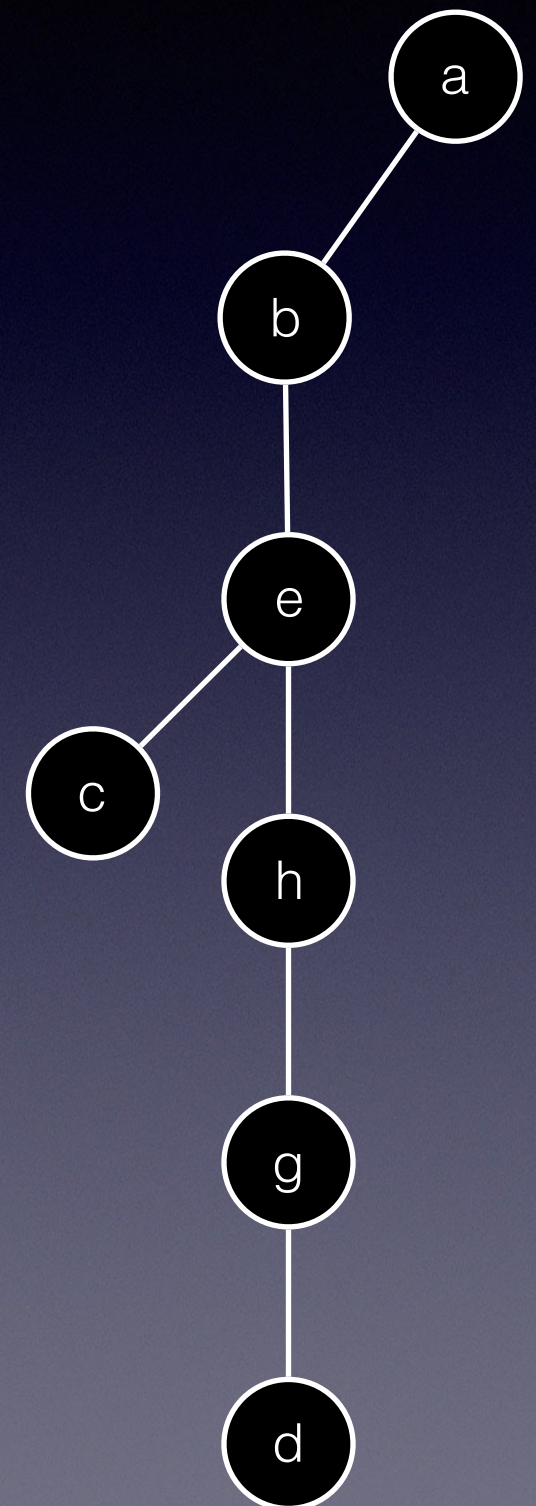


# Depth-first search



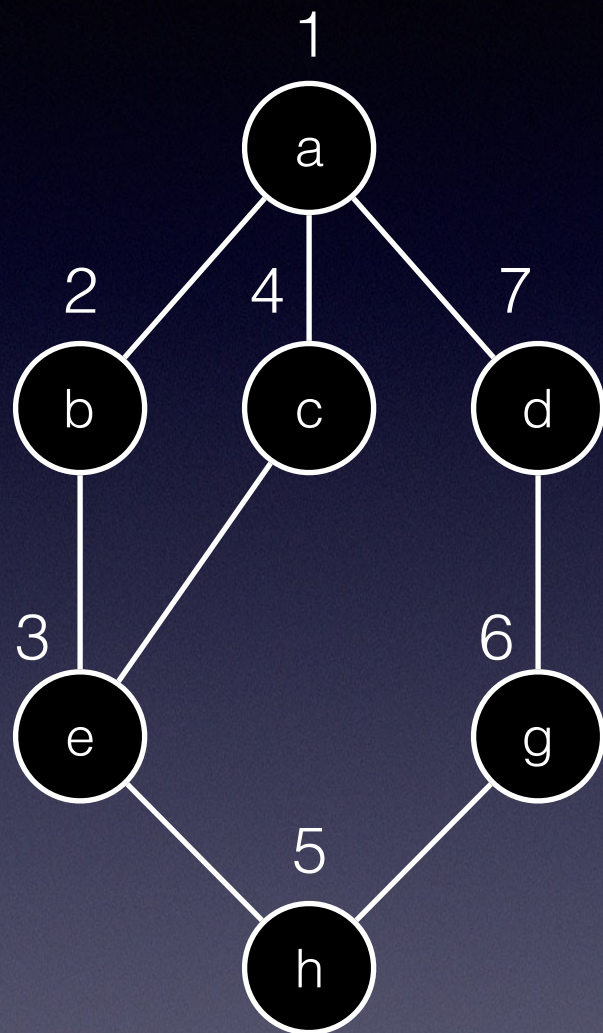
Stack: [d,c]

