

Design and Analysis of Algorithms

L24: Dijkstra's Algorithm

Single Source Shortest Path

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Bellman-Ford Algorithm

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Resources

- Text book 1: Sec 9.3 - Levitin
- R1: Introduction to Algorithms
 - Cormen et al.
- NPTEL: DAA
 - https://onlinecourses.nptel.ac.in/noc20_cs27/unit?unit=29&lesson=30
 - https://onlinecourses.nptel.ac.in/noc20_cs27/unit?unit=29&lesson=31

Single Source Shortest Path

- Applications
 - Supplying deliveries from a factory to various godowns
 - Minimum time/cost
 - KSIT: Moving from quadrangle to your class rooms
 - Minimum time taken

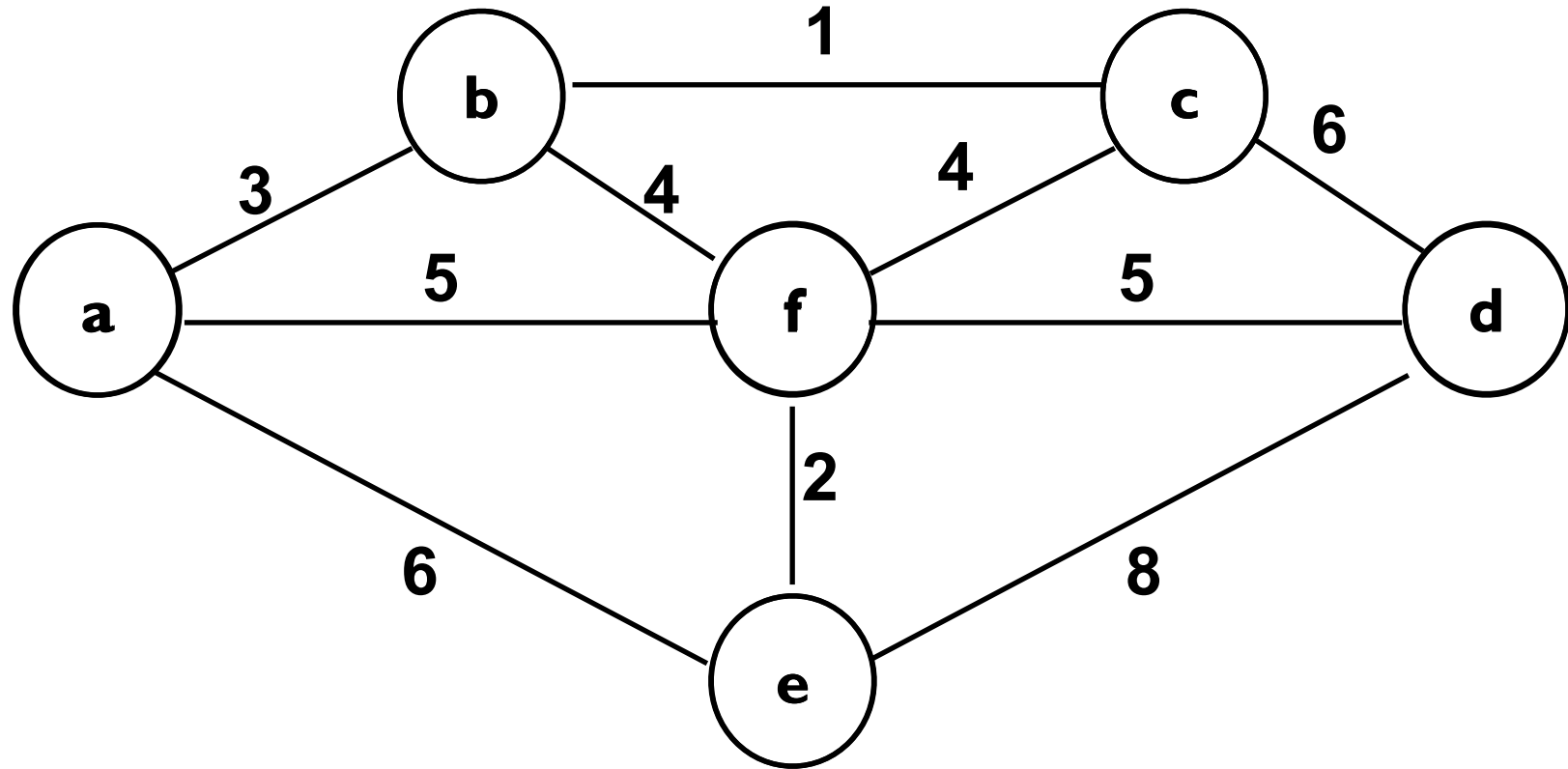
DFS and BFS Traversal

- Both DFS and BFS perform graph traversal
- Both take linear time in terms of size of graph when using adjacency lists i.e. $O(|E|)$
- We can find path by keeping parent information
