HW8 Problem 2

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John Clouse

Initialize

CKF State

```
X_{ckf} = zeros(2,len);
diff_ckf = zeros(2,len);
for ii = 1:len
    H1 = [1 \ 2*eps(ii)];
    P1_ap = eye(2)*std_dev(ii)*std_dev(ii);
    K1 = P1_ap*H1'*inv(H1*P1_ap*H1' + R);
    X_{est1} = X_{ap0} + K1*(H1*X_{exact} - H1*X_{ap0});
    P1 = (eye(2) - K1*H1)*P1_ap;
    X_ap1 = X_est1;
    %P1 is now P2 ap
    P2_ap = P1;
    H2 = [1 \ 3*eps(ii)];
    K2 = P2_ap*H2'*inv(H2*P2_ap*H2' + R);
    X_{est2} = X_{ap1} + K2*(H2*X_{exact} - H2*X_{ap1});
    P2 = (eye(2) - K2*H2)*P2_ap;
    X_{ckf}(:,ii) = X_{est2};
```

```
diff_ckf(:,ii) = X_exact - X_ckf(:,ii);
end

row = 2;
HW8_P2_plot(eps, -diff_ckf, row, 'Kalman', logx_fig, loglog_fig)
```

Joseph State

```
I = eye(2);
X_joseph = zeros(2,len);
diff_joseph = zeros(2,len);
for ii = 1:len
    H = [1 \ 2*eps(ii); 1 \ 3*eps(ii)];
    P ap = I*std dev(ii)*std dev(ii);
    X_ap = X_ap0;
    for jj = 1:2
        K = P_ap^*H(jj,:)'*inv(H(jj,:)^*P_ap^*H(jj,:)' + R);
        P = (I-K*H(jj,:))*P_ap*(I-K*H(jj,:))' + K*R*K';
        X_{est} = X_{ap} + K*(H(jj,:)*X_{exact} - H(jj,:)*X_{ap});
        P_ap = P; % a priori for next measurement
        X_ap = X_est;
    end
    X \text{ joseph}(:,ii) = X \text{ est};
    diff_joseph(:,ii) = X_exact - X_joseph(:,ii);
end
row = 3;
HW8_P2_plot(eps, -diff_joseph, row, 'Joseph', logx_fig, loglog_fig)
```

Potter State

```
X_potter = zeros(2,len);
diff_potter = zeros(2,len);
for ii = 1:len
    H = [1 \ 2*eps(ii); 1 \ 3*eps(ii)];
    P ap = I*std dev(ii)*std dev(ii);
    X_ap = X_ap0;
    W_bar = sqrt(P_ap);
    for jj = 1:2
        F = W_bar*H(jj,:)';
        alpha = inv(F'*F + R);
        gamma = 1/(1+sqrt(R*alpha));
        K = alpha*W_bar*F;
        W = W_bar-gamma*K*F';
        X_{est} = X_{ap} + K*(H(jj,:)*X_{exact} - H(jj,:)*X_{ap});
        W_bar = W; % sequential update
        X_ap = X_est;
    end
    X_potter(:,ii) = X_est;
    diff_potter(:,ii) = X_exact - X_potter(:,ii);
end
row = 4;
HW8_P2_plot(eps, -diff_potter, row, 'Potter', logx_fig, loglog_fig)
```

Batch State

```
X_batch = zeros(2,len);
diff_batch = zeros(2,len);
for ii = 1:len
    H = [1 \ 2*eps(ii); 1 \ 3*eps(ii)];
    info_mat = inv(I*std_dev(ii)*std_dev(ii));
    info_mat = info_mat + H(1,:)'*inv(R)*H(1,:);
    info_mat = info_mat + H(2,:)'*inv(R)*H(2,:);
    N = inv(I*std_dev(ii)*std_dev(ii))*X_ap0;
    N = N + H(1,:)'*inv(R)*H(1,:)*X_exact;
    N = N + H(2,:)'*inv(R)*H(2,:)*X_exact;
    X_est = inv(info_mat)*N;
    X_{batch}(:,ii) = X_{est};
    diff_batch(:,ii) = X_exact - X_batch(:,ii);
end
row = 1;
HW8_P2_plot(eps, -diff_batch, row, 'Batch', logx_fig, loglog_fig)
```

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