Visiting:





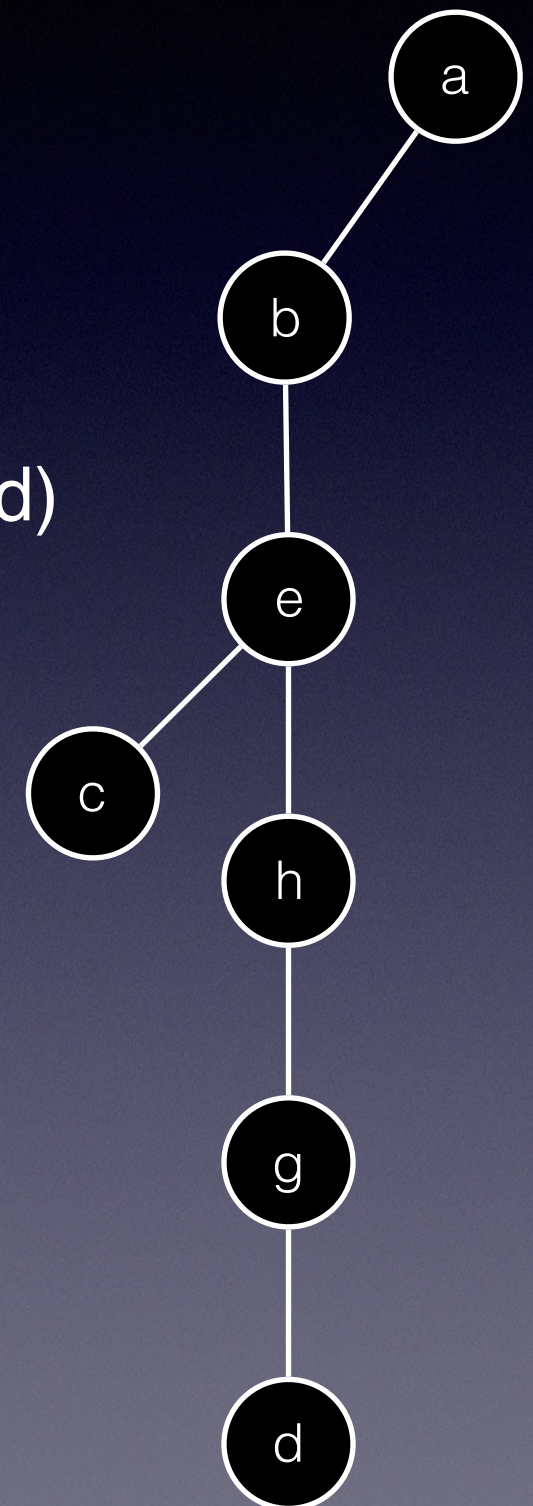
# Depth-first search



Stack: [d]

