



SN65MLVD201, SN65MLVD203 SN65MLVD206, SN65MLVD207

SLLS558B-DECEMBER 2002-REVISED SEPTEMBER 2005

MULTIPOINT-LVDS LINE DRIVER AND RECEIVER

FEATURES

- Low-Voltage Differential 30- Ω to 55- Ω Line Drivers and Receivers for Signaling Rates (1) Up to 200 Mbps
- Type-1 Receivers Incorporate 25 mV of Hysteresis
- Type-2 Receivers Provide an Offset(100 mV)
 Threshold to Detect Open-Circuit and Idle-Bus Conditions
- Meets or Exceeds the M-LVDS Standard TIA/EIA-899 for Multipoint Data Interchange
- Controlled Driver Output Voltage Transition Times for Improved Signal Quality
- -1 V to 3.4 V Common-Mode Voltage Range Allows Data Transfer With 2 V of Ground Noise
- Bus Pins High Impedance When Disabled or $V_{cc} \le 1.5 \text{ V}$
- 100-Mbps Devices Available (SN65MLVD200A, 202A, 204A, 205A)
- M-LVDS Bus Power Up/Down Glitch Free

 The signaling rate of a line, is the number of voltage transitions that are made per second expressed in the units bps (bits per second).

APPLICATIONS

- Low-Power High-Speed Short-Reach Alternative to TIA/EIA-485
- Backplane or Cabled Multipoint Data and Clock Transmission
- Cellular Base Stations
- Central-Office Switches
- Network Switches and Routers

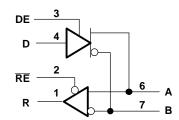
DESCRIPTION

The SN65MLVD201, 203, 206, and 207 are multipoint-low-voltage differential (M-LVDS) line drivers and receivers, which are optimized to operate at signaling rates up to 200 Mbps. All parts comply with the multipoint low-voltage differential signaling (M-LVDS) standard TIA/EIA-899. These circuits are similar to their TIA/EIA-644 standard compliant LVDS counterparts, with added features to address multipoint applications. The driver output has been designed to support multipoint buses presenting loads as low as 30 $\Omega_{\rm c}$, and incorporates controlled transition times to allow for stubs off of the backbone transmission line.

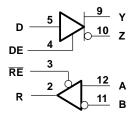
These devices have Type-1 and Type-2 receivers that detect the bus state with as little as 50 mV of differential input voltage over a common-mode voltage range of -1 V to 3.4 V. The Type-1 receivers exhibit 25 mV of differential input voltage hysteresis to prevent output oscillations with slowly changing signals or loss of input. Type-2 receivers include an offset threshold to provide a known output state under open-circuit, idle-bus, and other faults conditions. The devices are characterized for operation from -40°C to 85°C.

LOGIC DIAGRAM (POSITIVE LOGIC)

SN65MLVD201, SN65MLVD206



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Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.





These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ORDERING INFORMATION

PART NUMBER	FOOTPRINT	RECEIVER TYPE	PACKAGE MARKING
SN65MLVD201D	SN75176	Type 1	MF201
SM65MLVD203D	SN75ALS180	Type 1	MLVD203
SN65MLVD206D	SN75176	Type 2	MF206
SM65MLVD207D	SN75ALS180	Type 2	MLVD207

PACKAGE DISSIPATION RATINGS

PACKAGE	T _A ≤ 25°C POWER RATING	DERATING FACTOR ABOVE T _A = 25°C	T _A = 85°C POWER RATING
D(8)	725 mW	5.8 mW/°C	377 mW
D(14)	950 mW	7.6 mW/°C	494 mw

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted) (1)

			VALUE / UNIT	
Supply voltage range (2),	V _{CC}		−0.5 V to 4 V	
	D, DE, RE		−0.5 V to 4 V	
Input voltage range	A, B (201, 206)		-1.8 V to 4 V	
	A, B (203, 207)	A, B (203, 207)		
Output valtage renge	R		-0.3 V to 4 V	
Output voltage range	Y, Z, A, or B		-1.8 V to 4 V	
	Human Body Model (3)	A, B, Y, and Z	±8 kV	
Electrostatic discharge	numan body woder	All pins	±2 kV	
	Charged-Device Model (4)	All pins	±1500 V	
Continuous power dissipa	ation		See Dissipation Rating Table	
Storage temperature range			−65°C to 150°C	

⁽¹⁾ Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

		MIN	NOM	MAX	UNIT
V _{CC}	Supply voltage	3	3.3	3.6	V
V _{IH}	High-level input voltage	2		V _{CC}	V
V _{IL}	Low-level input voltage	GND		0.8	V
	Voltage at any bus terminal V _A , V _B , V _Y or V _Z	-1.4		3.8	V
$ V_{ID} $	Magnitude of differential input voltage	0.05		V _{CC}	V
T _A	Operating free-air temperature	-40		85	°C

All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

Tested in accordance with JEDEC Standard 22, Test Method A114-A. Tested in accordance with JEDEC Standard 22, Test Method C101.