- BFS computes shortest path in terms of number of edges i.e. all edges have same cost
 - Does not work when edges have different costs
- In DFS, vertex numbering (previsit(), postvisit()) reveals interesting information about graph
 - e.g. backedges, forward edges, cross edges
 - it does not find shortest path though

Single Source Shortest Path

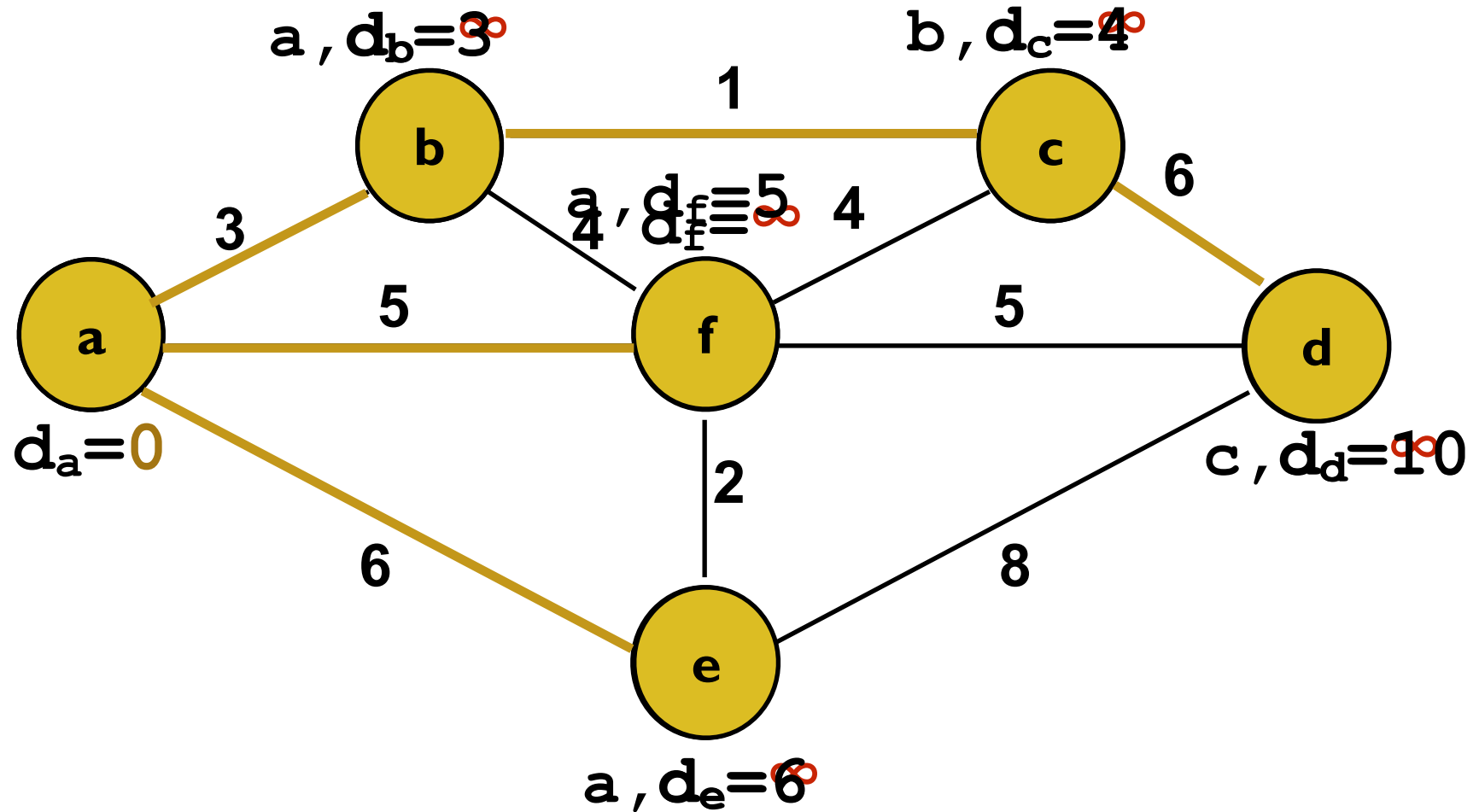
- Goal: Given a weighted connected (directed) graph G , find shortest paths from source vertex s to each of the other vertices
 - Path cost: sum of cost each edge on the path
- Dijkstra's algorithm
 - Approach similar to Prim's algorithm for MST
 - Computes numerical labels differently
 - Among vertices not in the tree,
 - Find the vertex v with the smallest sum $d_u + w(u, v)$, where
 - $u \in V$ whose shortest path found in previous iteration
 - d_u is the length of shortest path from s to u

