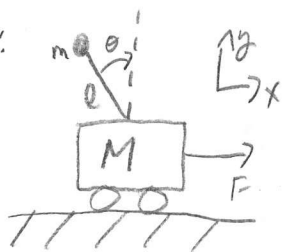


Problem 1:



$$(M+m)\ddot{x} - m l \ddot{\theta} \cos \theta + m l \dot{\theta}^2 \sin \theta = F$$

$$l \ddot{\theta} - g \sin \theta = \ddot{x} \cos \theta$$

$$y = x - l \sin \theta = h_1$$

a) Linearize EOMs

$$(M+m)\ddot{x} - m(g \sin \theta + \ddot{x} \cos \theta) \cos \theta + m l \dot{\theta}^2 \sin \theta - F = 0$$

$$\ddot{u} = F$$

$$\ddot{x} = \begin{pmatrix} \dot{x} \\ \ddot{x} \\ \dot{\theta} \\ \ddot{\theta} \end{pmatrix}, \quad \ddot{x} = \begin{pmatrix} \dot{x} \\ \ddot{x} \\ \dot{\theta} \\ \ddot{\theta} \end{pmatrix} = \begin{bmatrix} \dot{x} \\ -\frac{m g \sin \theta \cos \theta + m l \dot{\theta}^2 \sin \theta - F}{M+m-m \cos \theta} \\ \dot{\theta} \\ \ddot{\theta} = \frac{\dot{x} \cos \theta + g \sin \theta}{l} \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \\ f_4 \end{bmatrix}$$

$$\frac{\partial f_2}{\partial \theta} = \frac{(-m g \cos^2 \theta + m g \sin^2 \theta + m l \dot{\theta}^2 \cos \theta)(M+m(1-\cos \theta)) - (g \cos \theta + l \dot{\theta}^2) m \sin \theta (m \sin \theta)}{(M+m(1-\cos \theta))^2}$$

$$\left. \frac{\partial f_2}{\partial \theta} \right|_{\substack{\theta=0 \\ \dot{\theta}=0}} = \frac{(-m g) M}{M^2} = -\frac{m}{M} g$$

$$\frac{\partial f_2}{\partial \dot{\theta}} = \frac{2 m l \dot{\theta} \sin \theta}{M+m(1-\cos \theta)} \Rightarrow \left. \frac{\partial f_2}{\partial \dot{\theta}} \right|_{\substack{\theta=0 \\ \dot{\theta}=0}} = 0$$

$$\frac{\partial f_3}{\partial \theta} = 1$$

$$\frac{\partial f_4}{\partial \theta} = \frac{\partial}{\partial \theta} \left[\frac{f_2 \cos \theta + \sin \theta}{l} \right] = \frac{\partial f_2}{\partial \theta} \frac{\cos \theta}{l} - f_2 \frac{\sin \theta}{l}$$

$$\left. \frac{\partial f_4}{\partial \theta} \right|_{\substack{\theta=0 \\ \dot{\theta}=0}} = -\frac{m}{M} \frac{g}{l}$$

$$\frac{\partial f_4}{\partial \dot{\theta}} = \frac{\partial f_2}{\partial \dot{\theta}} \frac{\cos \theta}{l} \Rightarrow \left. \frac{\partial f_4}{\partial \dot{\theta}} \right|_{\substack{\theta=0 \\ \dot{\theta}=0}} = 0$$

$$\frac{\partial h_1}{\partial x} = 1$$

$$\left. \frac{\partial h_1}{\partial \theta} \right|_{\theta=0} = -l \cos \theta \big|_{\theta=0} = -l$$

$$\left. \frac{\partial f_2}{\partial u} \right|_{\theta=0} = -\frac{1}{M}, \quad \left. \frac{\partial f_4}{\partial u} \right|_{\theta=0} = \left[\frac{\partial f_2}{\partial \theta} \frac{\cos \theta}{l} - f_2 \frac{\sin \theta}{l} \right]_{\theta=0} = -\frac{1}{M l}$$