DEVICE ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

PARAMETER		ETER	TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
		Driver only	$\overline{\text{RE}}$ and DE at V _{CC} , R _L = 50 Ω , All others open		13	22	
	Cupply ourrent	Both enabled	\overline{RE} at V_{CC} , DE at 0 V, R_L = No Load, All others open		1	4	mA
ICC	Supply current	Both enabled	$\overline{\text{RE}}$ at 0 V, DE at V _{CC} , R _L = 50 Ω , All others open		16	24	ША
		Receiver only	$\overline{\text{RE}}$ at 0 V, DE at 0 V, R _L = 50 Ω , All others open		4	13	

⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

DRIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN ⁽¹⁾	TYP ⁽²⁾ MAX	UNIT
$ V_{AB} $ or $ V_{YZ} $	Differential output voltage magnitude	See Figure 2	480	650	mV
$\Delta V_{AB} $ or $\Delta V_{YZ} $	Change in differential output voltage magnitude between logic states	See Figure 2	-50	50	mV
V _{OS(SS)}	Steady-state common-mode output voltage		0.8	1.2	V
$\Delta V_{OS(SS)}$	Change in steady-state common-mode output voltage between logic states	See Figure 3	-50	50	mV
V _{OS(PP)}	Peak-to-peak common-mode output voltage			150	mV
$V_{Y(OC)}$ or $V_{A(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0	2.4	V
$V_{Z(OC)}$ or $V_{B(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0	2.4	V
$V_{P(H)}$	Voltage overshoot, low-to-high level output	See Figure 5		1.2 V _{SS}	V
$V_{P(L)}$	Voltage overshoot, high-to-low level output	See Figure 5	-0.2 V _{SS}		V
I_{IH}	High-level input current (D, DE)	V _{IH} = 2 V	0	10	μΑ
$I_{\rm IL}$	Low-level input current (D, DE)	$V_{IL} = 0.8 \ V$	0	10	μΑ
$JI_{OS}J$	Differential short-circuit output current magnitude	See Figure 4		24	mA
I _{OZ}	High-impedance state output current (driver only)	$-1.4 \text{ V} \le \text{V}_{\text{Y}} \text{ or V}_{\text{Z}} \le 3.8 \text{ V},$ Other output = 1.2 V	-15	10	μA
I _{O(OFF)}	Power-off output current	$ \begin{array}{l} -1.4 \text{ V} \leq \text{V}_{\text{Y}} \text{ or } \text{V}_{\text{Z}} \leq 3.8 \text{ V}, \\ \text{Other output} = 1.2 \text{ V}, \\ \text{0 V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V} \end{array} $	-10	10	μA
C _Y or C _Z	Output capacitance	$V_I = 0.4 \sin(30E6\pi t) + 0.5 \text{ V}, ^{(3)}$ Other input at 1.2 V, Driver disabled		3	pF
C_{YZ}	Differential output capacitance	$V_{AB} = 0.4 \sin(30E6\pi t) \text{ V}, ^{(3)}$ Driver disabled		2.5	pF
C _{Y/Z}	Output capacitance balance, (C _Y /C _Z)		0.99	1.01	

⁽¹⁾ The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

⁽²⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

⁽³⁾ HP4194A impedance analyzer (or equivalent)

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RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted (1)

	PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
V	Desitive asing differential input valtege threshold	Type 1				50	m)/
V _{IT+}	Positive-going differential input voltage threshold	Type 2				150	mV
V	Negative gains differential input voltage threshold	Type 1	See Figure 9 and Table 1 and	-50			mV
V _{IT-}	Negative-going differential input voltage threshold	Type 2	Table 2	50			IIIV
V	Differential input valtere by storagic (V/ V/)	Type 1			25		m)/
V _{HYS}	Differential input voltage hysteresis, (V _{IT+} - V _{IT})	Type 2			0		mV
V _{OH}	High-level output voltage		$I_{OH} = -8 \text{ mA}$	2.4			V
V _{OL}	Low-level output voltage		I _{OL} = 8 mA			0.4	V
I _{IH}	High-level input current (RE)		V _{IH} = 2 V	-10		0	μA
I _{IL}	Low-level input current (RE)		V _{IL} = 0.8 V	-10		0	μA
I _{OZ}	High-impedance output current		V _O = 0 V or 3.6 V	-10		15	μA
C _A or C _B	Input capacitance		$V_I = 0.4 \sin(30E6\pi t) + 0.5 V$, (2) Other input at 1.2 V		3		pF
C _{AB}	Differential input capacitance		V _{AB} = 0.4 sin(30E6πt) V ⁽²⁾			2.5	pF
C _{A/B}	Input capacitance balance, (C _A /C _B)			0.99		1.01	

 ⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.
 (2) HP4194A impedance analyzer (or equivalent)



BUS INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER	Т	EST CONDITIO	ONS	MIN	TYP ⁽¹⁾	MAX	UNIT
		$V_A = 3.8 V$,	$V_B = 1.2 V,$		0		32	
I _A	Receiver or transceiver with driver disabled input current	$V_A = 0 V \text{ or } 2.4 V,$	$V_{B} = 1.2 \text{ V}$		-20		20	μΑ
	alcablea input current	$V_A = -1.4 V$,	V _B = 1.2 V		-32		0	
		V _B = 3.8 V,	V _A = 1.2 V		0		32	
I_B	Receiver or transceiver with driver disabled input current	$V_B = 0 V \text{ or } 2.4 V,$	$V_A = 1.2 \text{ V}$		-20		20	μΑ
	disabled input surrent	$V_B = -1.4 \text{ V},$	V _A = 1.2 V		-32		0	
I _{AB}	Receiver or transceiver with driver disabled differential input current (I _A – I _B)	$V_A = V_B$	$1.4 \le V_A \le 3.8$	3 V	-4		4	μΑ
		V _A = 3.8 V,	V _B = 1.2 V,	0 V ≤ V _{CC} ≤ 1.5 V	0		32	
I _{A(OFF)}	Receiver or transceiver power-off input current	V _A = 0 V or 2.4 V,	V _B = 1.2 V,	0 V ≤ V _{CC} ≤ 1.5 V	-20		20	μΑ
	mpat carrent	$V_A = -1.4 V$,	V _B = 1.2 V,	$0 \text{ V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V}$	-32		0	
		$V_B = 3.8 V,$	$V_A = 1.2 V,$	$0 \text{ V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V}$	0		32	
I _{B(OFF)}	Receiver or transceiver power-off input current	$V_B = 0 \text{ V or } 2.4 \text{ V},$	V _A = 1.2 V,	0 V ≤ V _{CC} ≤ 1.5 V	-20		20	μΑ
		$V_B = -1.4 V$,	$V_A = 1.2 V$,	$0 \text{ V} \leq \text{V}_{\text{CC}} \leq 1.5 \text{ V}$	-32		0	
I _{AB(OFF})	Receiver input or transceiver power-off differential input current (I_A - I_B)	$V_A = V_B$, $0 \text{ V} \le V_{CC}$	≤ 1.5 V, −1.4 ≤	$V_A \le 3.8 \text{ V}$	-4		4	μΑ
C _A	Transceiver with driver disabled input capacitance	$V_A = 0.4 \sin (30E6\pi)$	et) + 0.5V ⁽²⁾ ,	V _B = 1.2 V		5		pF
C _B	Transceiver with driver disabled input capacitance	$V_{B} = 0.4 \sin (30E6\pi)$	et) + 0.5 V ⁽²⁾ ,	V _A = 1.2 V		5		pF
C _{AB}	Transceiver with driver disabled differential input capacitance	V _{AB} = 0.4 sin (30E6	iπt)V ⁽²⁾				3	pF
C _{A/B}	Transceiver with driver disabled input capacitance balance, (C _A /C _B)				0.99		1.01	

⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

DRIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

PARAM	IETER	TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{PLH}	Propagation delay time, low-to-high-level output		1	1.5	2.4	ns
t _{PHL}	Propagation delay time, high-to-low-level output		1	1.5	2.4	ns
t _r	Differential output signal rise time	Con Figure 5	1		1.6	ns
t _f	Differential output signal fall time	See Figure 5	1		1.6	ns
t _{sk(p)}	Pulse skew (t _{PHL} - t _{PLH})			0	100	ps
t _{sk(pp)}	Part-to-part skew ⁽²⁾				1	ns
t _{jit(per)}	Period jitter, rms (1 standard deviation) ⁽³⁾	100 MHz clock input ⁽⁴⁾		2	3	ps
t _{jit(pp)}	Peak-to-peak jitter ⁽³⁾⁽⁵⁾	200 Mbps 2 ¹⁵ –1 PRBS input ⁽⁶⁾		30	130	ps
t _{PHZ}	Disable time, high-level-to-high-impedance output				7	ns
t _{PLZ}	Disable time, low-level-to-high-impedance output	Coo Figure 6			7	ns
t _{PZH}	Enable time, high-impedance-to-high-level output	See Figure 6			7	ns
t _{PZL}	Enable time, high-impedance-to-low-level output				7	ns

⁽¹⁾ All typical values are at 25°C and with a 3.3-V supply voltage.

⁽²⁾ HP4194A impedance analyzer (or equivalent)

⁽²⁾ t_{sk(pp)} is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits.