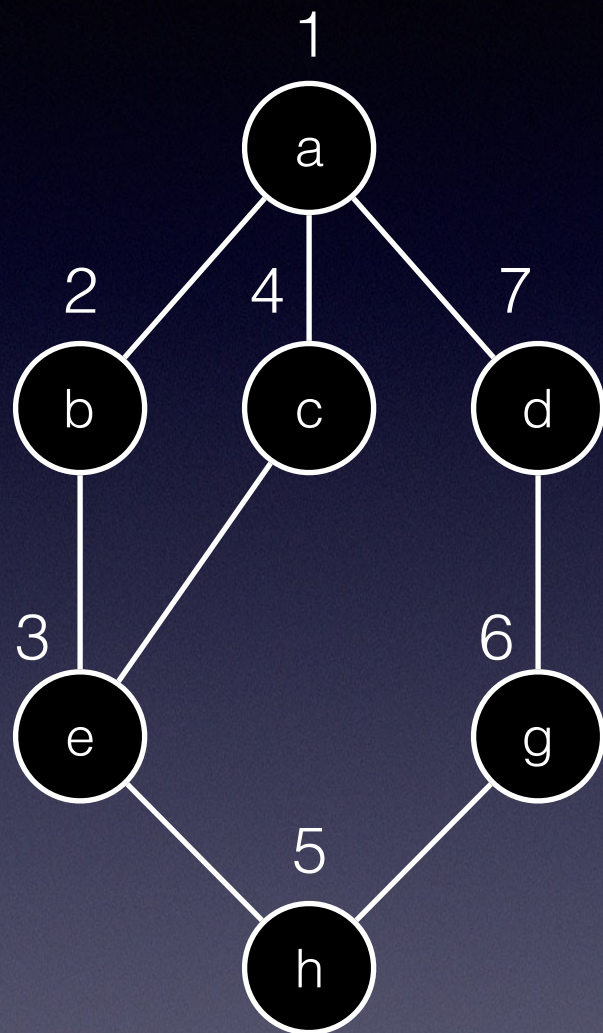
Visiting: c

(do nothing already visited)





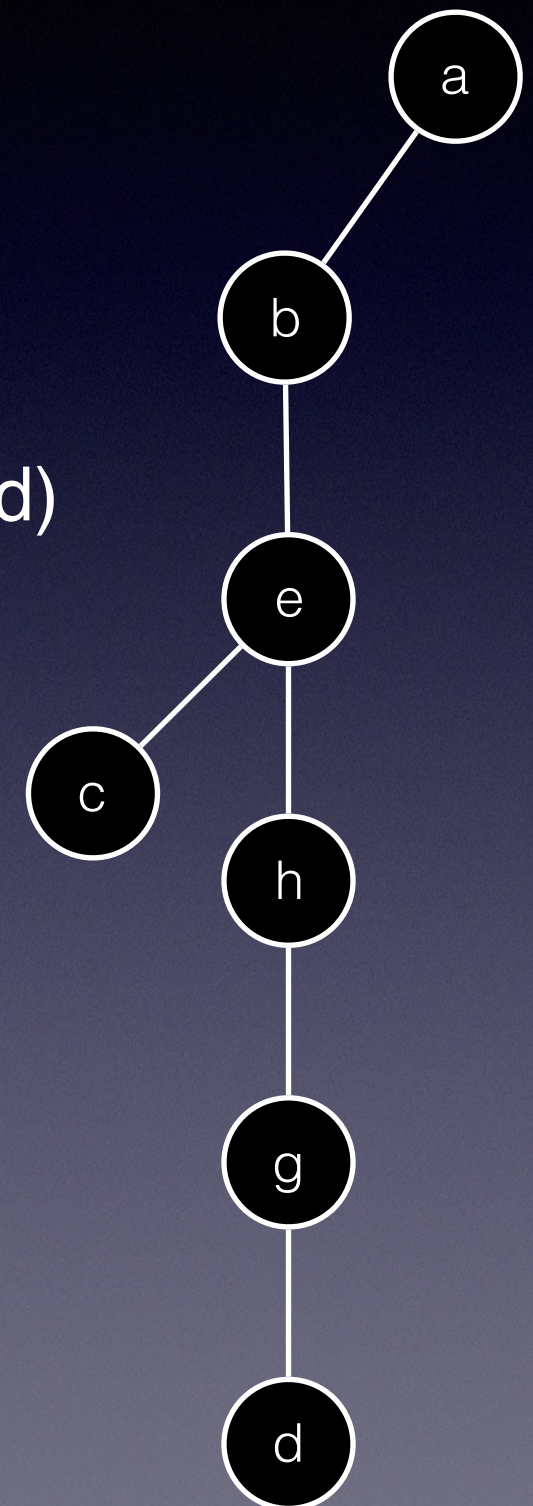
# Depth-first search



Stack: []

