Shih-Hao Liu Dec. 02, 2020

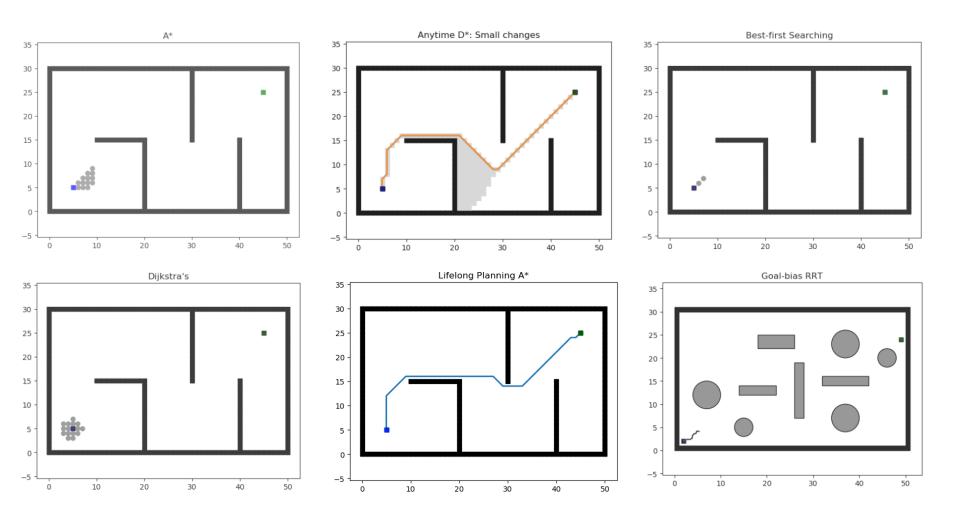
when I have a map

000 000			000 040	000 050	000 060	
			出貨架	電腦	DLP	
010 000	010 010					
	灰貨架					
020 000	020 010					
	灰貨架					
030 000	030 010				030 060	教室上課區域
	灰貨架					7 X主工术 型以
040 000						
050 000					050 060	
					牆	
060 000				060 050	060 060	
				充電站	牆	

How to Plan a Route

000 000					000 040	000	050	000 060	
					出貨架	電腦		DLP	
010 000	010 010								
	灰貨架					E			
020 000	020 010								
	灰貨架								
030 000	030 010							030 060	教室上課區域
	灰貨架			S					双至上 床
040 000									
050 000								050 060	
	R						•	牆	
060 000						060	050	060 060	
	R			R	充電站		牆		

- Route Plan Solution
- Best-First Searching
- Dijkstra 's
- A*
- Bidirectional-A*
- Repeated A*
- Anytime Repairing A* (ARA*)
- Learning Real-Time A* (LRTA*)
- Real-Time Adaptive A* (RTAA*)
- Dynamic A* (D*)
- Lifelong Planning A*
- Anytime D*



Maze Solving Algorithm

- A*
- Best-First Searching
- Depth-First Searching
- Random Mouse Algorithm

DO

• Use the any algorithm to plan the route.