³⁾ Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.

⁽⁴⁾ $t_r = t_f = 0.5 \text{ ns } (10\% \text{ to } 90\%), \text{ measured over } 30 \text{ k samples.}$

⁽⁵⁾ Peak-to-peak jitter includes jitter due to pulse skew $(t_{sk(p)})$.

⁽⁶⁾ $t_r = t_f = 0.5 \text{ ns (10% to 90%), measured over 100 k samples.}$

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RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP ⁽¹⁾	MAX	UNIT
t _{pLH}	Propagation delay time, low-to-high-level output			2	4	6	ns
t _{pHL}	Propagation delay time, high-to-low-level output			2	4	6	ns
t _r	Output signal rise time			1		2.3	ns
t _f	Output signal fall time		C _L = 15 pF, See Figure 10	1		2.3	ns
	Dulgo alsoy (lt t l)	Type 1			100	300	ps
t _{sk(p)}	Pulse skew ($ t_{pHL} - t_{pLH} $)	Type 2			300	500	ps
t _{sk(pp)}	Part-to-part skew ⁽²⁾					1	ns
t _{jit(per)}	Period jitter, rms (1 standard deviation)(3)		100 MHz clock input ⁽⁴⁾		4	7	ps
	Dock to mock iittoways	Type 1	200 Mbps 2 ¹⁵ –1 PRBS input ⁽⁶⁾		300	700	ps
t _{jit(pp)}	Peak-to-peak jitter(3)(5)	Type 2	200 Mbps 210-1 PRBS Input(0)		450	800	ps
t _{pHZ}	Disable time, high-level-to-high-impedance output					10	ns
t _{pLZ}	Disable time, low-level-to-high-impedance output		Saa Firum 44			10	ns
t _{pZH}	Enable time, high-impedance-to-high-level output		See Figure 11			15	ns
t _{pZL}	Enable time, high-impedance-to-low-level output					15	ns

(1) All typical values are at 25°C and with a 3.3-V supply voltage.

 $t_{sk(pp)}$ is the magnitude of the time difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits.

⁽³⁾ Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.
(4) V_{ID} = 200 mV_{pp} (LVD201, 203), V_{ID} = 400 mV_{pp} (LVD206, 207), V_{cm} = 1 V, t_r = t_f = 0.5 ns (10% to 90%), measured over 30 k samples.
(5) Peak-to-peak jitter includes jitter due to pulse skew (t_{sk(p)}).
(6) V_{ID} = 200 mV_{pp} (LVD201, 203), V_{ID} = 400 mV_{pp} (LVD206, 207), V_{cm} = 1 V, t_r = t_f = 0.5 ns (10% to 90%), measured over 100 k samples.



PARAMETER MEASUREMENT INFORMATION

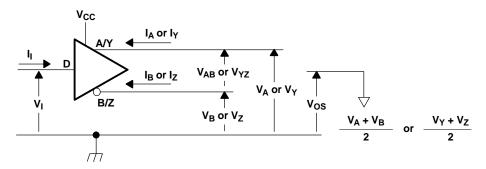
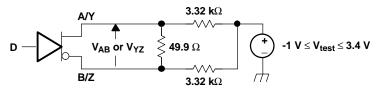
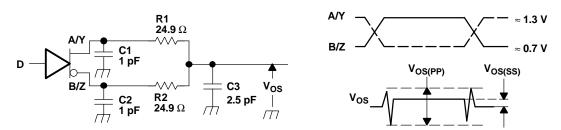


Figure 1. Driver Voltage and Current Definitions



A. All resistors are 1% tolerance.

Figure 2. Differential Output Voltage Test Circuit



- A. All input pulses are supplied by a generator having the following characteristics: t_r or t_f≤ 1 ns, pulse frequency = 500 kHz, duty cycle = 50 ± 5%.
- B. C1, C2 and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
- C. R1 and R2 are metal film, surface mount, ±1%, and located within 2 cm of the D.U.T.
- D. The measurement of V_{OS(PP)} is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 3. Test Circuit and Definitions for the Driver Common-Mode Output Voltage

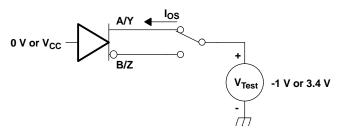
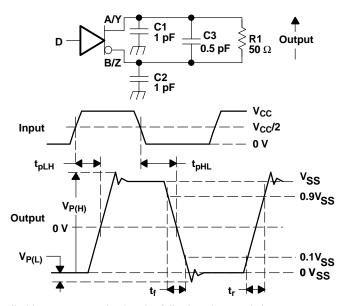