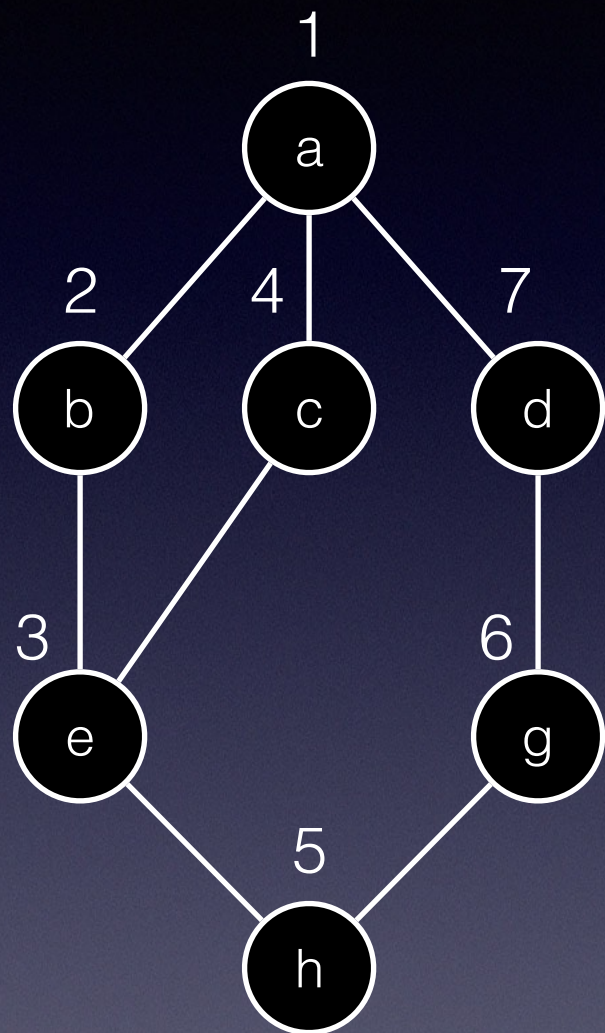
Visiting: d

(do nothing already visited)



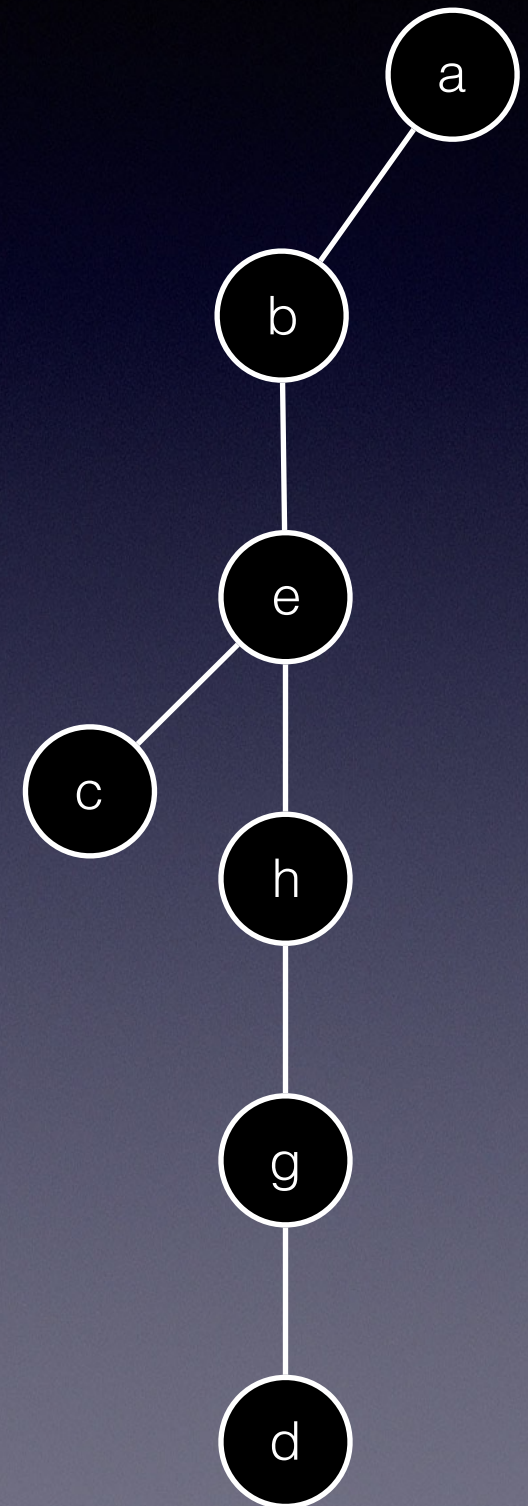


# Depth-first search



Stack: []

Visiting:



Depth-first will find what it's looking for eventually, assuming the graph isn't infinitely large. If you write your DFS program recursively, as our book does, you don't need an explicit stack because recursion's use of the call stack takes care of those details for us.