Example: Dijkstra's Algorithm



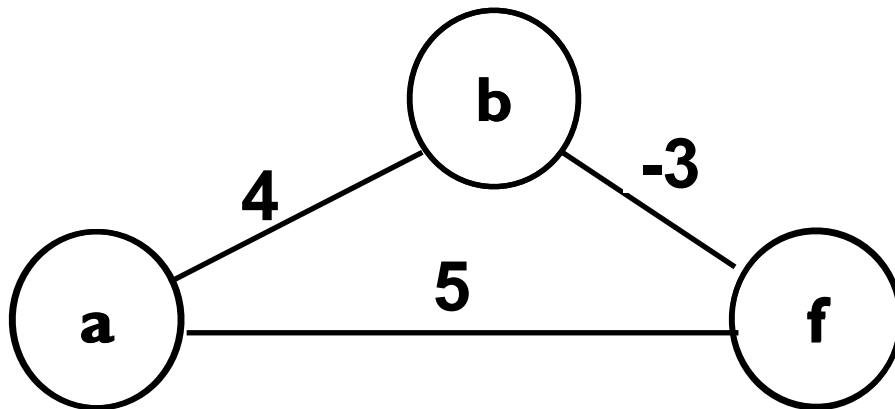
- Q: Construct an SSSP using Dijkstra's algo starting from vertex a

Example: Dijkstra's Algorithm



Notes on Dijkstra's Algorithm

- Proof of correctness:
 - Using induction
- Works with graph with +ve weights only
 - Build a counter example with -ve weight where Dijkstra's algorithm does not work
- Works for both directed and undirected graphs



Algorithm: Dijkstra's Algorithm

```
Algo Dijkstra( $G, s$ )  
// i/p: a weighted connected graph  $G = (V, E)$ , and src  $s$   
//    all edges are non-negative weights  
// o/p: Length  $d_v$  of a shortest path from  $s$  to  $v$ .  
//    along with it predecessor vertex from  $v$  to  $s$ .  
Initialize( $Q$ ) // priority queue of vertices is empty initially  
for each vertex  $v \in V$ , do  
     $d_v \leftarrow \infty$ ;  $p_v \leftarrow \text{Null}$ ;  
    Insert( $Q, v, d_v$ ) // initialize vertex priority in priority  $Q$   
 $d_s \leftarrow 0$ ;  
Decrease( $Q, s, d_s$ )  
 $p_s \leftarrow \text{Null}$ ;  
 $V_T \leftarrow \emptyset$ 
```

Algorithm: Dijkstra's Algorithm...

```
Algo Dijkstra (G, s) ...  
  for i=0 to |V|-1 do  
    u = DeleteMin(Q) //time implementation based  
    VT = VT ∪ {u}  
    for every vertex w ∈ V - VT adjacent to u, do  
      if du + weight(u, w) < dw, then  
        dw ← du + weight(u, w)  
        pw ← u  
        Decrease(Q, w, dw) //time implementation based  
      fi  
    end //for w ∈ V - VT  
  end //for i=0  
end //algo
```

Analysis: Dijkstra's Algorithm...

