

Matt Mazur

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Hey there! I'm the founder of Preceden, a web-based timeline maker, and a data analyst consultant. I also built Lean Domain Search and many other software products over the years.











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A Step by Step Backpropagation Example

Background

Backpropagation is a common method for training a neural network. There is <u>no shortage of papers</u> online that attempt to explain how backpropagation works, but few that include an example with actual numbers. This post is my attempt to explain how it works with a concrete example that folks can compare their own calculations to in order to ensure they understand backpropagation correctly.

If this kind of thing interests you, you should sign up for my newsletter where I post about AI-related projects that I'm working on.

Backpropagation in Python

You can play around with a Python script that I wrote that implements the backpropagation algorithm in this Github repo.

Backpropagation Visualization

For an interactive visualization showing a neural network as it learns, check out my Neural Network visualization.

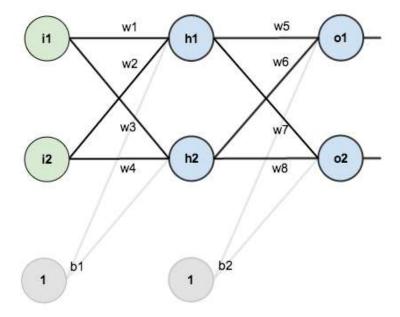
Additional Resources

If you find this tutorial useful and want to continue learning about neural networks, machine learning, and deep learning, I highly recommend checking out Adrian Rosebrock's new book, <u>Deep Learning for Computer Vision with Python</u>. I really enjoyed the book and will have a full review up soon.

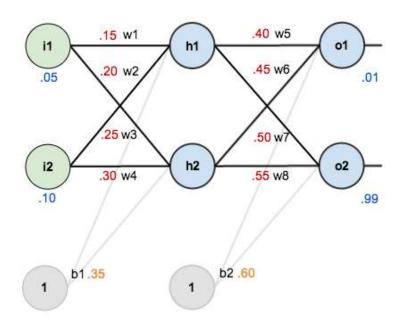
Overview

For this tutorial, we're going to use a neural network with two inputs, two hidden neurons, two output neurons. Additionally, the hidden and output neurons will include a bias.

Here's the basic structure:



In order to have some numbers to work with, here are the initial weights, the biases, and training inputs/outputs:



The goal of backpropagation is to optimize the weights so that the neural network can learn how to correctly map arbitrary inputs to outputs.

For the rest of this tutorial we're going to work with a single training set: given inputs 0.05 and 0.10, we want the neural network to output 0.01 and 0.99.

The Forward Pass

To begin, lets see what the neural network currently predicts given the weights and biases above and inputs of 0.05 and 0.10. To do this we'll feed those inputs forward though the network.

We figure out the *total net input* to each hidden layer neuron, *squash* the total net input using an *activation function* (here we use the *logistic function*), then repeat the process with the output layer neurons.

Total net input is also referred to as just net input by some sources.

Here's how we calculate the total net input for h_1 :

$$net_{h1} = w_1 * i_1 + w_2 * i_2 + b_1 * 1$$

$$net_{h1} = 0.15 * 0.05 + 0.2 * 0.1 + 0.35 * 1 = 0.3775$$

We then squash it using the logistic function to get the output of h_1 :

$$out_{h1} = \frac{1}{1 + e^{-net_{h1}}} = \frac{1}{1 + e^{-0.3775}} = 0.593269992$$

Carrying out the same process for h_2 we get:

$$out_{h2} = 0.596884378$$

We repeat this process for the output layer neurons, using the output from the hidden layer neurons as inputs.

