## Initial data for stat OD project

```
mu = 3.986004415e14; %m3/s2
J2 = 1.082626925638815e-3;
Re = 6378136.3; %m
theta_dot = 7.2921158553e-5; %rad/s
site(1).name = 'Pacific Ocean Ship Sensor';
site(1).id = 101;
site(1).r = [-5127510.0 -3794160.0 0.0]'; % m
site(2).name = 'Pirinclik, Turkey';
site(2).id = 337;
site(2).r = [3860910.0 3238490.0 3898094.0]'; % m
site(3).name = 'Thule, Greenland';
site(3).id = 394;
site(3).r = [549505.0 -1380872.0 6182197.0]'; % m
ri = [757700.0 5222607.0 4851500.0]';
vi = [2213.21 4678.34 -5371.30]';
drag.Cd = 2.0;
drag.A = 3.0; % m
drag.m = 970; %kg
% kilometerize everything
% mu = mu*1e-9;
Re = Re*1e-3;
% site1.r = site1.r*1e-3; %km
% site2.r = site2.r*1e-3; %km
% site3.r = site3.r*1e-3; %km
% ri = ri*1e-3;%km
vi = vi*1e-3;%km/s
state = [ri; vi; mu; J2; drag.Cd; site(1).r; site(2).r; site(3).r];
% Set up propagator options
propagator_opts.mu = mu;
propagator opts.drag = drag;
propagator_opts.drag.use = 1;
propagator_opts.drag.model_params.rho0 = 3.614e-13; %kg/m3
propagator_opts.drag.model_params.r0 = 700000+6378136.3;
propagator_opts.drag.model_params.H = 88667;
propagator_opts.drag.model_params.theta_dot = theta_dot;
propagator_opts.J2.use = 1;
propagator_opts.J2.params.J2 = J2;
```

```
propagator_opts.J2.params.mu = mu;
propagator opts.J2.params.Re = Re;
propagator_opts.OD.use = 1;
propagator_opts.OD.state_len = 18;
propagator_opts.OD.A_mat_handle = @stat_od_proj_A;
propagator_opts.OD.A_params.Re = Re;
propagator_opts.OD.A_params.area = drag.A;
propagator_opts.OD.A_params.rho = propagator_opts.drag.model_params.rho0;
propagator_opts.OD.A_params.theta_dot = theta_dot;
propagator_opts.OD.A_params.m = drag.m;
propagator_opts.OD.A_params.H = propagator_opts.drag.model_params.H;
important block = [9 9];
propagator_opts.OD.A_params.important_block = important_block;
propagator_opts.OD.A_params.state_len = propagator_opts.OD.state_len;
STM_i = eye(propagator_opts.OD.state_len);
state = [state; reshape(STM_i(1:important_block(1),1:important_block(2)),...
    important_block(1)*important_block(2),1)];
```

Published with MATLAB® R2013b