Figure 4. Driver Short-Circuit Test Circuit

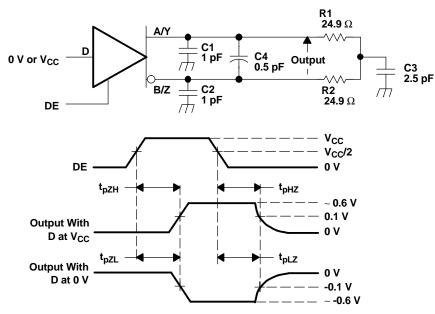


PARAMETER MEASUREMENT INFORMATION (continued)



- A. All input pulses are supplied by a generator having the following characteristics: t_r or t_f≤ 1 ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
- B. C1, C2, and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
- C. R1 is a metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
- D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 5. Driver Test Circuit, Timing, and Voltage Definitions for the Differential Output Signal



- A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_r \le 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
- B. C1, C2, C3, and C4 includes instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
- C. R1 and R2 are metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
- D. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 6. Driver Enable and Disable Time Circuit and Definitions



PARAMETER MEASUREMENT INFORMATION (continued)

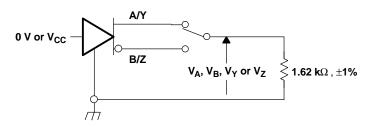
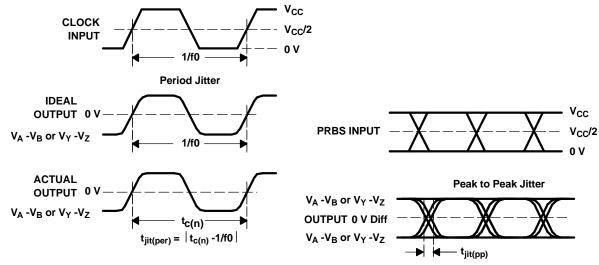


Figure 7. Maximum Steady State Output Voltage



- A. All input pulses are supplied by an Agilent 8304A Stimulus System.
- B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
- C. Period jitter is measured using a 100 MHz 50 ±1% duty cycle clock input.
- D. Peak-to-peak jitter is measured using a 200Mbps 2¹⁵-1 PRBS input.

Figure 8. Driver Jitter Measurement Waveforms

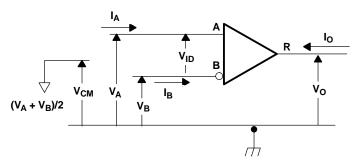


Figure 9. Receiver Voltage and Current Definitions



Table 1. Type-1 Receiver Input Threshold Test Voltages

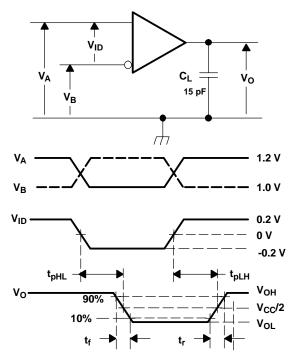
	APPLIED RESULTING DIFFERENTIAL VOLTAGES INPUT VOLTAGE		RESULTING COMMON- MODE INPUT VOLTAGE	RECEIVER OUTPUT ⁽¹⁾
VIA	V_{IB}	V _{ID}	V _{IC}	
2.400	0.000	2.400	1.200	Н
0.000	2.400	-2.400	1.200	L
3.800	3.750	0.050	3.775	Н
3.750	50 3.800 -0.050		3.775	L
-1.350	-1.400	0.050	-1.375	Н
-1.400	-1.350	-0.050	-1.375	L

(1) H = high level, L = low level, output state assumes receiver is enabled $(\overline{RE} = L)$

Table 2. Type-2 Receiver Input Threshold Test Voltages

	LIED AGES	RESULTING DIFFERENTIAL INPUT VOLTAGE	RESULTING COMMON- MODE INPUT VOLTAGE	RECEIVER
VIA	V _{IB}	V_{ID}	V _{IC}	OUTPUT ⁽¹⁾
2.400	0.000	2.400	1.200	Н
0.000	2.400	-2.400	1.200	L
3.800	3.650	0.150	3.725	Н
3.800	3.750	0.050	3.775	L
-1.250	-1.400	0.150	-1.325	Н
-1.350	-1.400	0.050	-1.375	L

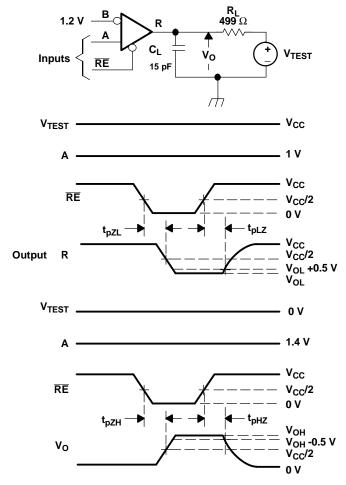
(1) H = high level, L = low level, output state assumes receiver is enabled ($\overline{RE} = L$)



- A. All input pulses are supplied by a generator having the following characteristics: t_r or t_f≤ 1 ns, frequency = 50 MHz, duty cycle = 50 ± 5%. C_L is a combination of a 20%-tolerance, low-loss ceramic, surface-mount capacitor and fixture capacitance within 2 cm of the D.U.T.
- B. The measurement is made on test equipment with a -3 dB bandwidth of at least 1 GHz.