Here's the output for O_1 :

$$net_{o1} = w_5 * out_{h1} + w_6 * out_{h2} + b_2 * 1$$

$$net_{o1} = 0.4 * 0.593269992 + 0.45 * 0.596884378 + 0.6 * 1 = 1.105905967$$

$$out_{o1} = \frac{1}{1 + e^{-net_{o1}}} = \frac{1}{1 + e^{-1.105905967}} = 0.75136507$$

And carrying out the same process for O_2 we get:

$$out_{o2} = 0.772928465$$

Calculating the Total Error

We can now calculate the error for each output neuron using the <u>squared error</u> <u>function</u> and sum them to get the total error:

$$E_{total} = \sum_{n=1}^{\infty} \frac{1}{2} (target - output)^2$$

Some sources refer to the target as the ideal and the output as the actual.

The $\frac{1}{2}$ is included so that exponent is cancelled when we differentiate later on. The result is eventually multiplied by a learning rate anyway so it doesn't matter that we introduce a constant here [1].

For example, the target output for o_1 is 0.01 but the neural network output 0.75136507, therefore its error is:

$$E_{o1} = \frac{1}{2}(target_{o1} - out_{o1})^2 = \frac{1}{2}(0.01 - 0.75136507)^2 = 0.274811083$$

Repeating this process for O_2 (remembering that the target is 0.99) we get:

$$E_{o2} = 0.023560026$$

The total error for the neural network is the sum of these errors:

$$E_{total} = E_{o1} + E_{o2} = 0.274811083 + 0.023560026 = 0.298371109$$

The Backwards Pass

Our goal with backpropagation is to update each of the weights in the network so that they cause the actual output to be closer the target output, thereby minimizing the error for each output neuron and the network as a whole.

Output Layer

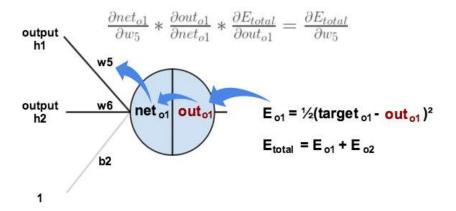
Consider w_5 . We want to know how much a change in w_5 affects the total error, aka $\frac{\partial E_{total}}{\partial w_5}$.

 $\frac{\partial E_{total}}{\partial w_5}$ is read as "the partial derivative of E_{total} with respect to w_5 ". You can also say "the gradient with respect to w_5 ".

By applying the chain rule we know that:

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial w_5}$$

Visually, here's what we're doing:



We need to figure out each piece in this equation.

First, how much does the total error change with respect to the output?

$$E_{total} = \frac{1}{2}(target_{o1} - out_{o1})^2 + \frac{1}{2}(target_{o2} - out_{o2})^2$$

$$\frac{\partial E_{total}}{\partial out_{o1}} = 2 * \frac{1}{2} (target_{o1} - out_{o1})^{2-1} * -1 + 0$$

$$\frac{\partial E_{total}}{\partial out_{o1}} = -(target_{o1} - out_{o1}) = -(0.01 - 0.75136507) = 0.74136507$$

-(target-out) is sometimes expressed as out-target

When we take the partial derivative of the total error with respect to out_{o1} , the quantity $\frac{1}{2}(target_{o2}-out_{o2})^2$ becomes zero because out_{o1} does not affect it which means we're taking the derivative of a constant which is zero.

Next, how much does the output of O_1 change with respect to its total net input?

The partial <u>derivative of the logistic function</u> is the output multiplied by 1 minus the output:

$$out_{o1} = \frac{1}{1 + e^{-net_{o1}}}$$

$$\frac{\partial out_{o1}}{\partial net_{o1}} = out_{o1}(1 - out_{o1}) = 0.75136507(1 - 0.75136507) = 0.186815602$$

Finally, how much does the total net input of o1 change with respect to w_5 ?

$$net_{o1} = w_5 * out_{h1} + w_6 * out_{h2} + b_2 * 1$$

$$\frac{\partial net_{o1}}{\partial w_5} = 1 * out_{h1} * w_5^{(1-1)} + 0 + 0 = out_{h1} = 0.593269992$$

Putting it all together:

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial w_5}$$

$$\frac{\partial E_{total}}{\partial w_5} = 0.74136507 * 0.186815602 * 0.593269992 = 0.082167041$$

