Fork/Join

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Fork/Join or **Divide** and **Conquer** is a very powerful abstraction to solve hierarchical problems

The Abstraction

When talking about hierarchical problems, think about quick sort, merge sort, file system or general tree navigation and such.

- *Fork/Join* algorithms essentially splits a problem at hand into several smaller sub-problems and recursively applies the same algorithm to each of the sub-problems.
- Once the sub-problem is small enough, it is solved directly.
- The solutions of all sub-problems are combined to solve their parent problem, which, in turn, helps solve its own parent problem.



The JSR-166y library leaves a couple of rough edges, which can hurt you

The **JSR-166y** library solves *Fork/Join* orchestration pretty nicely for us, but leaves a couple of rough edges, which can hurt you, if you don't pay attention enough. You still deal with threads, pools and synchronization barriers.

The GPars Abstraction Convenience Layer

GPars can hide the complexities of dealing with threads, pools, barriers and RecursiveActions from you, yet let you leverage the powerful *Fork/Join* implementation in *jsr166y*.

ForkJoin Sample

```
import static groovyx.gpars.GParsPool.runForkJoin
import static groovyx.gpars.GParsPool.withPool
//feel free to experiment with the number of fork/join threads in the pool
withPool(1) {pool ->
    println """Number of files: ${
        runForkJoin(new File("./src")) {file ->
            long count = 0
            file.eachFile {
                if (it.isDirectory()) {
                    println "Forking a child task for $it"
                    forkOffChild(it) //fork a child task
                } else {
                    count++
            }
            return count + (childrenResults.sum(0))
            //use results of children tasks to calculate and store own result
   }"""
}
```

Fork/Join Saves Your Resources

Fork/Join operations can be safely run with small number of threads thanks to internally using the TaskBarrier class to synchronize the threads.

While a thread is blocked inside an algorithm waiting for its sub-problems to be calculated, the thread is silently returned to the pool to take on any of the available sub-problems from the task queue and process them. Although the algorithm creates as many tasks as there are sub-directories and tasks wait for the sub-directory tasks to complete, as few as one thread is enough to keep the computation going and eventually calculate a valid result.

If you'd like to know more, check out the _Fork/Joinsection of the User Guide.