```
function euler_angles = DCM2Euler( seq_string, DCM )
%DCM2Euler Turn a DCM set into an Euler angle set in the specified sequence
fcnPrintQueue(mfilename('fullpath'))
euler_angles = zeros(3,1);
if strcmp(seq_string,'321')
   euler_angles(2) = asin(-DCM(1,3));
    euler\_angles(1) = atan2(DCM(1,2),DCM(1,1));
    euler\_angles(3) = atan2(DCM(2,3),DCM(3,3));
elseif strcmp(seq_string,'121')
    euler_angles(2) = acos(DCM(1,1));
    euler\_angles(1) = atan2(DCM(1,2),-DCM(1,3));
    euler\_angles(3) = atan2(DCM(2,1),DCM(3,1));
else
    fprintf('this rotation sequence is not supported');
end
end
```

Published with MATLAB® R2013b