You'll often see this calculation combined in the form of the delta rule:

$$\frac{\partial E_{total}}{\partial w_5} = -(target_{o1} - out_{o1}) * out_{o1}(1 - out_{o1}) * out_{h1}$$

Alternatively, we have $\frac{\partial E_{total}}{\partial out_{o1}}$ and $\frac{\partial out_{o1}}{\partial net_{o1}}$ which can be written as $\frac{\partial E_{total}}{\partial net_{o1}}$, aka δ_{o1} (the Greek letter delta) aka the *node delta*. We can use this to rewrite the calculation above:

$$\delta_{o1} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} = \frac{\partial E_{total}}{\partial net_{o1}}$$

$$\delta_{o1} = -(target_{o1} - out_{o1}) * out_{o1}(1 - out_{o1})$$

Therefore:

$$\frac{\partial E_{total}}{\partial w_5} = \delta_{o1} out_{h1}$$

Some sources extract the negative sign from \(\gamma \) so it would be written as:

$$\frac{\partial E_{total}}{\partial w_5} = -\delta_{o1}out_{h1}$$

To decrease the error, we then subtract this value from the current weight (optionally multiplied by some learning rate, eta, which we'll set to 0.5):

$$w_5^+ = w_5 - \eta * \frac{\partial E_{total}}{\partial w_5} = 0.4 - 0.5 * 0.082167041 = 0.35891648$$

Some sources use α (alpha) to represent the learning rate, others use η (eta), and others even use ϵ (epsilon).

We can repeat this process to get the new weights w_6 , w_7 , and w_8 :

$$w_6^+ = 0.408666186$$

$$w_7^+ = 0.511301270$$

$$w_8^+ = 0.561370121$$

We perform the actual updates in the neural network *after* we have the new weights leading into the hidden layer neurons (ie, we use the original weights, not the updated weights, when we continue the backpropagation algorithm below).

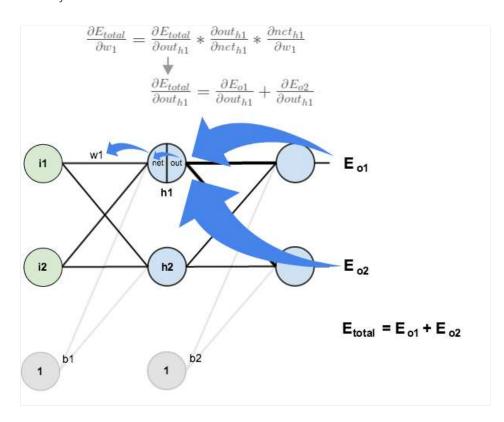
Hidden Layer

Next, we'll continue the backwards pass by calculating new values for w_1 , w_2 , w_3 , and w_4 .

Big picture, here's what we need to figure out:

$$\frac{\partial E_{total}}{\partial w_1} = \frac{\partial E_{total}}{\partial out_{h1}} * \frac{\partial out_{h1}}{\partial net_{h1}} * \frac{\partial net_{h1}}{\partial w_1}$$

Visually:



We're going to use a similar process as we did for the output layer, but slightly different to account for the fact that the output of each hidden layer neuron contributes to the output (and therefore error) of multiple output neurons. We know that out_{h1} affects both out_{o1} and out_{o2} therefore the $\frac{\partial E_{total}}{\partial out_{h1}}$ needs to take into consideration its effect on the both output neurons:

$$\frac{\partial E_{total}}{\partial out_{h1}} = \frac{\partial E_{o1}}{\partial out_{h1}} + \frac{\partial E_{o2}}{\partial out_{h1}}$$

Starting with $\frac{\partial E_{o1}}{\partial out_{h1}}$:

$$\frac{\partial E_{o1}}{\partial out_{h1}} = \frac{\partial E_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial out_{h1}}$$