- Implementation using Adjacency matrix
 - Priority Q using unsorted array
 - Outer for loop ($i=0$ to $|V|-1$): $O(|V|)$ times
 - DeleteMin takes $O(|V|)$ times
 - Total time for all vertices: $O(|V|^2)$
 - Decrease(Q, w, d_w) takes $O(1)$ time
 - Total time for all vertices: $O(|E|)$
 - Time Complexity: $O(|V|^2)$

Analysis: Dijkstra's Algorithm

- Implementation using Adjacency List
 - Priority Q using Heap
 - Outer for loop ($i=0$ to $|V|-1$): $O(|V|)$ times
 - DeleteMin takes $O(\lg |V|)$ times
 - Total time for all vertices: $O(|V| \lg |V|)$
 - Decrease(Q, w, d_w) takes $O(\lg |V|)$ time
 - Total time for all vertices: $O(|E| \lg |V|)$
 - Time Complexity: $O(|E| \lg |V|)$

Greedy Approach: Disjkstra's Algo

- Greedy Approach:
 - Make a sequence of choices
 - One choice at a time
 - Next choice is based on current best value
 - Once a choice is made (a node is chosen), this choice is never changed
- Dijkstra's Algo:
 - Select vertex with minimum distance from source
 - (from via previously selected vertices)
 - Greedy approach is optimal in this case

Questions

- Q1: what adjustments if any need to be made in Dijkstra's algorithm to solve the single-source shortest-paths problem for directed weighted graphs.
- Ans:
 - Do we need any changes? Just follow the directed edges.

Questions

- Q2: Find a shortest path between two given vertices of a weighted graph or digraph. (This variation is called the single-pair shortest-path problem.)
- Ans:
 - Start from one vertex as source
 - Iterate the for loop till you find 2nd vertex.

Questions

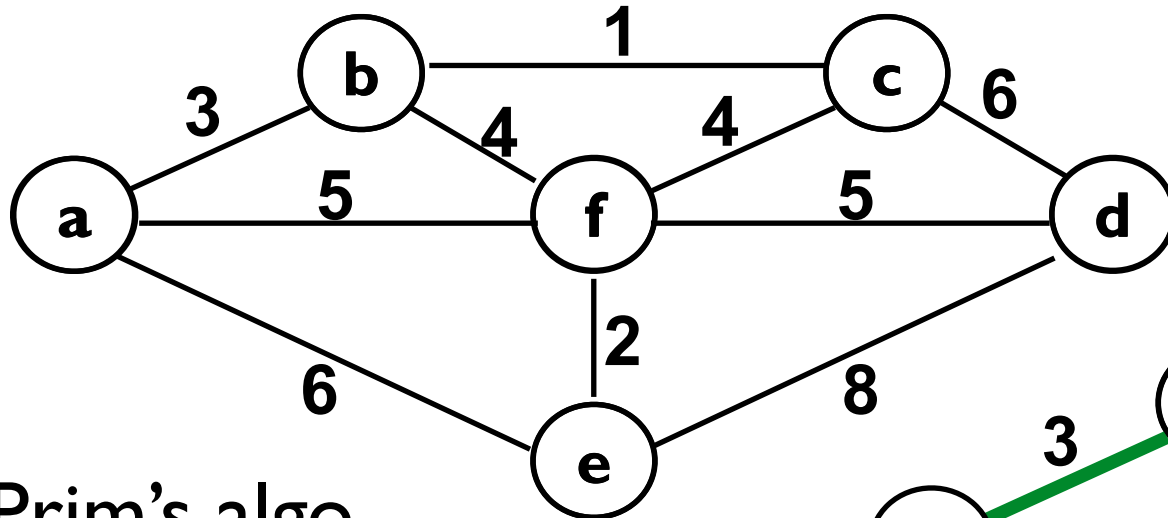
- Q3: Find the shortest paths to a given vertex from each other vertex of a weighted graph. (This variation is called the single destination shortest-paths problem.)
- Ans: Undirected graph
 - Start from the destination vertex as source
 - Find the shortest path from this to all other vertices
 - Reverse the path
- Ans: directed graph
 - Reverse the direction of all edges.
 - Start from the destination vertex as source
 - Find the shortest path from this src to all other vertices
 - Reverse the path