Figure 10. Receiver Timing Test Circuit and Waveforms

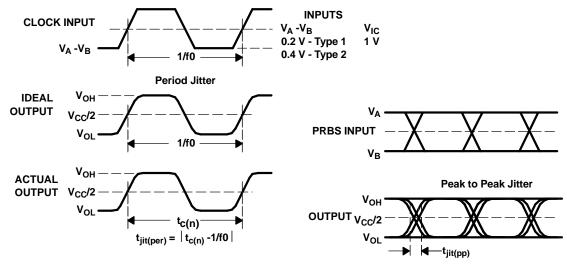




- A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_r \le 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
- B. R_L is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.
- C. R_L is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.
- D. C_L is the instrumentation and fixture capacitance within 2 cm of the DUT and $\pm 20\%$.

Figure 11. Receiver Enable/Disable Time Test Circuit and Waveforms

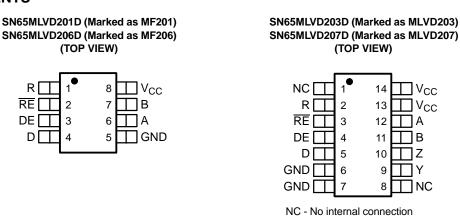




- A. All input pulses are supplied by an Agilent 8304A Stimulus System.
- B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
- C. Period jitter is measured using a 100 MHz 50 ±1% duty cycle clock input.
- D. Peak-to-peak jitter is measured using a 200 Mbps 2¹⁵-1 PRBS input.

Figure 12. Receiver Jitter Measurement Waveforms

PIN ASSIGNMENTS





DEVICE FUNCTION TABLES

TYPE-1 RECEIVER (201, 203)

INPUTS	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R
V _{ID} ≥ 50 mV	L	Н
$-50 \text{ mV} < V_{\text{ID}} < 50 \text{ mV}$	L	?
$V_{ID} \le -50 \text{ mV}$	L	L
Х	Н	Z
X	Open	Z
Open Circuit	L	?

TYPE-2 RECEIVER (206, 207)

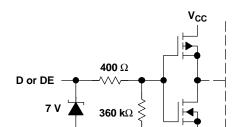
INPUTS	OUTPUT	
$V_{ID} = V_A - V_B$	RE	R
V _{ID} ≥ 150 mV	L	Н
50 mV < V _{ID} < 150 mV	L	?
$V_{ID} \le 50 \text{ mV}$	L	L
X	Н	Z
X	Open	Z
Open Circuit	L	L

DRIVER

INPUT	ENABLE	OUTPUTS		
D	DE	A OR Y	B OR Z	
L	Н	L	Н	
Н	Н	Н	L	
OPEN	Н	L	Н	
Х	OPEN	Z	Z	
Х	L	Z	Z	

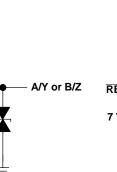
H = high level, L = low level, Z = high impedance, X = Don't care, ? = indeterminate

EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS

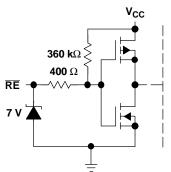


DRIVER INPUT AND DRIVER ENABLE

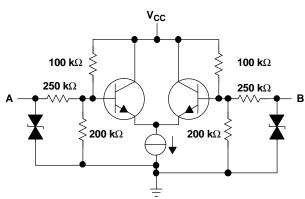
DRIVER OUTPUT V_{CC}



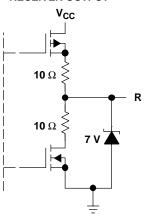
RECEIVER ENABLE



RECEIVER INPUT

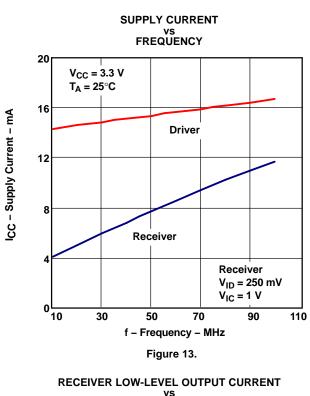


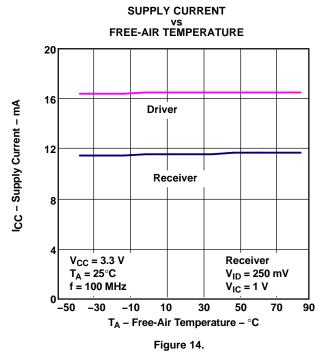
RECEIVER OUTPUT



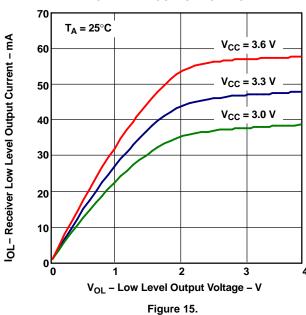


TYPICAL CHARACTERISTICS

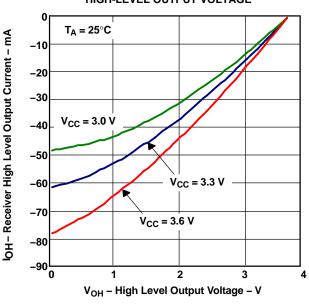




vs LOW-LEVEL OUTPUT VOLTAGE



RECEIVER HIGH-LEVEL OUTPUT CURRENT vs HIGH-LEVEL OUTPUT VOLTAGE



tpLH

tpHL

70

90



1

-50

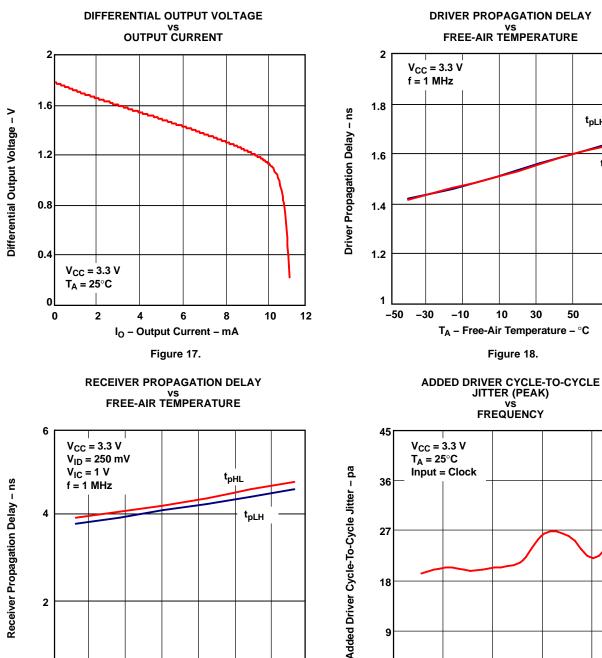
-30

-10

10

30

TYPICAL CHARACTERISTICS (continued)



 T_A – Free-Air Temperature – $^{\circ}$ C Figure 19.

70

90

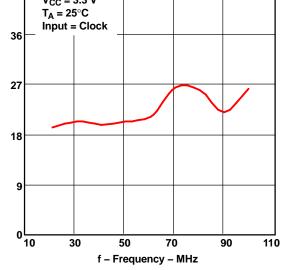


Figure 20.



TYPICAL CHARACTERISTICS (continued)

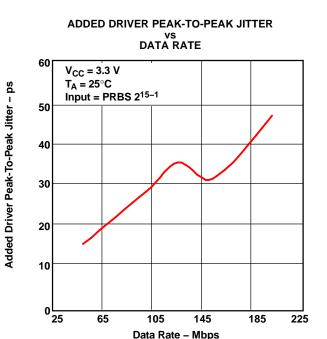
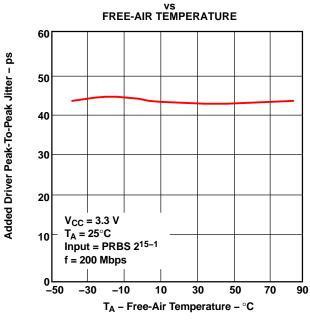


Figure 21.

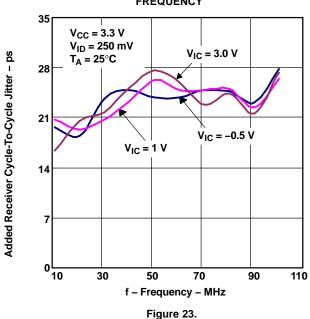


ADDED DRIVER PEAK-TO-PEAK JITTER

Figure 22.

ADDED RERCEIVER PEAK-TO-PEAK JITTER

ADDED RECEIVER CYCLE-TO-CYCLE JITTER vs FREQUENCY



Added Receiver Peak-To-Peak Jitter – ps

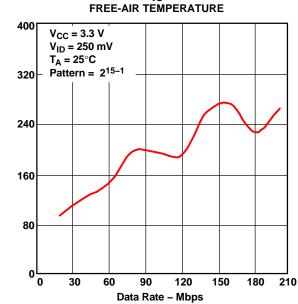
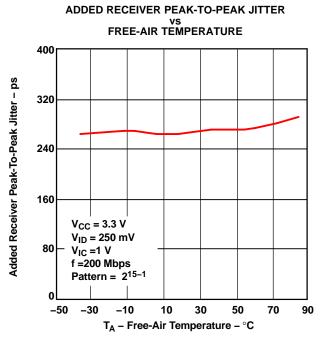


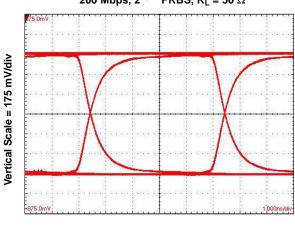
Figure 24.