We can calculate $\frac{\partial E_{o1}}{\partial net_{o1}}$ using values we calculated earlier:

$$\frac{\partial E_{o1}}{\partial net_{o1}} = \frac{\partial E_{o1}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} = 0.74136507 * 0.186815602 = 0.138498562$$

And $\frac{\partial net_{o1}}{\partial out_{h1}}$ is equal to w_5 :

$$net_{o1} = w_5 * out_{h1} + w_6 * out_{h2} + b_2 * 1$$

$$\frac{\partial net_{o1}}{\partial out_{b1}} = w_5 = 0.40$$

Plugging them in:

$$\frac{\partial E_{o1}}{\partial out_{h1}} = \frac{\partial E_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial out_{h1}} = 0.138498562 * 0.40 = 0.055399425$$

Following the same process for $\frac{\partial E_{o2}}{\partial out_{h1}}$, we get:

$$\frac{\partial E_{o2}}{\partial out_{h1}} = -0.019049119$$

Therefore:

$$\frac{\partial E_{total}}{\partial out_{h1}} = \frac{\partial E_{o1}}{\partial out_{h1}} + \frac{\partial E_{o2}}{\partial out_{h1}} = 0.055399425 + -0.019049119 = 0.036350306$$

Now that we have $\frac{\partial E_{total}}{\partial out_{h1}}$, we need to figure out $\frac{\partial out_{h1}}{\partial net_{h1}}$ and then $\frac{\partial net_{h1}}{\partial w}$ for each weight:

$$out_{h1} = \frac{1}{1 + e^{-net_{h1}}}$$

$$\frac{\partial out_{h1}}{\partial net_{h1}} = out_{h1}(1 - out_{h1}) = 0.59326999(1 - 0.59326999) = 0.241300709$$

We calculate the partial derivative of the total net input to h_1 with respect to w_1 the same as we did for the output neuron:

$$net_{h1} = w_1 * i_1 + w_3 * i_2 + b_1 * 1$$

$$\frac{\partial net_{h1}}{\partial w_1} = i_1 = 0.05$$

Putting it all together:

$$\frac{\partial E_{total}}{\partial w_1} = \frac{\partial E_{total}}{\partial out_{h1}} * \frac{\partial out_{h1}}{\partial net_{h1}} * \frac{\partial net_{h1}}{\partial w_1}$$

$$\frac{\partial E_{total}}{\partial w_1} = 0.036350306 * 0.241300709 * 0.05 = 0.000438568$$

You might also see this written as:

$$\frac{\partial E_{total}}{\partial w_1} = \left(\sum_o \frac{\partial E_{total}}{\partial out_o} * \frac{\partial out_o}{\partial net_o} * \frac{\partial net_o}{\partial out_{h1}}\right) * \frac{\partial out_{h1}}{\partial net_{h1}} * \frac{\partial net_{h1}}{\partial w_1}$$

$$\frac{\partial E_{total}}{\partial w_1} = \left(\sum_o \delta_o * w_{ho}\right) * out_{h1}(1 - out_{h1}) * i_1$$

$$\frac{\partial E_{total}}{\partial w_1} = \delta_{h1} i_1$$

We can now update w_1 :

$$w_1^+ = w_1 - \eta * \frac{\partial E_{total}}{\partial w_1} = 0.15 - 0.5 * 0.000438568 = 0.149780716$$

Repeating this for w_2 , w_3 , and w_4

$$w_2^+ = 0.19956143$$

$$w_3^+ = 0.24975114$$

$$w_4^+ = 0.29950229$$

Finally, we've updated all of our weights! When we fed forward the 0.05 and 0.1 inputs originally, the error on the network was 0.298371109. After this first round of backpropagation, the total error is now down to 0.291027924. It might not seem like much, but after repeating this process 10,000 times, for example, the error plummets to 0.0000351085. At this point, when we feed forward 0.05 and 0.1, the two outputs neurons generate 0.015912196 (vs 0.01 target) and 0.984065734 (vs 0.99 target).