Questions

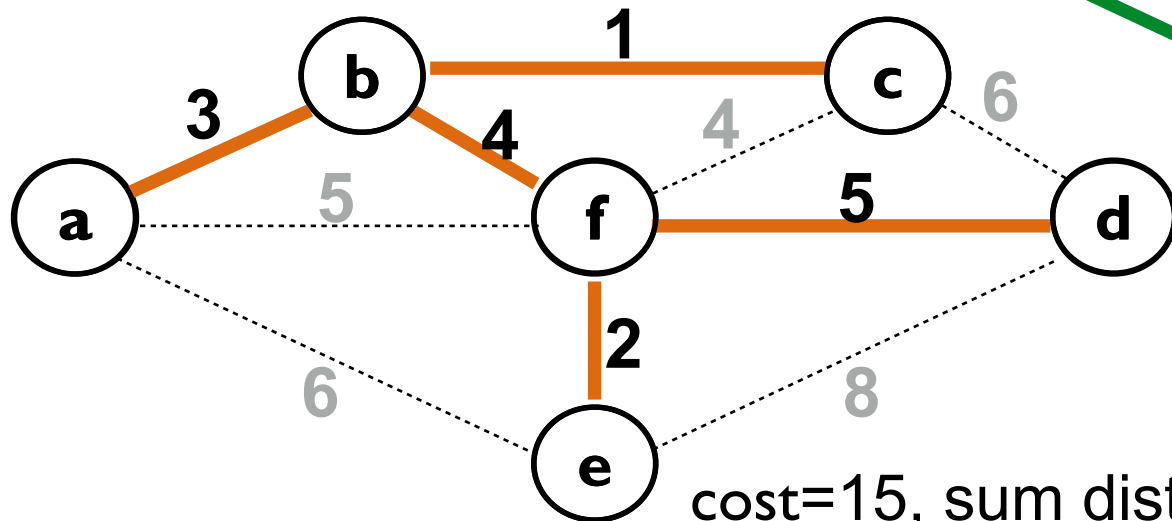
- Q4: Solve the single-source shortest-path problem in a graph with non-negative numbers assigned to its vertices (and the length of a path defined as the sum of the vertex numbers on the path).
- Hint:
 - The weight of the edge is sum of non-negative numbers assigned to vertices of the corresponding edge.

Dijkstra vs Prim Algo

- Do both give same tree? Consider the example

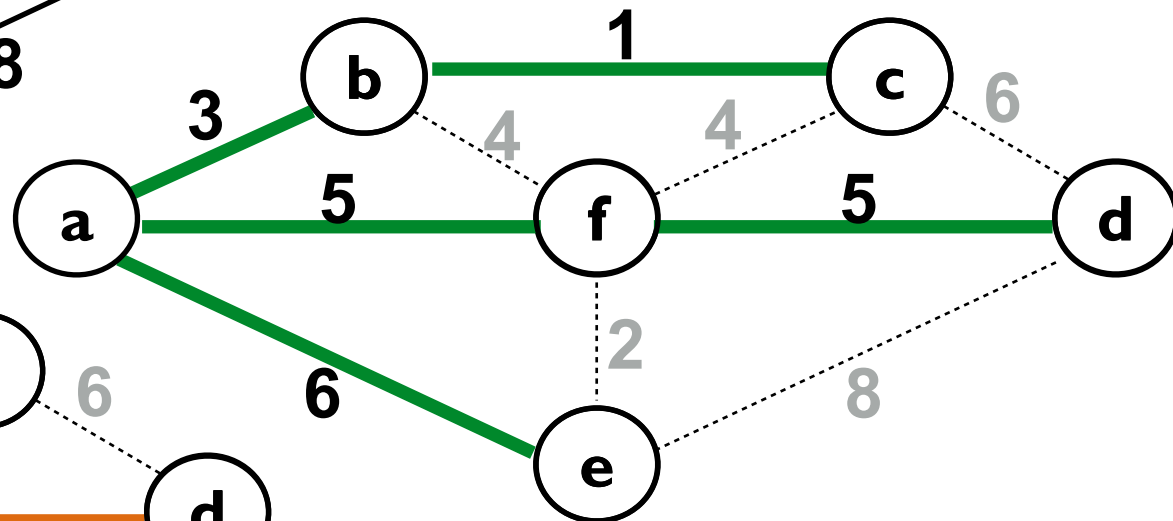


Prim's algo



cost=15, sum distance=38

Dijkstra algo



cost=20, sum distance=28

Summary

- Dijkstra's algorithm
 - Keeps shortest length for each vertex from source s
 - Keep predecessor with each vertex towards s
 - Different from Prim's algorithm
 - Dijkstra: Chooses vertex with min shortest length from source
 - Prim: chooses edges with minimum weight from current spanning tree (and not from src)