TYPICAL CHARACTERISTICS (continued)





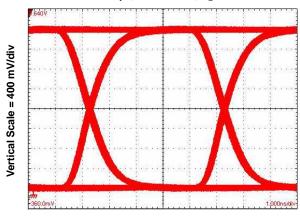


Horizontal Scale = 1 ns/div

Figure 25.

Figure 26.

SN65MLVD201 RECEIVER OUTPUT EYE PATTERN 200 Mbps, 2^{15-1} PRBS, $R_L = 15 \Omega$



Horizontal Scale = 1 ns/div Figure 27.

APPLICATION INFORMATION

Receiver Input Threshold (Failsafe)

The MLVD standard defines a type 1 and type 2 receiver. Type 1 receivers include no provisions for failsafe and have their differential input voltage thresholds near zero volts. Type 2 receivers have their differential input voltage thresholds offset from zero volts to detect the absence of a voltage difference. The impact to receiver output by the offset input can be seen in Table 3 and Figure 28.

Table 3. Receiver Input Voltage Threshold Requirements

RECEIVER TYPE	OUTPUT LOW	OUTPUT HIGH
Type 1	$-2.4 \text{ V} \le \text{V}_{\text{ID}} \le -0.05 \text{ V}$	$0.05 \text{ V} \le \text{V}_{\text{ID}} \le 2.4 \text{ V}$
Type 2	$-2.4 \text{ V} \le \text{V}_{\text{ID}} \le 0.05 \text{ V}$	0.15 V ≤ V _{ID} ≤ 2.4 V

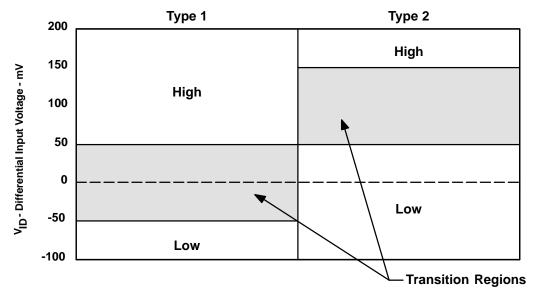


Figure 28. Expanded Graph of Receiver Differential Input Voltage Showing Transition Region



LIVE INSERTION/GLITCH-FREE POWER UP/DOWN

The SN65MLVD201/203/206/207 family of products offered by Texas Instruments provides a glitch-free powerup/down feature that prevents the M-LVDS outputs of the device from turning on during a powerup or powerdown event. This is especially important in live insertion applications, when a device is physically connected to an M-LVDS multipoint bus and VCC is ramping.

While the M-LVDS interface for these devices is glitch free on powerup/down, the receiver output structure is not.Figure 29 shows the performance of the receiver output pin, R (CHANNEL 2), as Vcc (CHANNEL 1) is ramped.

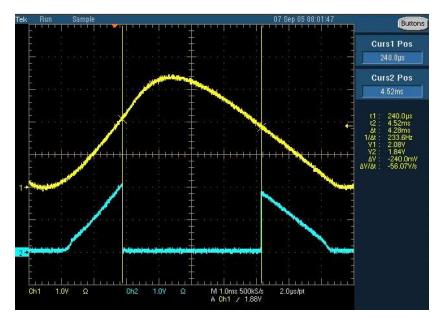


Figure 29. M-LVDS Receiver Output: VCC (CHANNEL 1), R Pin (CHANNEL 2)

The glitch on the R pin is independent of the $\overline{\text{RE}}$ voltage. Any complications or issues from this glitch are easily resolved in power sequencing or system requirements that suspend operation until VCC has reached a steady state value.





.com 4-Nov-2005

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan ⁽²⁾	Lead/Ball Finish	MSL Peak Temp ⁽³⁾
SN65MLVD201D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD201DG4	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD201DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD201DRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD203D	ACTIVE	SOIC	D	14	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD203DR	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD203DRG4	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD206D	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD206DR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD206DRE4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD207D	ACTIVE	SOIC	D	14	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD207DR	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
SN65MLVD207DRG4	ACTIVE	SOIC	D	14	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS) or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

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(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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D (R-PDSO-G14)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES:

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- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-012 variation AB.



D (R-PDSO-G8)

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