If you've made it this far and found any errors in any of the above or can think of any ways to make it clearer for future readers, don't hesitate to <u>drop me a note</u>. Thanks!

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Experimenting with a The State of Emergent I'm going to write more Neural Network-based Mind often. For real this time. Poker Bot In "Emergent Mind" In "Writing" In "Poker Bot"

Posted on <u>March 17, 2015</u> by <u>Mazur</u>. This entry was posted in <u>Machine Learning</u> and tagged <u>ai</u>, <u>backpropagation</u>, <u>machine learning</u>, <u>neural networks</u>. Bookmark the <u>permalink</u>.

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798 thoughts on "A Step by Step Backpropagation Example"

← Older Comments



chantiq1000x

June 21, 2018 at 9:44 am

can you tell me why h1 = w1*x1 + w2*x2 +b ? why not h1 = w1 * x1 + w3* x3 + b

Reply



Joseph

- August 1, 2018 at 9:28 pm

The labeling is slightly ambiguous because the weights were not put right on top of the links/edges. w2 is not going from i1 to h2, it is going from i2 to h1. That is, the weights are labeled to the left of their respective links/edges, not to the right. This is a little bit more obvious in the first graph.

<u>Reply</u>

George Skrimpas

June 21, 2018 at 12:23 pm

I think the correct formula for H1 is: netH1 = w1*i1 + w3*i2 + b1*1i use w3 instead of w2, since I2 is linked to H1 via w3. Will you plz confirm?

<u>Reply</u>



deepak

June 27, 2018 at 11:31 am

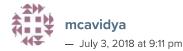
many errors dude mainly the computation of $d(h1)/d(o2))=-(0.01-0.772928465)^*$ $(0.772928465)(1-0.772928465))^*$ 0.45

<u>Reply</u>



It really helped me to understand how back propagation works. Keep up the good work.

<u>Reply</u>



Thanks Mazur for this numerical example. Such an example provides the best way to learn the working of an algorithm. It helped me a lot. Many thanks.

Going through the example, I was wondering whether the biases b1, b2 are being treated as constants. Is it not necessary to adjust their values also?

<u>Reply</u>



Mayank Gupta

- August 6, 2018 at 5:10 am

Yes. In this article, biases were treated as constants to keep things simple. If you understood the math explained in this article, you can easily update the biases as well. In reality, biases are also updated.

Reply



enginbozaba

- September 11, 2018 at 1:24 pm

Are we updating the bias values by setting up the dE / db1 and dE / db2 chains?

<u>Reply</u>



Pony

July 3, 2018 at 10:16 pm

This is great! Thank you for the step by step explanation

<u>Reply</u>



Jerome lemoine

- July 6, 2018 at 3:04 pm

Hi matt

Great document, very pedagogic!

Maybe a little mistake in the calculation of the net_h1 and net_h2:

A Step by Step Backpropagation Example - Matt Mazur

net $h1= w1\times i1 + w3\times i3 + b1$

(Analog mistake for net_h2)

The mistake is communicated to the numerical application also

Reply



lamductan

— July 25, 2018 at 4:56 am

This explaination and visualization is very well understanding. It helps me so much because it takes me a lot of time to know how really backpropagation does. Thank you very much.

Reply



A Step by Step Backpropagation Example – Deep Learning



ieffminich

— July 31, 2018 at 5:21 pm

Outstanding explainer for back propagation. Thanks, Matt!

Reply



Mayank Gupta

- August 6, 2018 at 5:07 am

I was a bit frustrated with this backpropagation topic and was struggling to have a clear mental picture of backpropagation.

Your article radically improved my understanding. Your article was so clear that I was actually able to write my own code to implement backpropagation. Thank you very much.

If you ever plan to expand on this article, I request you to add some details about how weights are updated for all the samples (your article explained the case for one sample.)

Thanks again for this wonderful article!

Reply



arnulfo

— August 6, 2018 at 11:07 pm

Reblogged this on conlatio.