Problem 1 cont.

$$\delta \ddot{\mathbf{x}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{m}{M}g & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -\frac{m}{M}\frac{g}{\ell} & 0 \end{pmatrix} \delta \mathbf{x} + \begin{pmatrix} 0 \\ -\frac{1}{M} \\ 0 \\ -\frac{1}{M\ell} \end{pmatrix} \delta \ddot{u}$$

$$\delta y = [1 \ 0 \ -\ell \ 0] \delta \mathbf{x} + 0 \cdot \delta \ddot{u}$$

b) $\ell \ddot{\theta} = \dot{x}/\ell \Rightarrow \delta \ddot{x} = \ell \delta \ddot{\theta} = \frac{d}{dt} \dot{x} = \frac{d^2}{dt^2} x \Rightarrow x = \ell \iint \frac{d^2}{dt^2} \theta \Rightarrow \theta = \frac{x}{\ell} + c$
 rows 2 & 4 are not independent

let $\tilde{\mathbf{x}}_L = \begin{pmatrix} \theta \\ \dot{\theta} \end{pmatrix}$, $u = F$, y

about $\tilde{\mathbf{x}}_L = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\dot{\tilde{\mathbf{x}}}_L = \begin{bmatrix} 0 & 1 \\ -\frac{m}{M}\frac{g}{\ell} & 0 \end{bmatrix} \tilde{\mathbf{x}}_L + \begin{bmatrix} 0 \\ -\frac{1}{M\ell} \end{bmatrix} \ddot{u}$$

$$y = [0 \ 0] \tilde{\mathbf{x}}_L + 0 \cdot \ddot{u}$$

Problem 2: Given SS model

$$\dot{\vec{x}} = \begin{bmatrix} 0 & 1 \\ -25 & -4 \end{bmatrix} \vec{x} + \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \vec{u}, \quad \vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$\vec{y} = \mathbf{I} \vec{x} + [0] \vec{u}$$

a) Find TF matrix

$$\frac{\vec{Y}(s)}{\vec{U}(s)} = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B} + \mathbf{D}$$

$$s\mathbf{I} - \mathbf{A} = \begin{pmatrix} s & -1 \\ 25 & s+4 \end{pmatrix} \Rightarrow \det(s\mathbf{I} - \mathbf{A}) = s^2 + 4s + 25 = A(s)$$

$$\text{cofactor} = \begin{pmatrix} s+4 & -25 \\ 1 & s \end{pmatrix}$$

$$\text{cofactor}^T = \begin{pmatrix} s+4 & 1 \\ -25 & s \end{pmatrix}$$

$$\begin{pmatrix} s+4 & 1 \\ -25 & s \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} s+4 & s+4+1 \\ -25 & s-25 \end{pmatrix}$$

$$\boxed{\frac{\vec{Y}(s)}{\vec{U}(s)} = \begin{pmatrix} B_{11}(s) & B_{12}(s) \\ B_{21}(s) & B_{22}(s) \end{pmatrix} \cdot \frac{1}{A(s)} = \begin{pmatrix} s+4 & s+5 \\ -25 & s-25 \end{pmatrix} \cdot \frac{1}{s^2 + 4s + 25}}$$

b) on next page

c) graph on next page

The $T(s)_{21}$ term is the input 1, output 2 channel. It starts at zero because the B matrix shows that the first input has no direct impact on the second output. Looking at the Laplace transform, it is in the form of a decaying sine wave:

$$\mathcal{L}^{-1}\left[\frac{25}{s^2 + 4s + 25}\right] = \mathcal{L}^{-1}\left[\frac{-25 \frac{\sqrt{21}}{\sqrt{21}}}{(s+2) + 21}\right] = -\frac{25}{\sqrt{21}} \cdot e^{-2\omega t} \sin \omega t \cdot u(t)$$

The other terms are superpositions of decaying sine + cosine waves. The outputs directly affect their outputs, which lead to the cos terms. The impulse with zero I.C.'s cause this response.