Reply



Amin

August 7, 2018 at 9:51 am

Goog job! But this is 3-layer network only. If it is 4-layer then how we calculate the dEtotal/dout(h1)?

dEh2/dout(h1) will not be know. Because we don't have the value for dEh2 (the error for hidden layer 2). I need an explanation here. Thanks!

<u>Reply</u>



Zhijie Chen

— August 15, 2018 at 11:12 am

You use the value that comes from the previous layer. For instance dE/dout i1 = dE/dnet h1 * dnet h1/ dout i1 = dE/dout h1 * dout h1/ dnet h1 * dnet h1/dout i1, in which dE/dout h1 and dout h1/ dnet h1 have been calculated by the previous layer.

Reply



Knut Leiß

November 14, 2018 at 4:36 am

I got the same problem and I don't understand the answer.

Why is dE/dout i1 =dE/dnet h1 * dnet h1/dout i1?

This ignores the contribution of out i1 to the error through h2!?

So, I assume the term dE/dnet h2 * dnet h2/dout i1 needs to be added!?

But then, why is it OK to just use the sum, mathematically?

Reply



Frank

– August 15, 2018 at 3:27 pm

Question: do all neurons in a layer use the same bias weight or is there a individual weight per neuron? I.e. In the example it looks like that b1 is used for both hidden neurons and b2 for both output neurons.

Btw: nice and easy to follow example!

<u>Reply</u>



Aaron

October 23, 2018 at 1:20 am

In reality each bias would be adjusted too, but in the example seems like they are only focusing on weights, and specifically the hidden layers.

<u>Reply</u>



Implementing a flexible neural network with backpropagation from scratch



anil

— August 21, 2018 at 12:03 am

i think this is best explain backpropagation with detail kudos!

Reply



Important Links | Tejalal Choudhary



Garrett

August 24, 2018 at 11:07 pm

This was a fantastic write up. I am using it to study the algorithm while currently in an Al course at uni. I was wondering if you could add to this and describe momentum in the same way. Thank you

Reply



Rafay

August 27, 2018 at 1:09 pm

Thanks a lot Matt for making this. Your blog and the Stanford's CS231n lectures are the best resources on this.

Reply



<u>Deep learning for product managers – part 1 – Kai's notebook</u>



Alan Wake

— August 31, 2018 at 7:52 am

Thank you very much! I've been looking exactly for this

<u>Reply</u>



【每日AI收集】BP神经网络 - 每日AI



Sneha

— September 9, 2018 at 5:07 am

This page is very helpful to solve the problems.

Amazing page !!

Thank you!!

Reply



Kevin

- September 15, 2018 at 1:22 am

Thanks for the great example. One question though:

During the backpropagation, you find the new values for w5-w8 and continue backpropagating the previous hidden layer. There you need the value of dnet_o1/dout_h1, which equals w5. Do we use the original value of w5, 0.4, as it is done here or its updated value, 0.35891648?

Reply



Artem

— September 15, 2018 at 12:20 pm

Thank you for explanation. I didn't get one thing. Why we multyply by -1 derivative of total error? is this because target is constant and out1 is function?

<u>Reply</u>



Abin Singh

— September 21, 2018 at 4:08 am

You said in the beginning that we are going to work with only a single training set (1 row with 2 features). Then how we are getting two outputs. It should be one right.

Can you please clarify?

<u>Reply</u>



Jimmy Johnson

September 25, 2018 at 1:00 am

Very nice explanation.

Thanks for taking the time to do this.

<u>Reply</u>



swapna

September 27, 2018 at 9:36 am

its really very helpful..thanks for such a wonderful doc

<u>Reply</u>



September 29, 2018 at 3:14 pm

Carrying out the same process for h_2 we get:

out_{h2} = 0.596884378

I got 0.666522 for h2 because i did: activation_function(0.25 * 0.05 + 0.3 * 0.1 + 0.65 * 1)

<u>Reply</u>



R S SARATHI KANNAN

October 5, 2018 at 11:52 pm

Hi,

It is a good work. I am struck at here, Following the same process for $frac[\partial E_{02}]$ (\partial out_{h1}), we get:

 $\frac{h1}{} = -0.019049119$ (partial derivative of H1out from E2)... how to calculate out_H1 from E2

Reply



Martin Ennemoser

October 13, 2018 at 4:10 am

Thanks for this awesome explanation.

<u>Reply</u>



Kartikey arora

— October 18, 2018 at 10:54 am

This article was really very helpful for me as i was very confused and stuck with tha backprop calculations and u just explained it with an example in a very nice way thanks a lot

Reply



<u>A simple natural language category classifier with Keras – GrownSoftware</u>



Ravi

— October 21, 2018 at 3:51 am

Final wieghts after 10,000 iterations are 0.378509988350132 0.657019976700263 0.477300705684786

A Step by Step Backpropagation Example - Matt Mazur

- 0.754601411369569
- -3.892977198865724
- -3.868416687703616
- 2.861810948620059
- 2.925688966771616

<u>Reply</u>



Ana

October 30, 2018 at 2:23 pm

I've got the same, is that right? aren't weights supposed to be between 1-10? Reply



Neuronal networking in VBA+Excel



Aaron

October 22, 2018 at 11:01 pm

This is an awesome post, I was confused about how the error propagates through the hidden layer. Working through each step made the equations seem intuitive. Someone should really make an animation for this.

Reply



[D] Is there a book or resource about machine learning that teaches different algorithms with step by step calculations for simple examples? Like how a mathematics or physics book would. | Premium Blog! | Development code, Android, los anh Tranning IT



Raja

— October 24, 2018 at 7:16 pm

Hi Experts, I tried this approach, for some reason my weights and error keeps increasing, doesn't seem to reduce for certain inputs, any idea whats happening?

<u>Reply</u>



eduhelp2016

— October 27, 2018 at 5:47 am

Lovely!!!!!!!!!!

Reply



T.smart

October 29, 2018 at 3:08 am

A Step by Step Backpropagation Example – Matt Mazur

- it is my answer,
- 0 0.291027774
- 1 0.283547133
- 2 0.275943289
- 3 0.268232761
- 4 0.260434393
- 5 0.252569176
- 6 0.244659999
- 7 0.236731316
- 8 0.228808741
- 0 0.2200007+1
- 9 0.220918592
- 10 0.213087389
- 11 0.205341328
- 12 0.197705769
- 13 0.190204742
- 14 0.182860503
- 15 0.175693166
- 16 0.168720403
- 17 0.16195725
- 18 0.155415989
- 19 0.149106135
- 20 0.14303449
- 21 0.137205276 22 0.131620316
- 23 0.126279262
- 24 0.121179847
- 25 0.116318143
- 26 0.111688831
- 27 0.107285459
- 28 0.103100677
- 29 0.099126464
- 30 0.095354325
- 31 0.091775464 32 0.088380932
- 33 0.085161757
- 34 0.082109043
- I am not sure that it is right.

<u>Reply</u>



PARAMESHA K

— October 31, 2018 at 9:05 pm

Whether the BP should run far all the training samples or individual samples?

Reply



<u>Understanding Evolved Policy Gradients – Al+ NEWS</u>



purnenduprabhat

— November 11, 2018 at 3:38 am

Excellent explanation! Cleared my doubt.

Reply



Sebastian

— November 11, 2018 at 9:45 am

Great explanation. Thanks. Many authors who write books consider themselves as being smart just because they provide some complicated formulas from wikipedia with 10,000 different index symbols. But I do not think they are smart at all. They do not know their audience. This simple example is better than all books that I have which try to explain back propagation with fomrulas... I did not realize it is that simple. It is just taking derivative over and over again. Thank you very much!

Reply

Santiago Fernando Gomez

— November 19, 2018 at 5:22 pm

This is amazing, the best explanation I have found over the internet. Great job!

<u>Reply</u>

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